

# Paper presentation at ACML 2022

DALE: Differential Accumulated Local Effects for efficient and accurate global explanations

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# eXplainable AI (XAI)

- Black-box model  $f(\cdot) : \mathcal{X} \rightarrow \mathcal{Y}$ , trained on  $\mathcal{D}$
- XAI extracts interpretable properties:
  - Tabular data - Which features favor a prediction?
  - Computer Vision - Which image areas confuse the model?
  - NLP - Which words classified the comment as offensive?
- Categories:
  - Global vs local
  - Model-agnostic vs Model-specific
  - Output? number, plot, instance etc.

Feature Effect: global, model-agnostic, outputs plot

# Feature Effect

$y = f(x_s) \rightarrow$  plot showing the effect of  $x_s$  on the output  $y$

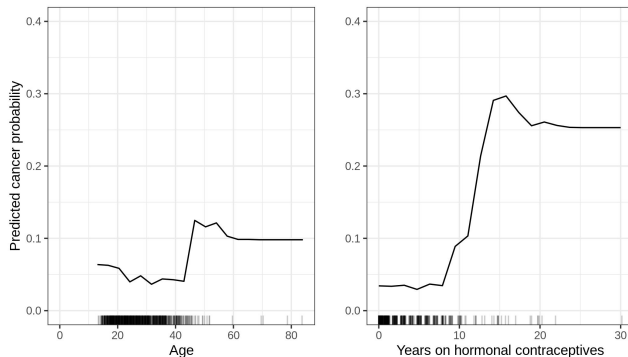


Figure: Image taken from Interpretable ML book (Molnar, 2022)

Feature Effect is simple and intuitive.

# Feature Effect Methods

- $x_s \rightarrow$  feature of interest,  $\mathbf{x}_c \rightarrow$  other features
- How to isolate  $x_s$ ??
- Difficult task:
  - ▶ features are correlated
  - ▶  $f$  has learned complex interactions

# Feature Effect Methods

- PDP (Friedman, 2001)
  - ▶  $f(x_s) = \mathbb{E}_{\mathbf{x}_c}[f(x_s, \mathbf{x}_c)]$
  - ▶ **Unrealistic instances**
  - ▶ e.g.  $f(x_{\text{age}} = 20, x_{\text{years\_contraceptives}} = 20) = ??$

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PDP vs MPlot vs ALE

# Feature Effect Methods

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  - ▶ **Unrealistic instances**
  - ▶ e.g.  $f(x_{\text{age}} = 20, x_{\text{years\_contraceptives}} = 20) = ??$
- MPlot (Apley and Zhu, 2020)
  - ▶  $\mathbf{x}_c | x_s: f(x_s) = \mathbb{E}_{\mathbf{x}_c | x_s}[f(x_s, \mathbf{x}_c)]$
  - ▶ **Aggregated effects**
  - ▶ Real effect:  $x_{\text{age}} = 20 \rightarrow 10, x_{\text{years\_contraceptives}} = 20 \rightarrow 10$
  - ▶ MPlot may assign 17 to both

PDP vs MPlot vs ALE

# Feature Effect Methods

- PDP (Friedman, 2001)
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  - ▶ **Aggregated effects**
  - ▶ Real effect:  $x_{\text{age}} = 20 \rightarrow 10, x_{\text{years\_contraceptives}} = 20 \rightarrow 10$
  - ▶ MPlot may assign 17 to both
- ALE(Apley and Zhu, 2020)
  - ▶  $f(x_s) = \int_{x_{\min}}^{x_s} \mathbb{E}_{\mathbf{x}_c|z}[\frac{\partial f}{\partial x_s}(z, \mathbf{x}_c)] \partial z$
  - ▶ **Resolves both failure modes**

PDP vs MPlot vs ALE

# ALE approximation

ALE definition:  $f(x_s) = \int_{x_{s,min}}^{x_s} \mathbb{E}_{\mathbf{x}_c|z} \left[ \frac{\partial f}{\partial x_s}(z, \mathbf{x}_c) \right] \partial z$

ALE approximation:  $f(x_s) = \underbrace{\sum_k^{k_x} \frac{1}{|S_k|} \sum_{i: \mathbf{x}^i \in S_k} \underbrace{[f(z_k, \mathbf{x}_c^i) - f(z_{k-1}, \mathbf{x}_c^i)]}_{\text{point effect}}}_{\text{bin effect}}$

