

# 電子電路實驗 3,4: CMOS Operational Amplifier

## 實驗預報

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## 1 Objectives

1. To make sure all the MOS of the circuit are able to enter saturation region so that the circuit can be applied to be an operational amplifier.
2. To comprehend the method of eliminating the Crossover Distortion of a class-B output stage.

## 2 Procedures

### 2.1 DC Analysis

#### 2.1.1 DC Analysis of CD4007

1. The condition of entering saturation region of NMOS:  $V_{GD} \leq V_T(1.8\text{ V})$ .
2. The condition of entering saturation region of PMOS:  $V_{GD} \geq V_T(-1.8\text{ V})$ .
3. Supply voltage  $-V_{SS} = -8\text{ V}$  and  $V_{DD} = +8\text{ V}$  to the circuit.
4. Provide voltage source  $V_{CC} = +15\text{ V}$ , and  $-V_{CC} = -15\text{ V}$  to the circuit.
5. Use digital multi-meter to confirm whether all of the MOS components are able to enter saturation region as adjusting VR  $1\text{ k}\Omega$ .

#### 2.1.2 Detail procedure of DC Analysis of the Two-stage OP-Amp circuit

1. adjust VR  $R_2 = 10\text{ k}\Omega$  and check whether  $(Q_5, Q_7, Q_8)$  are all able to enter saturation region, that is,  $V_{GD5,7,8} \geq V_T(-1.8\text{ V})$ . If one of them is not so, change the chip of CD4007 #A and recheck again.
2. Use multi-meter to measure  $V_{GD5}, V_{GD7}, V_{GD8}$ .

3. adjust VR  $R_2 = 10\text{ k}\Omega$  and check whether  $(Q_1, Q_2)$  are all able to enter saturation region, that is,  $V_{GD1,2} \geq V_T$  ( $-1.8\text{V}$ ). If one of them is not so, change the chip of CD4007 #B and recheck again.
4. Use multi-meter to measure  $V_{GD1}, V_{GD2}$ .
5. In Fig.5, Use heck whether  $(Q_3, Q_4)$  are all able to enter saturation region, that is,  $V_{GD3,4} \geq V_T$  ( $-1.8\text{V}$ ). If one of them is not so, change the chip of CD4007 #C and recheck again.
6. Use multi-meter to measure  $V_{GD3}, V_{GD4}$ .

### 2.1.3 DC Analysis of the Two-stage OP-Amp circuit

1. In Fig. 6, adjust VR ( $R_3$ )  $1\text{ k}\Omega$  and use multi-meter to measure  $V_A$  and  $V_E$  , and check whether  $V_E$  is adjustable. If it not so , trouble shoot the circuit. Check whether there is any wrong layout in your breadboard and whether the VR ( $R_3$ ) is functional by multimeter.
2. Record  $V_A, V_E$ .

### 2.1.4 Circuit implementation

1. In Fig. 2, adjust VR ( $R_3$ )  $1\text{ k}\Omega$  and use multi-meter to measure  $V_A, V_D, V_E, V_F$

## 2.2 Small-signal Analysis

### 2.2.1 Voltage Gain

1. Adjust VR ( $R_3$ ) in Fig. 3 to have  $V_F \approx 0$ .
2. In Fig 4, apply the input small signal  $V_i$  to the breadboard by using function generator to generate  $v_i = v_{ac} \sin(2\pi ft), 2v_{ac} = 20mV_{p-p}, f = 1\text{ kHz}$ .
3. Make sure that the  $v_i$  is measured from the breadboard by using the probe from CH1 in oscilloscope.
4. Oscilloscope  $\triangleright$ YT mode.
5. Adjust VR ( $R_3$ )  $1\text{ k}\Omega$  in Fig. 2-2 to have maximum small-signal voltage gain  $V_F/V_i$  .
6. Keep the previous adjustment of  $R_3$  constantly.
7. Record the voltage gain  $A_M$ .
8. Record the  $V_F, R_3$ .
9. Confirm whether the voltage gain is the same as the slope of teh curve at transition region measured in the step 6 at Exp 3.
10. Increase/Decrease  $V_i$  until the waveform of  $V_F$  just distort.
11. Record the peak-to-peak value of  $V_i$ .

### 2.2.2 Frequency Response

1. Set  $v_i = v_{ac} \sin(2\pi ft)$ ,  $2v_{ac} = 20 \text{ mV}_{p-p}$ ,  $f = 1 \text{ kHz}$ .
2. Function generator  $\triangleright$  Adjust Frequency and observe the voltage gain  $A_v$  in oscilloscope until  $A_v = \sqrt{2}A_M$ .
3. Record the frequency  $f_{3db}$ .
4. Change the frequency of input voltage source, and record the input and output voltage shown in oscilloscope.

### 2.2.3 Internal frequency compensation

1. Use  $R_2 = 100 \text{ k}\Omega$ ,  $C_2 = 10 \text{ pF}$  in to implement the compensation circuit in Fig. 5.
2. Record the voltage gain  $A_{M,2}$ , dynamic range  $V_i$ , and frequency  $f_{3dM,2}$ .

### 2.2.4 Feedback network compensation

1. Use  $R_2 = 100 \text{ k}\Omega$ ,  $C_2 = 10 \text{ pF}$  in to implement the compensation circuit in Fig. 3.
2. In Fig. 6, apply the input small signal  $V_i$  to the breadboard by using function generator to generate  $v_i = v_{ac} \sin(2\pi f_t)$ ,  $2v_{ac} = 100 \text{ mV}_{p-p}$ ,  $f = 1 \text{ kHz}$ .
3. Record the voltage gain  $A_{M,2}$ , dynamic range  $V_i$ , and frequency  $f_{3dM,2}$ .