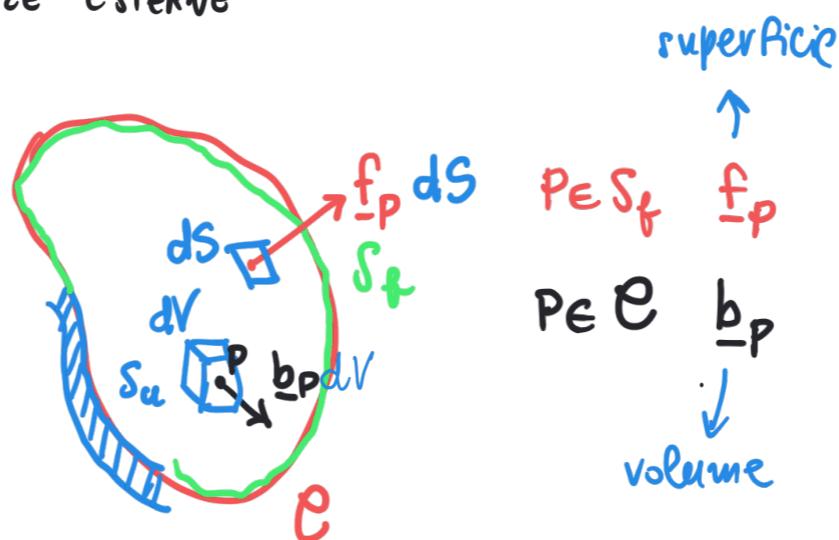


Consideriamo un corpo continuo tridimensionale
 Supponiamo che una parte della sua superficie S_u
 sia vincolata a fermo & che la porzione
 rimanente sia soggetta a forze note f
 forze esterne di volume descritte da vettori
 vettoriali b tali che le forze che agiscono
 su un elemento dV sono a punti a $b dV$.

FORZE ESTERNE



$$\underline{R}(S') = \int_{S'} f_p dS \quad \underline{R}(C) = \int_{C'} b_p dV$$

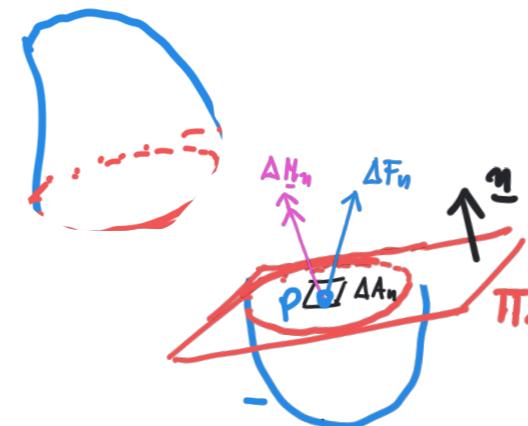
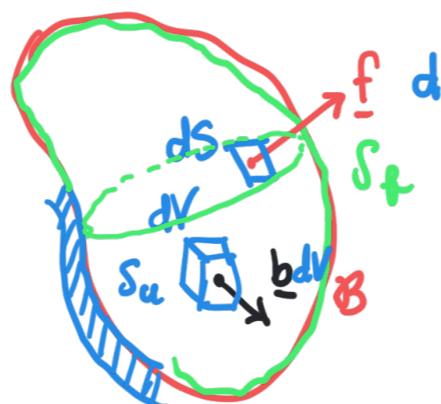
↑
superficie
↓
volume

$P \in S_f \quad f_p$

$P \in \mathcal{B} \quad b_p$

Per effetto delle forze esterne, si inserisce nel corpo delle tensioni interne. Per convenience si considerano un piano Π

$$\underline{R}(S') = \int_{S'} f_p dS \quad \underline{R}(S) = \int_{V'} b_p dV$$

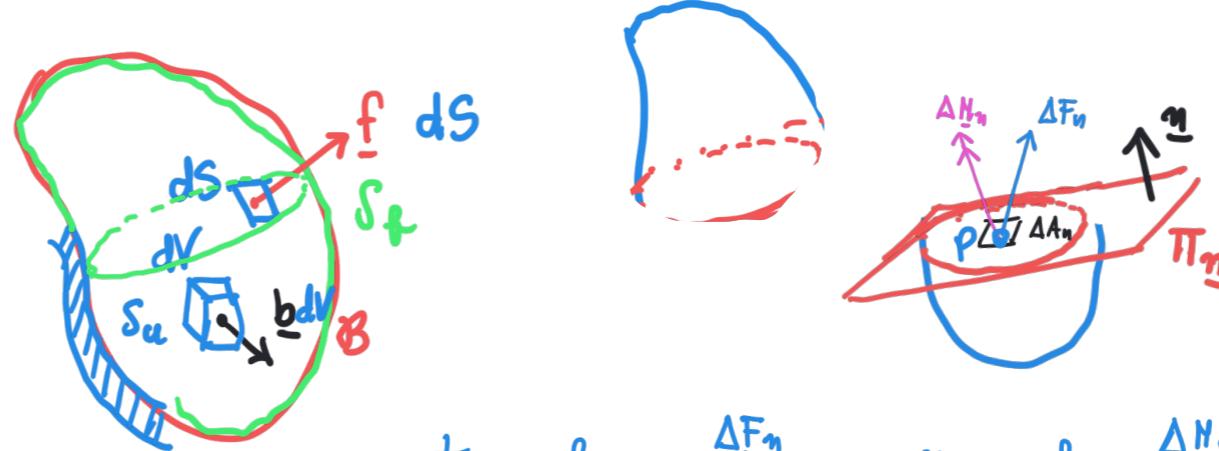


$$\underline{t}_n := \lim_{\Delta A_n \rightarrow 0} \frac{\Delta F_n}{\Delta A_n}$$

$$\underline{m}_n := \lim_{\Delta A_n \rightarrow 0} \frac{\Delta H_n}{\Delta A_n}$$

Continua di Cauchy: $\underline{m}_n = 0$

• $\underline{t}_n = \underline{t}_n(p)$ tensione di Cauchy



$$\underline{t}_n := \lim_{\Delta A_n \rightarrow 0} \frac{\Delta F_n}{\Delta A_n}$$

