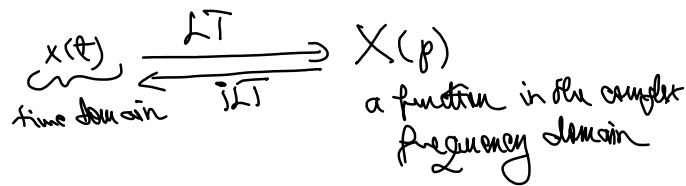


Seminar 10

Wednesday, December 2, 2020 6:02 PM

The Laplace Transform

- it is a mathematical tool



ex1) signals

- continuous time \rightarrow Laplace transform
- discrete time \rightarrow Z transform, Fourier transform

ex2) solving differential equations with boundary conditions

$y(t) = c_1 e^{at} + c_2 \cos(3t)$
using the L.T. we get the answer directly

$f: \mathbb{R} \rightarrow \mathbb{C}$ the original
 $F(p) = \int_0^{\infty} f(t) e^{-pt} dt \stackrel{\text{not.}}{=} \mathcal{L}[f(t)](p)$ the image

$$\mathcal{L}[\underbrace{f(t)}_{\text{original}}](p) = \underbrace{F(p)}_{\text{image}}$$

$$\mathcal{L}[a](p) = \frac{a}{p}$$

$$\mathcal{L}[e^{\lambda t}](p) = \frac{1}{p - \lambda}$$

$$\mathcal{L}[t^n](p) = \frac{n!}{p^{n+1}}, n \in \mathbb{N}$$

$$\mathcal{L}[t^\alpha](p) = \frac{\Gamma(\alpha+1)}{p^{\alpha+1}}, \alpha \in \mathbb{C} \text{ \& } \lambda > -1$$

$$\mathcal{L}[f(at)](p) = \frac{1}{a} \mathcal{L}[f(t)]\left(\frac{p}{a}\right)$$

$$\mathcal{L}[e^{at} \cdot f(t)](p) = \mathcal{L}[f(t)](p - a)$$

translation of the image

$$\mathcal{L}\left[\frac{d}{dt} f(t)\right](p) = (-1) \cdot (\mathcal{L}[f(t)](p))'$$

$$\mathcal{L}\left[t^n \cdot f(t)\right](p) = (-1)^n (\mathcal{L}[f(t)](p))^{(n)}$$

differentiation of the image

$$\mathcal{L}[\sin(at)](p) = \frac{a}{p^2 + a^2}$$

$$\mathcal{L}[\cos(at)](p) = \frac{p}{p^2 + a^2}$$

$$\mathcal{L}[\sinh(at)](p) = \frac{a}{p^2 - a^2}$$

$$\mathcal{L}[\cosh(at)](p) = \frac{p}{p^2 - a^2}$$

$$\mathcal{L}\left[\int_0^t f(\tau) d\tau\right](p) = \frac{1}{p} \cdot \mathcal{L}[f(t)](p) \quad \text{integration of the original}$$

$$\mathcal{L}\left[\frac{f(t)}{t}\right](p) = \int_p^{\infty} \mathcal{L}[f(t)](q) dq \quad \text{integration of the image}$$

1) Find the images by the Laplace transform of the originals

$$a) \mathcal{L}[\sinh(at)](p) = \mathcal{L}\left[\frac{e^{at} - e^{-at}}{2}\right](p) = \frac{1}{2}(\mathcal{L}[e^{at}](p) - \mathcal{L}[e^{-at}](p))$$

$$= \frac{1}{2}\left(\frac{1}{p-a} - \frac{1}{p+a}\right) = \frac{1}{2} \cdot \frac{p+a-p+a}{p^2-a^2} = \frac{a}{p^2-a^2}$$

$$b) \mathcal{L}[\cos(3t)](p) = \frac{p}{p^2+9}$$

$$= \frac{1}{3} \mathcal{L}[\cos t]\left(\frac{p}{3}\right) = \frac{1}{3} \frac{\frac{p}{3}}{\left(\frac{p}{3}\right)^2 + 1} = \frac{p}{p^2+9}$$

