Structure

void setup(){ ... }
Initialization function.

void loop(){ ... }
Main program loop.

Control Structures

Run a block of code only if a condition is true. If an else statement is present, run this block if condition is false.

for(int i=0; i<255; i++){ ... }
Loop for a set count.</pre>

while(x<5){ ... }

Loop while a condition is true.

break

Escape from a loop control structure,

continue

Escape from the current iteration of a control structure

General Operators

Assignment.

+, -, *, /, %

Plus, minus, multiply, divide, modulo.

==, !=

Equal to, not equal to.

<, <=, >, >=

Less than, less than or equal to, greater than, greater than or equal to.

Bitwise Operators

&, |, ^, ~

Bitwise AND, OR, XOR, NOT.

<<. >>

Bitwise left shift, bitwise right shift.

Compound Operators

++, --, +=, -=, *=, /=, &=, !=

Increment, decrement, compound addition, compound subtraction, compound multiplication, compound division, compound bitwise AND, compound bitwise OR.

Pointer Access

&, [;]

Reference operator, dereference operator.

Constants

HIGH, LOW

Pin value constants.

OUTPUT, INPUT, INPUT_PULLUP, INPUT PULLDOWN

Pin mode constants.

true, false

Boolean constants.

Data Types

void

Function type declaration for functions that return no information.

boolean

eg, true or false

char

8-bit (1-byte) number from -128 to 127.

byte

8-bit (1-byte) unsigned number from 0 to 255.

int

32-bit (4-byte) value from -2,147,483,648 to 2.147.483.647.

unsigned int

32-bit (4-byte) value from 0 to 4,294,967,295.

long

32-bit (4-byte) value from -2,147,483,648 to 2.147.483.647.

unsigned long

32-bit (4-byte) value from 0 to 4,294,967,295.

short

16-bit (2-byte) value from 32,768 to 32,767.

float

32-bit (4-byte) floating point number.

double

64-bit (8-byte) floating point number.

Arrays

int myArray[6];

An unpopulated integer array with 6 slots.

int $myArray[] = \{1,2,3,4,5,6\};$

A populated integer array with 6 slots.

int $myArray[6] = \{1,2,3,4\};$

A partially populated integer array with explicitly 6 slots.

Strings

Basic strings are represented as char arrays, however the spark core also has a <u>String class</u> with many more helper methods.

```
char s1[15];
char s2[6] = {'s','p','a','r','k'};
char s3[6] = {'s','p','a','r','k','\0'};
char s4[] = "spark";
char s5[6] = "spark";
char s6[15] = "spark";
```

Math

min(x, y);

Calculates the minimum of two numbers.

max(x, y);

Calculates the maximum of two numbers.

abs(x);

Computes the absolute value of a number.

constrain(x, min, max);

Constrains a number to be within a range.

map(x, fromMin, fromMmax, toMin, toMax);

Re-maps a number from one range to another.

pow(base, exponent);

Calculates the value of a number raised to a power.

sqrt(x);

Calculates the square root of a number.

Time

The spark core comes with basic timing methods, but also has a <u>Time class</u> with many more helper methods.

millis();

Returns the number of milliseconds since the Spark Core began running the current program.

micros():

Returns the number of microseconds since the Spark Core began running the current program.

delay(ms);

Pauses the program for the amount of time (in miliseconds) specified.

delayMicroseconds(ms);

Pauses the program for the amount of time (in microseconds) specified.

1/0

pinMode(pin, mode);

Configures the specified pin to behave either as an input or output.

digitalWrite(pin, value);

Write a HIGH or a LOW value to a digital pin.

digitalRead(pin);

Reads the value from a specified digital pin, either HIGH or LOW.

analogWrite(pin, value);

Writes an analog value (PWM wave) to a pin.

analogRead(pin);

Reads the value from the specified analog pin. Values range between 0 and 4095.



Interrupts

attachInterrupt(pin, function, mode);

Specifies a function to call when an external interrupt occur

detachInterrupt(pin);

Turns off the given interrupt.

noInterrupts();

Disabled interrupts.

interrupts();

Re-enabled interrupts.

Tone

tone(pin, frequency, duration);

Generates a square tone on the given pin.

noTone(pin);

Stops the current tone playing on the given pin

RGB

RGB.control(bool);

Takes and gives back user control of the built in RGB LED.

RGB.color(red, green, blue);

Set the color of the RGB with three values, 0 to

RGB.brightness(val);

Scale the brightness value of all three RGB colors with one value. 0 to 255.

Servo

servo.attach(pin);

Setup a servo on a particular pin.

servo.detach():

Detach the servo variable from its pin.

servo.write(angle);

Set the angle of the servo.

servo.read();

Reads the current angle of the servo.

Cloud Functions

Spark.variable(name, var, type);

Expose a variable through the Spark Cloud.

Spark.function(name, function);

Expose a function through the Spark Cloud.

Spark.publish(name, data);

Publish an event through the Spark Cloud.

Spark.subscribe(name, function);

Subscribe to events published by Cores.

Cloud API

HEADER Bearer {ACCESS TOKEN}, ?access_token={ACCESS_TOKEN}

Authenticates the request with the given access token.

GET /v1/devices/{DEVICE ID}/{VARIABLE}

Read a variables exposed through the Spark Cloud from the given device.

POST /v1/devices/{DEVICE ID}/{FUNCTION}

Call a method exposed through the Spark Cloud on the given device.

GET /v1/devices/{DEVICE_ID}/events/ [/{EVENT}]

Open an SSE connection to the given devices event stream. .

Misc

// ...

Single line comment.

/* ... */

Multi-line comment.

#define ANSWER 42

Constant variable declaration.

#include <myLib.h>

Includes a third party library.

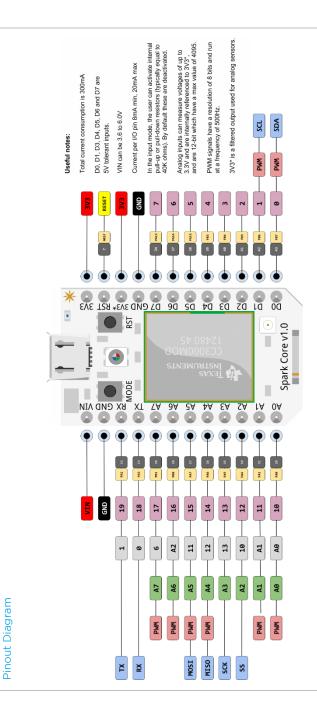




Diagram Created by Jonathan Beri / BDub http://google.com/+jonathanberi