

Analysis_of_Uncertainty

May 25, 2017

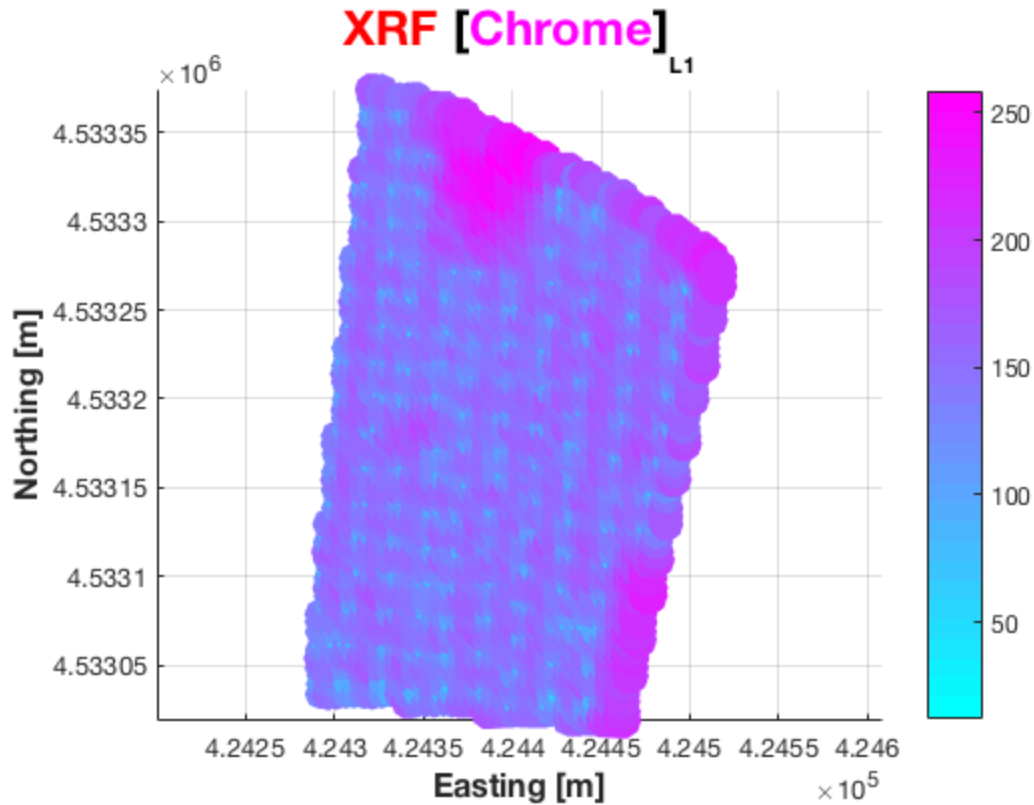
0.0.1 P A R s

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In [18]: WDIR = '~/git/seminars/Siti_Contaminati/';  
load( fullfile(WDIR,'geotables.mat'), 'T' )  
  
In [42]: % ____Geostatistical Conditional Simulation____  
% <L1>  
ChEl      = 'Chrome';  
NSIM      = 200;  
opt       = strcat( 'empty2NaN' );  
L         = 1;% for loop on L = 1:3 !!  
gcs.L     = greadtext( fullfile(WDIR,['L',num2str(L),'_gcs_raw.txt']), ',', '\n', '\t', '\r', '\f' );  
  
In [43]: Easting      = cae(gcs.L,1);  
Northing    = cae(gcs.L,2);  
gcssim      = 1;% for loop on gcssim = 1:NSIM  
%eval( ['GCSMAP = cell2mat(gcs.L',num2str(L),'(2:end,2+gcssim));'] )% +2 :: ~Easting+Northing  
GCSMAP      = cae(gcs.L,2+gcssim);  
  
SIMs        = cae(gcs.L,3:NSIM+2);  
  
In [53]: xylabfs = 12;  
%% ----- spread on GCS maps  
MED = median(SIMs,2);  
MEA = mean(SIMs,2);  
STD = std(SIMs,[],2);  
SumSim = sum( SIMs, 2 );  
  
% S C A T T E R  
MAP2PLOT = STD;  
Idepths = (T(1).xrf_limsup + T(1).xrf_liminf) / 2;  
Zm = zeros(size(GCSMAP)) + Idepths(L);  
figure  
% scatter3( Easting, Northing, -Zm(:), SumSim,SumSim, 'filled' )  
scatter3( Easting, Northing, -Zm(:), MAP2PLOT,MAP2PLOT, 'filled' )  
colormap(cool(32)), colorbar  
title(['\fontsize{18}\color{red}XRF \color{black}[\color{magenta}',ChEl,...  
'\color{black}]\fontsize{10}_{L',num2str(L),'}' ], 'FontWeight','b','FontSize',22)
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xlabel('Easting [m]', 'FontWeight', 'b', 'FontSize', xlabfs),
ylabel('Northing [m]', 'FontWeight', 'b', 'FontSize', xlabfs),
zlabel('Depth [mm]', 'FontWeight', 'b', 'FontSize', xlabfs)
view(2), axis equal