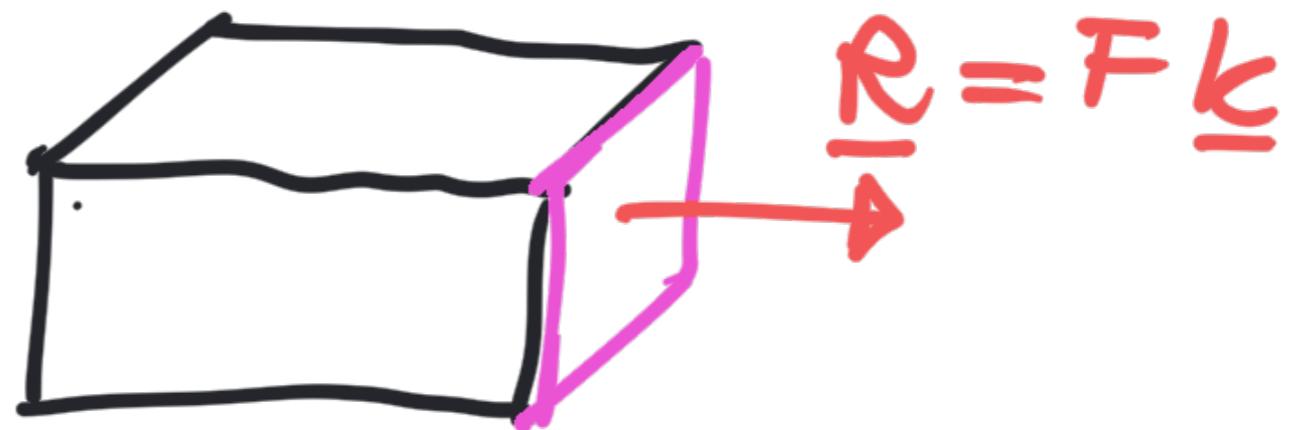
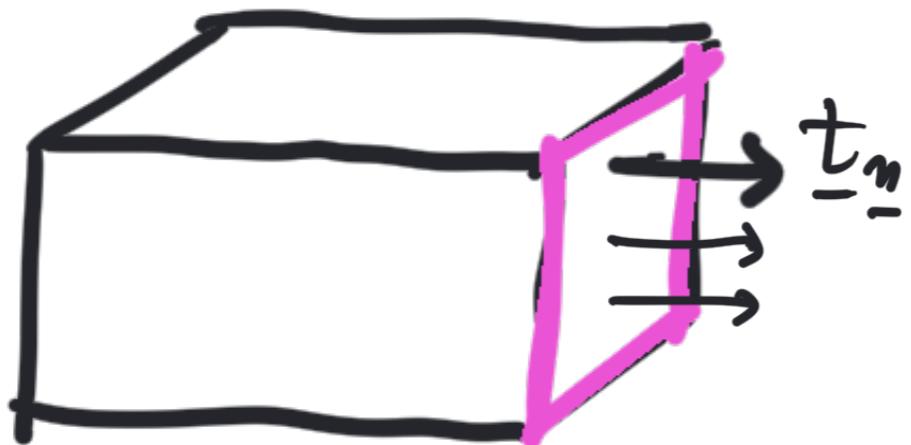
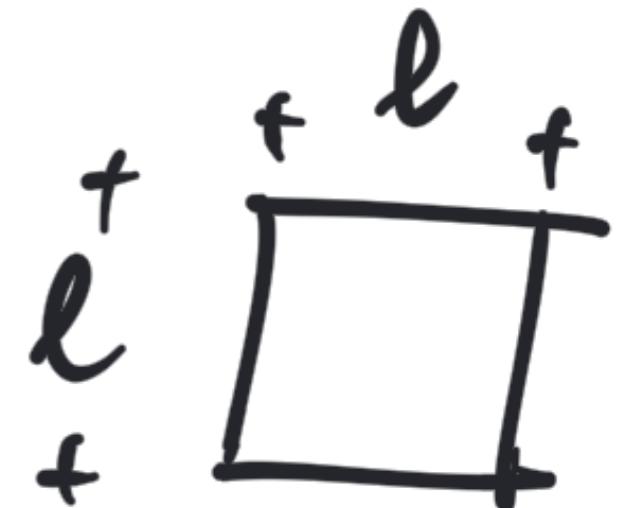
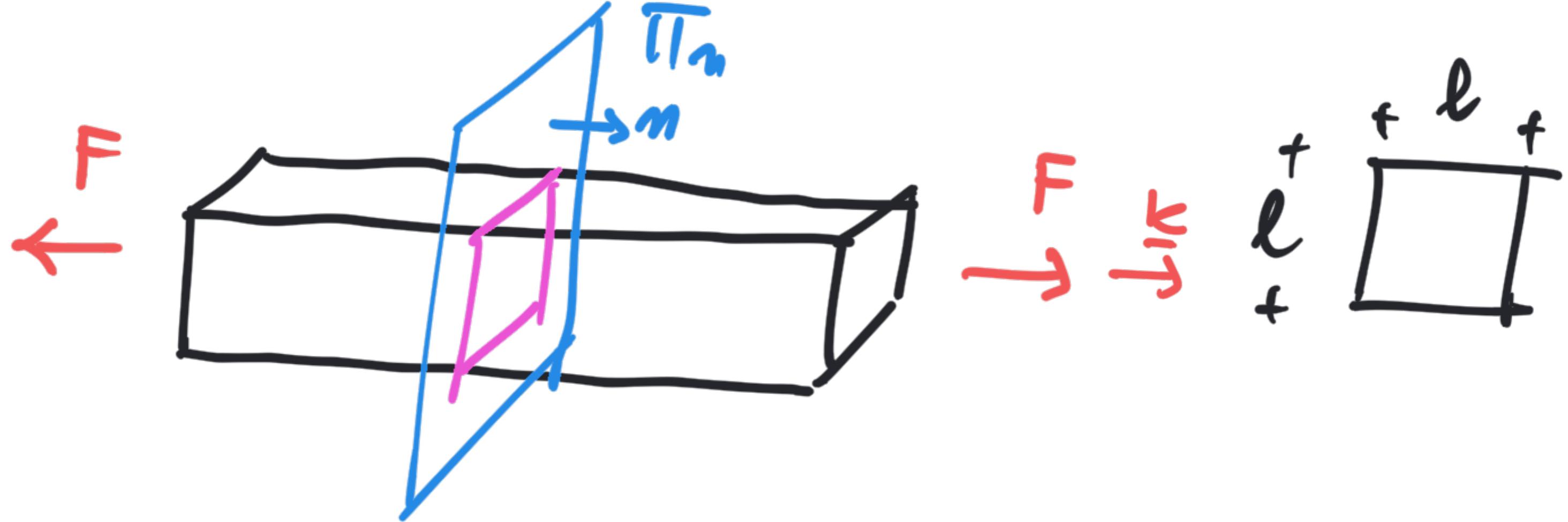
$$\underline{m}_n := \lim_{\Delta A_n \rightarrow 0} \frac{\Delta N_n}{\Delta A_n}$$

