EXERCISE 2B HIGH PERFORMANCE COMPUTING

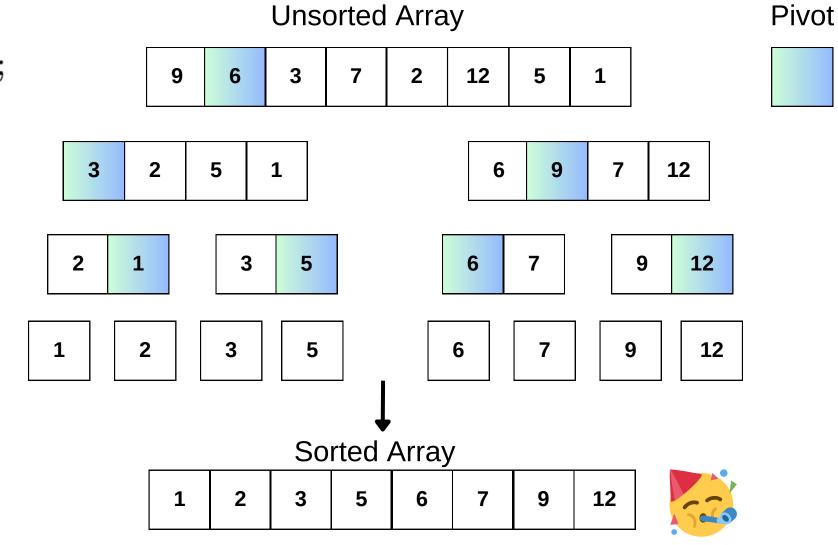
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A QUICK LOOK AT QUICKSORT ALGORITHM

- Sorting algorithm that follows the divide-and-conquer paradigm;
- \bullet Consider an array X with n elements;
- Select an element (called pivot) x_{i^*} , with $i^* \in \{0, ..., n-1\}$;
- Divides the array into the following two partitions:

$$X_{<} = \{x_i \in X : x_i < x_{i^*}, i \in \{0, ..., n-1\}\}$$
$$X_{\ge} = \{x_i \in X : x_i \ge x_{i^*}, i \in \{0, ..., n-1\}\}$$

• Recursive call in each partition



PARALLELIZATION STRATEGY: OMP

Algorithm 1 Pseudocode of OMP Quicksort

```
 \begin{array}{l} \mathbf{procedure} \; \mathbf{OMP\_QUICKSORT}(data, start, end, cmp\_ge) \\ size \leftarrow end - start \\ \mathbf{if} \; size > 2 \; \mathbf{then} \\ mid \leftarrow \mathbf{PARTITIONING}(data, start, end, cmp\_ge) \\ \#\mathbf{pragma} \; \mathbf{omp} \; \mathbf{task} \\ \mathbf{OMP\_QUICKSORT}(data, start, mid, cmp\_ge) \\ \#\mathbf{pragma} \; \mathbf{omp} \; \mathbf{task} \\ \mathbf{OMP\_QUICKSORT}(data, mid + 1, end, cmp\_ge) \\ \mathbf{else} \\ \mathbf{if} \; (size == 2) \; \mathbf{and} \; (data[start] \geq data[end - 1]) \; \mathbf{then} \\ \mathbf{SWAP}(data[start], data[end - 1]) \\ \mathbf{end} \; \mathbf{if} \\ \mathbf{end} \; \mathbf{if} \\ \mathbf{end} \; \mathbf{procedure} \\ \end{array}
```

