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In [1]: %matplotlib inline
import numpy as np
import matplotlib.pyplot as plt
import copy
plt.rc('font', family='serif')
executed in 301ms, finished 02:18:25 2021-12-05
```

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In [2]: d=1000 # d: dimension
n=2000 # n: number of points
A = np.random.normal(size=(n,d)) / np.sqrt(n) # matrix containing the data points
y = np.random.normal(size=n)
lambda= 1
executed in 78ms, finished 02:18:25 2021-12-05
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We consider the Ridge cost function:

$$f(x) = \frac{1}{2} \|Ax - y\|^2 + \frac{\lambda}{2} \|x\|^2, \quad (1)$$

where $\lambda > 0$ is some regularization parameter that we take equal to 1. The matrix A and the vector y are defined in the cell above.

(a) Show that f can be written in the format the function f of Problem 12.2, for some $M \in \mathbb{R}^{d \times d}$, $b \in \mathbb{R}^d$ and $c \in \mathbb{R}$. Compute numerically the values of L and μ . Plot the eigenvalues of $H_f(x)$ using an histogram.

We can manipulate the expression by expanding the terms with the squared norms, and then perform algebra to achieve the desired structure of $f(x) = x^T M x - \langle x, b \rangle + c$

$$\begin{aligned} f(x) &= \frac{1}{2} \|Ax - y\|^2 + \frac{\lambda}{2} \|x\|^2 \\ f(x) &= \frac{1}{2} (Ax - y)^T (Ax - y) + \frac{\lambda}{2} x^T x \\ f(x) &= \frac{1}{2} (x^T A^T A x - 2x^T A^T y + y^T y) + \frac{\lambda}{2} x^T x \\ f(x) &= \frac{1}{2} x^T (A^T A + \lambda Id) x - x^T A^T y + \frac{y^T y}{2} \end{aligned} \quad (2)$$