Continuo di Cauchy : $\underline{m}_n = 0$

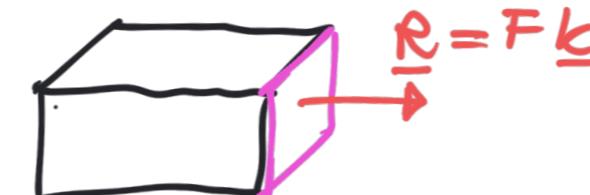
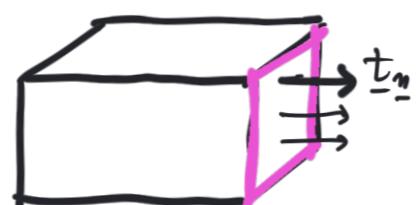
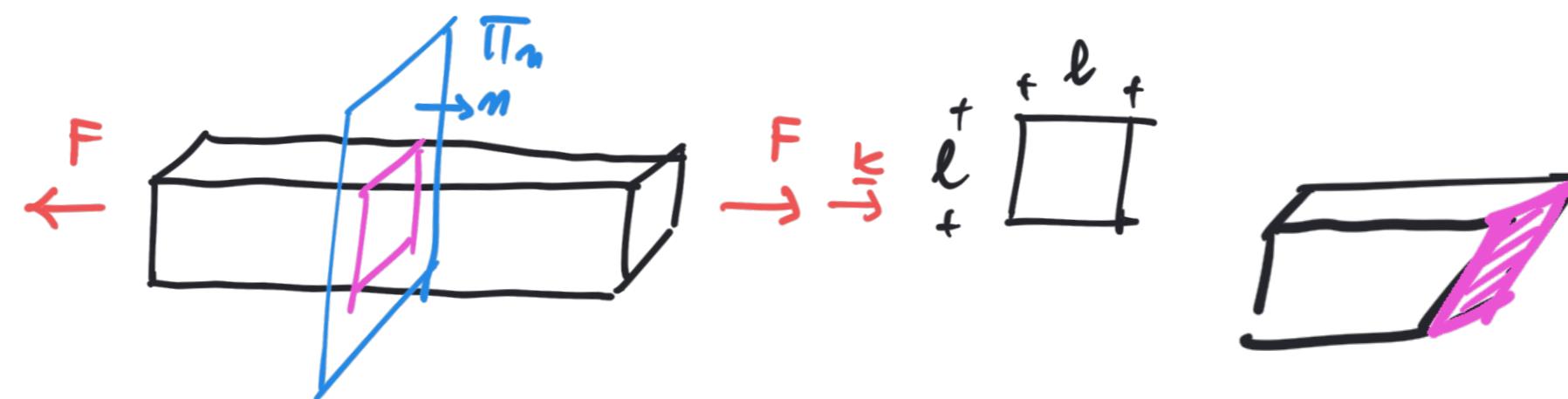
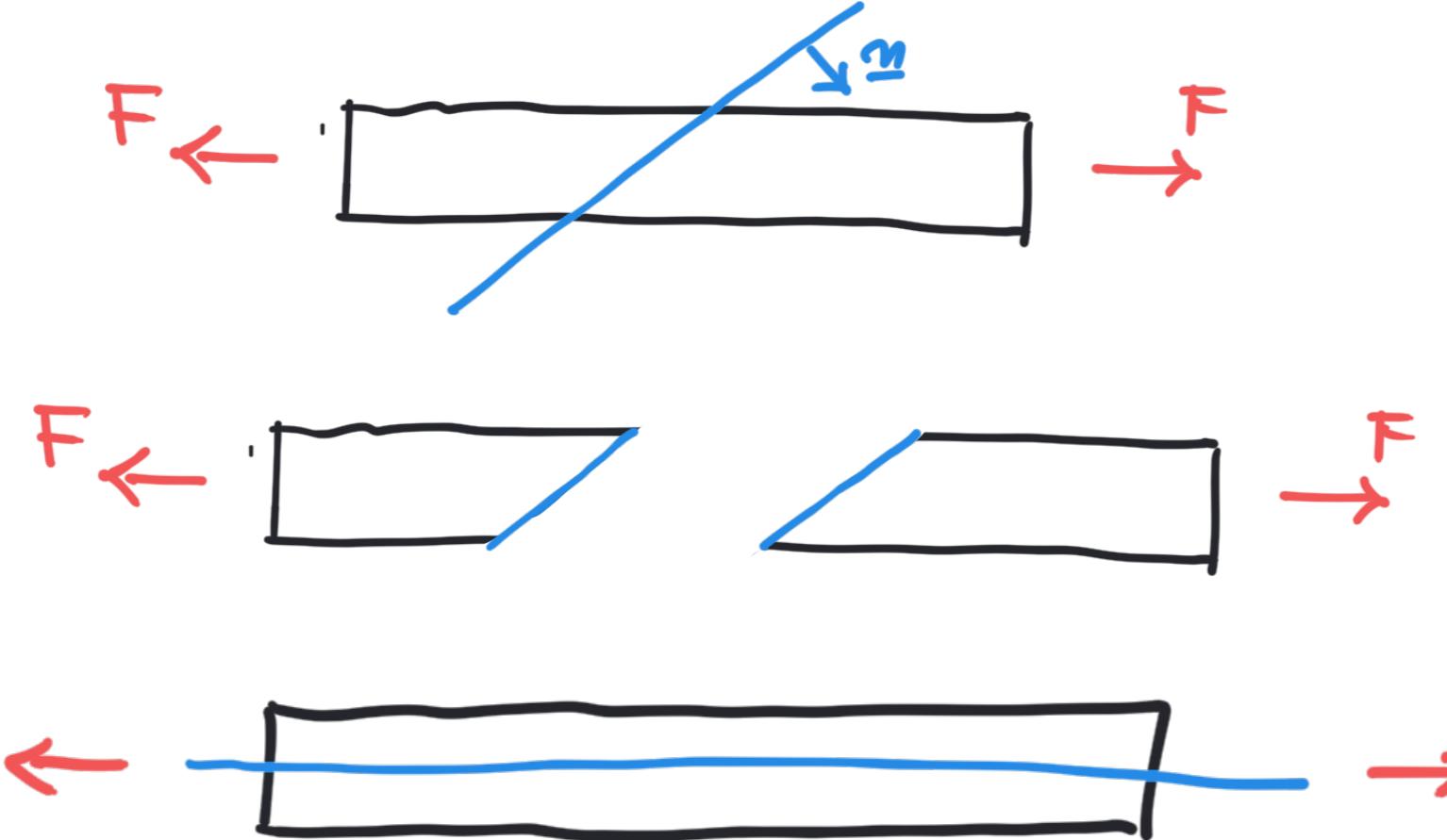
$\underline{t}_n = \underline{t}_n(P)$ "tensione di Cauchy in P agente secondo la giacitura di normale n "

