Categories of convex sets

November 9, 2017

1 The categories Conv and GConv

Let **Conv** denote the category whose objects are convex structures satisfying (c1)-(c4), with affine maps as morphisms. This is the Eilenberg-Moore category for the distribution monad.

For $X \in \mathbf{Conv}$, the elements of $\mathbf{Conv}(X, \mathbb{R})$ are called *functionals*. Note that $\mathbf{Conv}(X, \mathbb{R})$ can be given a structure of a vector space, which we denote by A(X), with an ordering defined by the wedge $A(X)^+$ of positive affine maps. Clearly, $A(X)^+$ is an Archimedean cone, but there is no order unit in general.

Example 1.1. Let $X = \mathbb{R}$, with usual affine structure. Any affine map $f : \mathbb{R} \to \mathbb{R}$ has the form f(x) = ax + b for some $a, b \in \mathbb{R}$. It follows that the only elements in $A(X)^+$ are positive constants, none of which can be an order unit.

Let $A_b(X)$ denote the vector subspace of bounded functionals, $A_b(X)^+$ the set of positive bounded functionals and let 1_K denote the constant $1_K(x) \equiv 1$. Then $(A_b(X), A_b(X)^+, 1_X)$ is an order unit Banach space, with order unit norm satisfying

$$||f||_{1_X} = \sup_{x \in X} |f(x)|.$$

Let also $E(X) := \mathbf{Conv}(X, [0, 1])$, then E(X) is the interval between 0 and 1_X in $(A_b(X), A_b(X)^+)$. Functionals in E(X) will be called *effects*.

A convex structure X is called *geometric* if it is isomorphic to a convex subset of a vector space. Any such isomorphism will be called a geometric representation of X. The category **GConv** of geometric convex sets is a full

subcategory of **Conv**. [6, Thm. 1.3] gives an intrinsic characterization of geometric convex sets. Further, by [6, Thm. 1.2], X is geometric iff it is separated by elements of A(X). In this case, the map $\phi: X \to A(X)'$, given by

$$\phi(x)(f) = f(x), \qquad f \in A(X), \ x \in X,$$

is a geometric representation of X. We will identify X with its image $\phi(X)$ in A(X)'. Note that this image lies in the hyperplane $\{\varphi \in A(X)', \ \varphi(1_X) = 1\}$, which does not contain 0. Put $V(X) := \operatorname{span}\{X\} \subseteq A(X)', \ V(X)^+ := \bigcup_{\lambda \geq 0} \lambda X \subseteq (A(X)^+)'$. Let $u_X \in V(X)'$ be given by the restriction of the functional $1_X \in A(X) \subseteq A(X)''$.

Proposition 1.2. (i) $V(X)^+$ is a generating cone in V(X), with base X.

- (ii) $(A(X), A(X)^+) \simeq (V(X)', (V(X)^+)')$, in the category **OVS**.
- (iii) $(A_b(X), A_b(X)^+, 1_X) \simeq (V(X)^*, (V(X)^+)^*, u_X)$, in the category **OUS**, where $V(X)^*$ is the space of functionals bounded with respect to the base seminorm and $(V(X)^+)^* = V(X)^* \cap (V(X)^+)'$, see [5].

Proof. $V(X)^+$ is a generating wedge in V(X) by definition. Let $v \in V(X)^+ \cap -V(X)^+$, so that there are some $a, b \in \mathbb{R}^+$ and $x, y \in X$ such that v = ax = -by. Assume a + b > 0, then by convexity

$$0 = \frac{a}{a+b}x + \frac{b}{a+b}y \in X,$$

which is impossible. Hence a = b = 0 and v = 0. To show that X is a base of $V(K)^+$, it suffices to observe that $X = \{v \in V(X)^+, u_X(v) = 1\}$. This proves (i).

