

# Internship Project Documentation

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## 1 Introduction

The aim of the project is to develop what in cybersecurity and IoT is called a data diode, a unidirectional communication device for data exchange. The importance behind this project is that industrial data diodes are expensive devices, and implementing a high amount of them like for this specific use case is a very costly move, but with software implementations (firewalls) or hardware implementations (serial or optical communication built to be unidirectional) it is possible to have cheaper data diodes that are almost as functional for most use case scenario. The setup includes two Raspberry Pi model 3 and a TTL-232R-3V3 cable with a specific configuration which we will highlight later.

## 2 Devices

### 2.1 Raspberry Pi

As far as choosing the best Raspberry Pi model for the job, I have chosen to use the Raspberry Pi 3 as it's a nice midway point between performance and cost. This particular machine should be able to handle the data size we are planning to share (around 1Gb/day), at a cost that is much lower than that of a Raspberry Pi 4, since the higher clock of the RPi4 won't help with serial communication limitations. The machines are configured as follows:

- Raspberry Pi 3 Model B Ver1.2:
  - Quad Core 1.2GHz Broadcom BCM2837 64bit CPU
  - 1GB RAM
  - BCM43438 wireless LAN and Bluetooth Low Energy (BLE) on board
  - 100 Base Ethernet
  - 40-pin extended pinout with GPIO support
  - 4 USB 2 ports
  - 4 Pole stereo output and composite video port
  - Full size HDMI
  - CSI camera port for connecting a Raspberry Pi camera
  - DSI display port for connecting a Raspberry Pi touchscreen display
  - Micro SD port for loading your operating system and storing data
  - Upgraded switched Micro USB power source up to 2.5A
  - Raspberry Pi OS Lite (latest version)

- 16GB microSD card

Using the RPI-Imager tool I installed the latest Raspberry Pi OS image. Upon first boot up, remember that RPi login is username: pi, password: raspberry. As Raspberry Pi OS Lite is an OS without a desktop environment, we don't have a systems setting manager with a GUI, luckily we can use the utility *raspi-config* to enable a series of features useful for testing software. Using the command *sudo raspi-config* we can open the utility, once in the main menu we change these specific settings:

- In the system options:
  - Enable WIFI for ssh purposes.
  - Change username and password if needed.
- In the interface options:
  - Enable SSH.
  - Enable Serial interface, remembering to disable login shell but enable serial interface.
- Run *sudo apt-get upgrade* to make sure all packages are up to date before using *raspi-config*.
- Disable bluetooth:
  - We won't be using bluetooth for the project, so we disable it, making the final product more secure.
  - We disable bluetooth by adding *dtoverlay=disable-bt* in */boot/config.txt*.
- Troubleshooting
  - Check that UART is enabled in */boot/config.txt* by adding *enable\_UART=1*.
  - Check that serial console is disabled by removing *console=serial0,115200* or *console=ttyS0,115200* in */boot/cmdline.txt*.
  - Check for permissions in the dialout group.
  - Check that */dev/serial0* doesn't have a getty console running on it. In case it does, it can be disabled by using the commands: *sudo systemctl stop serial-getty@ttyS0.service* and *sudo systemctl disable serial-getty@ttyS0.service*.
- Additional software:
  - Run *sudo apt-get install python3* to install Python in it's latest version.
  - Run *sudo apt-get install python3-pip* to install Python's package manager.
  - Run *pip install pyserial* to install the serial library that we will be using to have the machines communicate.

## 2.2 Serial cable

As mentioned earlier, the serial communication will go through a TTL-232R-3V3 cable, which is USB-to-serial, with +3.3V TTL levels UART signals. The cable has 5-pins on one end, and USB on the other. With the cable plugged in we run the command *ls /dev/tty\** on both RPi machines so we have an idea of what port we use to send or receive data on each RPi in the serial communication, for the port that's sending data it will be */dev/ttyS0*, while for the other port it should be */dev/ttyUSB0*. Raspian will always map the serial port to the alias */dev/serial0*,

so it is suggested to use the alias in programming. Here below in Figure 1 there is an image showing how the cable is meant to be plugged in, while in the Appendix 1 there is an extract from the documentation of the cable, showing the functionality of all the cable pins.