$$[\underline{t}_n] = F L^{-2} \quad (\text{Pa}) \quad \begin{matrix} \text{pascal} \\ \nwarrow \text{millimetre} \end{matrix}$$

$\underline{m} \neq 0$ Continuo "polo". (fotelli Gererat)

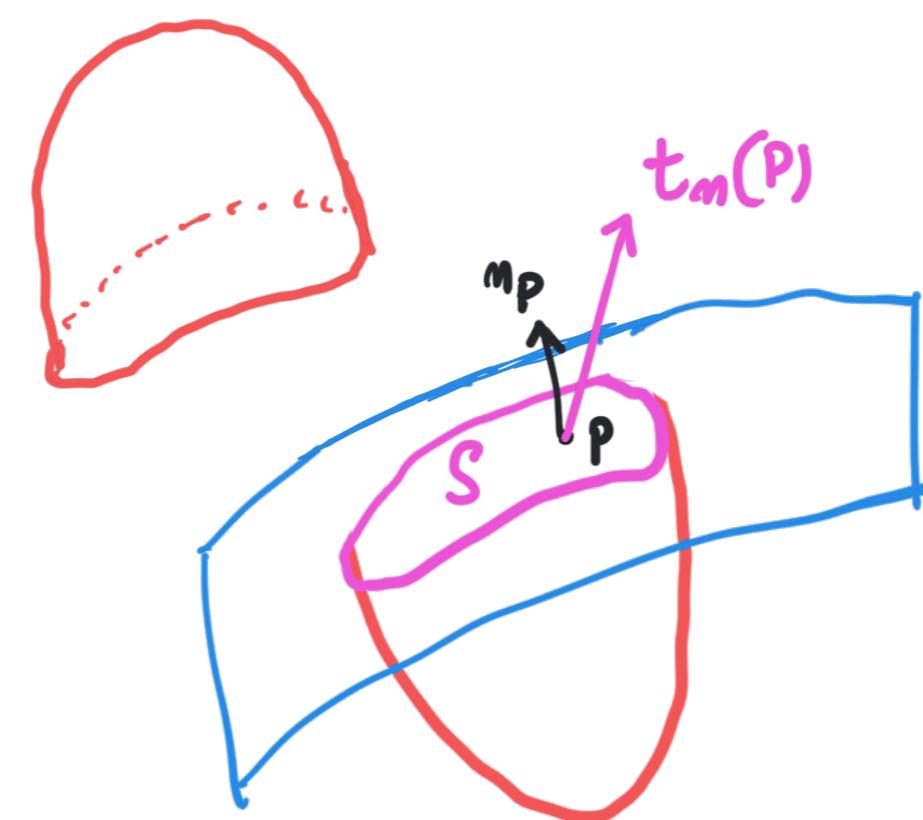


$$|t_m| = \frac{F}{e^2}$$

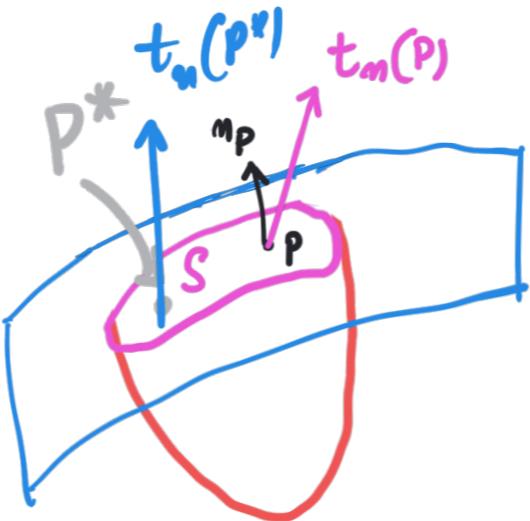


$$|t_m| = \frac{F}{\ell^2}$$

Consideriamo un corpo continuo. Supponiamo di tagliarlo con una superficie di forma arbitraria



$$\underline{R} = \int_S t_m(P) dA \quad \text{forza risult. esercita su } S$$



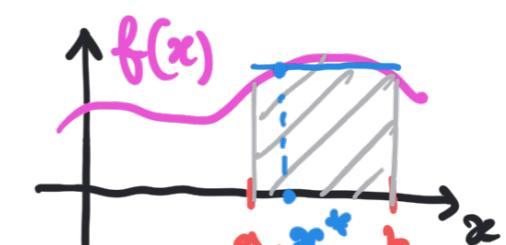
$$\underline{R} = \int_S t_m(P) dA \quad \text{forza risult. esercita su } S$$

