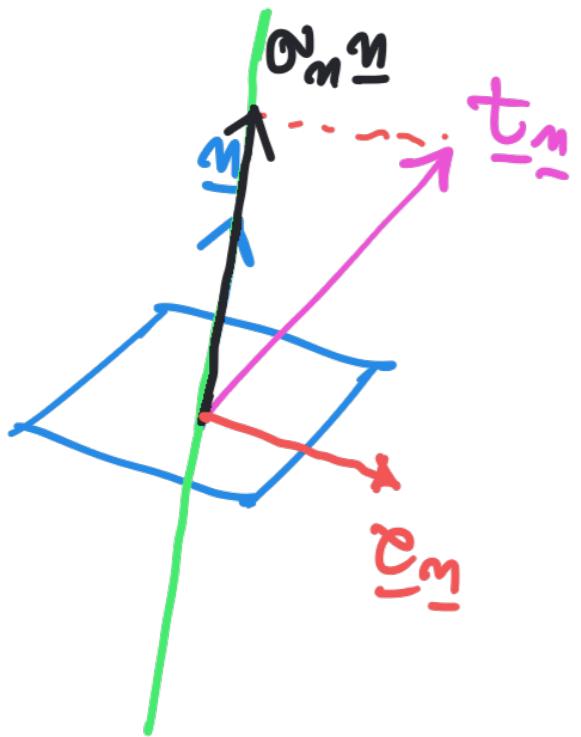


# MEMO:



$$\sigma_n = \underline{t}_n \cdot \underline{n} \quad (\text{tensione normale})$$

$$\underline{t}_n = \sigma_n \underline{n} + \underline{\epsilon}_n = \underline{T} \underline{n}$$

↑ comp.  
normale

↑ comp.  
tang.

$$[\underline{T}] = \begin{bmatrix} \sigma_x & \epsilon_{yx} & \epsilon_{zx} \\ \epsilon_{xy} & \sigma_y & \epsilon_{zy} \\ \epsilon_{xz} & \epsilon_{yz} & \sigma_z \end{bmatrix}$$

Problema: cerchiamo le giaciture  $\underline{n}$  tali che  $\underline{\epsilon}_n = \underline{0}$

$$\Leftrightarrow \underline{T} \underline{n} = \sigma_n \underline{n}$$



$\underline{n}$  autovettore di  $\underline{T}$

$\sigma_n$  autoval. di  $\underline{T}$

$\underline{n}$  duez. princ.

$\sigma_n$  tens. princ.

Problema: cerchiamo le direzioni  $\underline{m}$  tali che  $\underline{\sigma}_m \underline{m} = \underline{0}$

$$\Leftrightarrow \underline{\sigma}_m \underline{m} = \underline{0}$$

$\underline{m}$  autovettore di  $\underline{\sigma}$

$\underline{m}$  dirz. princ.

$\sigma_m$  autoval. di  $\underline{\sigma}$

$\sigma_m$  teur. princ.

$$\cdot \quad \underline{\sigma}_m \underline{m} = \sigma_m \underline{m} = \underline{0}$$

$$\begin{cases} (\underline{\sigma} - \sigma_m \underline{I}) \underline{m} = \underline{0} \\ \alpha^2 + \beta^2 + \gamma^2 = 1 \end{cases}$$

$$|\underline{m}| = 1$$

$$[\underline{m}] = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}$$

incognite:  $\alpha, \beta, \gamma, \sigma_m$

$$\begin{bmatrix} \alpha_x & \gamma_{yx} & \gamma_{zx} \\ \gamma_{xy} & \alpha_y & \gamma_{zy} \\ \gamma_{xz} & \gamma_{yz} & \alpha_z \end{bmatrix}$$

$$\det(\underline{I} - \sigma_m \underline{I}) = 0$$

(\*)

$$\sigma_m^3 - I_1 \sigma_m^2 + I_2 \sigma_m - I_3 = 0$$

$\uparrow$        $\uparrow$        $\uparrow$   
invariabili di  $\underline{I}$

$$I_1 = \operatorname{tr} \underline{I}$$

$$I_2 = \frac{1}{2} [(t_r \underline{I})^2 - \operatorname{tr} \underline{I}^2]$$

$$I_3 = \det \underline{I}$$

$$(14.32)$$

$$\underline{I}^2 = \underline{I} \underline{I}$$

$\underline{I} = \underline{I}^T \Rightarrow$  il polinomio (\*) ha radici reali.