Now we have our ridge regression cost function in similar structure to that of a quadratic convex function,

$$f(x) = x^T M x - \langle x, b \rangle + c, \text{ where in our case, } M = A^T A + \lambda Id, b = A^T y \text{ and, } c = \frac{y^T y}{2}$$

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In [3]: #Create the identity matrix and the hessian
I = np.identity(n=d)
hessian_matrix = A.T@A + lambd*I

#Get eigenvalues / vectors using numpy
eigen_values, eigen_vectors = np.linalg.eigh(hessian_matrix)

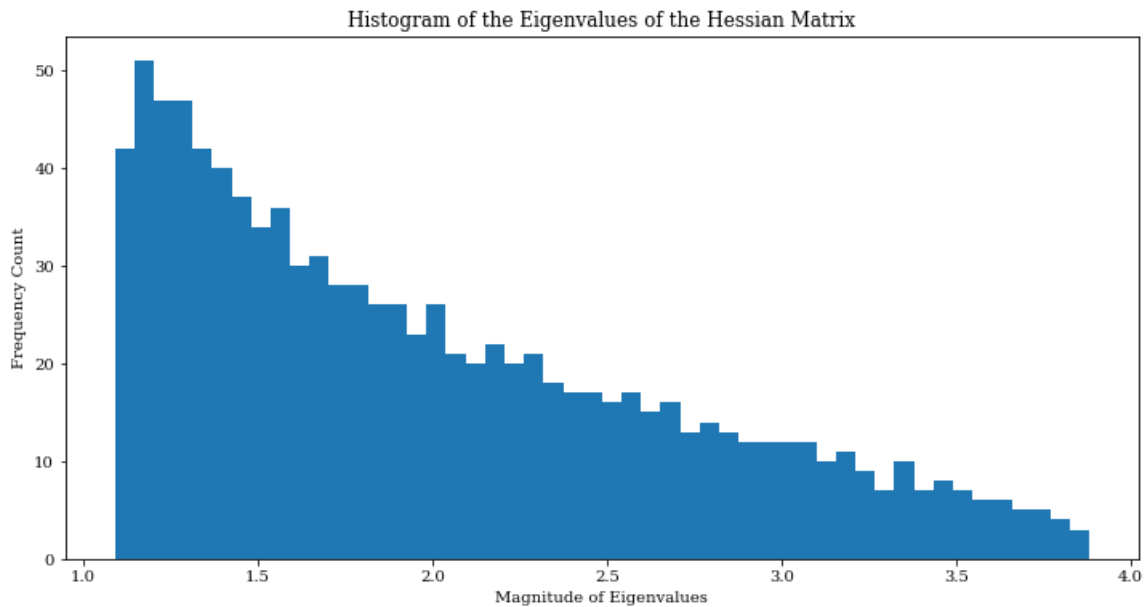
#Save min and max eigenvals for later
L = np.max(eigen_values)
mu = np.min(eigen_values)

#Plot the eigenvalues using a histogram
plt.figure(figsize=(12,6))
plt.hist(eigen_values, bins=50)[2]
plt.title('Histogram of the Eigenvalues of the Hessian Matrix')
plt.xlabel('Magnitude of Eigenvalues')
plt.ylabel('Frequency Count')

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Out[3]: Text(0, 0.5, 'Frequency Count')



(b) Implement gradient descent with constant step-size $\beta = 1/L$ (as in Problem 12.2), with random initial position x_0 . Plot the log-error $\log(\|x_t - x_*\|)$ as a function of t .

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In [4]: #Create a function to return log errors
def log_error_func(xt,xopt):
    difference = xt - xopt
    return np.log(np.linalg.norm(difference))