Teor. valor medio

$$\underline{R} = \text{area}(S) \cdot \underline{t}_m(P^*)$$

$P^* \in S$

↑
tensione media



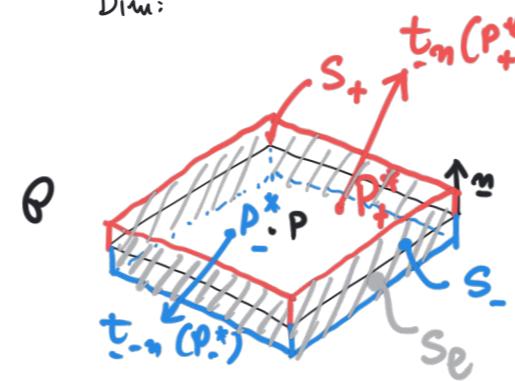
$$\int_a^b f(x) dx = (b-a) f(x^*)$$

$x^* \in (a, b)$

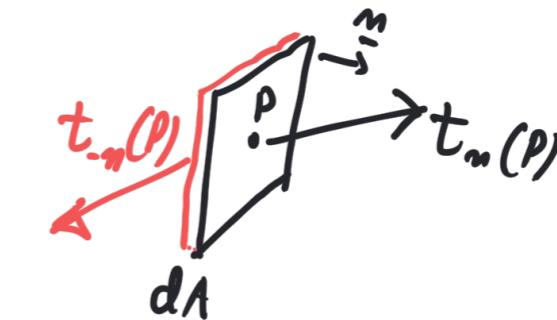
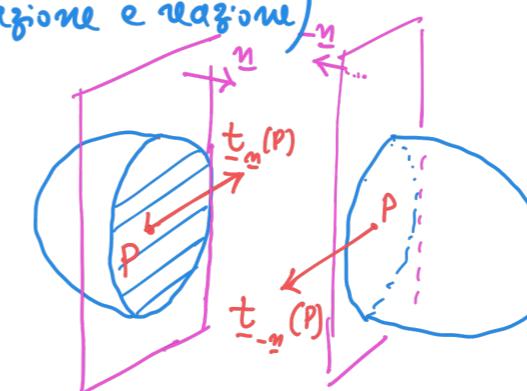
Lemma di Cauchy: (teorema di azione e reazione)

$$\underline{t}_m(P) = - \underline{t}_{-n}(P)$$

Dim:



$$P_+^k \in S_+ \\ P_-^k \in S_-$$



$$\underline{t}_m(P_+^k) + \underline{t}_{-n}(P_-^k) + \frac{f_\ell}{\epsilon^2} + \epsilon^2 b(P^k) = 0$$

$\epsilon \rightarrow$

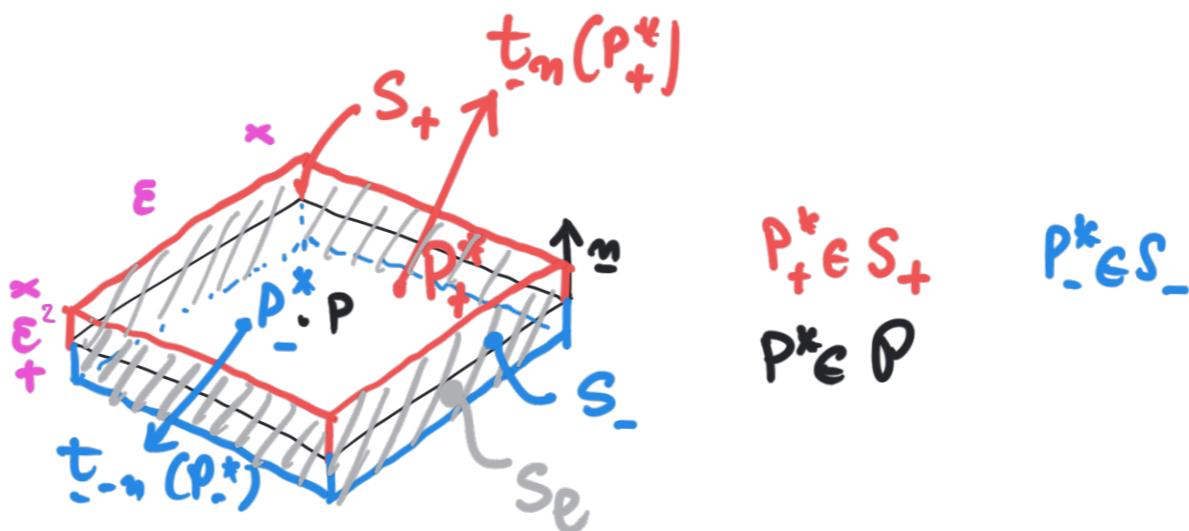
$$\underline{t}_m(P) + \underline{t}_{-n}(P) = 0$$

$$\text{area}(S_e) = 4\epsilon^3$$

Scomposizione del vettore tensione di Cauchy

$$\underline{t}_n = t_{nx} \underline{i} + t_{ny} \underline{j} + t_{nz} \underline{k} \quad \begin{bmatrix} \underline{t}_n \end{bmatrix} = \begin{bmatrix} t_{nx} \\ t_{ny} \\ t_{nz} \end{bmatrix} \quad \begin{bmatrix} \underline{m} \end{bmatrix} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}$$

$$\alpha = \underline{m} \cdot \underline{i} \quad \beta = \underline{m} \cdot \underline{j} \quad \gamma = \underline{m} \cdot \underline{k}$$



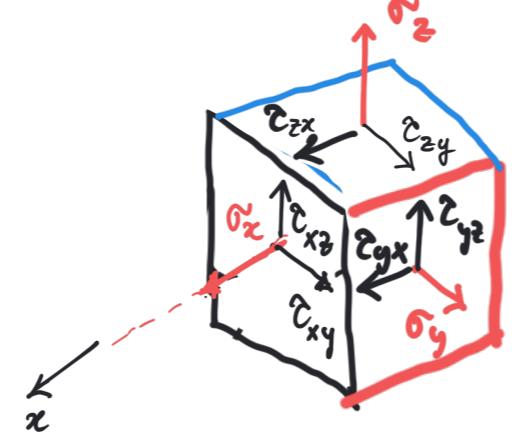
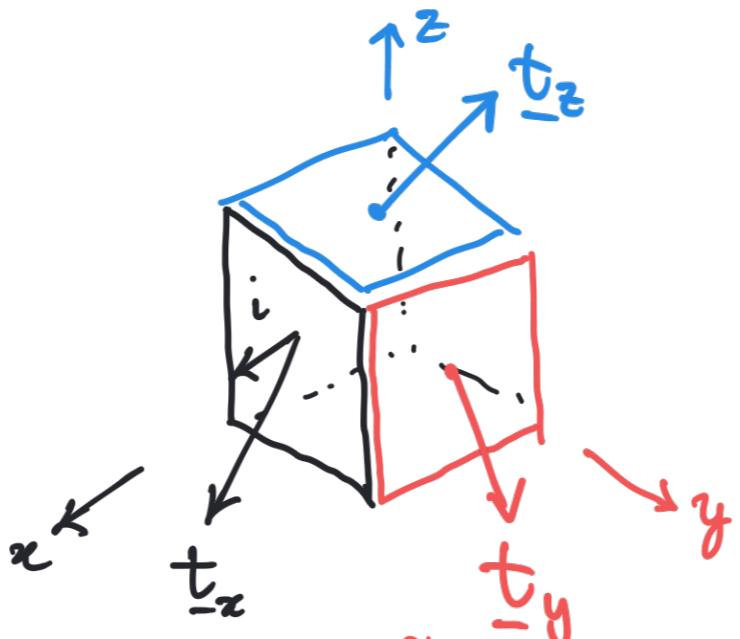
$$\underline{t}_n(P_+^*) + \underline{t}_{-n}(P_-^*) + \frac{\underline{f}_e}{\epsilon^2} + \epsilon \underline{b}(P^*) = \underline{0}$$