\uparrow
 $\mathcal{L}[f(at)](p) = \frac{1}{a} \mathcal{L}[f(t)]\left(\frac{p}{a}\right)$

$$c) \mathcal{L}[e^{2t} \cos(3t) + e^{3t} \sin(2t)](p) = \mathcal{L}[e^{2t} \cos(3t)](p) + \mathcal{L}[e^{3t} \sin(2t)](p)$$

$$= \mathcal{L}[\cos(3t)](p-2) + \mathcal{L}[\sin(2t)](p-3) = \frac{p}{p^2+9} \Big|_{p=p-2} + \frac{2}{p^2+4} \Big|_{p=p-3} =$$

$$= \frac{p-2}{(p-2)^2+9} + \frac{2}{(p-3)^2+4}$$

$\mathcal{L}[t^n](p) = \frac{n!}{p^{n+1}}$

$$d) \mathcal{L}[t^3 e^{-t}](p) \xrightarrow[\text{transf. of the image}]{\text{I method}} \mathcal{L}[t^3](p+1) = \frac{3!}{p^4} \Big|_{p=p+1} = \frac{3!}{(p+1)^4}$$

$$\xrightarrow[\text{differentiation of the image}]{\text{II method}} (-1)^3 (\mathcal{L}[e^{-t}](p))^{(3)} = - \left(\frac{1}{p+1}\right)^{(3)} = - \left(\frac{-1}{(p+1)^2}\right)''$$

$$= \left(\frac{1}{(p+1)^2}\right)' - \left(\frac{-2}{(p+1)^3}\right)' = 6 \frac{1}{(p+1)^4}$$

$$e) \mathcal{L}[t e^{2t} \cos t] \xrightarrow[\text{transf. of the image}]{} \mathcal{L}[t \cos t](p-2) = (-1)^1 (\mathcal{L}[\cos t])'(p-2) =$$

$$= - \left(\frac{p}{p^2+1}\right)' \Big|_{p=p-2} = - \frac{p^2+1-2p^2}{(p^2+1)^2} \Big|_{p=p-2} =$$

$$= \frac{p^2-1}{(p^2+1)^2} \Big|_{p=p-2} = \frac{(p-2)^2-1}{[(p-2)^2+1]^2}$$

diff the image $(-1)' (\mathcal{L}[e^{2t} \cos t](p))' = \dots$

f) $\mathcal{L}\left[\int_0^t \sin(3u) du\right](p) \xrightarrow{\text{intgr. of the original}} \frac{1}{p} \mathcal{L}[\sin(3t)](p) = \frac{1}{p} \cdot \frac{3}{p^2+9}$

$\mathcal{L}\left[\int_0^t f(s) ds\right](p) = \frac{1}{p} \mathcal{L}[f(t)](p)$

g) $\mathcal{L}\left[\int_0^t u^2 \cdot e^{-3u} du\right](p) = \frac{1}{p} \mathcal{L}[t^2 \cdot e^{-3t}](p) = \frac{1}{p} \mathcal{L}[t^2](p+3) =$
 $= \frac{1}{p} \cdot \frac{2!}{p^3} \Big|_{p=p+3} = \frac{1 \cdot 2!}{p(p+3)^3} = \frac{2!}{p(p+3)^3}$
 \uparrow
 $\mathcal{L}[t^2](p) = \frac{2!}{p^{2+1}} = \frac{2!}{p^3}$

h) $\mathcal{L}\left[\int_0^t \frac{\sin u}{u} du\right](p) \xrightarrow{\text{intgr. of the original}} \frac{1}{p} \mathcal{L}\left[\frac{\sin t}{t}\right](p) \xrightarrow{\text{int. of the image}}$
 $= \frac{1}{p} \int_p^\infty \mathcal{L}[\sin t](y) dy = \frac{1}{p} \int_p^\infty \frac{1}{y^2+1} dy = \frac{1}{p} \arctan y \Big|_p^\infty =$
 $= \frac{1}{p} \left(\frac{\pi}{2} - \arctan p \right) \xrightarrow{\uparrow} \frac{1}{p} \cdot \arctan \frac{1}{p}$
 $\arctan y + \arctan \frac{1}{y} = \frac{\pi}{2}$

i) $\mathcal{L}[t^2 \cdot \cos t](p) \xrightarrow{\text{diff of the image}} (-1)' (\mathcal{L}[\cos(t)](p))'' = \left(\frac{p}{p^2+1} \right)'' =$
 $= \left(\frac{p^2+1-2p^2}{(p^2+1)^2} \right)' = \left(\frac{-p^2+1}{(p^2+1)^2} \right)' = \frac{-2p(p^2+1)^2 - 2(p^2+1) \cdot 2p \cdot (1-p^2)}{(p^2+1)^4} =$
 $= \frac{-2p^3 - 2p - 4p + 4p^3}{(p^2+1)^3} = \frac{2p^3 - 6p}{(p^2+1)^3}$