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In [5]: #Initialize a vairable to hold random position, create step size
random_position = np.random.normal(size=d)
step_size = 1/L
current_position = random_position

#Calculate optimal x* from part a
optimal_x = np.linalg.inv(hessian_matrix)@A.T@y

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In [6]: #Initialize variables for graph
iterations = []
log_error_arr = []

#Begin gradient descent
for i in range(150):
    current_position = current_position - ((1/L)*(hessian_matrix@current_position - A.T@y))

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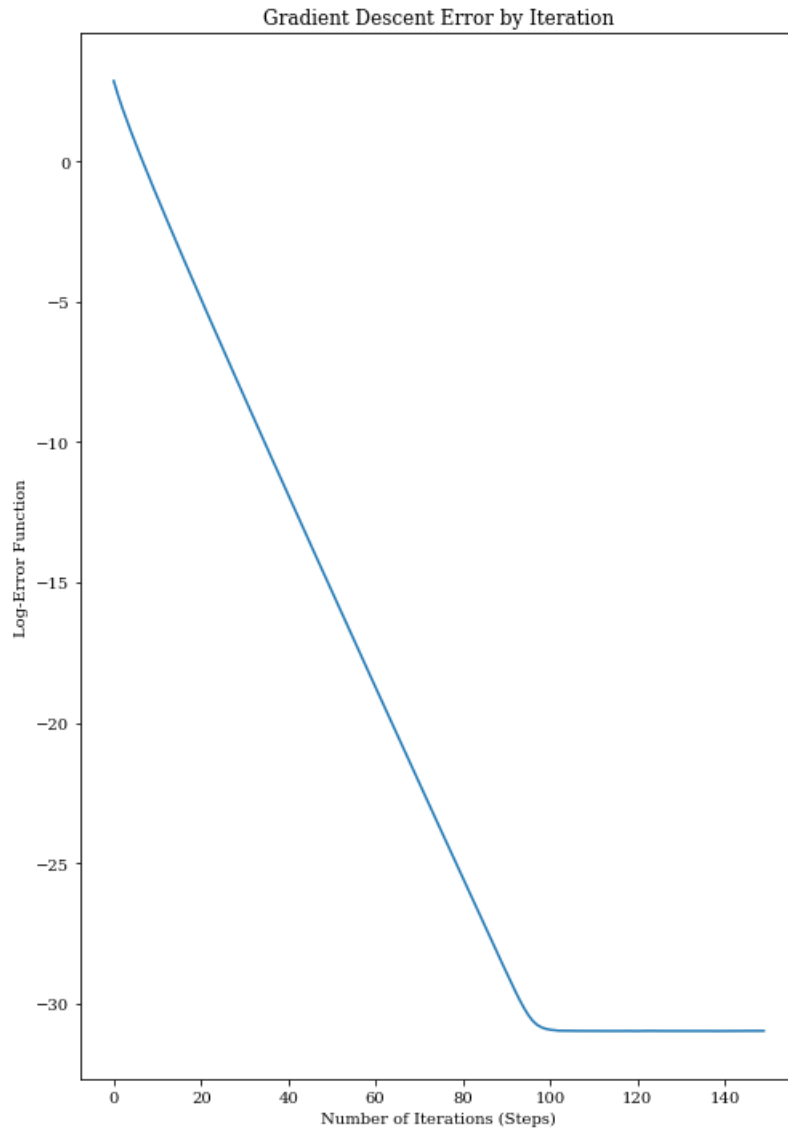
iterations.append(i)
log_error_arr.append(log_error_func(current_position, optimal_x))

plt.figure(figsize=(8,12))
plt.plot(iterations,log_error_arr)
plt.xlabel('Number of Iterations (Steps)')
plt.ylabel('Log-Error Function')
plt.title('Gradient Descent Error by Iteration')

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Out[6]: Text(0.5, 1.0, 'Gradient Descent Error by Iteration')



(c) Implement gradient descent with momentum, with the same parameters as in Problem 12.4. Plot the log-error $\log(\|x_t - x_*\|)$ as a function of t , on the same plot than the log-error of gradient descent without momentum. On the same plot, plot also the lines of equation

$$y = \log(1 - \mu/L) \times t \quad \text{and} \quad y = \log\left(\frac{\sqrt{L} - \sqrt{\mu}}{\sqrt{L} + \sqrt{\mu}}\right) \times t. \quad (3)$$

