# **Modelling of Complex Systems**

#### Randomness

#### **Outline:**

- Randomness and random numbers
- Probabilities and probability distributions
- Sampling random numbers

Randomness is the (actual or apparent) lack of predictability in events, sequences of symbols, etc. A random sequence has no order, and does not follow an understandable pattern.

Coin flipping: heads or tails?

Defining heads=1 and tails=0, we get sequences like 0010111010....

After N trials heads appears  $N_h$  times and tails appears  $N_t$  times, with the constraint  $N_h + N_t = N$ .

We can estimate the probabilities of finding heads and tails as:

$$P_h = \frac{N_h}{N}$$
 and  $P_t = \frac{N_t}{N}$ 



The **normalization condition** imposes that

$$P_h + P_t = \frac{N_h}{N} + \frac{N_t}{N} = \frac{N_h + N_t}{N} = 1$$

It is important to understand that, rigorously speaking, the probabilities can be defined in this way only in the limit of  $N \to \infty$ , i.e.:

$$P_h = \lim_{N \to \infty} \frac{N_h}{N}$$
 and  $P_t = \lim_{N \to \infty} \frac{N_t}{N}$ .

For example, flipping the coin 2 times we can easily get 11, which would lead us to  $P_h = 1$  and  $P_t = 0$ . But for a perfect coin we must have  $P_h = P_t = 0.5$ . Clearly, 2 flips are not enough to get accurate estimates for the probabilities, we must increase the number N.

#### **Rolling dices:**

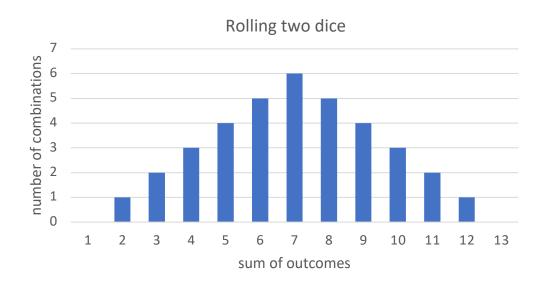
If the dice is fair, each number 1 to 6 has the same probability of 1/6.

We can effectively determine if a dice is fair by rolling it many times and analysing the sequence of events.



If we roll two dice, the sum of the outcomes is a number from 2 to 12.

In this case, the probability of each number is no longer uniform.





#### **Buffon's Needle problem (1733):**

What is the probability that a needle thrown to the floor will land across a line between two boards?

$$P = \frac{2}{\pi} \frac{l}{d}$$

This result can be used to approximate the number  $\pi$  in a Monte Carlo experiment.

Monte Carlo methods use randomness to solve numerical problems. Their precision increases with the number of trials.



### Law of large numbers

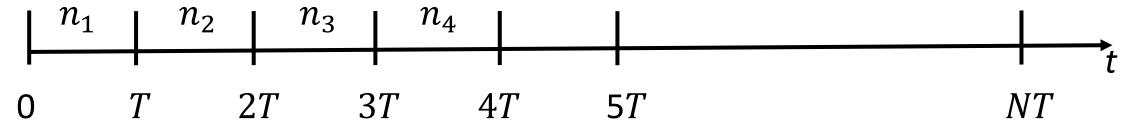
The law of large numbers states that as the number of trial of a random process increases a sample average approaches its expected value.

Consider a random variable X with k possible values, say  $X_1, \ldots, X_k$ , and corresponding probabilities  $P_1, \ldots, P_k$ . Then the expected value, or **expectation**, of X is  $\langle X \rangle = \sum_{i=1}^k X_i P_i$ .

Take a sample of N trials of the variable, denoted  $x_1, ..., x_N$  (to avoid confusion). The **sample average** is  $\bar{X} = \frac{1}{N} \sum_{j=1}^{N} x_j$ .

The law of large numbers ensures that  $\lim_{N\to\infty} \overline{V} = \langle V \rangle$ .

Let us count the number of cars that pass on a street under our window during an interval  ${\cal T}$ 



where N is the number of intervals. We get a sequence of random integer numbers:  $n_1, n_2, n_3, n_4, \dots n_N$ .

Every random number  $n_i$  takes a value 0,1, 2, 3, ....

Let us analyze this sequence:

We count the number of intervals where  $n_i = n$ .

We define this number as N(n).

