



Dipartimento
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e Astronomia
Galileo Galilei



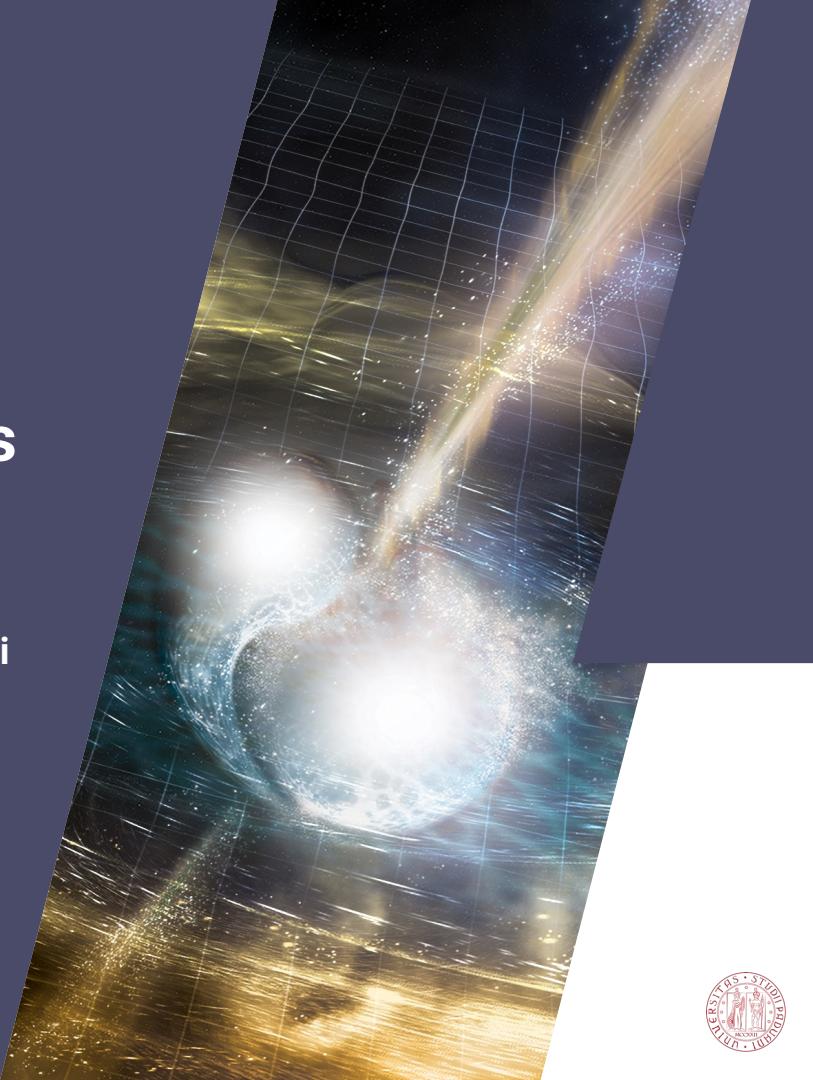
UNIVERSITÀ
DEGLI STUDI
DI PADOVA

Distribution of a Population of Gravitational Waves Sources

By Giulia Doda & Laura Ravagnani

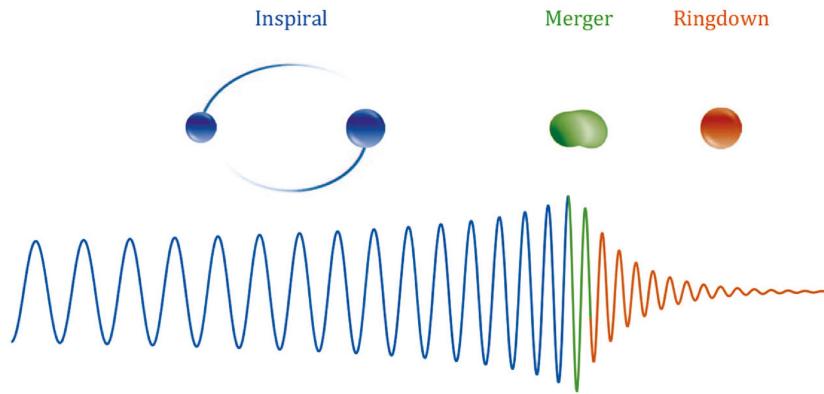
*Advanced Statistics for Physics
Analysis – Final Project*

4th July 2023



Introduction

Gravitational waves (GW) are ripples in space-time traveling at the speed of light. The most common **sources** of GWs are compact binary coalescences (**CBCs**). Compact binary systems are binary black holes (BBHs), binary neutron stars (BNSs), and black hole/neutron star binaries (NS-BHs).



The **interaction** between the two objects and their subsequent **merger** result in a **GW emission**.

The Physical Problem

Why do we care about the population distribution of GW sources?