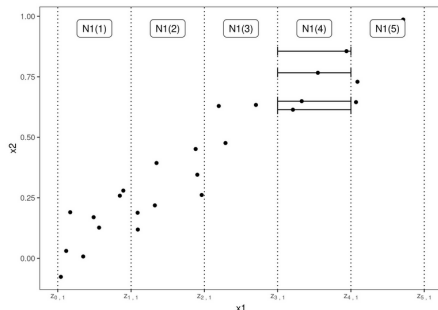


Figure: Image taken from Interpretable ML book (Molnar, 2022)



# ALE approximation

ALE approximation from  $\mathcal{D} = \{\mathbf{x}^i, y^i\}_{i=1}^N$

$$f(x_s) = \underbrace{\sum_k \frac{1}{|S_k|} \sum_{i: \mathbf{x}^i \in S_k} \underbrace{[f(z_k, \mathbf{x}_c^i) - f(z_{k-1}, \mathbf{x}_c^i)]}_{\text{point effect}}}_{\text{bin effect}}$$

- 2 evaluations of  $f$  per point  $\rightarrow$  slow
- change bin limits, pay again  $2 * N$  evaluations of  $f \rightarrow$  restrictive
- broad bins may create out of distribution (OOD) samples  $\rightarrow$  not-robust in wide bins

ALE approximation has some weaknesses

# DALE - Differential ALE

DALE, from the dataset  $\mathcal{D} = \{\mathbf{x}^i, y^i\}_{i=1}^N$

$$f(x_s) = \Delta x \underbrace{\sum_k \frac{1}{|\mathcal{S}_k|} \sum_{i: \mathbf{x}^i \in \mathcal{S}_k} \underbrace{\left[ \frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}}_{\text{bin effect}}$$

- only change point effect computation
- Fast  $\rightarrow$  use of auto-differentiation, all derivatives in a single pass
- Versatile  $\rightarrow$  point effects computed once, change bins without cost
- Secure  $\rightarrow$  does not create artificial instances

For **differentiable** models, DALE resolves ALE weaknesses

# DALE is faster and versatile - theory

$$f(x_s) = \underbrace{\Delta x \sum_k \frac{1}{|\mathcal{S}_k|} \sum_{i: \mathbf{x}^i \in \mathcal{S}_k}}_{\text{bin effect}} \underbrace{\left[ \frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}$$

- Faster
  - ▶ gradients wrt all features  $\nabla_{\mathbf{x}} f(\mathbf{x}^i)$  in a single pass
  - ▶ auto-differentiation must be available (deep learning)
- Versatile
  - ▶ Change bin limits, with near zero computational cost

DALE is faster and allows redefining bin-limits

# DALE is faster and versatile - Experiments

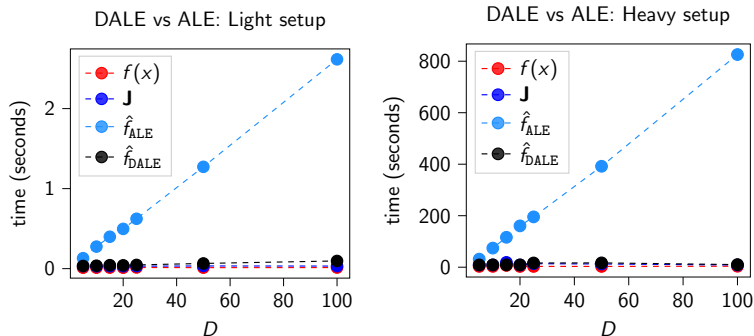


Figure: Light setup; small dataset ( $N = 10^2$  instances), light  $f$ . Heavy setup; big dataset ( $N = 10^5$  instances), heavy  $f$

DALE considerably accelerates the estimation

# DALE uses on-distribution samples - Theory

$$f(x_s) = \underbrace{\sum_k \frac{1}{|\mathcal{S}_k|} \sum_{i: \mathbf{x}^i \in \mathcal{S}_k} \underbrace{\left[ \frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i) \right]}_{\text{point effect}}}_{\text{bin effect}}$$