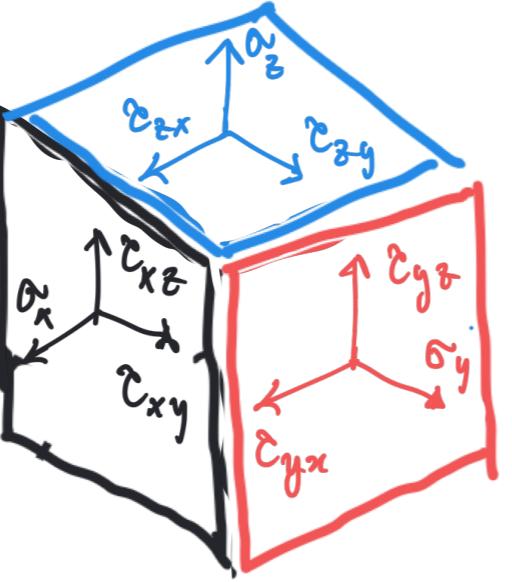
autovettori relativi ad autov. distinti  
sono fra loro ortogonal.

Esiste una base ortonormale

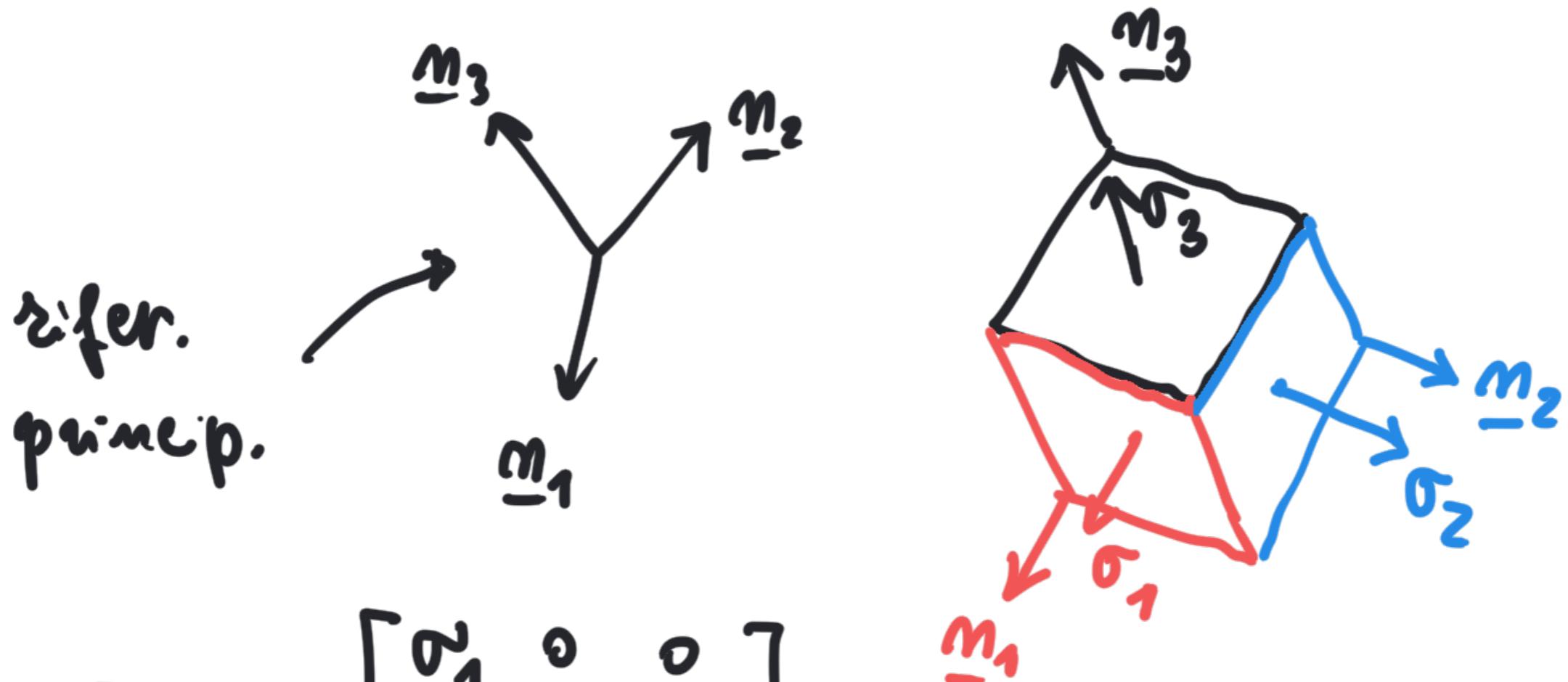
$\underline{m}_1, \underline{m}_2, \underline{m}_3$  d'autov.