The population distribution of GW sources can answer some questions about the **evolution of the Universe and of the GW sources** themselves:

- *How many GW sources are there in the Universe?*
- *Has the population of compact objects changed as the Universe has evolved?*
- *How do compact binaries form?*

Each possible answer is associated with a different population distribution of GW sources.



Our Problem

How can we understand the population distribution of GW sources from GW observations?

Interferometers such as LIGO and Virgo observe GWs from CBCs, and from these events we can obtain information about the population distribution of GW sources. More specifically, in this work **we want to understand from some simulated observations whether the population density follows one distribution or another.**



Our Problem

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we will focus on observations from BNS mergers



Our Analysis

1

Statistical
model for the
number of
sources N

2

Simple
detection
efficiency
model ε

3

Simulated GW
observations
from two
different
population
models

4

Analysis of the
population
density n

5

n estimate
dependencies
on the
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time T and the
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A Statistical Model for N

Hypotheses

- cosmological redshift $z \ll 1$
- numerical density of the sources population $n \ll 1 \text{ Mpc}^{-3} \text{ yrs}^{-1}$
- volume $V = 4\pi R^2 \Delta R$
- statistically independent sources positions



average number of sources

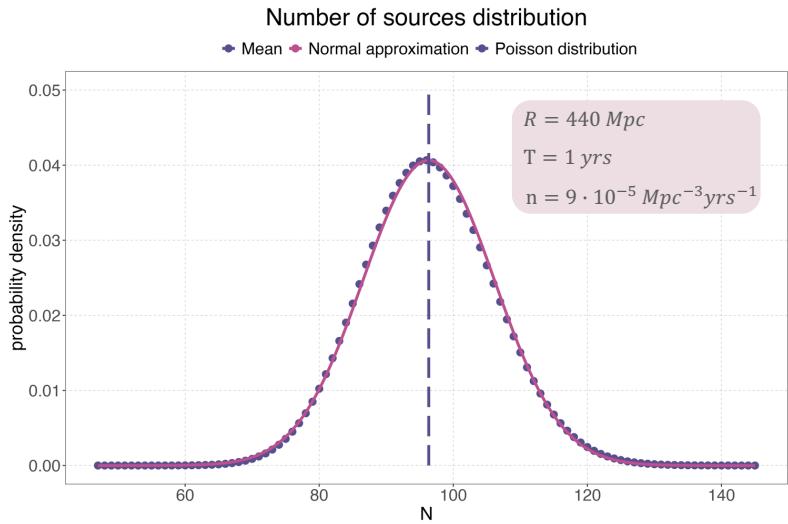
in a time interval T :

$$\langle N \rangle = nTV = nT4\pi R^2 \Delta R$$



the number of sources N

follows a **Poisson probability distribution** with rate $\lambda = \langle N \rangle$



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Simulated GW observations from two different population models