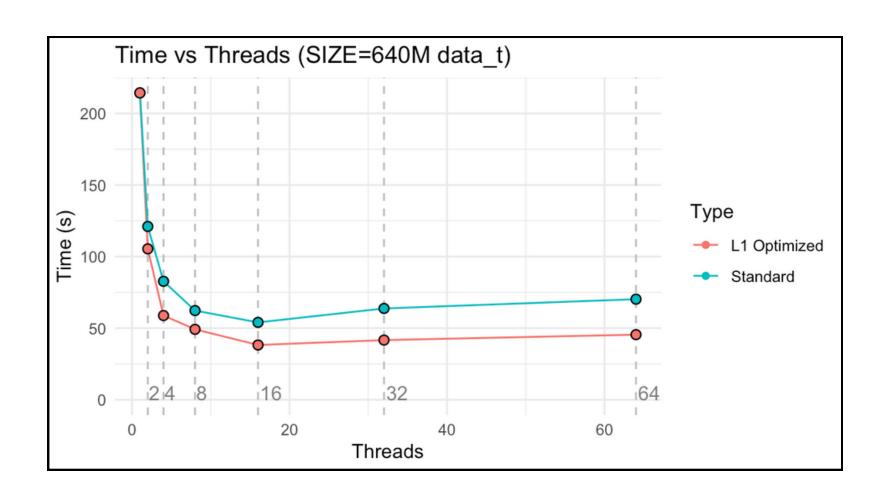
- Parallelism introduced primarily through the use of omp tasks
- Tasks facilitate the parallel execution of recursive calls, allowing the partitions X_{\leq} and X_{\geq} to be sorted concurrently;
- Tasks allow for a dynamic scheduling: runtime system intelligently distributes tasks to the available threads, as they become accessible
- Valuable flexibility in scenarios where the workload of each task is unpredictable at compile-time (pivot-partition size dependency)

OMP L1-CACHE OPTIMIZATION

Algorithm 2 Pseudocode of OMP Quicksort (L1 optimized)

```
procedure OMP_QUICKSORT_L1(data, start, end, cmp\_ge)
   size \leftarrow end - start
   if size > 2 then
      mid \leftarrow PARTITIONING(data, start, end, cmp\_ge)
      if size > SIZE_{-}L1 then
          #pragma omp task
          OMP\_QUICKSORT(data, start, mid, cmp\_ge)
          #pragma omp task
          OMP\_QUICKSORT(data, mid + 1, end, cmp\_ge)
      else
          SERIAL_QUICKSORT(data, start, mid, cmp\_ge)
          SERIAL_QUICKSORT(data, mid + 1, end, cmp\_ge)
      end if
   else
      if (size == 2) and (data[start] \ge data[end - 1]) then
         SWAP(data[start], data[end - 1])
      end if
   end if
end procedure
```

- data_t: array of DATA_SIZE doubles
- Default DATA_SIZE= $8 \longrightarrow data_t requires 64 bytes;$
- EPYC nodes equipped with an L1 cache of 4 MiB \longrightarrow 4194304 bytes
- Max number of data_t that can fit within the L1 cache: L1_SIZE = 65536



MPI APPROACH

INITIAL SETUP

- $X_0, ..., X_{P-1}$ data chunks generated by processes $P_0, ..., P_{P-1}$
- Initially, all the segments $X_0, ..., X_{P-1}$ are unordered
- Processes are divided into 2 groups basing on their rank:
 - 1. upper processes (with rank $p > \frac{P-1}{2}$)
 - 2. lower processes (with rank $p \leq \frac{P-1}{2}$)

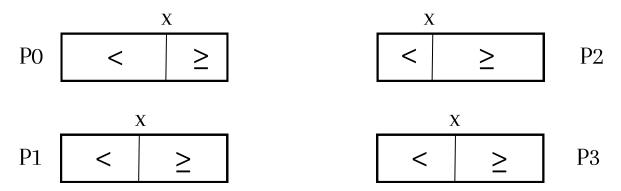
OBJECTIVE

$$X_0 \leq ... \leq X_{P-1}$$
, with $X_i \leq X_j \iff \forall x_i \in X_i, \forall x_j \in X_j, x_i \leq x_j$

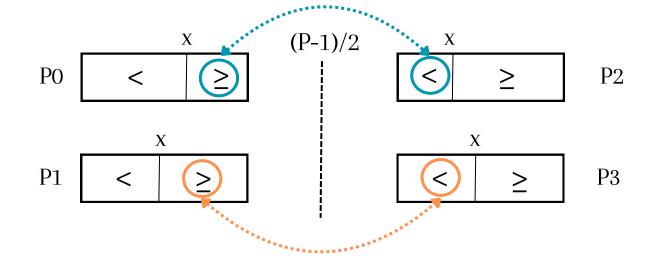
PROCEDURE

- 1. Select a global pivot and broadcast it to all the processes
- 2. Partition the chunk of each process p into 2 sub-arrays: $X_{\leq}^{(p)}$ and $X_{\geq}^{(p)}$
- 3. Exchange data portions between each process p of the upper group and process $p' = p \left(\frac{P-1}{2} + 1\right)$ of the lower group. In particular:
 - p sends its lower partition $X_{<}^{(p)}$ to p'
 - p' sends its upper partition $X_{\geq}^{(p')}$ to p
- 4. Recursive call in each group of processes

