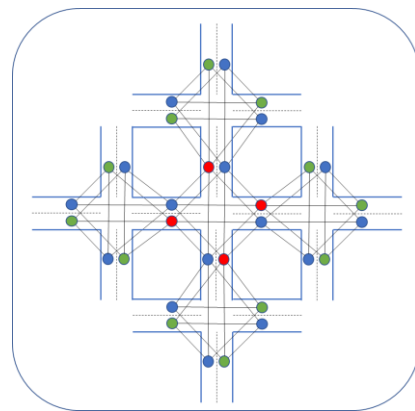
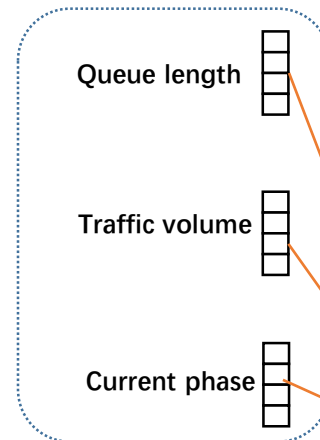


环境观察



节点回归