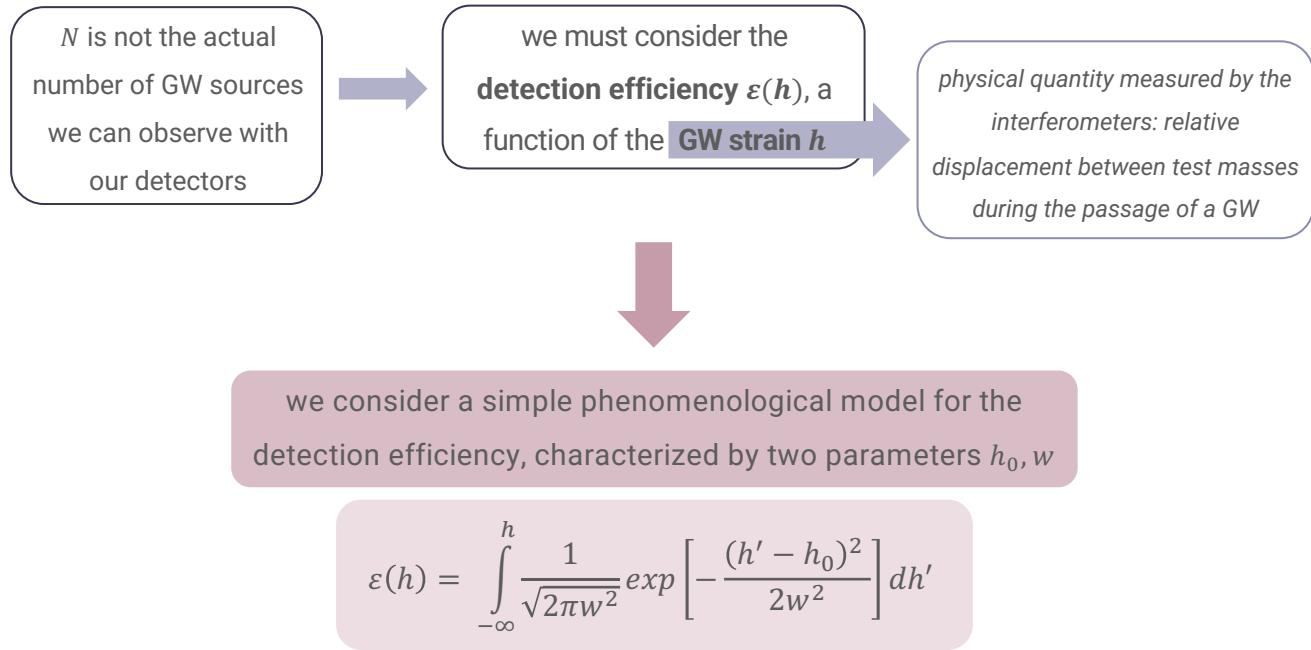
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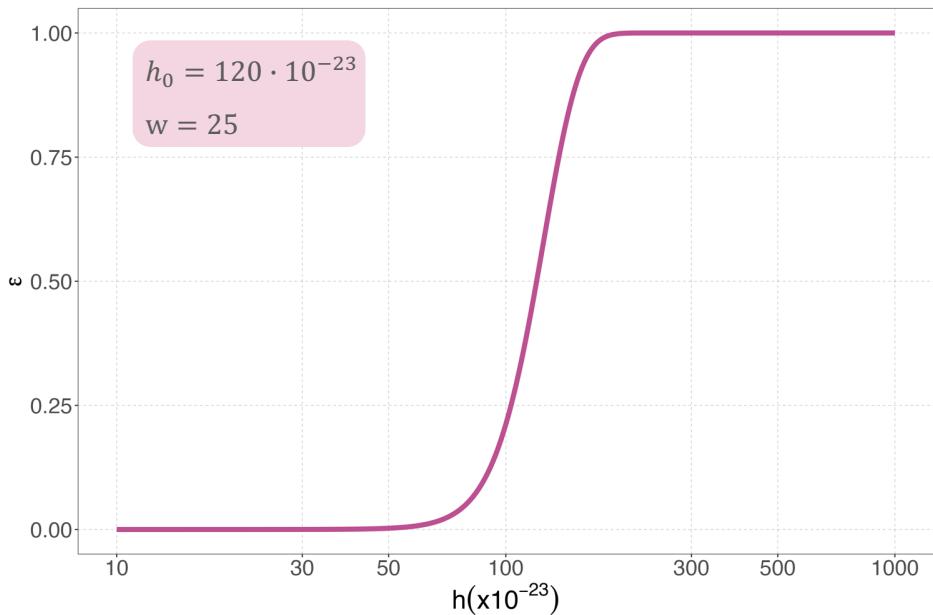
n estimate dependencies on the observation time T and the source distance r

Detection Efficiency



Then, the **number observed sources** results in $N_{obs} = N\varepsilon(h) = nTV\varepsilon(h)$

Detection Efficiency $\varepsilon(h)$



h_0

strain produced by a source positioned at distance r_0 such that

$$\varepsilon(h_0) = 0.5$$

w

adjusts the sigmoid slope around h_0

$$w \ll 1 \leftrightarrow \frac{\partial \varepsilon}{\partial h} \Big|_{h_0} \gg 1$$

Detection Efficiency $\hat{\varepsilon}(r)$

For the purpose of the analysis, we ignore distinctions due to:

- sources **polarization**
- sources **orientation**

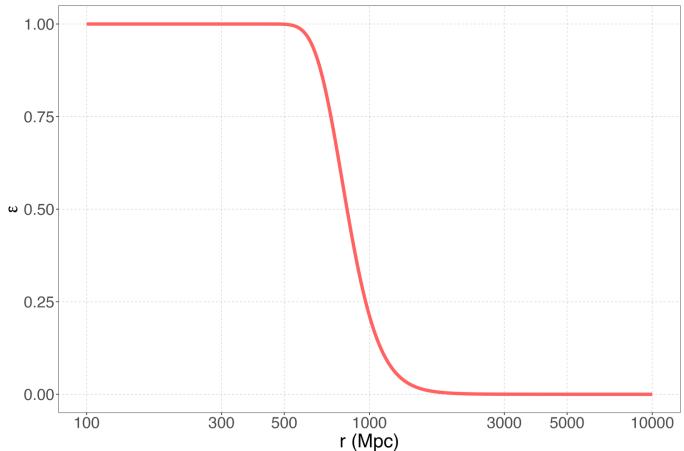
$$h \propto \frac{1}{r}$$

We also assume that the source **distance** is known with **no error**.