$\epsilon \rightarrow$

$$\underline{t}_n(P) + \underline{t}_{-n}(P) = \underline{0}$$

$$\text{area}(S_e) = 4\epsilon^3$$

Componenti speciali delle tensione



tensore degli sforzi

$$[T(P)]$$

$$\begin{bmatrix} \alpha_x \\ \tau_{xy} \\ \tau_{xz} \\ \tau_{yz} \end{bmatrix} \rightarrow \begin{bmatrix} \alpha_x \\ \tau_{yz} \\ \alpha_y \\ \tau_{yz} \end{bmatrix} \rightarrow \begin{bmatrix} \tau_{zx} \\ \tau_{zy} \\ \alpha_z \end{bmatrix}$$

matrice rappresentativa dell' tensore T

notazione

$$\underline{t}_x \equiv \underline{t}_i \quad \underline{t}_y = \underline{t}_j$$

$$\underline{t}_z \equiv \underline{t}_k \quad \underline{t}_{-x} \equiv \underline{t}_{-i}$$

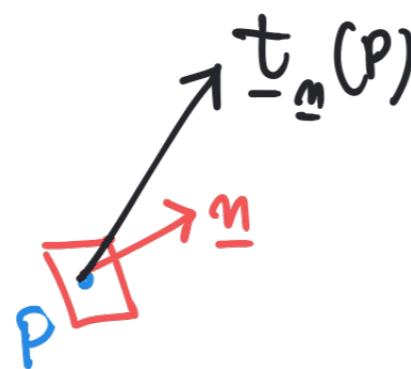
$$-\underline{t}_x = -\underline{t}_i$$

$$[\underline{t}_x] = \begin{bmatrix} \alpha_x \\ \tau_{xy} \\ \tau_{xz} \end{bmatrix}$$

$$[\underline{t}_y] = \begin{bmatrix} \tau_{yz} \\ \alpha_y \\ \tau_{yz} \end{bmatrix}$$

$$[\underline{t}_z] = \begin{bmatrix} \tau_{zx} \\ \tau_{zy} \\ \alpha_z \end{bmatrix}$$

FORMULA DI CAUCHY



$$[t_{\underline{m}}(P)] = [I(P)] [n]$$

notazione

$$\begin{aligned} t_x &= t_i & t_g &= t_j \\ t_z &= t_k & t_{-x} &= t_{-i} \\ -t_x &= -t_i & \text{"} & \text{"} \end{aligned}$$

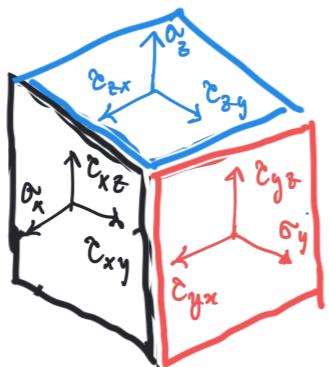
$$[n] = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}$$

$$\text{Es: } \underline{m} = \underline{i} \quad [n] = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad [T(P)] [n] = \begin{bmatrix} \alpha_x \\ \alpha_{xy} \\ \alpha_{xz} \end{bmatrix}$$

$$[t_x] = \begin{bmatrix} \alpha_x \\ \alpha_{xy} \\ \alpha_{xz} \end{bmatrix}$$

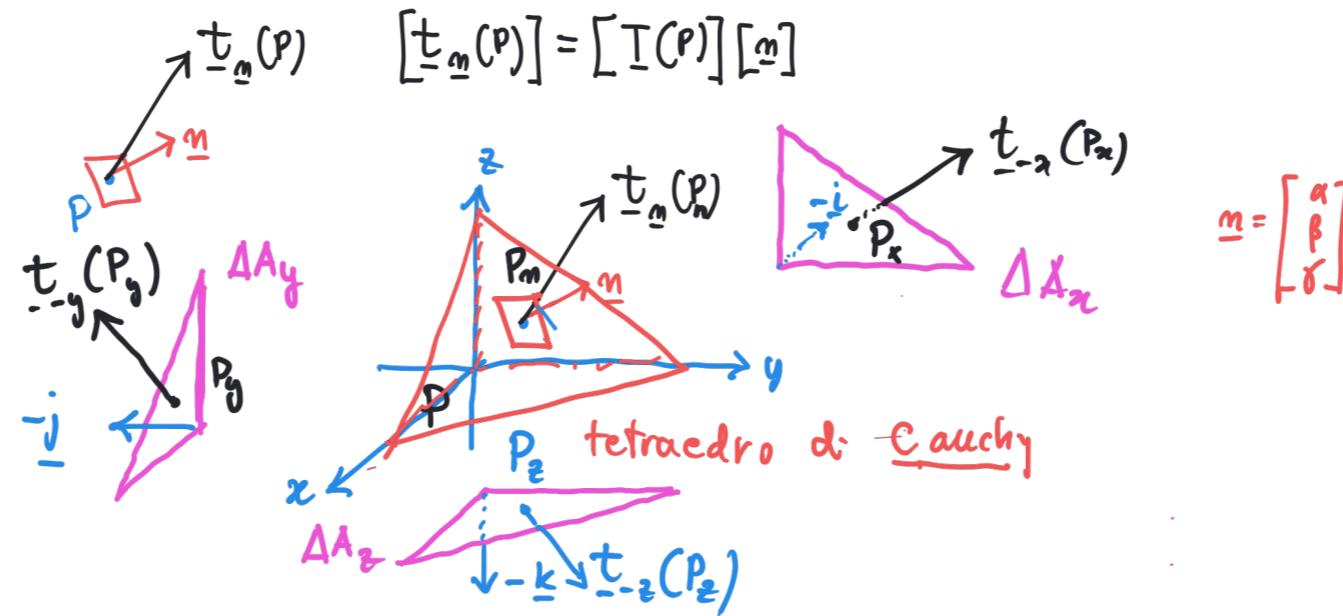
$$[t_y] = \begin{bmatrix} \alpha_{yx} \\ \alpha_y \\ \alpha_{yz} \end{bmatrix}$$