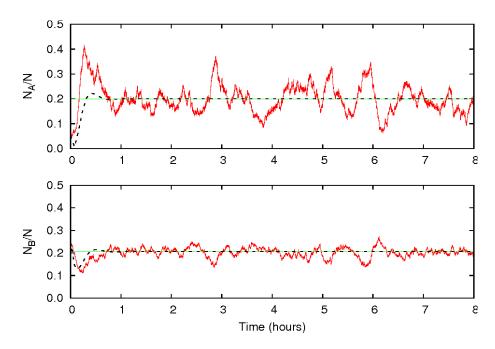
- Clearly  $\sum_{n=0}^{\infty} N(n) = N$ .
- The probability to observe n cars is  $P(n) = \lim_{N \to \infty} \frac{N(n)}{N}$ .
- Normalization condition:  $\sum_{n=0}^{\infty} P(n) = \sum_{n=0}^{\infty} \frac{N(n)}{N} = 1$ .
- The mean value of random numbers:  $\langle n \rangle = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N} n_i$ .
- · We can rewrite this equation in another form,

$$\langle n \rangle = \frac{1}{N} \sum_{i=1}^{N} n_i = \frac{1}{N} \sum_{n=0}^{\infty} N(n) n = \sum_{n=0}^{\infty} \frac{N(n)}{N} n = \sum_{n=0}^{\infty} P(n) n$$
$$\langle n \rangle = \sum_{n=0}^{\infty} n P(n)$$

**Fluctuations.** We define a deviation of  $n_i$  from the mean value  $\langle n \rangle$   $\delta n_i = n_i - \langle n \rangle$ .

It is obvious that

$$\sum_{i=1}^{N} \delta n_i = \sum_{i=1}^{N} (n_i - \langle n \rangle) = \sum_{i=1}^{N} n_i - \sum_{i=1}^{N} \langle n \rangle$$
$$= N \langle n \rangle - N \langle n \rangle = 0$$



**Variance.** In order to measure how strong are fluctuations we introduce a so-called variance as follows:

$$\sigma^{2} = \frac{1}{N} \sum_{i=1}^{N} (\delta n_{i})^{2} = \frac{1}{N} \sum_{i=1}^{N} (n_{i} - \langle n \rangle)^{2}$$

Using the probability distribution function P(n) we get

$$\sigma^2 = \sum_{n=0}^{\infty} P(n)(n - \langle n \rangle)^2 = \sum_{n=0}^{\infty} P(n)(n^2 - 2n\langle n \rangle + \langle n \rangle^2)$$

$$= \sum_{n=0}^{\infty} P(n)n^2 - 2\langle n \rangle \sum_{n=0}^{\infty} P(n)n + \langle n \rangle^2 \sum_{n=0}^{\infty} P(n)$$

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# **Probability distribution**

The statistics of a random variable X is described by its probability mass distribution function P(X).

- P(X) assigns a probability to each possible value of X.
- P(X) must obey normalization  $\sum_{X} P(X) = 1$ .
- The mean value (expectation) of X is defined as  $\langle X \rangle = \sum_X X P(X)$ .
- The variance of X is:  $var(X) = \sum_{X} (X \langle X \rangle)^2 P(X) = \langle X^2 \rangle \langle X \rangle^2$
- More generally, the average of a function of X, say f(X), is defined as  $\langle f \rangle = \sum_X f(X) P(X)$ .

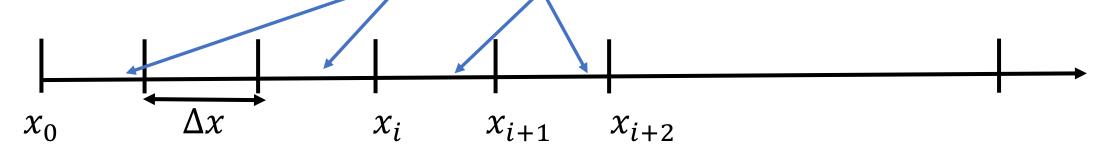
#### **Continuous random variables**

In many cases, random variables can take any value belonging to a continuous interval. Then, there infinitely many values allowed, each of them occurring with probability 0...

To deal with continuous random variables we introduce the concept of **probability density**, and probability density distribution function.

#### **Continuous random variables**

Lets consider, for example, velocities of cars  $v_i$ . We have a random sequence of real numbers  $v_1, v_2, v_3, v_4, ..., v_N$ . We divide the axis of real numbers into intervals (bins) of equal width  $\Delta x$ 



We count the number values of v in the interval  $(x_i, x_{i+1}]$ , i.e.,

$$x_i < v_n \le x_{i+1}$$
, and denote this number as  $\Delta N(x_i, x_{i+1})$ .