We can then express the detection efficiency as a function of the distance r :

$$\hat{\varepsilon}(r) = \varepsilon(r(h)) \propto \varepsilon\left(\frac{1}{h}\right)$$



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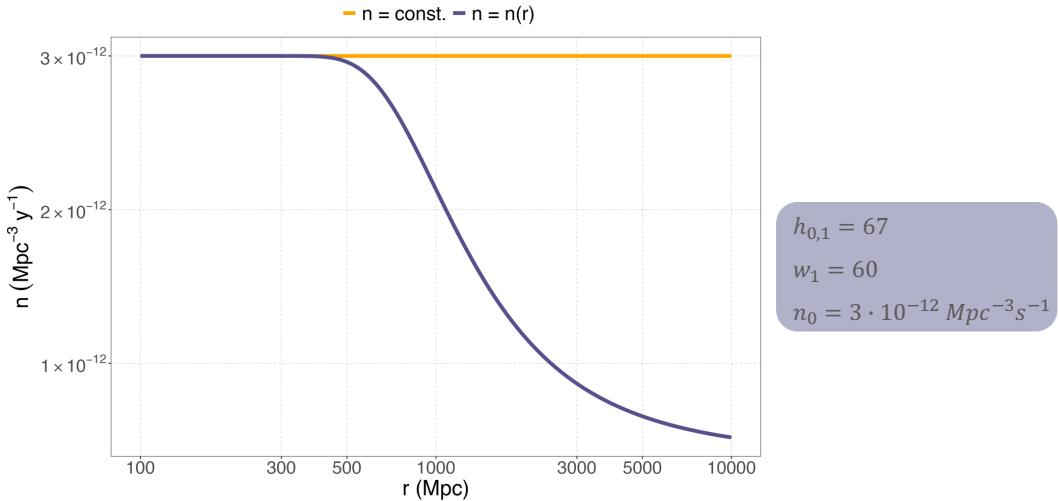
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Models for n



1st model: $n = \text{const.}$

the population density is constant over the source distance r :

$$n = 3 \cdot 10^{-12} \text{ Mpc}^{-3} \text{s}^{-1}$$

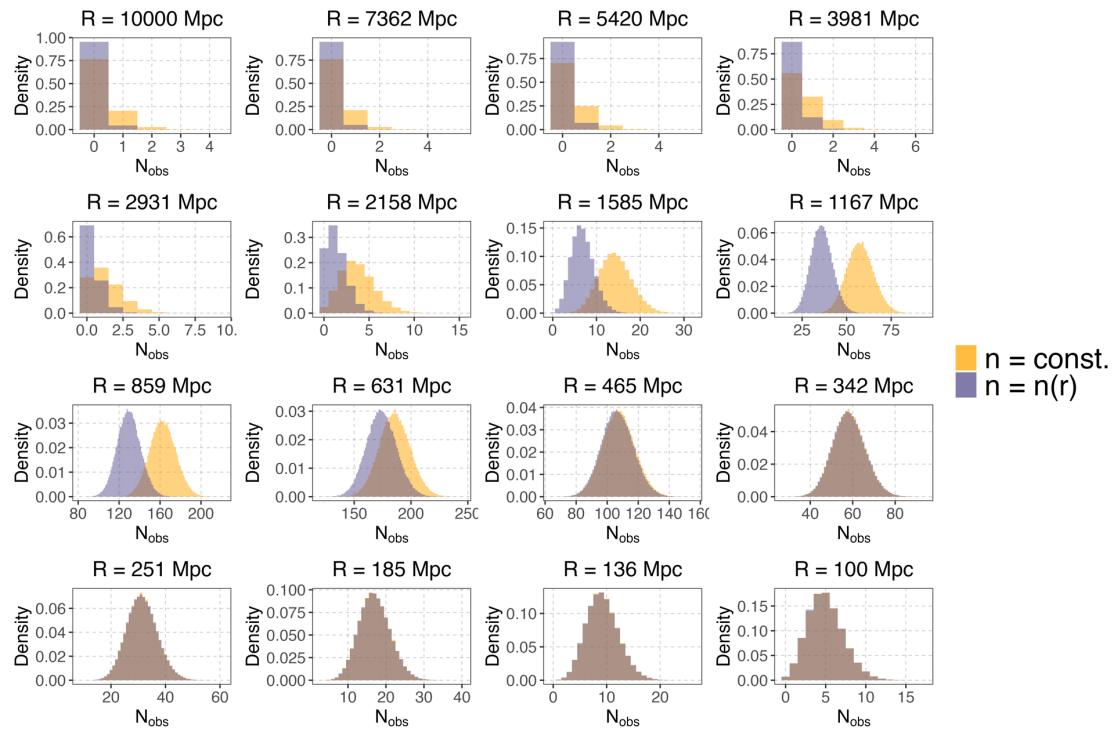
2nd model: $n = n(r)$

the population density decreases with the source distance r following a sigmoid function:

$$n(h) = n_0 \int_{-\infty}^h \frac{1}{\sqrt{2\pi w_1^2}} \exp\left[-\frac{(h' - h_{0,1})^2}{2w_1^2}\right] dh'$$