- point effect **independent** of bin limits
  - ▶  $\frac{\partial f}{\partial x_s}(\mathbf{x}_s^i, \mathbf{x}_c^i)$  computed on real instances  $\mathbf{x}^i = (\mathbf{x}_s^i, \mathbf{x}_c^i)$
- bin limits affect only the **resolution** of the plot
  - ▶ wide bins  $\rightarrow$  low resolution plot, bin estimation from more points
  - ▶ narrow bins  $\rightarrow$  high resolution plot, bin estimation from less points

DALE enables wide bins without creating out of distribution instances

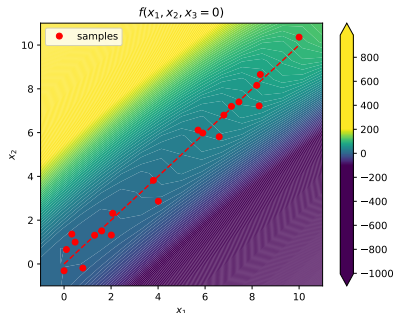
# DALE uses on-distribution samples - Experiments

$$f(x_1, x_2, x_3) = x_1 x_2 + x_1 x_3 \pm g(x)$$

$$x_1 \in [0, 10], x_2 \sim x_1 + \epsilon, x_3 \sim \mathcal{N}(0, \sigma^2)$$

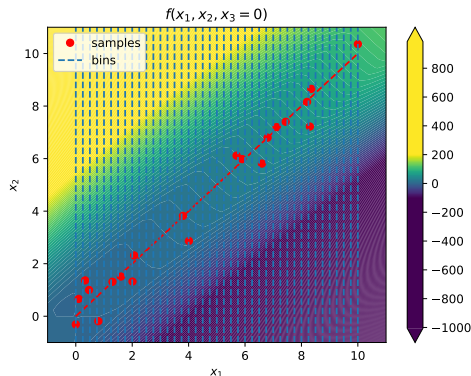
$$f_{\text{ALE}}(x_1) = \frac{x_1^2}{2}$$

- point effects affected by  $(x_1 x_3)$   
( $\sigma$  is large)
- bin estimation is noisy (samples are few)



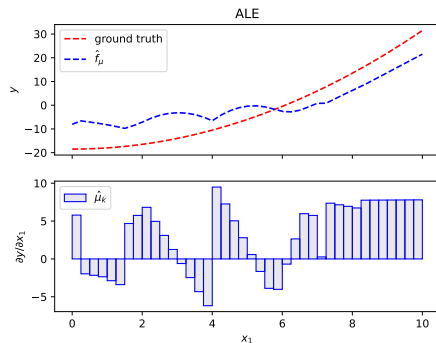
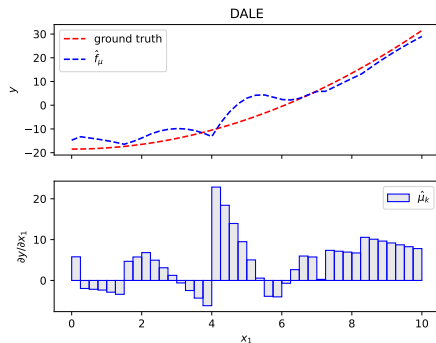
Intuition: we need wider bins (more samples per bin)

# DALE vs ALE - 40 Bins



- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: on-distribution, noisy bin effect → poor estimation

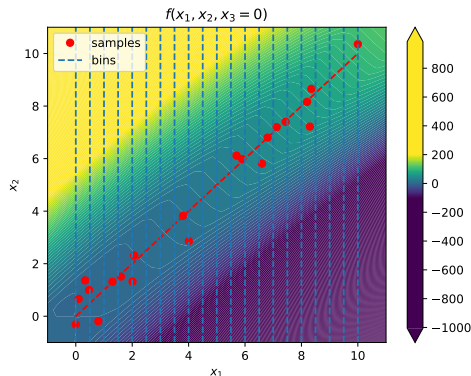
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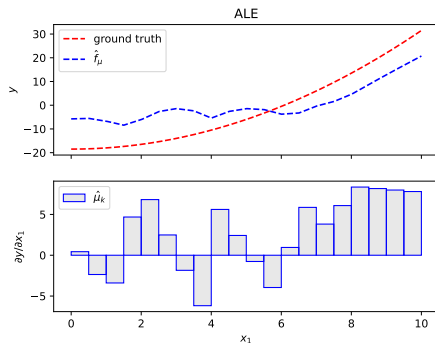
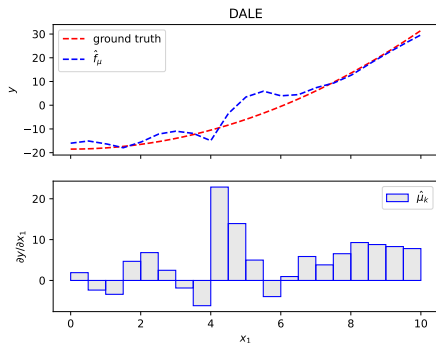