```
In [7]: ▾ #Define gradient_descent_with_momentum:
▾ def gradient_with_momentum(beta, gamma, current, old):

    #Calcualte new position
    new = current - beta*(hessian_matrix@current - A.T@y) + gamma*(current - old)

    #Return the new position, and the t-1 position
    return new, current

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In [8]: ▾ #Define the bounds of each gradient descent approach
▾ def momentum_bound_gd(arr):
    messy_part = np.log(((L**0.5)-(mu**0.5))/((mu**0.5)+(L**0.5)))
    return messy_part*np.array(arr)

▾ def standard_gd_bound(arr):
    messy_part = np.log(1-(mu/L))
    return messy_part * np.array(arr)

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In [9]: ▾ #Initialize random position, current position, and t-1 position variables
starting_position = np.random.normal(size=d)
current_position = old_position = starting_position

#Get the optimal solution for x
optimal_x = np.linalg.inv(hessian_matrix)@A.T@y

#Calculate beta and gamma parameters from 12.4
beta = 4/(((L**0.5)+(mu**0.5))**2)
gamma = (((L**0.5)-(mu**0.5))/((L**0.5)+(mu**0.5)))**2

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In [10]: ▾ #Initialize variables to track iteration
iterations2 = []
log_error_arr2 = []

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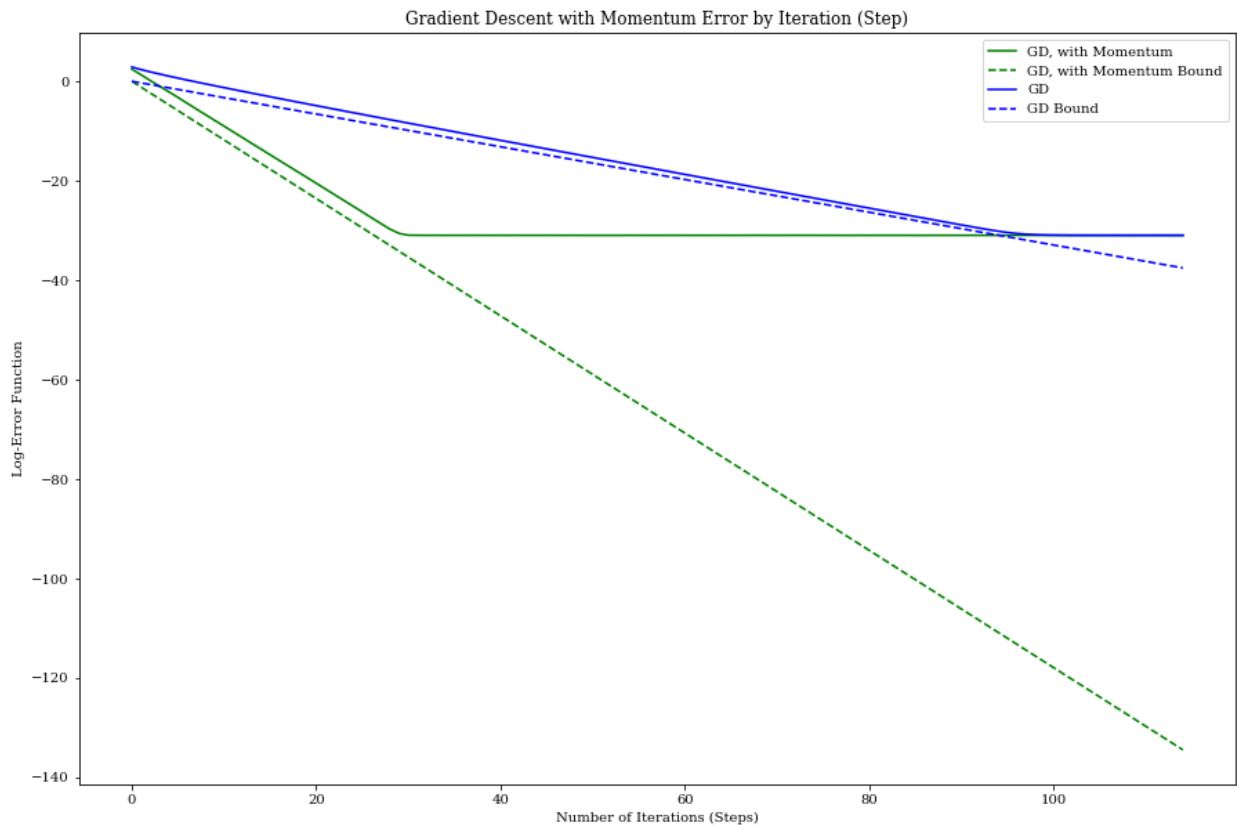
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In [11]: ▾ #Begin Iterating
▾ for i in range(150):
    current_position, old_position = gradient_with_momentum(beta, gamma, current_position, ol
    iterations2.append(i)
    log_error_arr2.append(log_error_func(current_position, optimal_x))

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In [12]: #Plot Graphs
plt.figure(figsize=(15,10))
plt.plot(iterations2[:115],log_error_arr2[:115], c='g', label='GD, with Momentum')
plt.plot(iterations2[:115], momentum_bound_gd(iterations2[:115]), 'g--',label='GD, with Moment
plt.plot(iterations[:115],log_error_arr[:115], c='b',label='GD')
plt.plot(iterations[:115], standard_gd_bound(iterations[:115]), 'b--',label='GD Bound')

plt.xlabel('Number of Iterations (Steps)')
plt.title('Gradient Descent with Momentum Error by Iteration (Step)')
plt.ylabel('Log-Error Function')
plt.legend()
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Out[12]: <matplotlib.legend.Legend at 0x21203a2d3c8>



Observation: Gradient Descent with Momentum approaches optimal solution nearly 3 times faster than normal gradient descent, which requires nearly 100 iterations to achieve optimal solution