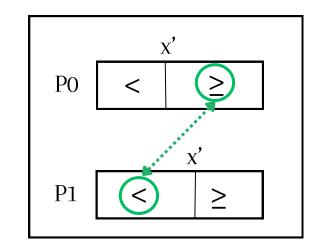
Step 1: select global pivot (x) and partition chunks

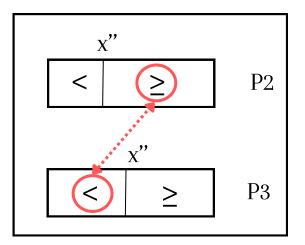


Step 2: group processes and exchange partitions



Step 3: recursive call on each group





PIVOT SELECTION AND LOAD IMBALANCE

- Quicksort's main drawback: processes might have very different workloads
- This aspect regards both the serial version both the hybrid configuration

SERIAL ALGORITHM ISSUES

- Pivot choice originally determined within the partitioning() function
- Lomuto partition scheme, which selects the rightmost element of the array
- 2 adjustments: "Median of three" rule + pivot positioning

HYBRID ALGORITHM ISSUES

How should we choose the global pivot?

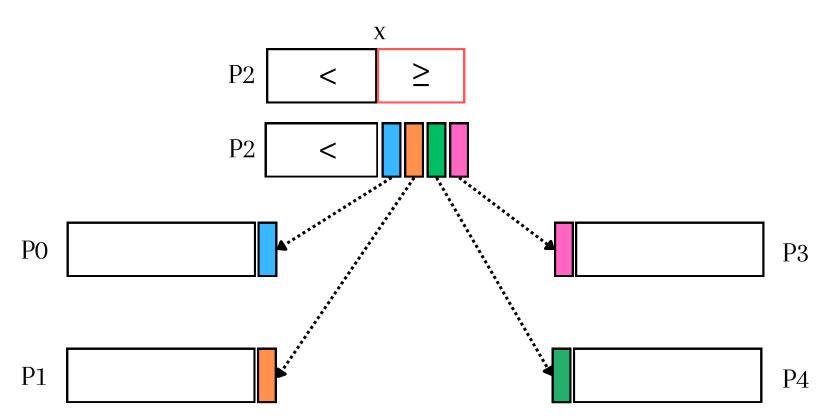
- Random choice not recommended
- "Median of three"-like strategy
- Hyper-Quicksort and Parallel Sort Regular Sampling (PSRS)
- My idea:
 - 1. Each process selects a random element from its chunk, with a seed based on its rank (just to enhance the degree of randomness)
 - 2. Such values are broadcasted to rank 0, populating an array of pivots
 - 3. The pivots array is then sorted, and its median is selected as the global pivot to start the partitioning phase

Algorithm 3 Pseudocode of "median-of-three"

```
mid \leftarrow \frac{\text{start} + (\text{end} - 1)}{2}
if cmp_ge(data[start], data[mid]) then
   SWAP(data[start], data[mid])
end if
if cmp_ge(data[mid], data[end-1]) then
   SWAP(data[mid], data[end-1])
end if
if cmp_ge(data[mid], data[start]) then
   SWAP(data[start], data[mid])
end if
pivot \leftarrow data[start]
```

