## Probabilistic and Statistical Modeling

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## Helping Material

#### Primer on Probabilistic Modeling

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https://www.inf.ed.ac.uk/teaching/courses/pmr/22-23/assets/notes/probabilistic-modelling-primer.pdf
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## Session 1 – Recap

#### What we covered:

- ▶ **Probabilistic Modeling:** Model the world using probabilities
- Probabilistic Reasoning (Inference): Use knowns to infer unknowns
- ▶ Bayesian Analysis: Modeling and Reasoning with Bayes' rule.
- ▶ Core Rules of Probability: The sum, product and Bayes' rule.
- Example: Alzheimer's diagnostic test.

#### • What's still to explore:

- Our example was simple
  - ★ X: the test result a 1D random variable in  $\{0,1\}$
  - ★ Y: the disease status a 1D random variable in  $\{0,1\}$
- Real-world problems are more complex
  - ★ Involve high-dimensional random variables
  - ★ Involve complex relationships between variables
- ▶ How can we model these complexities?
  - Session 2 extended our probabilistic toolbox.
  - ★ Session 3 will show how to use it in practice.



## Session 2 – Recap

#### • What we covered:

- Multivariate Random Variables and Distributions:
  - ⋆ PDFs, PMFs and CDFs
  - ★ Key properties: expectation and variance.
  - ★ How to sample from these distributions.
  - Key-distributions: Bernoulli, Normal, Poisson.
- We now have powerful tools to model complexity!

#### • What's still to explore:

- ▶ A glue to connect our probabilistic tools for performing analysis.
- A principled and unified way to:
  - ★ Model complex relationships between variables
  - ★ Infer unknowns from knowns
  - ★ Make predictions about future observations
- ► The Bayesian framework is (among others) a powerful glue for this.

### Session 3 – Overview

### • What we'll explore:

- ▶ The Bayesian Framework with each key components:
  - ★ Prior Distribution: Our belief before seeing the data.
  - Likelihood: How compatible is the observed data is with different parameter values.
  - \* Posterior Distribution: Our updated beliefs after observing the data.
  - \* Predictive Distribution: Make predictions about new, unseen data.
- How to use the Bayesian framework for predictive tasks.

### Be confident. You already know important stuff:

- Session 1:
  - $\star$  Intuition about Bayesian modeling  $\to$  Alzheimer's test case
  - ★ Core probability rules: sum, product, and Bayes' rule
- Session 2:
  - ★ Multivariate random variables and distributions
  - \* Key properties: expectation and variance
  - ★ How to sample from these distributions



### Models

- The term "model" has multiple meanings, see e.g. https://en.wikipedia.org/wiki/Model
- Let's distinguish between three types of models:
  - probabilistic model
  - (parametric) statistical model
  - Bayesian model
- Note: the three types are often confounded, and often just called probabilistic or statistical model, or just "model".
- Introduction to Probabilistic Modelling → for further reading.

### Probabilistic model

• From first lecture:

A probabilistic model is an abstraction of reality that uses probability theory to quantify the chance of uncertain events.

- Example from the first lecture: cognitive impairment test
  - Sensitivity of 0.8 and specificity of 0.95 (Scharre, 2010)
  - Probabilistic model for presence of impairment (x = 1) and detection by the test (y = 1):
    - \* P(x = 1) = 0.11 (prior)
    - ★ P(y = 1 | x = 1) = 0.8 (sensitivity)
    - ★  $P(y = 0 \mid x = 0) = 0.95$  (specificity)

### Probabilistic model

- More technically: probabilistic model ≡ probability distribution (pmf/pdf).
- Probabilistic model was written in terms of the probability P.
- In terms of the pmf it is:
  - $p_{x}(1) = 0.11$
  - $p_{v|x}(1 \mid 1) = 0.8$
  - $p_{y|x}(0 \mid 0) = 0.95$
- Commonly written as:
  - p(x=1)=0.11
  - $p(y = 1 \mid x = 1) = 0.8$
  - $p(y=0 \mid x=0) = 0.95$
- where the notation for probability measure P and pmf p are confounded.



### Statistical model

- If we substitute the numbers with parameters, we obtain a (parametric) statistical model:
  - ▶  $p(x = 1) = \theta_1$
  - $p(y = 1 | x = 1) = \theta_2$
  - $p(y = 0 \mid x = 0) = \theta_3$
- For each value of the  $\theta_i$ , we obtain a different pmf.
- Dependency highlighted by writing:
  - $p(x=1;\theta_1)=\theta_1$
  - $p(y = 1 \mid x = 1; \theta_2) = \theta_2$
  - $p(y = 0 \mid x = 0; \theta_3) = \theta_3$
- $p(x, y; \theta)$  where  $\theta = (\theta_1, \theta_2, \theta_3)$  is a vector of parameters.
- or  $p(x, y \mid \theta)$ , for highlighting that  $\theta$  is considered a random variable.
- A statistical model corresponds to a set of probabilistic models, here indexed by the parameters  $\theta$ :  $\{p(x;\theta)\}_{\theta}$



# What is Bayesian modeling?

A Bayesian model turns a statistical model into a probabilistic one by treating parameters  $\theta$  as random variables.