To show (ii), let $\varphi \in V(X)'$, then clearly $\varphi|_X \in A(X)$ and $\varphi \in (V(X)^+)'$ iff $\varphi|_X \in A(X)^+$. Conversely, any $f \in A(X)$ extends to an element $\varphi_f \in V(X)'$, which is unique, since X is generating. To define the extension, put $\varphi_f(0) := 0$ and $\varphi_f(v) := af(x) - bf(y)$ for v = ax - by with $a, b \geq 0$ and $x, y \in X$. To show that this extension is well defined, assume that v = ax - by = cx' - dy' for $a, b, c, d \in \mathbb{R}^+$ and $x, x', y, y' \in X$. Then ax + dy' = cx' + by and applying u_X implies that a + d = c + b. If a + d = 0, then v = 0 and $\varphi_f(v) = 0 = af(x) - bf(y)$. Otherwise, we obtain

$$\frac{a}{a+d}x + \frac{d}{a+d}y' = \frac{c}{c+b}x' + \frac{b}{c+b}y$$

and since f is affine, we get back to af(x) - bf(y) = cf(x') - df(y'). This shows that $\varphi \mapsto \varphi|_X$ defines an order isomorphism of $(V(X)', (V(X)^+)')$ and $(A(X), A(X)^+)$.

(iii) follows directly by [5, Theorem 2 (iii)].

Remark 1.3. Let $\psi: X \to V$ be any geometric representation. Let $\tilde{\psi}: X \to V \oplus \mathbb{R}$ be defined by $\tilde{\psi}(x) = (\phi(x), 1)$, then the image $\tilde{\psi}(X)$ lies in the hyperplane $\{(v, a) \in V \oplus \mathbb{R}, \ u(x, a) := a = 1\}$. In all these constructions, we may replace ϕ with the representation $\tilde{\psi}$ and 1_X by the functional u. It is easy to see that all the resulting structures will be isomorphic.

2 BConv and CConv

A convex structure X is called *bounded* if X is geometric and $co(X \cup -X)$ is linearly bounded in V(X). The full subcategory of bounded convex structures will be denoted by **Bconv**.

Proposition 2.1. Bconv and BN are equivalent categories.

Proof. For $X \in \mathbf{Bconv}$, let $F(X) = (V(X), V(X)^+, X)$ and for an affine map $f: X \to Y$, define $F(f): V(X) \to V(Y)$ as the unique extension of f (existence an uniqueness is proved similarly as in the proof of Prop. 1.2). By [5, Prop. 5], F is a functor $\mathbf{BConv} \to \mathbf{BN}$. Since any $(V, P, K) \in \mathbf{BN}$ is isomorphic to F(K), F is surjective on objects and it is easy to see that it is also full and faithful. Hence F yields an equivalence of the two categories.

We have the following characterizations of objects in **Bconv**.

Proposition 2.2. Let X be a convex structure. Then the following conditions are equivalent.

- (i) X is geometric and the intrinsic semimetric ρ in X is a metric.
- (ii) (c5) holds and if for any $\epsilon \in (0,1]$, there are $p_{\epsilon}, q_{\epsilon} \in X$ with $< \epsilon, p, p_{\epsilon} > = < \epsilon, q, q_{\epsilon} >$, then p = q.
- (iii) X is separated by $A_b(X)$.
- (iv) X is separated by E(X).

(v) X is bounded.

Proof. The equivalence of (i) and (ii) follows essentially by [6, Thms. 1.3 and 2.2], since the second condition in (ii) is equivalent to the condition in [6, Thm. 2.2]. Indeed, assume that (ii) holds and let $\lambda_i \in [0,1]$, $p_i, q_i \in X$ be such that $\lambda_i \to 0$ and $\langle \lambda_i, p, p_i \rangle = \langle \lambda_i, q, q_i \rangle$. Then for any $\epsilon \in [0,1]$ we can find some i such that $\lambda_i \leq \epsilon$. Put $p_{\epsilon} = \langle \lambda_i/\epsilon, p, p_i \rangle, q_{\epsilon} = \langle \lambda_i/\epsilon, q, q_i \rangle$. By conditions (c3) and (c4), we obtain

$$\langle \epsilon, p, p_{\epsilon} \rangle = \langle \lambda_i, p, p_i \rangle = \langle \lambda_i, q, q_i \rangle = \langle \epsilon, q, q_{\epsilon} \rangle,$$

so that p = q. Since the converse is quite obvious, this proves the equivalence (i) \iff (ii). Moreover, the equivalence (i) \iff (v) follows by [6, Thm. 2.5] and [1] ([5, Prop. 5]). Since E(X) contains an order unit, $A_b(X)$ is spanned by E(X), so that (iii) and (iv) are equivalent.

