

VE281

Data Structures and Algorithms

Analyzing Algorithms; Sorting

Announcement

- Written Assignment One Released
 - Find the description on Canvas
 - Due time: 3:40 pm, Sep. 26th, 2016
- Midterm exam time: in lecture on Oct. 31st, 2016

Outline

- Analyzing Time Complexity of Programs
- Sorting Basics
- Merge Sort

Review

- Asymptotic Analysis: Big-Oh
 - Common functions and their growth rates
- Relatives of Big-Oh
 - Big-Omega
 - Theta

Analyzing Time Complexity of Programs

- For atomic statement, such as assignment, its complexity is $\Theta(1)$.
- For branch statement, such as if-else statement and switch statement, its complexity is that of the most expensive Boolean expression plus that of the most expensive branch.

```
if (Boolean_Expression_1) {Statement_1}  
else if (Boolean_Expression_2) {Statement_2}  
...  
else if (Boolean_Expression_n) {Statement_n}  
else {Statement_For_All_Other_Possibilities}
```

Analyzing Time Complexity of Programs

- For subroutine call, its complexity is that of the subroutine.
- For loops, such as while and for loop, its complexity is related the number of operations required in the loop.

Time Complexity Example One

- What is the time complexity of the following code?

```
sum = 0;  
for(i = 1; i <= n; i++)  
    sum += i;
```

- The entire time complexity is $\Theta(n)$.

Time Complexity Example Two

- What is the time complexity of the following code?

```
sum = 0;  
for(i = 1; i <= n; i++)  
    for(j = 1; j <= i; j++)  
        sum++;
```

- Note that the statements

```
j <= i;  
j++;  
sum++;
```

all occur (roughly) $1 + 2 + \dots + n = n(n + 1)/2$ times.

- The time complexity is $\Theta(n^2)$.

Time Complexity Example Three

- What is the time complexity of the following code?

```
sum = 0;  
for(i = 1; i <= n; i *= 2)  
    for(j = 1; j <= n; j++)  
        sum++;
```

- The outer loop occurs $\log n$ times.
- The statements **sum++** / **j<=n** / **j++** occur $n \log n$ times.
- The time complexity is $\Theta(n \log n)$.

Time Complexity Example Four

- What is the time complexity of the following code?

```
sum = 0;  
for(i = 1; i <= n; i *= 2)  
    for(j = 1; j <= i; j++)  
        sum++;
```

- The number of times that the statements **sum++** / **j<=i** / **j++** occur is

$$1 + 2 + 4 + 8 + \dots 2^{\log n} \approx 2n - 1$$

- The time complexity is $\Theta(n)$.

Multiple Parameters

- Example: Compute the rank ordering for all C (i.e., 256) pixel values in a picture of P (i.e., 64×64) pixels.

```
for(i=0; i<C; i++)    // Initialize count
```

$\Theta(C)$

```
    count[i] = 0;
```

```
for(i=0; i<P; i++)    // Look at all pixels
```

$\Theta(P)$

```
    count[value[i]]++; // Increment count
```

```
sort(count);          // Sort pixel counts
```

$\Theta(C \log C)$

- The time complexity is $\Theta(P + C \log C)$.

Space/Time Trade-off Principle

- One can often reduce time if one is willing to sacrifice space, or vice versa.
- Example: factorial
 - Iterative method: Get “n!” using a for-loop.
 - This requires $\Theta(1)$ memory space and $\Theta(n)$ runtime.
 - Table lookup method: Pre-compute the factorials for $1, 2, \dots, N$ and store all the results in an array.
 - This requires $\Theta(n)$ memory space and $\Theta(1)$ runtime (fetching from an array).

Outline

- Analyzing Time Complexity of Programs
- **Sorting Basics**
- Merge Sort

Sorting

- Given array A of size N , reorder A so that its elements are in order.
 - "In order" with respect to a consistent comparison function, such as " \leq " or " \geq ".
- Sorting order
 - Ascending order
 - Descending order
- Unless otherwise specified, we consider sorting in ascending order.

Characteristics of Sorting Algorithms

- Average case time complexity
- Worst case time complexity
- Space usage: **in place** or not?
 - **in place**: requires $O(1)$ additional memory.
 - Don't forget the stack space used in recursive calls.
- **Stability**: whether the algorithm maintains the relative order of records with equal keys.
 - Usually there is a secondary key whose ordering you want to keep. Stable sort is thus useful for sorting over multiple keys.

(4, b), (3, e), (3, b), (5, b)  (3, e), (3, b), (4, b), (5, b)

Sort on the first number

Stable!