**Goal:** Learn what we believe about  $\theta$  after seeing data — and use that to make predictions.

- A Bayesian model is a probabilistic model  $p(x, y, \theta)$
- In supervised settings, we consider x as observed, so we care about  $p(y, \theta \mid x)$ .

# Bayesian Modeling in Steps

### We don't know the full joint distribution $p(x, y, \theta)$ .

• If we did, every analysis would be trivial.

#### What we do have:

• Observed data  $\mathcal{D} = \{(x^{(i)}, y^{(i)})\}_{i=1}^N$  — i.i.d. samples from p(x, y)

#### What we assume:

- $p(y \mid x, \theta)$  how data is generated given a specific parameter  $\theta$
- ullet p( heta) our beliefs about the parameters before seeing data

#### What we want to learn:

- ullet  $p( heta \mid \mathcal{D})$  what we believe about the parameters after seeing data
- The predictive distribution  $p(y \mid x, \mathcal{D})$  predictions that account for parameter uncertainty
- ullet Possibly others: e.g. marginal likelihood  $p(\mathcal{D})$

# Bayesian Modeling for Supervised Tasks

- **Supervised learning:** We observe a dataset of input–output pairs  $\mathcal{D} = \{(x^{(i)}, y^{(i)})\}_{i=1}^N$  drawn from an unknown joint distribution p(x, y).
- Bayesian perspective: Use this data to learn the relationship  $x \mapsto y$  while capturing uncertainty in the model parameters.
- Hypothesis:
  - ▶ (1): assume a parametric family for  $p(y \mid x, \theta)$ , such as linear regression, neural networks, etc. (Parametric modeling assumption)
  - ightharpoonup (2): assume a prior belief over the parameters  $p(\theta)$  (prior assumption)

## Example: Linear Regression

- Hypothesis: The outcome depends linearly on some input plus noise.
- Example: Predict house price from size.
  - ➤ Y house price
  - ▶ *X* house size
  - ▶ Model:  $Y = wX + b + \epsilon$ , with  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
- $p(Y \mid X; \theta) = \mathcal{N}(Y \mid wX + b, \sigma^2)$
- Parameters:  $\theta = (w, b) 2$  variables.

## Example: Linear Regression

- Hypothesis: The outcome depends linearly on some input plus noise.
- Generalizes to any number of input features
- Example: Predict house price from size, number of rooms, and
  - ▶ *Y* house price
  - ▶  $X = (X_1, X_2, ..., X_d)$  house features (size, number of rooms, etc.)
  - ▶ Model:  $Y = wX + b + \epsilon$ , with  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
- $p(Y \mid X; \theta) = \mathcal{N}(Y \mid wX + b, \sigma^2)$
- Parameters:  $\theta = (w, b)$ : d + 1 variables.

## Example: Non-linear Regression

- Hypothesis: The relationship between input and output is complex and nonlinear plus noise.
- Example: Predict bike rentals from weather data.
  - Y number of bikes rented per hour
  - ▶ *X* weather features (temperature, humidity, etc.)
  - ▶ Model  $Y = f_{\theta}(X) + \epsilon$ , with  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
  - $f_{\theta}(X)$  is a non-linear function parameterized by  $\theta$ .
- $p(Y \mid X; \theta) = \mathcal{N}(Y \mid f_{\theta}(X), \sigma^2)$
- what is  $f_{\theta}(X)$ ?
  - lacktriangle A neural network with weights heta, normally of thousands of variables.
  - A random forest with decision trees where the structure and parameters are defined by  $\theta$ , normally of hundreds of variables.



## The Flexibility—and Cost—of the Bayesian Framework

- Bayesian framework is flexible: We can assume any model for  $p(y \mid x, \theta)$ .
  - ▶ Example:  $y = f_{\theta}(x) + \epsilon$ , where  $\epsilon \sim \mathcal{N}(0, \sigma^2)$  and  $f_{\theta}(x)$  can be a neural network, random forest, etc.
  - ▶ The output *y* can follow any distribution not just Normal: skewed, heavy-tailed, discrete (e.g., Poisson, Bernoulli), etc.
- But flexibility comes at a cost
  - the more complex  $p(y \mid x, \theta)$ :
    - **★** Complex  $\rightarrow$  a high-dimensional  $\theta$ .
    - **★** Complex  $\rightarrow$  a complex  $f_{\theta}(x)$
  - the harder it is to perform inference.