# DALE vs ALE - 20 Bins



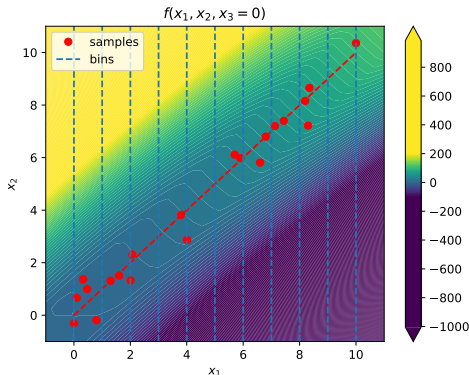
- DALE: on-distribution, noisy bin effect → poor estimation
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# DALE vs ALE - 20 Bins



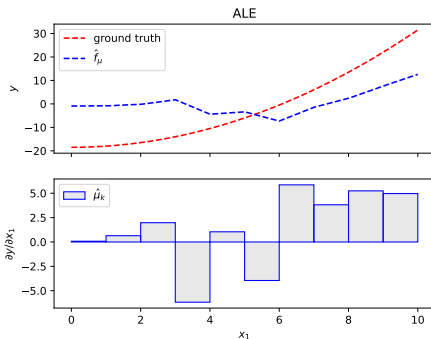
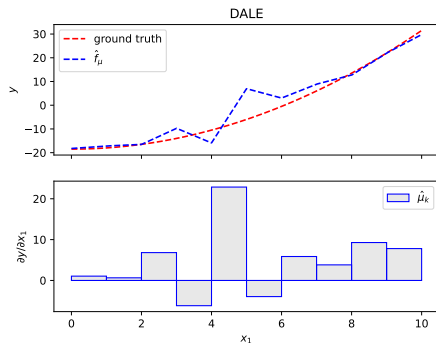
- DALE: on-distribution, noisy bin effect → poor estimation
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# DALE vs ALE - 10 Bins



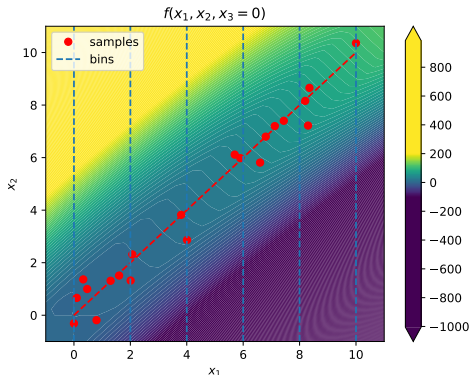
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: starts being OOD, noisy bin effect → poor estimation

# DALE vs ALE - 10 Bins



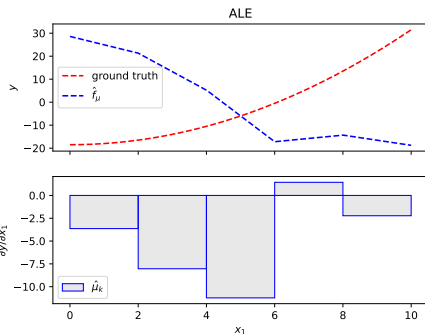
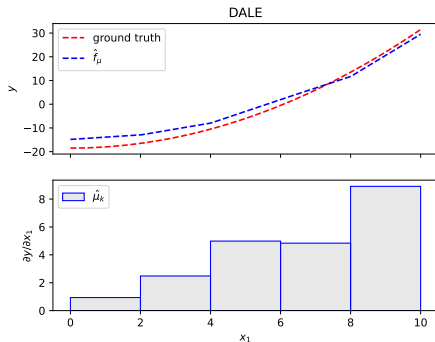
- DALE: on-distribution, noisy bin effect → poor estimation
- ALE: starts being OOD, noisy bin effect → poor estimation

