

# Management and analysis of physics datasets, Part. 1

## Eleventh Laboratory

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19/01/2021

## Laboratory Introduction

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- Some arithmetic operations in VHDL.
- FIR (Finite Impulse Response) filter in VHDL.

## Arithmetic operations

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Or rather, just the arithmetic operations preparatory for this laboratory.

- Numbers are represented as arrays.
- The numbers, in this laboratory, must be signed.
- The arithmetic operations exploited are sum and multiplication.
- The function to convert a *std\_logic\_vector* signal to a *signed* signal and vice versa are compulsory.

```
-- Uncomment the following library declaration if using  
-- arithmetic functions with Signed or Unsigned values  
use IEEE.NUMERIC_STD.ALL;
```

Declaration

```
signal x : std_logic_vector(N-1 downto 0);  
signal s : signed(N-1 downto 0);
```

Conversion

```
x <= std_logic_vector(s);  
s <= signed(x);
```

*std\_logic\_vector* Assignment

```
X <= "01010110";  
X <= x"a6";
```

*signed* Assignment

```
s <= to_signed(10, N);  
s <= to_signed(-10,N);
```

- $13 \times 3 = 39$ ;
- $1101_2 \times 11_2 = 100111_2$ ;
- $(4 \text{ elements}) \times (2 \text{ elements}) = 6 \text{ elements}$ ;
- $\Rightarrow$
- $(N1 - 1 \text{ downto } 0) \times (N2 - 1 \text{ downto } 0) = (N1 + N2 - 1 \text{ downto } 0)$ ;



If a number is less than one:

- $20 \times 0.75 = 15$ ;
- $10100_2 \times 0.11_2 = 1111_2$ ;
- **How realize this operation in VHDL?**
- Scale-up the number less than zero of certain quantity  $Q$ . For example  $Q = 3$ .
- $0.11_2 \ll Q = 110_2$ . That is  $0.75 * 2^3 = 6$ .
- Then:  $10100_2 \times 110_2 = 1111000_2$
- Finally scale-down of the same quantity  $Q$ , that is  $1111000_2 \gg Q = 111_2$ . That is  $120 : 2^3 = 15$ .

If a number is less than one:

- $20 \times 0.057 = 1.11$ ;
- But  $0.057 \times 2^Q$  for each  $Q$  chosen is never integer. Therefore it is necessary a trade-off between the number of bits and the approximation wished.

- In order to do this kind of arithmetic operations is necessary change the dimension of the arrays and scale (up or down) the numbers.
- The numbers in this laboratory are represented as **signed** type.
- You can find a complete list of the operation at this . Except the sum (+) and the multiplication (\*), may be useful two functions:
  1. RESIZE;
  2. SHIFT\_RIGHT.

## Finite Impulse Response filter

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## Finite impulse response

From Wikipedia, the free encyclopedia

In [signal processing](#), a **finite impulse response (FIR) filter** is a [filter](#) whose [impulse response](#) (or response to any finite length input) is of *finite* duration, because it settles to zero in finite time. This is in contrast to [infinite impulse response \(IIR\)](#) filters, which may have internal feedback and may continue to respond indefinitely (usually decaying).

The [impulse response](#) (that is, the output in response to a [Kronecker delta](#) input) of an  $N$ th-order discrete-time FIR filter lasts exactly  $N + 1$  samples (from first nonzero element through last nonzero element) before it then settles to zero.

FIR filters can be [discrete-time](#) or [continuous-time](#), and [digital](#) or [analog](#).

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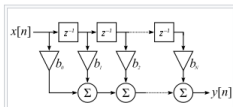
### Definition [ edit ]

For a [causal discrete-time](#) FIR filter of order  $N$ , each value of the output sequence is a weighted sum of the most recent input values:

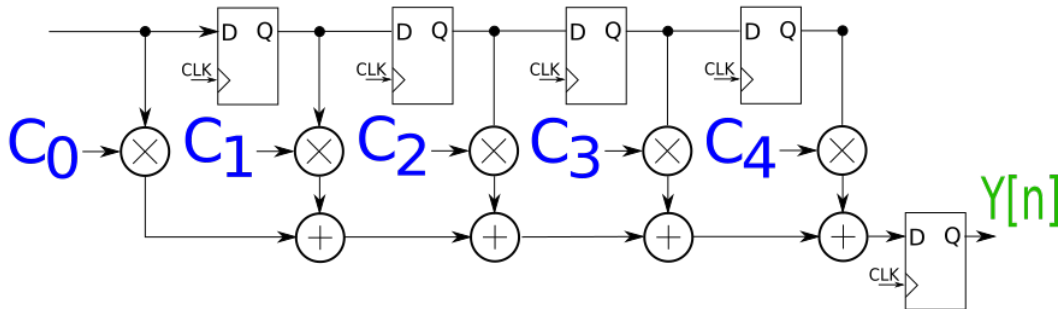
$$\begin{aligned}y[n] &= b_0x[n] + b_1x[n-1] + \cdots + b_Nx[n-N] \\ &= \sum_{i=0}^N b_i \cdot x[n-i],\end{aligned}$$

where:

- $x[n]$  is the input signal,
- $y[n]$  is the output signal,
- $N$  is the filter order; an  $N$ th-order filter has  $(N + 1)$  terms on the right-hand side



A direct form discrete-time FIR filter of order  $N$ . The top part is an  $N$ -stage delay line with  $N + 1$  taps. Each unit delay is a  $z^{-1}$  operator in [Z-transform](#) notation.

$X[n]$ 

This FIR filter circuit is described by the equation:  $y[n + 1] = \sum_{i=0}^4 x[n - i] * C_i$

FIR filter(4)  $y[n + 1] = \sum_{i=0}^N x[n - i] * C_i$

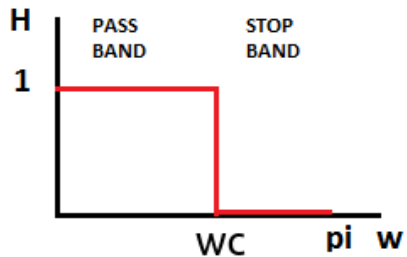
A numerical example. Data:

- $x[n] = 1 \forall n \geq 0$  ;
- $C_0 = 1, C_1 = 2, C_2 = 3, C_3 = 4, C_4 = 5,$

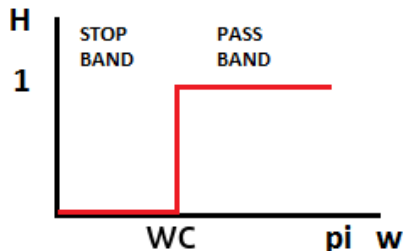
Then:

- $y[0] = 0$  ;
- $y[1] = x[0] * C_0 = 1;$
- $y[2] = x[1] * C_0 + x[0] * C_1 = 3;$
- $y[3] = x[2] * C_0 + x[1] * C_1 + x[0] * C_2 = 6$
- $y[4] = x[3] * C_0 + x[2] * C_1 + x[1] * C_2 + x[0] * C_3 = 10$
- $y[5] = x[4] * C_0 + x[3] * C_1 + x[2] * C_2 + x[1] * C_3 + x[0] * C_4 = 15$
- $y[n] = x[n-1] * C_0 + x[n-2] * C_1 + x[n-3] * C_2 + x[n-4] * C_3 + x[n-5] * C_4 \forall n \geq 5$

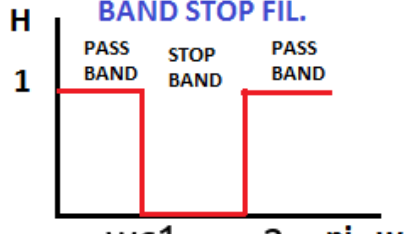
LOW PASS FIL.



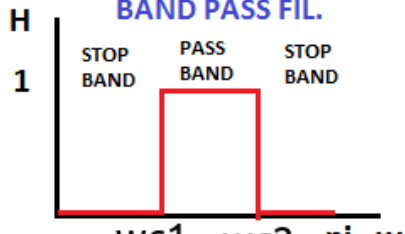
HIGH PASS FIL.



BAND STOP FIL.



BAND PASS FIL.





You can use the python function `firwin` to generate the FIR filter coefficients.

- It is set to compute the coefficients of a  $N$  tap digital low-pass filter.
- $N$  tap means  $N$  coefficients.
- 0.1 is the cutt-off frequency, that is  $w_c = 0.1 * \pi$ . For example a typical sampling frequency of an audio wav file is  $f_s = 11025$  Hz. So 0.1 means  $f_c = 0.1 * f_s / 2 \approx 550$  Hz.
- The script gives the coefficients:  $C_0 = C_4 = 0.19335315$ ,  $C_1 = C_3 = 0.20330353$  and  $C_2 = 0.20668665$ .

## FIR filter coefficients (2)