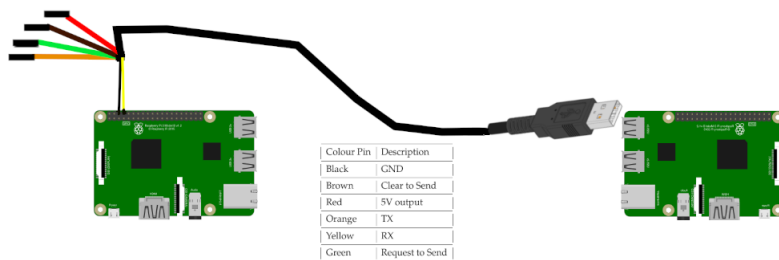


Figure 1: Pinout diagram

The cable pinout is peculiar as most pins are not used. The pins that get used are the ground pin and the pin that sends data over to the other RPi machine. Yellow pin is plugged in GPIO14, ground can be plugged in any of the RPi ground pins.

### 2.3 How is it a diode?

The importance behind this project is creating a diode-type communication, thus a unilateral communication, usually from a protected network to less protected or unprotected network. Below shown in Figure 2 how the two RPi interface within the network of Alstom devices, that is the first piece that shows how this setup has diode communication. The second piece is the pinout shown in Figure 1 in the chapter above, we can see that in the RPi placed in the private network, the serial pins that are plugged in are GND and TX, thus no data will be received through the cable by the RPi in the private network (RX pin is not plugged). These two factors create unidirectional communication similar to that of a diode.

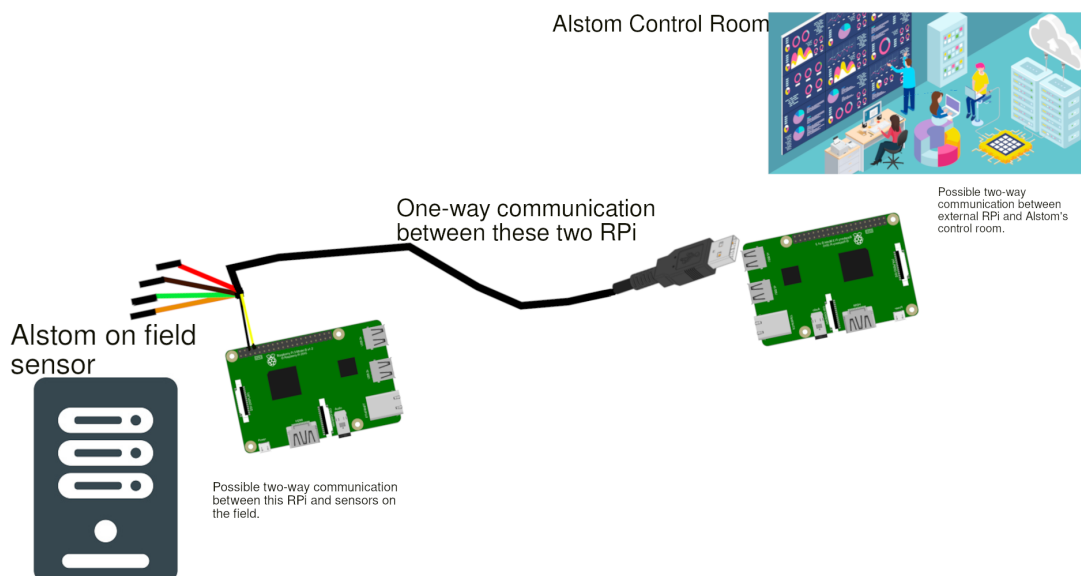


Figure 2: Network diagram

## 3 Program versions

### 3.1 Diagnostic test

The objective of this test is to see if the two RPi are connected correctly. In Appendix 2 we have example code and example output that can be used to troubleshoot and check that the cable has been plugged in correctly. In case this program won't run correctly, refer back to the troubleshooting section earlier. Make sure to run the code *sndtest.py* on the machine where the GPIO pins are being used, and *rcvtest.py* has to be run on the RPi where the USB is plugged in. It's suggested you start by running *rcvtest.py* using the command *python3 rcvtest.py*, and then run *python3 sndtest.py*.