$$[t_z] = \begin{bmatrix} \alpha_{zx} \\ \alpha_{zy} \\ \alpha_z \end{bmatrix}$$



$$[I(P)] = \begin{bmatrix} \alpha_x & \alpha_{yx} & \alpha_{zx} \\ \alpha_{xy} & \alpha_y & \alpha_{zy} \\ \alpha_{xz} & \alpha_{yz} & \alpha_z \end{bmatrix}$$

FORMULA DI CAUCHY



$$\underline{t}_m(P_m) \Delta A_n + \underline{t}_{-x}(P_x) \frac{\Delta A_x}{\Delta A_n} + \underline{t}_{-y}(P_y) \frac{\Delta A_y}{\Delta A_n} + \underline{t}_{-z}(P_z) \frac{\Delta A_z}{\Delta A_n} + b(P) \frac{\Delta V}{\Delta A_n} = 0$$

$$\underline{t}_m(P) + \underline{t}_{-x}(P) \alpha + \underline{t}_{-y}(P) \beta + \underline{t}_{-z}(P) \gamma + 0 = 0$$

$\Delta A_n \rightarrow 0$
 $P_m, P_x, P_y, P_z \rightarrow P$

$$\boxed{\underline{t}_m(P) = \underline{t}_x(P)\alpha + \underline{t}_y(P)\beta + \underline{t}_z(P)\gamma}$$

FORMULA DI CAUCHY

$$\underline{t}_m(p) = \begin{bmatrix} t_{mx} \\ t_{my} \\ t_{mz} \end{bmatrix} = \begin{bmatrix} \alpha_x \\ \alpha_{xy} \\ \alpha_{xz} \end{bmatrix} \alpha + \begin{bmatrix} \alpha_{yx} \\ \alpha_y \\ \alpha_{yz} \end{bmatrix} \beta + \begin{bmatrix} \alpha_{zx} \\ \alpha_{zy} \\ \alpha_z \end{bmatrix} \gamma$$

$$= \begin{bmatrix} \alpha_x & \alpha_{yx} & \alpha_{zx} \\ \alpha_{xy} & \alpha_y & \alpha_{zy} \\ \alpha_{xz} & \alpha_{yz} & \alpha_z \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = [T(p)] \underline{m}$$

$$\underline{t}_m(p) = \begin{bmatrix} t_{mx} \\ t_{my} \\ t_{mz} \end{bmatrix} = \begin{bmatrix} \alpha_x \\ \alpha_{xy} \\ \alpha_{xz} \end{bmatrix} \alpha + \begin{bmatrix} \alpha_{yx} \\ \alpha_y \\ \alpha_{yz} \end{bmatrix} \beta + \begin{bmatrix} \alpha_{zx} \\ \alpha_{zy} \\ \alpha_z \end{bmatrix} \gamma$$

$$= \begin{bmatrix} \alpha_x & \alpha_{yx} & \alpha_{zx} \\ \alpha_{xy} & \alpha_y & \alpha_{zy} \\ \alpha_{xz} & \alpha_{yz} & \alpha_z \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = [T(p)] \underline{m}$$

$$\underline{t}_m(p) = T(p) \underline{m}$$

↑ tensoro (appl. lin.)

$$[T(p)] = \begin{bmatrix} \alpha_x & \alpha_{yx} & \alpha_{zx} \\ \alpha_{xy} & \alpha_y & \alpha_{zy} \\ \alpha_{xz} & \alpha_{yz} & \alpha_z \end{bmatrix}$$

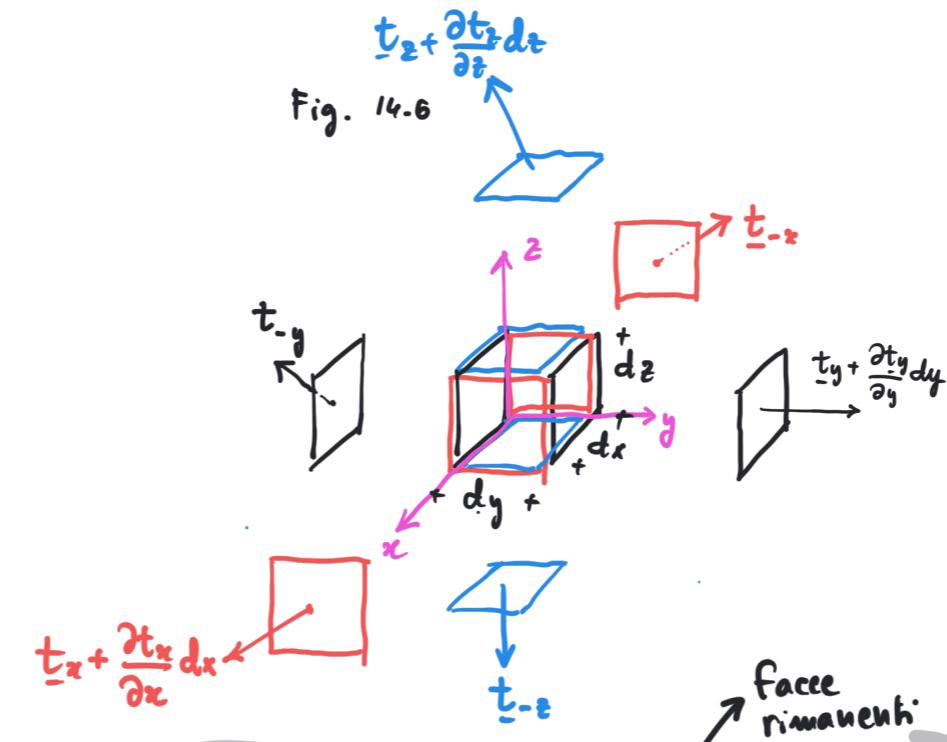
$$\boxed{\underline{t}_m(p) = \underline{t}_x(p)\alpha + \underline{t}_y(p)\beta + \underline{t}_z(p)\gamma} \quad (*)$$

$$[\underline{t}_x] = \begin{bmatrix} \alpha_x \\ \alpha_{xy} \\ \alpha_{xz} \end{bmatrix}$$

$$[\underline{t}_y] = \begin{bmatrix} \alpha_{yx} \\ \alpha_y \\ \alpha_{yz} \end{bmatrix}$$

$$[\underline{t}_z] = \begin{bmatrix} \alpha_{zx} \\ \alpha_{zy} \\ \alpha_z \end{bmatrix}$$