$\sigma_1, \sigma_2, \sigma_3$  autovalori.

$$\begin{bmatrix} \alpha_x & \gamma_{yx} & \gamma_{zx} \\ \gamma_{xy} & \alpha_y & \gamma_{zy} \\ \gamma_{xz} & \gamma_{yz} & \alpha_z \end{bmatrix}$$



$$[I(P)] = \begin{bmatrix} \sigma_x & \tau_{yx} & \tau_{zx} \\ \tau_{xy} & \sigma_y & \tau_{zy} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{bmatrix}$$



$$[I]_* = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix}$$

Oss: il r.f. princ. non è unico.

Ese:  $[T] = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{bmatrix}$

glob d' sforzo  
sferico

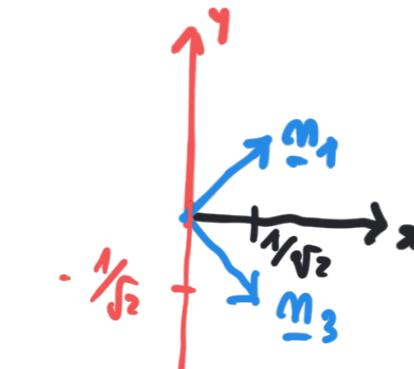
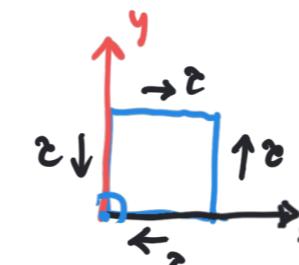
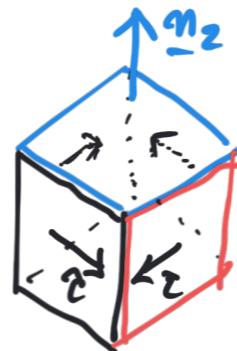
ogni r.f. è principale!

$$[T]_* = \begin{bmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{bmatrix}$$

qualsiasi altra base

ESEMPIO: taglio puro

$$[\underline{I}] = \begin{bmatrix} 0 & \tau & 0 \\ \tau & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



$$[\underline{I} - \sigma \underline{I}] = \begin{bmatrix} -\sigma & \tau & 0 \\ \tau & -\sigma & 0 \\ 0 & 0 & -\sigma \end{bmatrix}$$

$$\begin{aligned} \det(\underline{I} - \sigma \underline{I}) &= -\sigma \det \begin{pmatrix} -\sigma & \tau \\ \tau & -\sigma \end{pmatrix} = -\sigma(\sigma^2 - \tau^2) \\ &= -\sigma(\sigma + \tau)(\sigma - \tau) \end{aligned}$$

$$\sigma_1 = \sigma \quad \sigma_2 = 0 \quad \sigma_3 = -\tau$$

$$\begin{bmatrix} \tau & \tau & 0 \\ \tau & \tau & 0 \\ 0 & 0 & \tau \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$[\underline{m}_3] = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\tau & \tau & 0 \\ \tau & -\tau & 0 \\ 0 & 0 & -\tau \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & \tau & 0 \\ \tau & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