### 3.2 Data diode 0.1

In this initial implementation we switch from sending text to sending an actual file via serial communication. The improvements from this version to the next will be improved baudrate, meaning faster file transfer. In the next version SHA256 checksum will also be implemented to make sure file transfer is working correctly. Future improvements will be to include a handshake system via CTS/RTS signals. The code can be found in Appendix 3.

### 3.3 Data diode 0.2

This version of the program has SHA256 integration to validate file transfer and improved transfer speeds thanks to a much better baudrate. The limitations with this version of the program is that because of limitations of USB2.0 and limitations of the UART communication protocol, 115200 baudrate seems to be the maximum baudrate without introducing errors. Transfer speeds are improved from version 0.1 but they have be improved by changing the communication protocol, a comparative of baudrates can be seen in Table 1 and 2 below, while the code example can be seen in Appendix 4. What the table below also tells us, is that calculating SHA256 while sending the file doesn't make file transfer significantly slower. The 0.3 version of the program will include byte chunk communication instead of simple readlines.

File size (mb)	Time (s)	SHA256
1	1065.9	No
1	1065.9	Yes

Table 1: Transfer times with 9600 baudrate

File size (mb)	Time (s)	SHA256
1	88.8	No
1	88.8	Yes
5	448	Yes
10	892.7	Yes
20	1785.4	Yes

Table 2: Transfer times with 115200 baudrate

### 3.4 Data diode 0.3

The aim with version 0.3 of the program is to initially format the code so as to make it much more readable. As far as technical improvements we will include byte read instead of *readline()*, so as to make less calls to the read and write methods, also we will be splitting up the SHA256 algorithm from the copying of file contents. These two improvements should improve file transfer speeds.

## 4 Appendix

### 4.1 Appendix 1: Documentation extract

#### 4.2 TTL-232R-5V and TTL-232R-3V3 Cable Signal Descriptions

Header Pin Number	Name	Type	Colour	Description
1	GND	GND	Black	Device ground supply pin.
2	CTS#	Input	Brown	Clear to Send Control input / Handshake signal.
3	VCC	Output	Red	+5V output,
4	TXD	Output	Orange	Transmit Asynchronous Data output.
5	RXD	Input	Yellow	Receive Asynchronous Data input.
6	RTS#	Output	Green	Request To Send Control Output / Handshake signal.

**Table 4.1 TTL-232R-5V and TTL-232R-3V3 Cable Signal Descriptions**

### 4.2 Appendix 2: Diagnostic output and code example

Listing 1: sndtest.py

```
#!/usr/bin/env python
import time
import serial

ser = serial.Serial(
    port='/dev/serial0',
    baudrate = 9600,
    parity=serial.PARITY_NONE,
    stopbits=serial.STOPBITS_ONE,
    bytesize=serial.EIGHTBITS,
    timeout=1
)
counter=0

while True:
    ser.write(b'Write_counter: %d\n'%(counter))
    time.sleep(1)
    counter += 1
```

Listing 2: rcvtest.py

```
#!/usr/bin/env python
import time
import serial

ser = serial.Serial(
    port='/dev/ttyUSB0',
    baudrate = 9600,
    parity=serial.PARITY_NONE,
    stopbits=serial.STOPBITS_ONE,
    bytesize=serial.EIGHTBITS,
    timeout=1
)

while True:
    x=ser.readline()
    print(x)
```

Listing 3: output.txt

```
b'Write counter: 0\n'
b'Write counter: 1\n'
b'Write counter: 2\n'
b'Write counter: 3\n'
b'Write counter: 4\n'
b'Write counter: 5\n'
```