Assume (iv), then by Theorem [6, Thm. 1.2], X is geometric. By Proposition 1.2, any $f \in E(X)$ extends uniquely to a linear functional φ_f on V(X). Let $S = co(X \cup -X)$ and let $v_t := v + tw$ for $v, w \in V(X)$, $w \neq 0$ and $t \in \mathbb{R}$. Note that there must be some $g \in E(X)$ such that $\varphi_g(w) \neq 0$. Indeed, we have w = ax - by for $a, b \in \mathbb{R}^+$ and $x, y \in X$. If $\varphi_f(w) = 0$ for all $f \in E(X)$, then also $a - b = \varphi_{1_X}(w) = 0$, hence a = b and w = a(x - y). From $\varphi_f(w) = a(f(x) - f(y)) = 0$ for all $f \in E(X)$, it follows that either a = 0 or x = y, but in both cases w = 0.

If t is such that $v_t \in S$, then

$$\varphi_g(v_t) = \varphi_g(v) + t\varphi_g(w) \in g(S) = co(g(X) \cup -g(X)) \subseteq [-1, 1],$$

and since $\varphi_f(w) \neq 0$, this implies that t must be in a bounded interval. Hence (v) holds.

Finally, if (v) is true, then $(V(X), V(X)^+, X)$ is a base-normed space. By Proposition 1.2 (iii), the dual Banach space $V(X)^*$ is isomorphic to $A_b(X)$ and since the elements of $V(K)^*$ separate points of V(K), this implies (iii).

Let $X \in \mathbf{BConv}$ and let \tilde{V} be the completion of V(X) with respect to the base norm $\|\cdot\|_X$. Then V(X) is isometrically isomorphic to a norm-dense subspace in \tilde{V} and hence $\tilde{V}^* \simeq V(X)^* \simeq A_b(X)$. By [5, Theorem] and its proof, \tilde{V} has a structure of a base normed space $(\tilde{V}, \tilde{V}^+, \tilde{K})$, with $\tilde{V}^+ = \{v \in \tilde{V}, \langle f, v \rangle \geq 0, \ \forall f \in A_b(X)^+\}$ and $\tilde{K} = \{v \in \tilde{V}^+, \langle v, 1_X \rangle = 1\}$, moreover, $\|\cdot\|_{\tilde{K}} = \|\cdot\|_X$ on V(X).

Let $x \in \tilde{K}$. Since V(X) is dense in \tilde{V} , there is a sequence $v_n \in V(X)$ such that $\|v_n - x\|_{\tilde{K}} \to 0$, in particular, $\|v_n\|_X = \|v_n\|_{\tilde{K}} \to \|x\|_{\tilde{K}} = 1$. For any $n \in \mathbb{N}$, we have

$$v_n = \lambda_n x_n - \mu_n y_n, \quad x_n, y_n \in X, \ \lambda_n, \mu_n \ge 0, \ \lambda_n + \mu_n \le ||v_n||_X + \frac{1}{n},$$

hence $\lambda_n + \mu_n \to 1$. On the other hand,

$$\lambda_n - \mu_n = \langle 1_X, v_n \rangle \to \langle 1_X, x \rangle = 1$$

so that $\lambda_n \to 1$ and $\mu_n \to 0$. It follows that

$$\lim_{n} \lambda_n^{-1} x_n = \lim_{n} v_n = x$$

so that x is a limit of elements in X, hence \tilde{K} is the norm closure of X in \tilde{V} . Assume now that X is complete in the intrinsic metric ρ . Since $\rho(x,y) = \|x-y\|_X = \|x-y\|_{\tilde{K}}$, it follows that we must have $\tilde{K} = X$ and hence also $V(X) = \tilde{V}$ is a Banach space. This proves the following, see also [2] ([6, Thm. 2.7]).

Theorem 2.3. Let $X \in \mathbf{BConv}$ be such that (X, ρ) is a complete metric space. Then $(V(X), V(X)^+, X)$ is a base-normed Banach space.

The full subcategory of bounded convex structures that are complete in ρ will be denoted by **CConv**.

Proposition 2.4. CConv is equivalent to the category **BNB** of base-normed Banach spaces with a closed base.

References

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