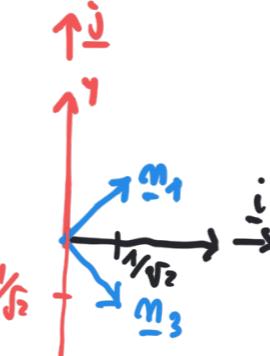
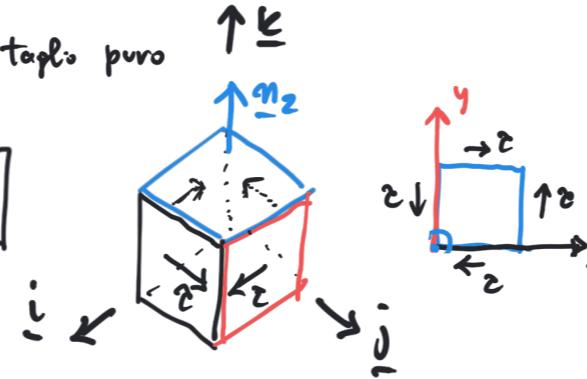
$$[\underline{m}_1] = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad |\underline{m}_1| = 1$$

$$[\underline{m}_2] = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \underline{m}_2 = k$$

att: anche  $-\underline{m}_1$  è una dirz. pone.

ESEMPIO: taglio puro

$$[I] = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

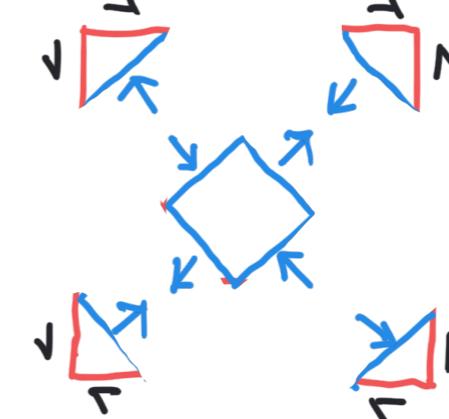
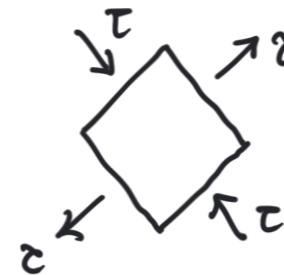
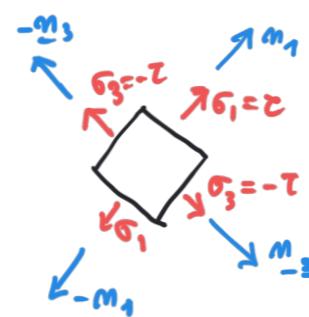
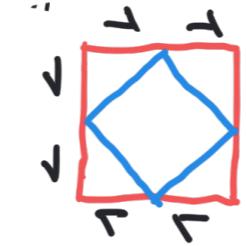
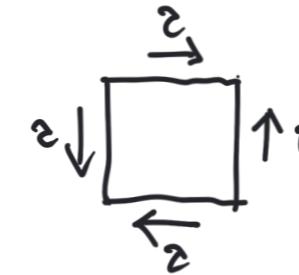


$$\sigma_1 = 0 \quad \sigma_2 = 0 \quad \sigma_3 = -2$$

$$m_1 = \frac{1}{\sqrt{2}}i + \frac{1}{\sqrt{2}}j$$

$$m_2 = k$$

$$m_3 = \frac{1}{\sqrt{2}}i - \frac{1}{\sqrt{2}}j$$



## Stress tensor:

- **flat triangular**

$$\sigma_1 > \sigma_2 > \sigma_3$$

- **flat cylindrical**

$$\sigma_1 = \sigma_2 \neq \sigma_3$$

- **flat sphere**

$$\sigma_1 = \sigma_2 = \sigma_3$$

Aribel d. Mohr

$$\sigma_n = \underline{\sigma} \cdot \underline{t}_n \\ = \underline{\sigma} \cdot \underline{l} \underline{n}$$