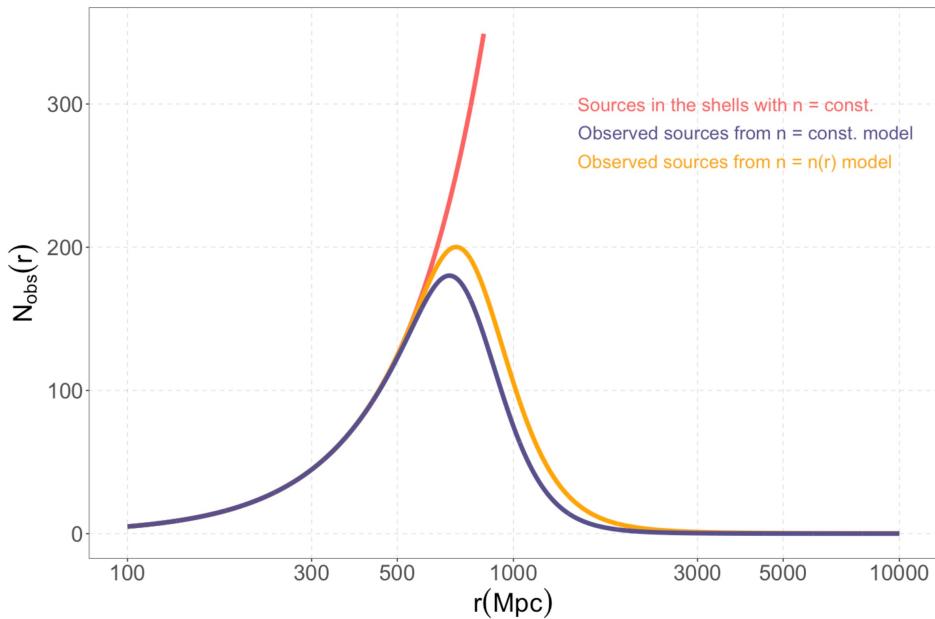
Simulations for N_{obs}

We simulate observations from both models following a **Poisson distribution with rate** $\lambda = n(r)TV$ keeping **fixed** the observation time T but changing the shell volume V by **changing** the source distance r



N vs N_{obs}

We compare also the number of observation N_{obs} as a function of r expected from the two different models for n and with the **number of sources N** if the population density is constant



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Bayesian inference on n

We now assume our **simulated data** of N_{obs} as **real data**



we want to find an estimate of $n(r)$ from the data as the source distance r varies,
for both datasets, so we perform **Bayesian inference**

First, we infer $\lambda = \hat{N}_{obs}$ and then we find an estimate and a reliability for $n(r)$ as

$$n(r) = \frac{\hat{N}_{obs}}{4\pi r^2 \Delta r T \varepsilon(r)} \quad \text{and} \quad \sigma_{n(r)} = \frac{\sigma_{\hat{N}_{obs}}}{4\pi r^2 \Delta r T \varepsilon(r)}$$

where \hat{N}_{obs} and $\sigma_{\hat{N}_{obs}}$ are respectively our best estimate and the reliability for N_{obs}

Bayesian inference on n

Bayes' theorem

$$P(\lambda|\{N\}) \propto f(\{N\}|\lambda) \times g(\lambda)$$

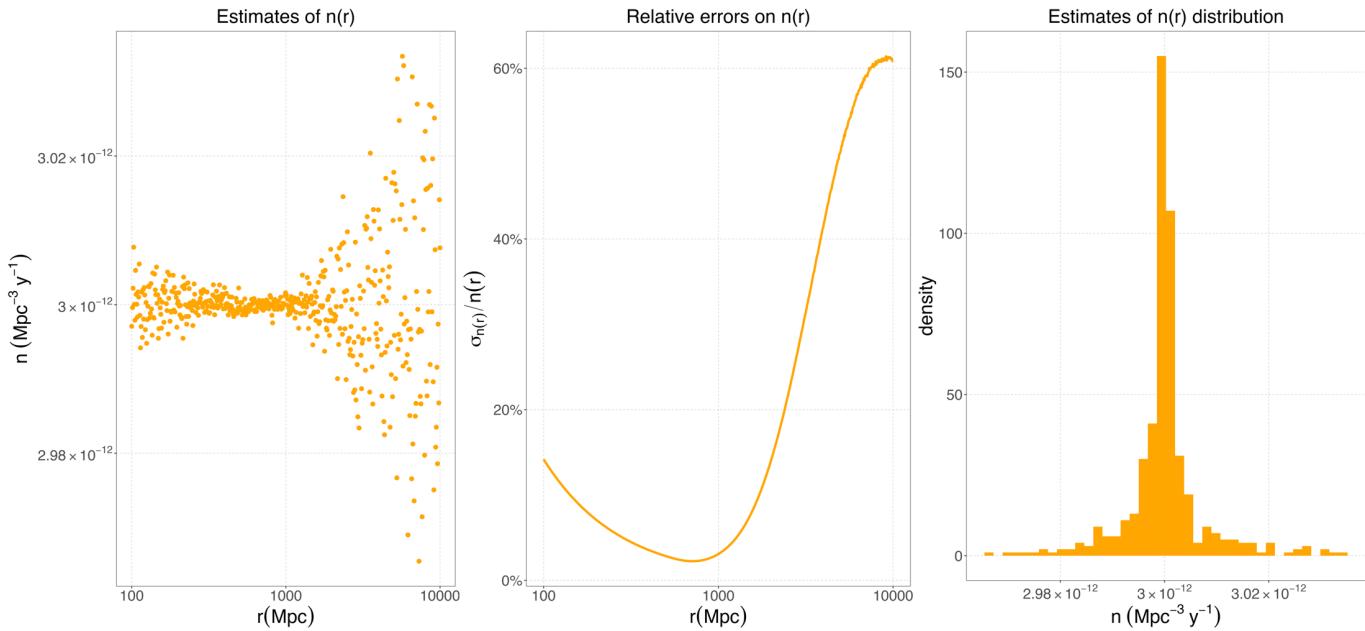
- Prior on λ : $Gamma(1, 0)$
- Likelihood of the data: $\prod Pois(\lambda = nTV) \rightarrow Gamma$
- Posterior for λ : $Gamma(\alpha_{post}, \beta_{post})$