#### 4.3 Appendix 3: Data diode 0.1 code example

Listing 4: sndfile0.1.py

```
import serial
import time
import os
from hurry.filesize import size, alternative

ser = serial.Serial(
    port = "/dev/serial0",
    baudrate = 9600,
    parity = serial.PARITY_NONE,
    stopbits = serial.STOPBITS.ONE,
    bytesize = serial.EIGHTBITS,
    timeout=1
)
#Initialize serial port

filesize = size(os.path.getsize('log.txt'), system=alternative)
#gets filesize in a nice manner to read,
#will be used for performance purposes

print("Starting _transfer ... _Time_started")
start_time= time.time()
```

```

#Here we open the file , and keep on reading until there's
#lines , we then send <<EOF>> to signal to the other
#machine that file transfer is over.

f = open("log.txt","rb")
line = f.readline()
while line:
    ser.write(line)
    line = f.readline()

ser.write(b"<<EOF>>\n")

f.close()

end_time = time.time() - start_time

print('Transfer completed ... _Filesize:', filesize , '._Time:', end_time , 'seconds.')
```

Listing 5: rcvfile0.1.py

```

import serial
import time

ser = serial.Serial(
    port = "/dev/ttyUSB0",
    baudrate = 9600,
    parity = serial.PARITY_NONE,
    stopbits = serial.STOPBITS_ONE,
    bytesize = serial.EIGHTBITS,
    timeout = 1
)

eof = b"<<EOF>>\n"

f = open("log.txt", "wb")

x = ser.readline()

while x != eof:
    f.write(x)
    x = ser.readline()
f.close()
```

#### 4.4 Appendix 4: Data diode 0.2 code example

Listing 6: sndfile0.2.py

```

import serial
import time
import os
from hurry.filesize import size, alternative
import hashlib
```

```

ser = serial.Serial(
    port = "/dev/serial0",
    baudrate = 115200,
    parity = serial.PARITY_NONE,
    stopbits = serial.STOPBITS_ONE,
    bytesize = serial.EIGHTBITS,
    timeout=1
)
#Initialize serial port

filesize = size(os.path.getsize('log.txt'), system=alternative)
#gets filesize in a nice manner to read, will be used for performance purposes

sha256_hash = hashlib.sha256()
#we will calculate the SHA256 of the file to verify integrity.

f = open("log.txt","rb")
print("Starting_transfer ... _Time_started")
start_time= time.time()
#Here we open the file, and keep on reading until there's lines
#we then send <<EOF>> to signal to the other machine that file transfer is over.
ser.flushOutput()
line = f.readline()
while line:
    sha256_hash.update(line)
    ser.write(line)
    line = f.readline()
end_time = time.time() - start_time
f.close()
ser.write(b"<<EOF>>\n")

sha256_hash = sha256_hash.digest() #digest transforms into string
ser.write(sha256_hash)

print('Transfer_completed ... _Filesize:', filesize, '._Time:', end_time, 'seconds.')
```

Listing 7: rcvfile0.2.py

```

import serial
import time
import hashlib

ser = serial.Serial(
    port = "/dev/ttyUSB0",
    baudrate = 115200,
    parity = serial.PARITY_NONE,
    stopbits = serial.STOPBITS_ONE,
    bytesize = serial.EIGHTBITS,
    timeout = 1
```



```

    )
#initialize serial port

eof = b"<<EOF>>\n"
#define EOF, signals to the receiver that the file is over

sha256_hash = hashlib.sha256()
#we will calculate the SHA256 of the file
#to verify it's integrity after transferring

f = open("log.txt", "wb")
#open file to write into
ser.flushInput()
x = ser.readline()
while x != eof:
#until file comes, decode, if x=eof then check if file transfered correctly
    sha256_hash.update(x)
    #decoding is done in bytes, so we make sha before making it in bits
    f.write(x)
    x = ser.readline()
f.close()

sha256_send = ser.read(32)
if sha256_send != sha256_hash.digest():
    print("File_Transfer_failed")
else:
    print("File_Transfer_success")

```