1 Notation List

We set the following notation rules:We refer to random variables (r.v.) using uppercase and calligraphic font $\mathcal{X}$, whereas to simple variables with plain lowercase x. Bold $\mathbf{x}$ denotes a vector variable, $\mathcal{X}_s$ the r.v. of the feature of interest and $\mathcal{X}_c$ the rest of the features so that $\mathcal{X} = (\mathcal{X}_s, \mathcal{X}_c)$ represents the input space. The black-box function is notated as f and the feature effect of the s-th feature as $f_{<\texttt{method}>}(x_s)$, where $< \texttt{method} >$ is the name of the feature effect method. The extensive list of symbols used in the paper is:

- s, index of the feature of interest
- $\mathcal{X}_s$, feature of interest as a r.v.
- $\mathcal{X}_c = (\mathcal{X}_{/s},)$, the rest of the features in as a r.v.
- $\mathcal{X} = (\mathcal{X}_s, \mathcal{X}_c)$, all input features as r.v.
- x_s, feature of interest
- $\mathbf{x}_c$, the rest of the features
- $\mathbf{x} = (x_s, \mathbf{x}_c)$, all the input features
- $\mathbf{X}$, training set
- $f(\cdot) : \mathbb{R}^D \rightarrow \mathbb{R}$, black box function
- D, dimensionality of the input
- N, number of training examples
- $\mathbf{x}^i$, i-th training example
- x_s^i, s-th feature of the i-th training example
- $\mathbf{x}_\mathbf{c}^i$, the rest of the features of the i-th training example
- $f_{\texttt{ALE}}^s(x) : \mathbb{R} \rightarrow \mathbb{R}$, feature effect computed by ALE for the s-th feature s
- $f_{\texttt{DALE}}^s(x) : \mathbb{R} \rightarrow \mathbb{R}$, feature effect computed by DALE for the s-th feature s
- $\hat{f}_{\texttt{ALE}}^s(x) : \mathbb{R} \rightarrow \mathbb{R}$, unnormalized feature effect computed by ALE for the s-th feature s
- $f_s(\mathbf{x}) = \frac{\partial f(x_s, \mathbf{x}_c)}{\partial x_s}$, the partial derivative of the s-th feature
- z_{k-1}, the left limit of the k-th bin
- z_k, the right limit of the k-th bin
- $\mathcal{S}_k = \{\mathbf{x}^i : x_s^i \in [z_{k-1}, z_k)\}$, the set of training points that belong to the k-th bin
- k_x the index of the bin that x belongs to
- $\hat{\mu}_k^s$, $\texttt{DALE}$ approximation of the mean value inside a bin, equals $\frac{1}{|\mathcal{S}_k|} \sum_{i:x^i \in \mathcal{S}_k} f_s(\mathbf{x}^i)$
- $(\hat{\sigma}_k^s)^2$, $\texttt{DALE}$ approximation of the variance inside a bin, equals $\frac{1}{|\mathcal{S}_k|-1} \sum_{i:x^i \in \mathcal{S}_k} (f_s(\mathbf{x}^i) - \hat{\mu}_k^s)^2$

2 Derivation of equations in the Background section

In this section, we present the derivations for obtaining the feature effect at the Background.

Example Definition. The black-box function and the generating distribution are:

$$f(x_1, x_2) = \begin{cases} 1 - x_1 - x_2 & , \text{if } x_1 + x_2 \leq 1 \\ 0 & , \text{otherwise} \end{cases} \tag{1}$$

$$p(\mathcal{X}_1 = x_1, \mathcal{X}_2 = x_2) = \begin{cases} 1 & x_1 \in [0, 1], x_2 = x_1 \\ 0 & \text{otherwise} \end{cases} \tag{2}$$

$$p(\mathcal{X}_1 = x_1) = \begin{cases} 1 & 0 \leq x_1 \leq 1 \\ 0 & \text{otherwise} \end{cases} \tag{3}$$

$$p(\mathcal{X}_2 = x_2) = \begin{cases} 1 & 0 \leq x_2 \leq 1 \\ 0 & \text{otherwise} \end{cases} \tag{4}$$

$$p(\mathcal{X}_2 = x_2 | \mathcal{X}_1 = x_1) = \delta(x_2 - x_1) \tag{5}$$

PDPlots. The feature effect computed by PDP plots is:

$$\begin{aligned} f_{\mathtt{PDP}}(x_1) = & \\ & = \mathbb{E}_{\mathcal{X}_2}[f(x_1, \mathcal{X}_2)] \\ & = \int_{x_2} f(x_1, x_2) p(x_2) \partial x_2 \\ & = \int_0^{1-x_1} (1 - x_1 - x_2) \partial x_2 + \int_{1-x_1}^{1} 0 \partial x_2 \\ & = \int_0^{1-x_1} 1 \partial x_2 + \int_0^{1-x_1} -x_1 \partial x_2 + \int_0^{1-x_1} -x_2 \partial x_2 \\ & = (1 - x_1) - x_1(1 - x_1) - \frac{(1 - x_1)^2}{2} \\ & = (1 - x_1)^2 - \frac{(1 - x_1)^2}{2} \\ & = \frac{(1 - x_1)^2}{2} \end{aligned} \tag{6}$$

Due to symmetry:

$$y = f_{\mathtt{PDP}}(x_2) = \frac{(1 - x_2)^2}{2} \tag{7}$$

MPlots. The feature effect computed by PDP plots is:

$$\begin{aligned} f_{\texttt{MP}}(x_1) = & \\ & = \mathbb{E}_{\mathcal{X}_2|\mathcal{X}_1=x_1}[f(x_1, \mathcal{X}_2)] \\ & = \int_{x_2} f(x_1, x_2) p(x_2|x_1) \partial x_2 \\ & = f(x_1, x_1) = \\ & = \begin{cases} 1 - 2x_1, & x_1 \leq 0.5 \\ 0, & \text{otherwise} \end{cases} \end{aligned} \tag{8}$$

Due to symmetry:

$$y = f_{\texttt{MP}}(x_2) = \begin{cases} 1 - 2x_2 & x_2 \leq 0.5 \\ 0, & \text{otherwise} \end{cases} \tag{9}$$

ALE The feature effect computed by ALE is:

$$\begin{aligned} \hat{f}_{\texttt{ALE}}(x_1) = & \\ & = \int_{z_0}^{x_1} \mathbb{E}_{\mathcal{X}_2|\mathcal{X}_1=z} \left[\frac{\partial f}{\partial z}(z, \mathcal{X}_2) \right] \partial z \\ & = \int_{z_0}^{x_1} \int_{x_2} \frac{\partial f}{\partial z}(z, x_2) p(x_2|z) \partial x_2 \partial z = \\ & = \int_{z_0}^{x_1} \frac{\partial f}{\partial z}(z, z) \partial z = \\ & = \begin{cases} \int_{z_0}^{x_1} -1 \partial z & x_1 \leq 0.5 \\ \int_{z_0}^{0.5} -1 \partial z + \int_{.5}^{x_1} 0 \partial z & x_1 > 0.5 \end{cases} \\ & = \begin{cases} -x_1 & x_1 \leq 0.5 \\ -0.5 & x_1 > 0.5 \end{cases} \end{aligned} \tag{10}$$

The normalization constant is:

$$\begin{aligned} c &= -\mathbb{E}[\hat{f}_{ALE}(x_1)] \\ &= -\int_{-\infty}^{\infty} \hat{f}_{ALE}(x_1) \\ &= -\int_{0}^{0.5} -z \partial z - \int_{0.5}^{1} -0.5 \partial z \\ &= \frac{0.25}{2} + 0.25 = 0.375 \end{aligned} \tag{11}$$

Therefore, the normalized feature effect is:

$$y = f_{ALE}(x_1) = \begin{cases} 0.375 - x_1 & 0 \leq x_1 \leq 0.5 \\ -0.125 & 0.5 < x_1 \leq 1 \end{cases} \tag{12}$$

Due to symmetry:

$$y = f_{ALE}(x_2) = \begin{cases} 0.375 - x_2 & 0 \leq x_2 \leq 0.5 \\ -0.125 & 0.5 < x_2 \leq 1 \end{cases} \tag{13}$$

3 First-order and Second-order DALE approximation

In the main part of the paper, we presented the first order ALE approximation as

$$f^s_{\texttt{DALE}}(x) = \Delta x \sum_{k=1}^{k_x} \frac{1}{|\mathcal{S}_k|} \sum_{i:\mathbf{x}^i \in \mathcal{S}_k} [f_s(\mathbf{x}^i)] \tag{14}$$