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In [50]: %% ----- Probability distribution function
%% ----- ___PIXEL___
% ----pars-----
THRESHOLD = 350;
ROW = [12,1492,1977];
% ----pars-----
pixel = SIMs(ROW,1:100);
figure(6), clf, plot(sort(pixel,2, 'descend'), 1:100, 'LineWidth', 2)
% cAX = axis; cAX(1)=0; axis(cAX);
cAX=axis;
title('Probability distribution functions of 3 random pixels')
ylabel('Probability, %')
xlabel(' [ChEl, ' concentration [ppm]' ] )

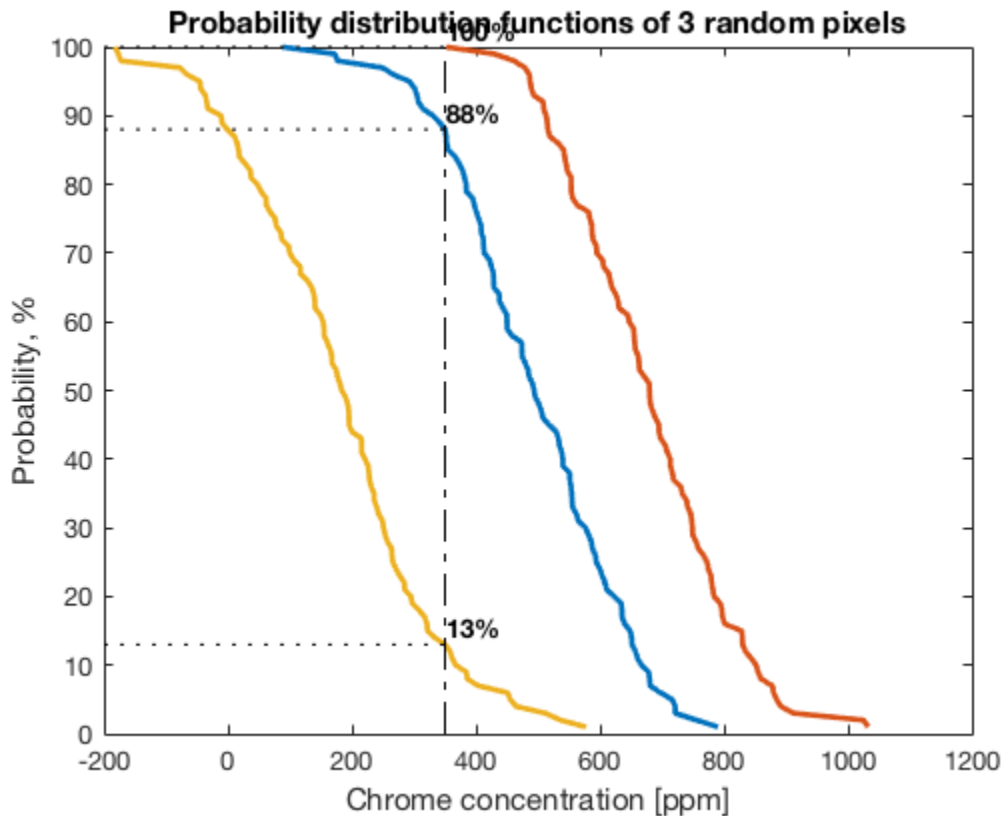
hold on, line([THRESHOLD,THRESHOLD],[0,100], 'LineStyle', '-.', 'color', 'k'), hold off

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Pr = sum(pixel>=THRESHOLD,2) / size(pixel,2) * 100;
% hold on, line(repmat([cAX(1),THRESHOLD],3,1),[Pr,Pr],'color','k'), hold off
hold on
for ii = 1:numel(ROW)
    if Pr(ii)==0, continue, end
    line([cAX(1),THRESHOLD],[Pr(ii),Pr(ii)],'LineStyle',':','color','k')
    text(THRESHOLD,Pr(ii),[num2str(Pr(ii)),'%'],'HorizontalAlignment','left','VerticalAlignment','bottom')
end
hold off

```



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In [52]: %% ----- MAP-----
% -----pars-----
THRESHOLD = 350;
% -----pars-----
Pr = sum(SIMs>=THRESHOLD,2) / size(SIMs,2) * 100;

% S C A T T E R
MAP2PLOT = Pr;
Idepths = (T(1).xrf_limsup + T(1).xrf_limin) / 2;
Zm = zeros(size(GCSMAP)) + Idepths(L);
figure(9)

```

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% scatter3( Easting, Northing, -Zm(:), SumSim,SumSim, 'filled' )
scatter3( Easting, Northing, -Zm(:), MAP2PLOT+0.1,MAP2PLOT, 'filled' )
colormap(cool(32)), colorbar
title(['\fontsize{18}\color{red}XRF \color{black}[\color{magenta}',ChEl,...
        '\color{black}]\fontsize{10}_{Probability Distribution}'], 'FontWeight','b','Font
xlabel('Easting [m]', 'FontWeight','b','FontSize',xylabfs),
ylabel('Northing [m]', 'FontWeight','b','FontSize',xylabfs),
zlabel('Depth [mm]', 'FontWeight','b','FontSize',xylabfs)
view(2),axis equal

```