tecnica  
normale

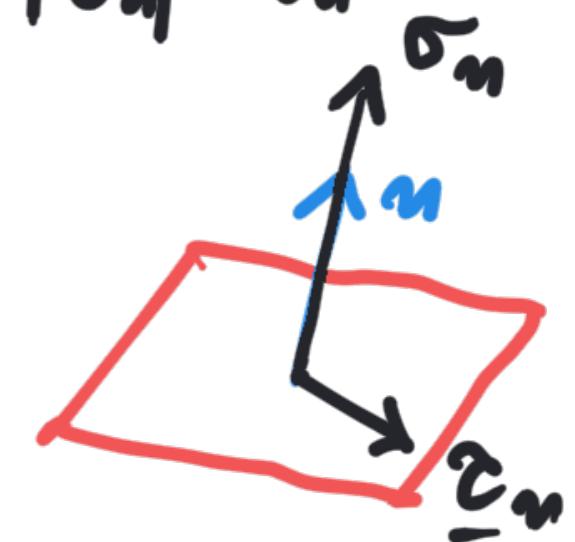
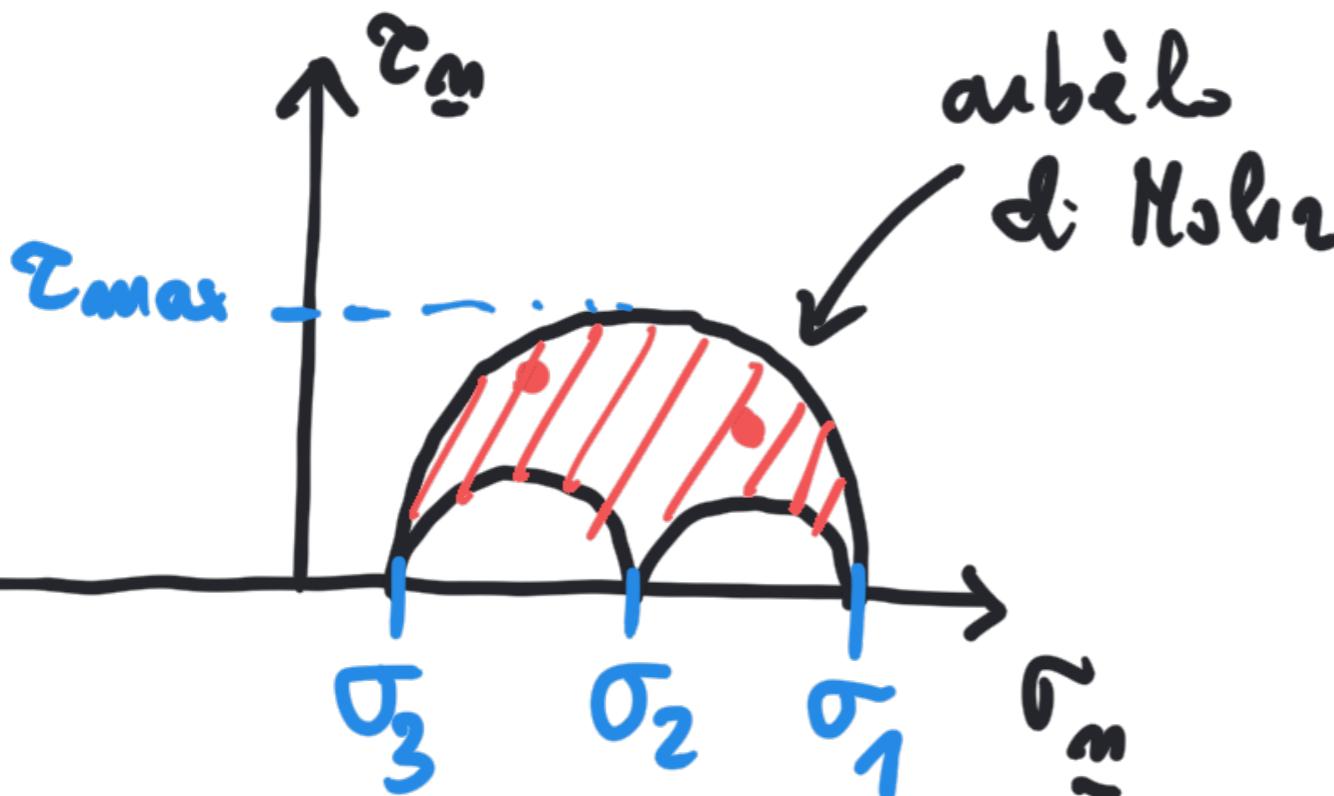
Problema: massimo

tecnica tang.