$$\alpha_{post} = 1 + \sum_{i=1}^{n_{sample}} N_{obs,i}$$
$$\beta_{post} = 0 + n_{sample}$$

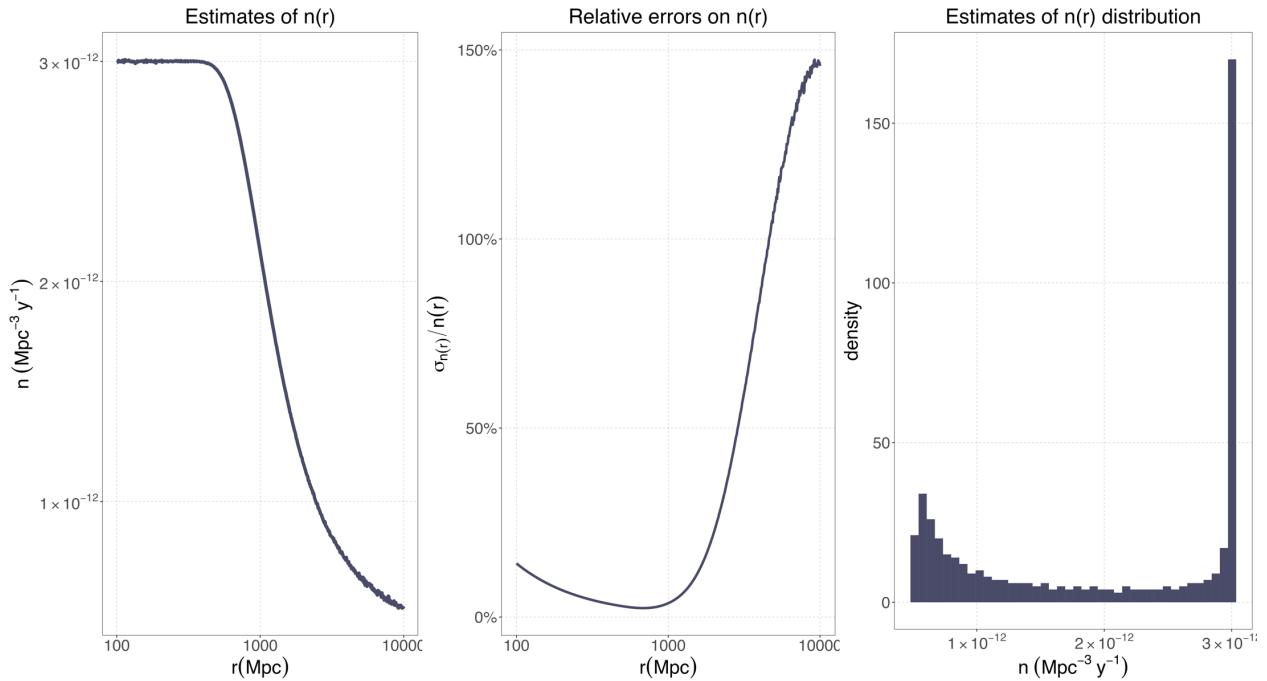
Bayesian inference on n

1st dataset – $n = const.$



Bayesian inference on n

2nd dataset – $n = n(r)$



Bayesian inference on $n(r)$ with JAGS

The analytical approach is not the only one and with MCMC

we can directly sample the posterior for $n(r)$



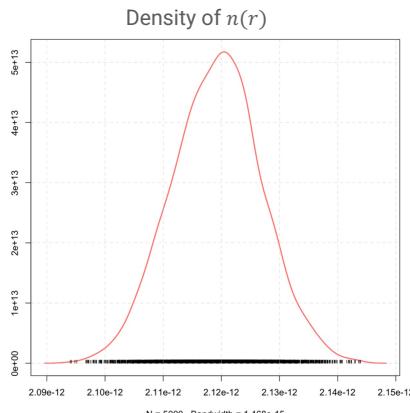
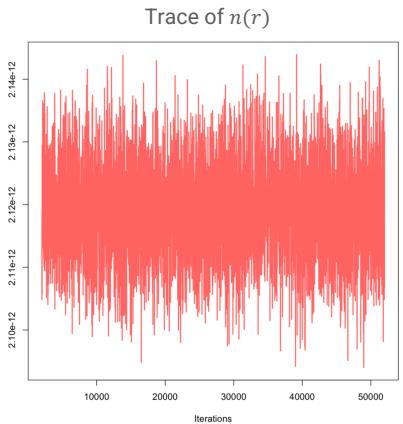
we simulate data only at $r = 10^3 \text{ Mpc}$ from the **second model** and we assume the data as real