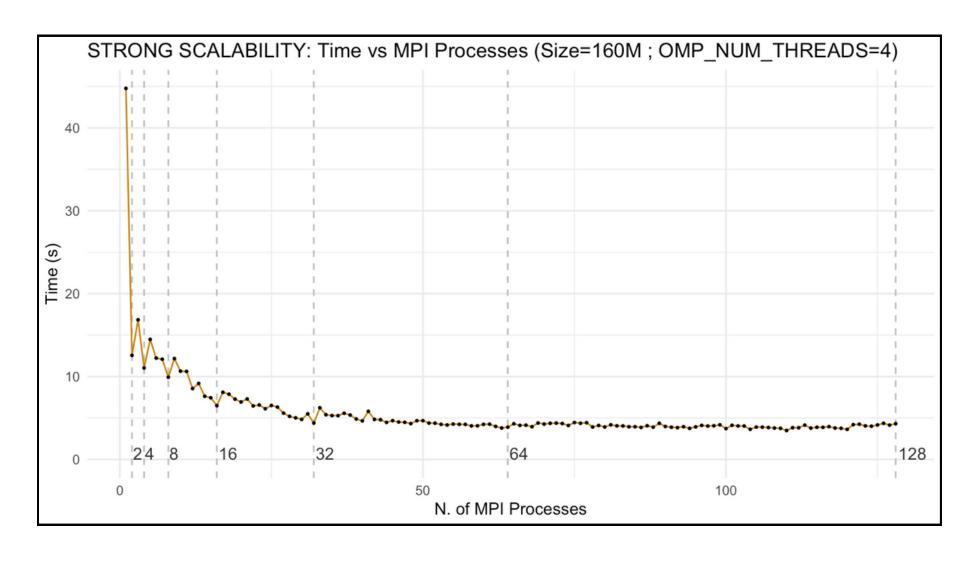
GENERALIZATION OF THE ALGORITHM

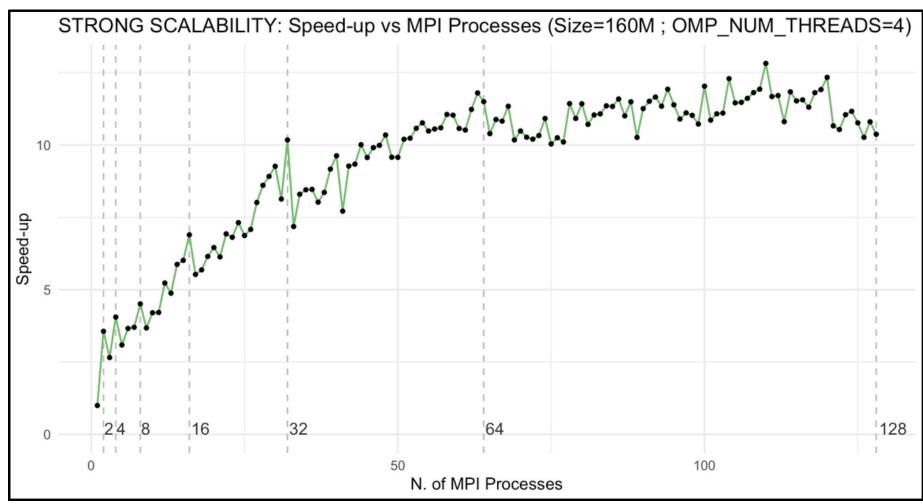
- 1. Select the global pivot and broadcast it to all the processes;
- 2. Partition the central process only (the one with rank $\frac{(P-1)}{2}$);
- 3. Compare the size of the two partitions $X_{<}^{\frac{(P-1)}{2}}$ and $X_{\geq}^{\frac{(P-1)}{2}}$. Scatter the elements of the minor partition to the other processes, while keeping the elements of the major partition;
- 4. Once concluded the scatter phase, proceed with the usual partitioning and data exchange procedure for all the other processes (with rank $p \neq \frac{(P-1)}{2}$);
- 5. Finally, assign the central process to the correct group for the recursive calls:
 - if the major partition was $X_{<}^{\frac{(P-1)}{2}}$, assign it to the group of processes with rank $p < \frac{(P-1)}{2}$
 - if the major partition was $X_{\geq}^{\frac{(P-1)}{2}}$, assign it to the group of processes with rank $p>\frac{(P-1)}{2}$