Types of Sorting Algorithms

- Sorting algorithms can be classified as **comparison sort** and **non-comparison sort**.
- **Comparison sort**: each item is compared against others to determine its order.
- **Non-comparison sort**: each item is put into predefined “bins” independent of the other items presented.
 - No comparison with other items needed.
 - It is also known as **distribution-based sort**.

Types of Sorting Algorithms

- General types of comparison sort
 - Insertion-based: insertion sort
 - Selection-based: selection sort, heap sort
 - Exchange-based: bubble sort, quick sort
 - Merging-based: merge sort
- Non-comparison sort:
counting sort, bucket sort, radix sort

Insertion Sort

- **A[0]** alone is a sorted array.
- For **i=1** to **N-1**
 - **Insert A[i]** into the appropriate location in the sorted array **A[0], ..., A[i-1]**, so that **A[0], ..., A[i]** is sorted.
 - To do so, save **A[i]** in a temporary variable **t**, shift sorted elements greater than **t** right, and then insert **t** in the gap.
- Time complexity? $O(N^2)$
- In place? Yes. $O(1)$ additional memory.
- Stable?
 - Yes, because elements are visited in order and equal elements are inserted after its equals.

Insertion Sort

Best Case Time Complexity

- For **$i=1$** to **$N-1$**
 - **Insert $A[i]$** into the appropriate location in the sorted array **$A[0], \dots, A[i-1]$** , so that **$A[0], \dots, A[i]$** is sorted.
- The **best case** time complexity is $O(N)$.
 - It happens when the array is already sorted.
 - For other sorting algorithms we will talk, their best case time complexity is $\Omega(N \log N)$.

Selection Sort

- For **$i=0$** to **$N-2$**
 - Find the smallest item in the array **$A[i]$** , ... , **$A[N-1]$** .
Then, swap that item with **$A[i]$** .
- Finding the smallest item requires **linear search**.
- Time complexity?
 - $O(N^2)$ **best case?**
- In place?
 - Yes. $O(1)$ additional memory.
- Stable?
 - No. $(3, e), (3, b), (2, a) \longrightarrow (2, a), (3, b), (3, e)$

Bubble Sort

For $i=N-2$ **downto** 0

For $j=0$ **to** i

If $A[j]>A[j+1]$ **swap** $A[j]$ **and** $A[j+1]$

- Compares two adjacent items and swap them to keep them in ascending order.
 - From the beginning to the end. The last item will be the largest.
- Time complexity? $O(N^2)$
- In place? Yes.
- Stable?
 - Yes, because equal elements will not be swapped.

Two Problems with Simple Sorts

- They learn only one piece of information per comparison and hence might compare every pair of elements.
 - Contrast with binary search: learns $N/2$ pieces of information with first comparison.
- They often move elements one place at a time (bubble sort and insertion sort), even if the element is “far” from its **final place**.
 - Contrast with selection sort, which moves each element exactly to its final place.
- Fast sorts attack these two problems.
 - Two famous ones: **merge sort** and **quick sort**.

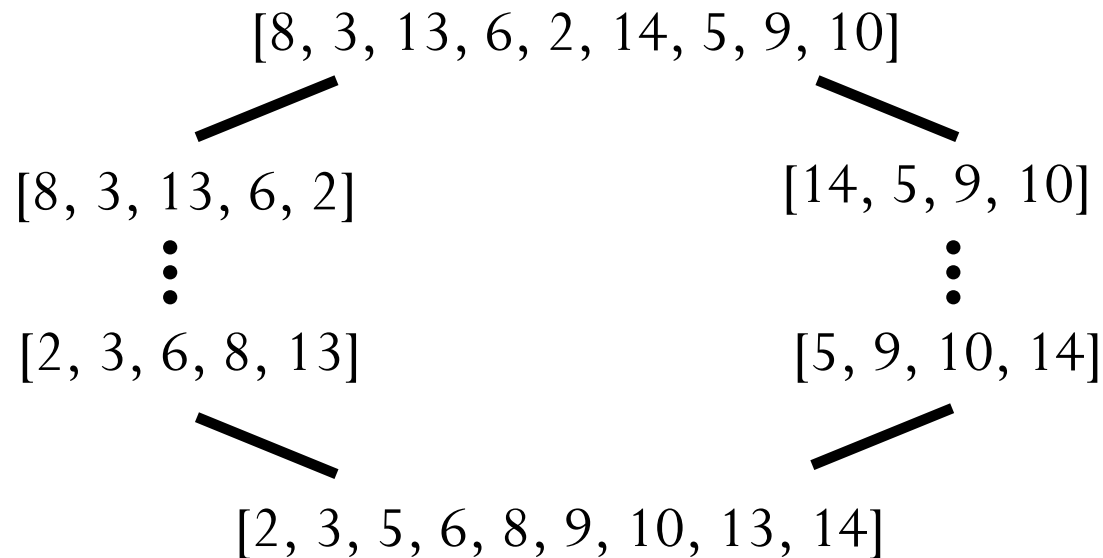
Outline

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- Merge Sort

Merge Sort

Algorithm

- Spilt array into two (roughly) equal subarrays.
- Merge sort each subarray recursively.
 - The two subarrays will be sorted.
- Merge the two sorted subarrays into a sorted array.



