

If X_1, \dots, X_n are RVs then

$$\underset{\sim}{X} = \begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix}$$

is called a multivariate random variable
or a random vector,

Defn: PMF/PDFs

If X_i 's are discrete then the joint PMF
as

$$f(\underline{x}) = f(x_1, x_2, \dots, x_n) = P(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n)$$

$\rightarrow \underline{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$

If X_i s are continuous then the joint PDF
is the function $f: \mathbb{R}^n \rightarrow \mathbb{R}$
so that for $A \subset \mathbb{R}^n$ then

$$P(\underline{X} \in A) = \int_A f(\underline{x}) d\underline{x} = \underbrace{\int_A \cdots \int_A f(x_1, \dots, x_n) dx_1 dx_2 dx_3 \cdots dx_n}_{n \text{ integrals}}$$

Expectation

If $g: \mathbb{R}^n \rightarrow \mathbb{R}$ then

$$E[g(\underline{X})] = \begin{cases} \sum_{x_1} \sum_{x_2} \sum_{x_3} \cdots \sum_{x_n} g(x_1, \dots, x_n) f(x_1, \dots, x_n) & (\text{discrete}) \\ \int \cdots \int g(x_1, \dots, x_n) f(x_1, \dots, x_n) dx_1 dx_2 \cdots dx_n & (\text{cts}) \end{cases}$$

Defns The marginal dist of X_i can be found as

$$p_{X_i}(x_i) = \begin{cases} \sum_{x_1} \sum_{x_2} \sum_{x_3} \cdots \sum_{x_{i-1}} \sum_{x_{i+1}} \cdots \sum_{x_n} f(x_1, \dots, x_n) & (\text{discrete}) \\ \int \cdots \int f(x_1, \dots, x_n) dx_1 \cdots dx_{i-1} dx_{i+1} \cdots dx_n & (\text{cts}) \end{cases}$$

$$\int \dots \int f(x_1, \dots, x_n) dx_1 \dots dx_{i-1} dx_{i+1} \dots dx_n$$

We can get the joint/marginal of some subsequence $X_{i_1}, X_{i_2}, \dots, X_{i_m}$ by summing or integrating the joint over all vars. but X_{i_1}, \dots, X_{i_m} .

Conditional Distributions

If I have two sets of RVs

X_1, \dots, X_n and Y_1, \dots, Y_m

the conditional dist. of the X s given Y s is

$$f(x_1, \dots, x_n | y_1, \dots, y_m) = \frac{f(x_1, \dots, x_n, y_1, \dots, y_m)}{f(y_1, \dots, y_m)}$$

Ex. Let X_1, \dots, X_4 have a joint PDF of

$$f(x_1, \dots, x_4) = \frac{3}{4}(x_1^2 + x_2^2 + x_3^2 + x_4^2)$$

for $0 < x_i < 1$

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a) $P(X_1 < 1/2, X_2 < 3/4, X_4 > 1/2)$

$$= \int \dots \int f(x) dx$$

$$= \int_{1/2}^1 \int_0^1 \int_0^{3/4} \int_0^{1/2} \frac{3}{4} (x_1^2 + x_2^2 + x_3^2 + x_4^2) dx_1 dx_2 dx_3 dx_4$$

$$= \dots = 3/256$$

b) What is dist of X_1 and X_2 ?

$$f(x_1, x_2) = \int_0^1 \int_0^1 f(x_1, \dots, x_4) dx_3 dx_4$$

$$= \int_0^1 \int_0^1 \frac{3}{4} (x_1^2 + x_2^2 + x_3^2 + x_4^2) dx_3 dx_4$$

$$= \dots = \frac{1}{2} + \frac{3}{4} (x_1^2 + x_2^2)$$

c) Expectation

$$\begin{aligned}
 E[X_1 X_2] &= \int \dots \int x_1 x_2 f(x_1, \dots, x_4) dx_1 \dots dx_4 \\
 &= \int_0^1 \int_0^1 \int_0^1 \int_0^1 x_1 x_2 \frac{3}{4} (x_1^2 + x_2^2 + x_3^2 + x_4^2) dx_3 dx_4 dx_1 dx_2 \\
 &= \int_0^1 \int_0^1 x_1 x_2 \left(\frac{1}{2} + \frac{3}{4} (x_1^2 + x_2^2) \right) dx_1 dx_2 \\
 &= \dots = 5/16
 \end{aligned}$$

④ Conditional dists

What is the cond. of X_3, X_4 given X_1, X_2 ?

$$f(x_3, x_4 | x_1, x_2) = \frac{f(x_1, \dots, x_4)}{f(x_1, x_2)} = \frac{\frac{3}{4} (x_1^2 + x_2^2 + x_3^2 + x_4^2)}{\frac{1}{2} + \frac{3}{4} (x_1^2 + x_2^2)}$$

Mutual Independence

We say X_1, \dots, X_n are mutually independent if for any sets $A_1, \dots, A_n \subset \mathbb{R}$

$$P(X_1 \in A_1, X_2 \in A_2, X_3 \in A_3, \dots, X_n \in A_n) \\ = P(X_1 \in A_1) \cdots P(X_n \in A_n).$$

Theorem: Independence + Factorization

If the support of X is a product space then the three following statements are equiv.