# DALE vs ALE - 5 Bins



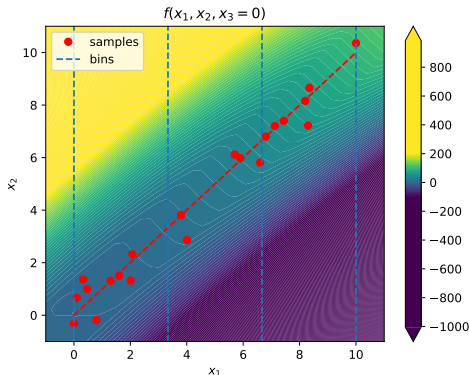
- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

# DALE vs ALE - 5 Bins



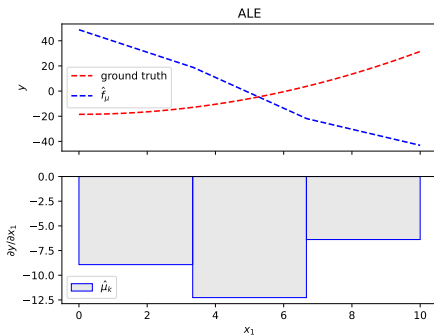
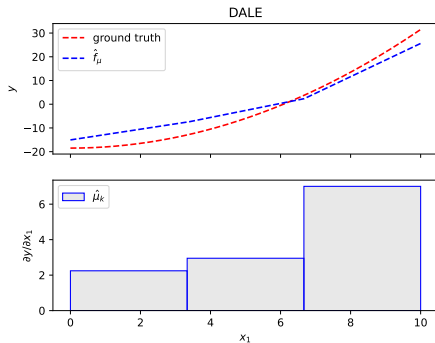
- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

# DALE vs ALE - 3 Bins



- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation

# DALE vs ALE - 3 Bins



- DALE: on-distribution, robust bin effect → good estimation
- ALE: completely OOD, robust bin effect → poor estimation



# Real Dataset Experiments - Efficiency

- Bike-sharing dataset(Fanaee-T and Gama, 2013)
- $y \rightarrow$  daily bike rentals
- $x$  : 10 features, most of them characteristics of the weather

Efficiency on Bike-Sharing Dataset (Execution Times in seconds)

|      | Number of Features |      |      |      |      |      |      |      |      |      |      |
|------|--------------------|------|------|------|------|------|------|------|------|------|------|
|      | 1                  | 2    | 3    | 4    | 5    | 6    | 7    | 8    | 9    | 10   | 11   |
| DALE | 1.17               | 1.19 | 1.22 | 1.24 | 1.27 | 1.30 | 1.36 | 1.32 | 1.33 | 1.37 | 1.39 |
| ALE  | 0.85               | 1.78 | 2.69 | 3.66 | 4.64 | 5.64 | 6.85 | 7.73 | 8.86 | 9.9  | 10.9 |

DALE requires almost same time for all features

# Real Dataset Experiments - Accuracy

- Difficult to compare in real world datasets
- We do not know the ground-truth effect
- In most features, DALE and ALE agree.
- Only  $X_{\text{hour}}$  is an interesting feature

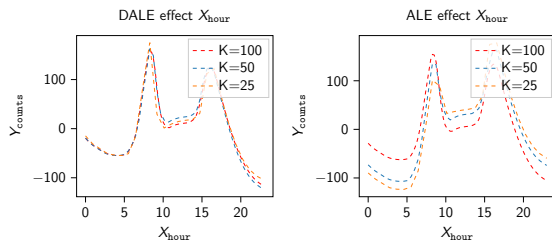


Figure: (Left) DALE (Left) and ALE (Right) plots for  $K = \{25, 50, 100\}$

# What next?





- How to (automatically) decide the optimal bin sizes?
  - ▶ Sometimes narrow bins are ok
  - ▶ Sometimes wide bins are needed
- Can we DALE are fast to decide optimal bin splitting?
- What about variable size bins?
- Model the uncertainty of the estimation?

DALE advantages can be a driver for future work

# Thank you

- Questions?

# References I

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