j) $\mathcal{L}\left[\frac{e^{-2t} - e^{-3t}}{t}\right](p) \xrightarrow{\text{integration of the image}} \int_p^\infty \mathcal{L}[e^{-2t} - e^{-3t}](y) dy =$
 $= \int_p^\infty \left(\frac{1}{y+2} - \frac{1}{y+3} \right) dy = \left[\ln(y+2) - \ln(y+3) \right] \Big|_p^\infty = \ln \frac{y+2}{y+3} \Big|_p^\infty$

$$= \int_p^\infty \left(\frac{1}{y+2} - \frac{1}{y+3} \right) dy = \left[\ln(y+2) - \ln(y+3) \right] /_p^\infty = \ln \frac{y+2}{y+3} /_p^\infty$$

$$= \underbrace{\lim_{x \rightarrow \infty} \ln \frac{x+2}{x+3}}_{=0} - \ln \frac{p+2}{p+3} = -\ln \frac{p+2}{p+3} = \ln \left(\frac{p+2}{p+3} \right)^{-1} = \underline{\underline{\ln \frac{p+3}{p+2}}}$$

② $X(p) \xrightarrow[\mathcal{L}^{-1}]{\text{ILT}} x(t)$

Find the originals $f(t)$ corresponding to the following images

a) $\mathcal{L}^{-1} \left[\frac{1}{p-3} \right] = e^{\textcircled{3}t}$

$\mathcal{L}[e^{\lambda t}](p) = \frac{1}{p-\lambda} \quad | \mathcal{L}^{-1}$
 $\mathcal{L}^{-1} \left[\frac{1}{p-\lambda} \right] = e^{\textcircled{\lambda}t}$

b) $\mathcal{L}^{-1} \left[\frac{1}{2p-3} \right] = \mathcal{L}^{-1} \left[\frac{1}{2(p-\frac{3}{2})} \right] = \frac{1}{2} \mathcal{L}^{-1} \left[\frac{1}{p-\frac{3}{2}} \right] = \frac{1}{2} e^{\textcircled{\frac{3}{2}}t}$

c) $\mathcal{L}^{-1} \left[\frac{1}{p^2+9} \right] = \frac{1}{3} \mathcal{L}^{-1} \left[\frac{3}{p^2+9} \right] = \frac{1}{3} \sin(3t)$

$\mathcal{L}[\sin(3t)](p) = \frac{3}{p^2+9}$
 $\mathcal{L}[\cos(3t)](p) = \frac{p}{p^2+9}$

d) $\mathcal{L}^{-1} \left[\frac{1}{p^3} \right] = \frac{1}{2!} \mathcal{L}^{-1} \left[\frac{2!}{p^3} \right] = \frac{1}{2} t^2$

$\mathcal{L}[t^2](p) = \frac{2!}{p^3}$

e) $\mathcal{L}^{-1} \left[\frac{3!}{(p-2)^4} \right] \underset{\uparrow}{=} \mathcal{L}^{-1} \left[\frac{3!}{p^4} /_{p=p-2} \right] = t^3 \cdot e^{2t}$
 $\mathcal{L}[t^3](p) = \frac{3!}{p^4}$

f) $\mathcal{L}^{-1} \left[\frac{1}{p(p-3)} \right] = \textcircled{*}$

$\mathcal{L}^{-1} \left[\frac{1}{p-a} \right] \quad \mathcal{L}^{-1} \left[\frac{1}{p+b} \right]$

we use partial fraction decomposition

$$\frac{1}{p(p-3)} = \frac{A}{p} + \frac{B}{p-3}$$

$$\Rightarrow 1 = A(p-3) + Bp$$

$$p=0 \Rightarrow -3A=1 \Rightarrow A = -\frac{1}{3}$$

$$p=3 \Rightarrow 3B=1 \Rightarrow B = \frac{1}{3}$$

$$\frac{1}{p(p-3)} = \frac{-1}{3p} + \frac{1}{3(p-3)} \quad \mathcal{L}^{-1} \left[\frac{1}{p-a} \right] = e^{at}$$

$$\Rightarrow \frac{1}{p(p-3)} = \frac{\frac{1}{3}}{p-3} - \frac{\frac{1}{3}}{p}$$

$$\textcircled{*} \mathcal{L}^{-1} \left[\frac{\frac{1}{3}}{p-3} \right] - \mathcal{L}^{-1} \left[\frac{\frac{1}{3}}{p} \right] = e^{3t} - \frac{1}{3}$$

$$p=3 \Rightarrow 3B=1 \Rightarrow B=\frac{1}{3}$$

$$\mathcal{L}^{-1} \left[\frac{1}{p-\lambda} \right] = e^{\lambda t} ; \mathcal{L}^{-1} \left[\frac{a}{p} \right] = a$$