STRONG SCALABILITY

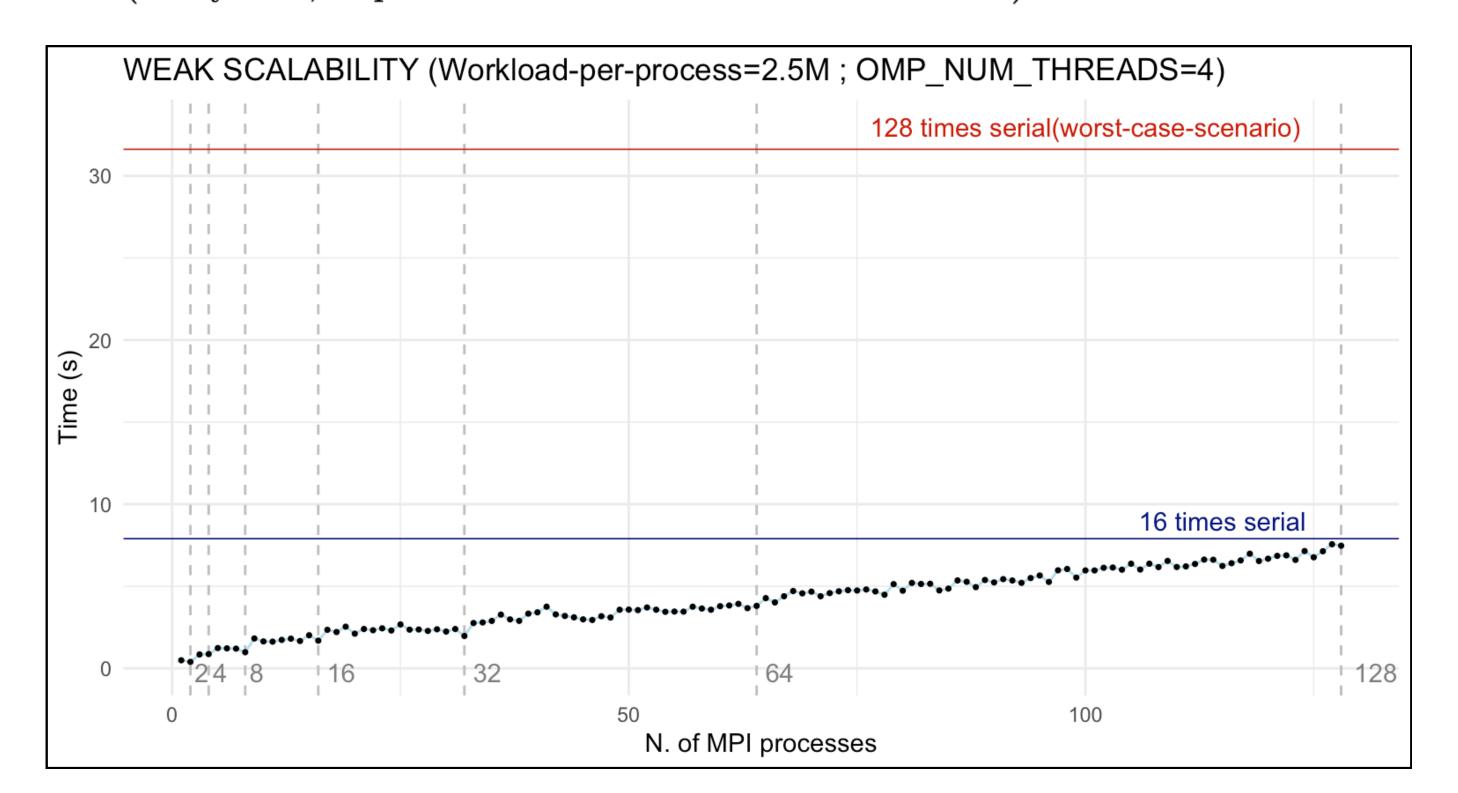
Strong scalability evaluation: size of the overall array fixed (to 160.000.000 size_t) and average sorting time (or, equivalently, the speed-up) measured by varying the number of MPI processes





WEAK SCALABILITY

Weak scalability evaluation: let the overall size n vary, keeping the workload-per-process as a constant (in my case, I opted for a workload of $2.500.000 \text{ size_t}$).



FINAL CONSIDERATIONS

- Both strong and weak scalability deviate from the ideal scenarios
- Strong scalability reveals a logarithmic trend
- Weak scalability upper-bounded by only 16 times the serial sorting time
- Clear limitations in scaling Quicksort
 - Recursive calls
 - Load imbalance issues
 - Exponential growth of MPI communications
- A worth highlighting achievement was the generalization of the algorithm