For keeping the equation compact, we ommit a small detail about the manipulation of the last bin. In reality, we take complete Δx steps until the $k_x - 1$ bin, i.e. the one that prepends the bin where x lies in. In the last bin, instead of a complete Δx step, we move only until the position x. Therefore, the exact first-order DALE approximation is

$$\begin{aligned} f^s_{\texttt{DALE}}(x) = \Delta x \sum_{k=1}^{k_x-1} \frac{1}{|\mathcal{S}_k|} \sum_{i:\mathbf{x}^i \in \mathcal{S}_k} [f_s(\mathbf{x}^i)] \\ + (x - z_{(k_x-1)}) \frac{1}{|\mathcal{S}_{k_x}|} \sum_{i:\mathbf{x}^i \in \mathcal{S}_{k_x}} [f_s(\mathbf{x}^i)] \end{aligned} \tag{15}$$

Following a similar line of thought we define the complete second-order DALE approximation as

$$\begin{aligned} f^{l,m}_{\texttt{DALE}}(x_l, x_m) = \Delta x_l \sum_{p=1}^{p_x-1} \Delta x_m \sum_{q=1}^{q_x-1} \frac{1}{|\mathcal{S}_{k,q}|} \sum_{i:\mathbf{x}^i \in \mathcal{S}_{k,q}} f_{l,m}(\mathbf{x}^i) \\ + (x_l - z_{(p_x-1)})(x_m - z_{(q_x-1)}) \frac{1}{|\mathcal{S}_{p_x,q_x}|} \sum_{i:\mathbf{x}^i \in \mathcal{S}_{p_x,q_x}} f_{l,m}(\mathbf{x}^i) \end{aligned} \tag{16}$$

4 Second-order ALE definition

The second-order ALE plot definintion is

$$f_{\mathtt{ALE}}^{l,m}(x_l, x_m) = c + \int_{x_{l,min}}^{x_l} \int_{x_{m,min}}^{x_m} \mathbb{E}_{\mathcal{X}_c|X_l=z_l, X_m=z_m}[f_{l,m}(\mathbf{x})] \partial z_l \partial z_m \tag{17}$$

where $f_{l,m}(\mathbf{x}) = \dfrac{\partial^2 f(x)}{\partial x_l \partial x_m}$.

5 DALE variance inside each bin

In this section, we show that the variance of the local effect estimation inside a bin, i.e. $\mathrm{Var}[\hat{\mu}_k^s]$ equals with $\frac{(\sigma_k^s)^2}{|\mathcal{S}_k|}$, where $(\sigma_k^s)^2 = \mathrm{Var}[f_s(\mathbf{x})]$.

$$\begin{aligned} \mathrm{Var}[\hat{\mu}_k^s] &= \mathrm{Var}[\frac{1}{|\mathcal{S}_k|} \sum_{i:x^i \in \mathcal{S}_k} f_s(\mathbf{x}^i)] \\ &= \frac{1}{|\mathcal{S}_k|^2} \sum_{i:x^i \in \mathcal{S}_k} \mathrm{Var}[f_s(\mathbf{x}^i)] \\ &= \frac{|\mathcal{S}_k|}{|\mathcal{S}_k|^2} \mathrm{Var}[f_s(\mathbf{x})] \\ &= \frac{(\sigma_k^s)^2}{|\mathcal{S}_k|} \end{aligned} \tag{18}$$

6 Attributes description in the bike-sharing dataset

In the final experiment, we use 11 features from the bike-sharing dataset. In the following list we quickly explain each one;

- $X_{\mathtt{year}}$: (0 = 2011, 1 = 2012)
- $X_{\mathtt{month}}$: (1=January, ..., 12=December)
- $X_{\mathtt{hour}}$: (0, ..., 23)
- $X_{\mathtt{holiday}}$: (0 = non-holiday, 1 = holiday)
- $X_{\mathtt{weekday}}$: (0 = Sunday, ..., 6 = Saturday)
- $X_{\mathtt{workingday}}$: (0 = non-workingday, 1 = workingday)
- $X_{\mathtt{weather-situation}}$: (1 = best weather situation, ..., 4 = worst weather situation)
- $X_{\mathtt{temp}}$: temperature in Celsius
- $X_{\mathtt{atemp}}$: feeling temperature in Celsius
- $X_{\mathtt{hum}}$: humidity $X_{\mathtt{windspeed}}$: windspeed

The target value we want to predict are the bike rentals counts $Y_{\mathtt{count}}$.