$$* g) \mathcal{L}^{-1} \left[\frac{1}{p^2-4p+11} \right] = \mathcal{L}^{-1} \left[\frac{1}{p^2-4p+4+7} \right] = \mathcal{L}^{-1} \left[\frac{1}{(p-2)^2+7} \right]$$

$$p^2-4p+11=0 \\ \Delta = 16-44 < 0 \Rightarrow \text{no real solutions}$$

$$\mathcal{L}^{-1} \left[\frac{a}{p^2+a^2} \right] = \sin(at)$$

$$= \frac{1}{\sqrt{7}} \mathcal{L}^{-1} \left[\frac{\sqrt{7}}{(p-2)^2+(\sqrt{7})^2} \right] = \frac{1}{\sqrt{7}} \mathcal{L}^{-1} \left[\frac{\sqrt{7}}{p^2+(\sqrt{7})^2} \right]_{p=p-2} = \frac{1}{\sqrt{7}} \sin(\sqrt{7}t) \cdot e^{2t}$$

$$* h) \mathcal{L}^{-1} \left[\frac{p}{p^2-6p+25} \right] = \mathcal{L}^{-1} \left[\frac{p}{p^2-6p+9+16} \right] = \mathcal{L}^{-1} \left[\frac{p}{(p-3)^2+16} \right] =$$

$$p^2-6p+25=0 \quad \Delta < 0 \Rightarrow \text{no real sol.}$$

$$\mathcal{L}^{-1} \left[\frac{p}{p^2+a^2} \right] = \cos(at)$$

$$= \mathcal{L}^{-1} \left[\frac{p-3+3}{(p-3)^2+4^2} \right] = \mathcal{L}^{-1} \left[\frac{p-3}{(p-3)^2+4^2} \right] + \frac{3}{4} \mathcal{L}^{-1} \left[\frac{4}{(p-3)^2+4^2} \right] =$$

$$= \mathcal{L}^{-1} \left[\frac{p}{p^2+4^2} \right]_{p=p-3} + \frac{3}{4} \mathcal{L}^{-1} \left[\frac{4}{p^2+4^2} \right]_{p=p-3} =$$

$$= e^{3t} \cdot \cos(4t) + \frac{3}{4} e^{3t} \cdot \sin(4t)$$

$$i) \mathcal{L}^{-1} \left[\frac{p}{p^2+p+1} \right] = \mathcal{L}^{-1} \left[\frac{p}{p^2+p+\frac{1}{4}+1-\frac{1}{4}} \right] = \mathcal{L}^{-1} \left[\frac{p}{(p+\frac{1}{2})^2+\frac{3}{4}} \right]$$

$$\Delta = 1-4 < 3$$

$$= \mathcal{L}^{-1} \left[\frac{p+\frac{1}{2}-\frac{1}{2}}{(p+\frac{1}{2})^2+(\frac{\sqrt{3}}{2})^2} \right] = \mathcal{L}^{-1} \left[\frac{p+\frac{1}{2}}{(p+\frac{1}{2})^2+(\frac{\sqrt{3}}{2})^2} \right] - \frac{1}{2} \mathcal{L}^{-1} \left[\frac{\frac{\sqrt{3}}{2}}{(p+\frac{1}{2})^2+(\frac{\sqrt{3}}{2})^2} \right]$$

$$-\frac{1}{2}t \quad \quad \quad -\frac{1}{2}t \quad \quad \quad \sqrt{3}/2$$

$$= e^{-\frac{1}{2}t} \cdot \cos\left(\frac{\sqrt{3}}{2}t\right) - \frac{1}{\sqrt{3}} e^{-\frac{1}{2}t} \cdot \sin\left(\frac{\sqrt{3}}{2}t\right).$$

homework:

$$1) \mathcal{L}\left[(t+1)\sin 2t\right](p)$$

$$2) \mathcal{L}^{-1}\left[\frac{2}{(p+5)^3}\right]$$

$$3) \mathcal{L}^{-1}\left[\frac{4}{(p-7)^4}\right]$$

$$4) \mathcal{L}^{-1}\left[\frac{3p+6}{p^2+3p}\right]$$

$$5) \mathcal{L}^{-1}\left[\frac{p}{p^2-5p+6}\right]$$

$$6) \mathcal{L}^{-1}\left[\frac{p}{p^2+3p+8}\right]$$

$$7) \mathcal{L}^{-1}\left[\frac{1}{p^2+2p+9}\right]$$