The total number of random numbers  $v_i$  in the sequence is

$$\sum_{i=0}^{\infty} \Delta N(x_i, x_{i+1}) = N$$

The probability density distribution function is defined as

$$P(x_i) = \lim_{N \to \infty, \Delta x \to 0} \frac{\Delta N(x_i, x_{i+1})}{N \Delta x}.$$

The probability density distribution can be understood as follows:  $P(x)\Delta x$  gives the probability of the random variable taking a value between in the interval  $(x, x + \Delta x]$  in the limit of  $\Delta x \to 0$ .

The normalization is  $\sum_{i=0}^{\infty} P(x_i) \Delta x = \sum_{i=0}^{\infty} \frac{\Delta N(x_i, x_{i+1})}{N \Delta x} \Delta x = 1$ .

In the limit  $N \to \infty, \Delta x \to 0$ , but still  $\Delta N(x_i, x_{i+1}) >> 1$ , we can use the integral representation

$$\sum_{i=0}^{\infty} P(x_i) \Delta x = \int_{-\infty}^{\infty} P(x) dx = 1$$

Mean value:  $\langle x \rangle = \sum_{i=0}^{\infty} x_i P(x_i) \Delta x = \int_{-\infty}^{\infty} x P(x) dx$ 

Variance:  $\sigma^2 = \sum_{i=0}^{\infty} (x_i - \langle x \rangle)^2 P(x_i) \Delta x = \int_{-\infty}^{\infty} (x - \langle x \rangle)^2 P(x) dx$ 

Suppose that we have a continuous random variable x with a known probability density distribution P(x). Let us consider another variable that is a function of x, say y = f(x).

What the probability density distribution of y say Q(y)?

Using a simple rational: the probability of x falling in an interval  $(x, x + \Delta x]$  must be equal to the probability of y falling inside  $(f(x), f(x + \Delta x)]$ 

$$P(x)\Delta x = Q(y)[f(x + \Delta x) - f(x)] = Q(y)\Delta y$$
  

$$\Leftrightarrow Q(y) = P(x)\frac{\Delta x}{\Delta y} = P(x)\left(\frac{\partial y}{\partial x}\right)^{-1}$$

$$Q(y) = \left(\frac{\partial y}{\partial x}\right)^{-1} P(x)$$

For example, a rescaling y = cx gives  $Q(y) = \frac{1}{c}P\left(\frac{y}{c}\right)$ .

Or, a power-law 
$$y = x^{\alpha}$$
 gives  $Q(y) = \frac{y^{1/\alpha - 1}}{\alpha} P(y^{1/\alpha})$ .

When facing multiple random variables, it is essential to take into consideration their correlation or independence.

More concretely, let us consider two random variables, X and Y, that appear simultaneously, that is, trial i consists of a pair of random numbers  $(X_i, Y_i)$ .

The joint statistics of X and Y is described by the **joint probability** distribution function P(X,Y) that assigns a probability to each possible pair of values of X and Y.

In this case, the normalization condition is  $\sum_{X} \sum_{Y} P(X,Y) = 1$ , and an average is  $\langle f \rangle = \sum_{X} \sum_{Y} f(X,Y) P(X,Y)$ .

 Two events are independent if the occurrence of one does not affect the probability of occurrence of the other.

For the joint probability distribution function independence means P(X,Y) = P(X)P(Y).

• We say two events are **correlated** when  $P(X,Y) \neq P(X)P(Y)$ , which implies that **one affects the other**.

For **independent variables** we can write for the average of their product as  $\langle X \cdot Y \rangle = \langle X \rangle \cdot \langle Y \rangle$ :

$$\langle X Y \rangle = \sum_{X} \sum_{Y} X Y P(X, Y) = \sum_{X} \sum_{Y} X P(X) Y P(Y)$$
$$= \left(\sum_{X} X P(X)\right) \left(\sum_{Y} Y P(Y)\right) = \langle X \rangle \langle Y \rangle$$

More generally, for independent variables the average of a product of two functions is

$$\langle f(X) \cdot g(Y) \rangle = \langle f(X) \rangle \cdot \langle g(Y) \rangle$$

When two random variables are **correlated**, we can usually get a measure of their pair correlations from the so-called **covariance** 

$$C_{XY} = \frac{1}{N} \sum_{i=1}^{N} \delta X_i \delta Y_i = \langle XY \rangle - \langle X \rangle \langle Y \rangle$$

Notice that when the variables are independent  $C_{XY} = 0$ .

Furthermore, the Pearson correlation coefficient is defined as

$$\rho_{XY} = \frac{C_{XY}}{\sigma_X \sigma_Y}$$

The same ideas are directly generalized to more than two variables.