Merge Sort

Pseudo-code

```
void mergesort(int *a, int left, int
    right) {
    if (left >= right) return;
    int mid = (left+right)/2;
    mergesort(a, left, mid);
    mergesort(a, mid+1, right);
    merge(a, left, mid, right);
}
```

Merge Two Sorted Arrays

- For example, merge $A = (2, 5, 6)$ and $B = (1, 3, 8, 9, 10)$.
- Compare the smallest element in the two arrays A and B and move the smaller one to an additional array C .
- Repeat until one of the arrays becomes empty.
- Then append the other array at the end of array C .

Merge Two Sorted Arrays

Implementation

- We actually do not “remove” element from arrays A and B.
 - We just keep a pointer indicating the smallest element in each array.
 - We “remove” element by incrementing that pointer.

```
i = j = k = 0;
while(i < sizeA && j < sizeB) {
    if(A[i] <= B[j]) C[k++] = A[i++];
    else C[k++] = B[j++];
}
if(i == sizeA) append(C, B);
else append(C, A)
```

Time complexity?

Time complexity is $O(\text{sizeA} + \text{sizeB})$

Merge Sort

Time Complexity

```
void mergesort(int *a, int left, int
    right) {
    if (left >= right) return;
    int mid = (left+right)/2;
    mergesort(a, left, mid);  $T(N/2)$ 
    mergesort(a, mid+1, right);  $T(N/2)$ 
    merge(a, left, mid, right);  $O(N)$ 
}
```

- Let $T(N)$ be the time required to merge sort N elements.
- Merge two sorted arrays with total size N takes $O(N)$.

Recursive relation: $T(N) = 2T(N/2) + O(N)$

Solve Recurrence: Master Method

- A “black box” for solving recurrence.
- However, there is an important assumption: all sub-problems have roughly **equal** sizes.
 - E.g., merge sort
 - Not apply to unbalanced division.

Solve Recurrence: Master Method

- Recurrence: $T(n) \leq aT\left(\frac{n}{b}\right) + O(n^d)$
 - Base case: $T(n) \leq \text{constant}$ for all sufficiently small n .
 - a = number of recursive calls (integer ≥ 1)
 - b = input size shrinkage factor (integer > 1)
 - $O(n^d)$: the runtime of merging solutions. d is real value ≥ 0 .
 - a, b, d are independent of n .

- Claim:

$$T(n) = \begin{cases} O(n^d \log n) & \text{if } a = b^d \\ O(n^d) & \text{if } a < b^d \\ O(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$

base doesn't matter

base matters!

Example of Merge Sort

Recurrence: $T(n) \leq aT\left(\frac{n}{b}\right) + O(n^d)$

Claim: $T(n) = \begin{cases} O(n^d \log n) & \text{if } a = b^d \\ O(n^d) & \text{if } a < b^d \\ O(n^{\log_b a}) & \text{if } a > b^d \end{cases}$

- $a = 2, b = 2, d = 1 \Rightarrow b^d = a$
- $T(n) = O(n \log n)$

Another Example: Binary Search

Recurrence: $T(n) \leq aT\left(\frac{n}{b}\right) + O(n^d)$

Claim: $T(n) = \begin{cases} O(n^d \log n) & \text{if } a = b^d \\ O(n^d) & \text{if } a < b^d \\ O(n^{\log_b a}) & \text{if } a > b^d \end{cases}$

- Exercise: What is a, b, d?

Merge Sort

Characteristics

- Not in-place
 - For efficient merging two sorted arrays, we need an auxiliary $O(N)$ space.
 - Recursion needs up to $O(\log N)$ stack space.
- Stable if **merge () maintains** the relative order of equal keys.

Divide-and-Conquer Approach

- Merge sort uses the **divide-and-conquer** approach.
- Recursively **breaking** down a problem into two or more sub-problems of the same (or related) type, until these become simple enough to be solved directly.
 - For merge sort, split an array into two and sort them respectively.
- The solutions to the sub-problems are then **combined** to give a solution to the original problem.
 - For merge sort, merge two sorted arrays.