we sample from the posterior distribution of $n(r)$ using **JAGS** and we perform Bayesian inference on $n(r)$



we find $n = (2.120 \pm 0.008) \cdot 10^{-12} \text{ Mpc}^{-3} \text{s}^{-1}$



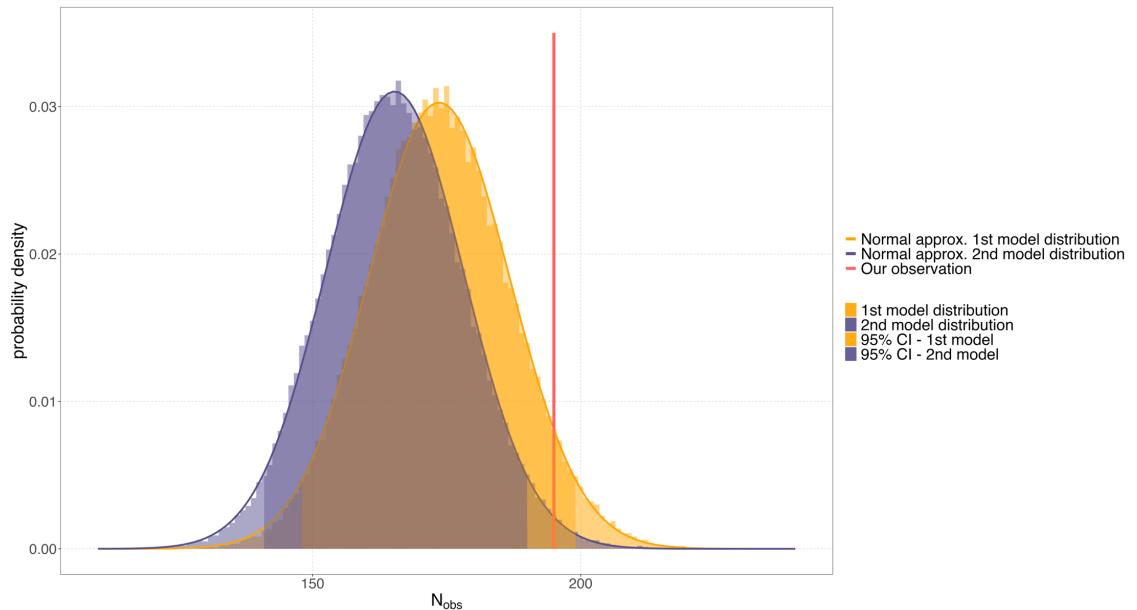
Bayesian HT

We now imagine to observe $N_{obs} = 195$ sources at $r = 600 \text{ Mpc}$:

we want to know if the correspondent population density belongs to the first or to the second model



Bayesian HT at $\alpha = 5\%$ level of significance



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n estimates dependencies from T and r

We want to understand in which range of observation time T we can discriminate the population density models, also with respect to the detection efficiency volume