- ① X_1, \dots, X_n are independent
- ② $f(x_1, \dots, x_n) = f(x_1)f(x_2) \cdots f(x_n) = \prod_{i=1}^n f(x_i)$
- ③ $F(x_1, \dots, x_n) = F(x_1) \cdots F(x_n)$

Theorem: Let X_1, \dots, X_n be independent.

- ① If $g_i: \mathbb{R} \rightarrow \mathbb{R}$ then $g_1(X_1), g_2(X_2), \dots, g_n(X_n)$ are independent.
- ② $E[X_1 X_2 X_3 \cdots X_n] = E[X_1]E[X_2] \cdots E[X_n].$

Corollary

If X_i s are independent and

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$$Z = \sum_{i=1}^n X_i$$

then $M_Z(t) = \prod_{i=1}^n M_{X_i}(t).$

Follow-on, let

$$Z = \sum_{i=1}^n (a_i X_i + b_i)$$

$$M_Z(t) = e^{t \sum_{i=1}^n b_i} \prod_{i=1}^n M_{X_i}(a_i t)$$

Ex. $X_i \sim N(\mu_i, \sigma_i^2)$ and they are independent

then

$$Y = \sum_{i=1}^n (a_i X_i + b_i) \sim N\left(\sum_{i=1}^n a_i \mu_i + b_i, \sum_{i=1}^n a_i^2 \sigma_i^2\right)$$

Multivariate Transformations

$$\text{Let } \underline{X} = (X_1, \dots, X_n)^T$$

$$\text{and } g: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\text{let } \underline{u} = g(\underline{x})$$

$$\uparrow u_i = g_i(x_1, \dots, x_n)$$

If \underline{x} has cts components and

$\rightarrow g$ is invertible

$\rightarrow g^{-1}$ is differentiable

then

$$f_{\underline{u}}(\underline{u}) = f_{\underline{x}}(g^{-1}(\underline{u})) |\det J|$$

$$J_{ij} = \frac{\partial g_i^{-1}}{\partial u_j}$$

Means / Variances for MU-RVs

Uni: $E[X] \in \mathbb{R}$

$$\text{Var}(X) = E[(X - EX)^2] \in \mathbb{R}$$

mv: $\underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$

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$$\mu = \mathbb{E}[\underline{X}] = \begin{bmatrix} \mathbb{E}[X_1] \\ \mathbb{E}[X_2] \\ \vdots \\ \mathbb{E}[X_n] \end{bmatrix} \in \mathbb{R}^n \quad \left. \begin{array}{l} \sim [X_n] \\ \text{expected value} \\ \text{of a vector} \end{array} \right\}$$

Covariance matrix

$$\Sigma = \text{Cov}(\underline{X}) \in \mathbb{R}^{n \times n}$$

where $\Sigma_{ij} = \text{Cov}(X_i, X_j)$

notice: $\Sigma_{ii} = \text{Cov}(X_i, X_i) = \text{Var}(X_i)$

$$\Sigma = \begin{bmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) & \dots \\ \text{Cov}(X_2, X_1) & \text{Var}(X_2) & \dots \\ \vdots & \vdots & \ddots \\ \vdots & \vdots & \vdots & \text{Var}(X_n) \end{bmatrix}$$

$$\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}X)^2]$$

$$\text{Cov}(\underline{X}) = \mathbb{E}[(\underline{X} - \mathbb{E}\underline{X})(\underline{X} - \mathbb{E}\underline{X})^T]$$

Theorem:

$\dots \quad m \quad \dots \quad m \times n \quad \dots$

If $a \in \mathbb{R}^m$ and $B \in \mathbb{R}^{m \times n}$ and \underline{X} is a n -component Rand. vector then

$$(1) E[a + B\underline{X}] = a + BE[\underline{X}]$$

$$(2) \text{Cov}(a + B\underline{X}) = B \text{Cov}(\underline{X}) B^T \leftarrow$$

Multivariate Normal

$$\underline{X} \sim N(\underline{\mu}, \Sigma)$$

$\underbrace{\hspace{1cm}}_{\underline{\mu} \in \mathbb{R}^n} \quad \underbrace{\hspace{1cm}}_{\Sigma \in \mathbb{R}^{n \times n}}$

then

$$f(\underline{X}) = (2\pi)^{-n/2} (\det \Sigma)^{-1/2} \exp\left(-\frac{1}{2}(\underline{X} - \underline{\mu})^T \Sigma^{-1}(\underline{X} - \underline{\mu})\right)$$

Special case: $\underline{\mu} = 0$ and $\Sigma = I$

we call this standard MV normal.

Theorem

If $\underline{X} \sim N(\underline{\mu}, \Sigma)$ and $a \in \mathbb{R}^m$ and $B \in \mathbb{R}^{n \times m}$ then

$$a + B \underset{\sim}{X} \sim N(a + B\mu, B\Sigma B^T)$$