

DE LA RECHERCHE À L'INDUSTRIE



On the road to TFEL 3.x

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A changing development model

- Up to now, MFront was developed to meet PLEIADES project needs :
 - clear financial support
 - clear objectives : fuel performances codes
- With open-source, things may change :
 - "open-sourcisation" was funded by EDF and CEA :
 - ▶ for 2015, support is limited to the web site maintenance and documentation (ex : mtest documentation)
 - interest of a broader community :
 - ▶ external contributions are welcomed !
 - ▶ search of additional financial support

**Planned new mfront
features**

- tangent consistent operator for `MultipleIsotropicMisesCreep`;
- plane stress (and generalised plane stress) support for specific behaviours

Interesting for the Cyrano fuel performances codes : planned for 2015/2016

- the mechanical behaviour shall (to be developed) :
 - give an estimate of the next time step
 - warn if the given strain increment is too large
 - warn if the given strain increment leads to unreliable results :
 - ▶ an increment of 10 % of the equivalent plastic strain is **not** admissible whatever the integration scheme is used
- consistent tangent operators in Cast3M/PLEIADES

**Depends on the evolution of the PLEIADES/COPL operator
(2015/2016)**

**Interesting evolutions
of MFront**

- TFEL heavily relies on advanced programming techniques :
 - this is a **serious** maintainability issue
- Most of those techniques are now part of the C++11 standard
 - this was anticipated !!
 - we reduced the code size by more than 10 % only by removing some header and using sed !
 - generated code is more than 11 % smaller !
- There could be a performance win

- the "true" Powell dogleg algorithm
- the Brent method (scalar non linear equation)
- introduce other trust region update algorithm :
 - in particular non monotonic ones

```
@DSL Implicit;
@Behaviour OrthotropicElasticity;

@OrthotropicBehaviour;
@RequireStiffnessTensor;
@Brick "StandardElasticity";
```

- making a portable behaviour requires *too much of boiler plate* code :
 - \approx 50% of the ImplicitNorton example
 - most of them are related to elasticity!
- most behaviours are build by adding (uncoupled) plastic/viscoplastic flows and a (damaged) elasticity tensor
- We want to introduce *mechanical behaviour bricks* in MFront :
 - must be compatible/consistent with current MFront practices
 - ▶ some parts of the behaviour may come from bricks, other may come from standard user code
 - ▶ one must take care of evil details : variation of material properties with temperature, etc..
 - ▶ requires a dependency manager à la licos
 - one may provide robust and optimised implementations
 - we already have an experimental Elasticity brick

- integration of some common mechanical behaviours can be written as a minimisation of this potential :

$$\rho \phi \left(\vec{Y} \Big|_{t+\Delta t}, \underline{\epsilon}^{to} \right) + \Delta t D \left(\frac{\vec{Y} \Big|_{t+\Delta t} - \vec{Y} \Big|_t}{\Delta t} \right)$$

- formalism used in `matlib`?
- could probably be extended to implicit standard materials (bipotential)...
- only requires on function definition :
 - (smart)-automatic differentiation?