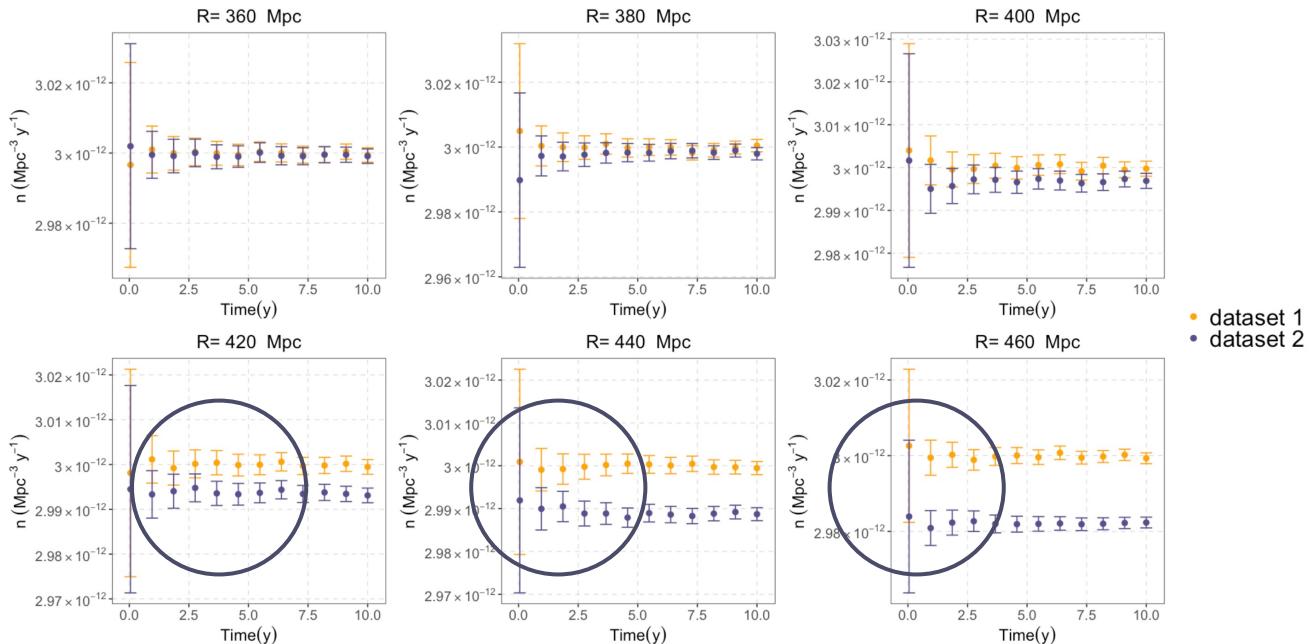
we perform the same Bayesian analysis as before, also considering the observation time T to study how it affects the estimates for n



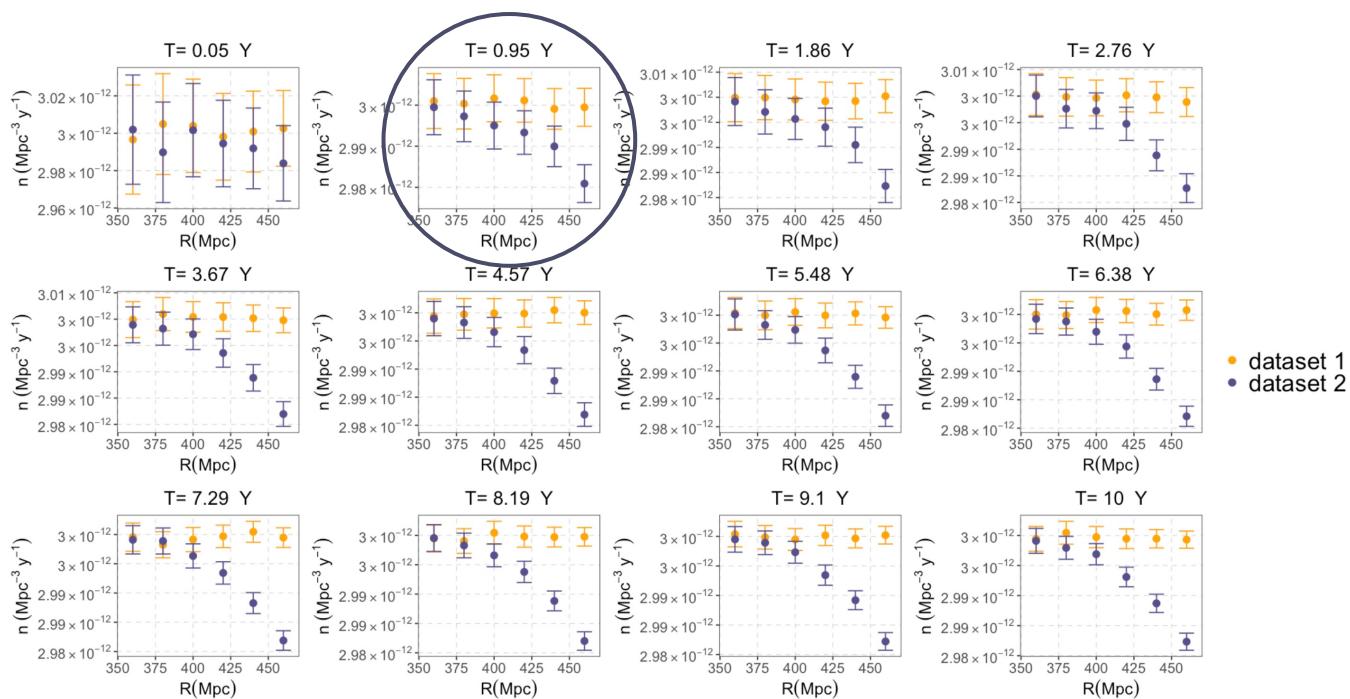
we compare n estimates to see if they are compatible



n estimates dependencies from T and r



n estimates dependencies from T and r



Conclusions

- **Introduction** to the real analysis done by the LIGO and Virgo collaboration
- Analysis of the **distribution of GW sources** with a simplified model for the detection efficiency
- Focus on **Bayesian inference** to study the sources population density



THANK YOU !