Fig. 14.6



$$\left(t_x + \frac{\partial t_x}{\partial x} dx \right) dy dz - t_x dy dz + \dots + b dx dy dz = 0$$

(14.15) $\boxed{\frac{\partial t_x}{\partial x} + \frac{\partial t_y}{\partial y} + \frac{\partial t_z}{\partial z} + b = 0}$ ← eq.n. indefinita
di equilibrio

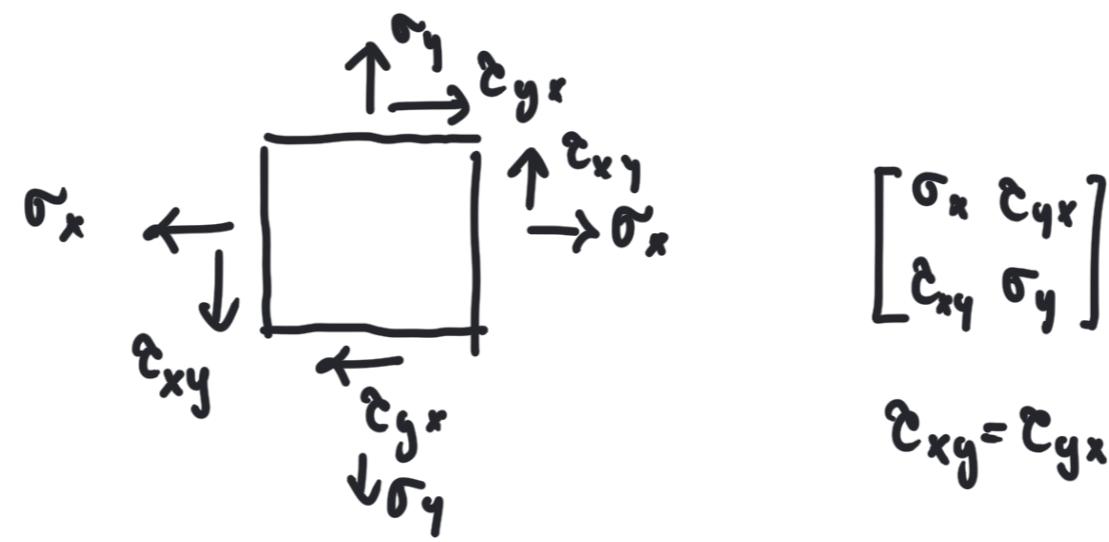
(14.16) $\frac{\partial}{\partial x} \sigma_x + \frac{\partial}{\partial y} \tau_{yx} + \frac{\partial}{\partial z} \tau_{zx} + b_x = 0$ ← div T

$$\frac{\partial}{\partial x} \tau_{xy} + \frac{\partial}{\partial y} \sigma_y + \frac{\partial}{\partial z} \tau_{zy} + b_y = 0$$

$$\frac{\partial}{\partial x} \tau_{xz} + \frac{\partial}{\partial y} \tau_{yz} + \frac{\partial}{\partial z} \sigma_z + b_z = 0$$

$$\text{div } \underline{T} + b = 0$$

Eq. momento



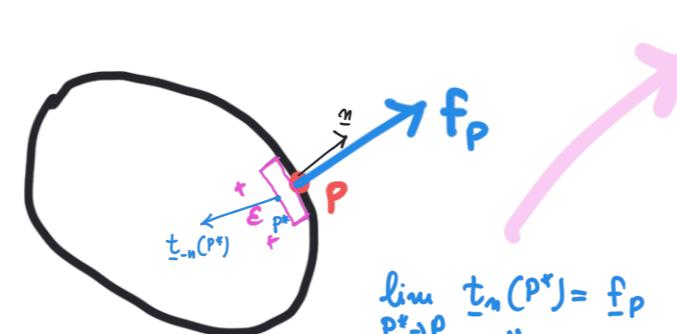
$$\begin{bmatrix} \sigma_x & \tau_{yx} \\ \tau_{xy} & \sigma_y \end{bmatrix}$$

$$\tau_{xy} = \tau_{yx}$$

$\underline{\sigma} = \underline{\sigma}^T$ (simmetria)

$\operatorname{div} \underline{\sigma} + \underline{b} = 0$

CONDIZ. CONTORNO



$$\underline{t}_{-n}(p^*) + \underline{f}_p + O(\epsilon) = 0$$

$$\underline{t}_n(p^*) = \underline{f}_p + O(\epsilon)$$

$$\lim_{p^* \rightarrow p} T(p^*) \underline{n}_p = f_p$$

||

$$T(p) \underline{n}_p$$

$$\underline{T}(p) \underline{n}_p = f_p$$

$$\underline{T} = \underline{T}^T \quad (\text{simmetria})$$

$$\operatorname{div} \underline{T} + \underline{b} = 0$$

PROBLEMA STAZIONARIO

$$\left. \begin{array}{l} \operatorname{div} \underline{\mathbf{T}} + \underline{\mathbf{b}} = \mathbf{0} \\ \underline{\mathbf{T}} = \underline{\mathbf{T}}^T \quad (\text{simmetria}) \end{array} \right\} \text{in } \mathcal{C}$$

N.B.: 3 eq.ni diff. l.
6 incognite

$$\underline{\mathbf{T}}_{\mathbf{n}} = \underline{\mathbf{f}} \quad \text{in } \mathcal{S}_f$$

PROBLEMA STATICO

$$\operatorname{div} \underline{T} + \underline{b} = 0$$

$$\underline{T} = \underline{T}^T \text{ (simmetria)}$$

} in Ω

N.B.: 3 eq.ni diff. l.
6 incogniti

$$\underline{T} \underline{m} = \underline{f} \quad \text{in } \mathcal{S}_f$$