$$0 \leq \tau_n = |\underline{\tau}_n|$$

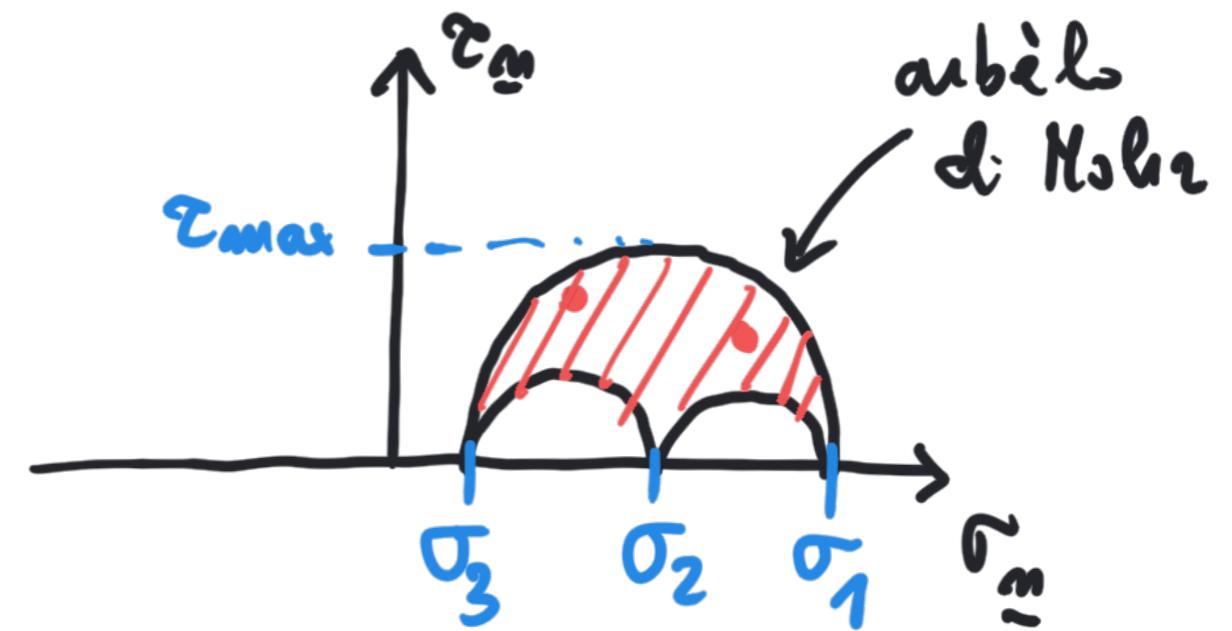
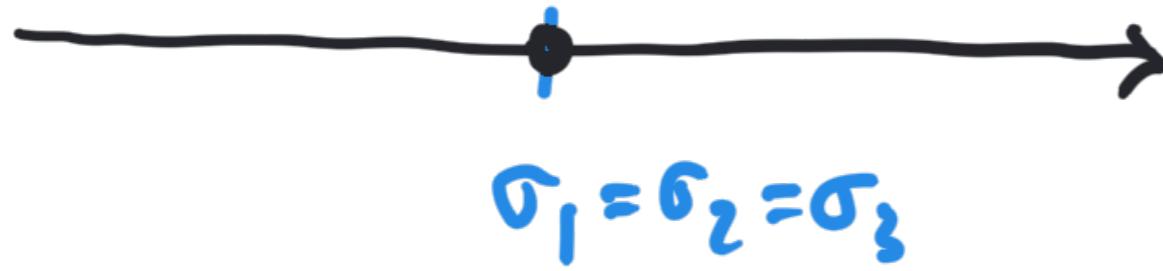
intensità  
tecnica  
tang.

$$= \sqrt{|\underline{t}_n|^2 - \sigma_n^2}$$



$$\tau_{max} = \frac{1}{2} |\sigma_1 - \sigma_3|$$

# Stato sfenico



# Stato cilindrico

