EVERYTHING YOU NEED TO KNOW ABOUT POINTER ANALYSIS 10 RULES

BASED ON WORK FROM

- "Efficient and Effective Handling of Exceptions in Java Points-To Analysis" Kastrinis G., Smaragdakis Y. (CC'13)
- "Pick Your Contexts Well: Understanding Object-Sensitivity" Smaragdakis Y., Bravenboer M., Lhoták O. (POPL'11)
- "Strictly Declarative Specification of Sophisticated Points-to Analyses" Bravenboer M., Smaragdakis Y. (OOPSLA'09)

University of Athens ~ PL lab (PLAST)

Yannis Smaragdakis George Kastrinis George Balatsouras

Aggelos Biboudis Kostas Ferles George Kollias Prodromos Gerakios

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()

Represent objects as
allocation sites
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a → new A1(), new A2()
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a → new A1(), new A2()
foo::b → new A1(), new A2()
bar::b → new A1(), new A2()
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a → new A1(), new A2()
foo::b → new A1(), new A2()
bar::b → new A1(), new A2()
Not the most precise, right?
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a → new A1(), new A2()
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a → new A1(), new A2()

Add "context" to variables
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a (foo) → new A1()
id::a (bar) → new A2()

Add "context" to variables
```

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a (foo) → new A1()
id::a (bar) → new A2()
foo::b → new A1()
bar::b → new A2()
Add "context" to variables
```

10 RULES? NO ALGORITHMS?

10 RULES? NO ALGORITHMS?

Using Datalog

10 RULES? NO ALGORITHMS?

Using Datalog Purely declarative

de·clar·a·tive

/di'kle(ə)rətiv/

Adjective

Computing denoting high-level programming languages which can be used to solve problems without requiring the programmer to specify an exact procedure to be followed.

~ Oxford dictionaries

de·clar·a·tive

From algorithms to specifications

Adjective

Computing denoting high-level programming languages which can be used to solve problems without requiring the programmer to specify an exact procedure to be followed.

~ Oxford dictionaries

```
INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
```

head

```
INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
    body
```

```
Output relations in red

INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←

CALLGRAPH(invo, callerCtx, meth, calleeCtx),

ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
```

```
INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
```

Input relations in blue



meth(..,from,..)



```
meth(..,from,..)
```

```
INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
```



meth(..,from,..)

```
INTERPROCASSIGN(to, calleeCtx, from, callerCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALARG(invo, i, from), FORMALARG(meth, i, to).
```

```
invo: meth(..,from,..) ---
callerCtx
meth(..,to,..) {
    calleeCtx
```



to = meth(..)



```
to = meth(..)
```

```
INTERPROCASSIGN(to, callerCtx, from, calleeCtx) ←
    CALLGRAPH(invo, callerCtx, meth, calleeCtx),
    ACTUALRETURN(invo, to), FORMALRETURN(meth, from).
```

```
invo: to = meth(..) ---
callerCtx
meth(..) {
    return from;
}
calleeCtx
```



```
to = meth(..)
```



var = new A()

```
RECORD(heap, ctx) = hctx,

VARPOINTSTO(var, ctx, heap, hctx) \(
REACHABLE(meth, ctx), ALLOC(var, heap, meth).
```

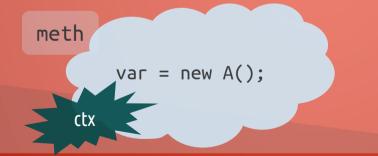


```
var = new A()
```

```
RECORD(heap, ctx) = hctx,

VARPOINTSTO(var, ctx, heap, hctx) \leftarrow

REACHABLE(meth, ctx), ALLOC(var, heap, meth).
```







```
var = new A()
```

```
RECORD(heap, ctx) = hctx, new context!

VARPOINTSTO(var, ctx, heap, hctx) \leftarrow

REACHABLE(meth, ctx), ALLOC(var, heap, meth).
```





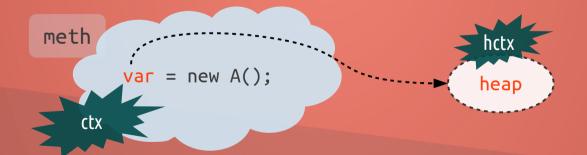


var = new A()

```
RECORD(heap, ctx) = hctx,

VARPOINTSTO(var, ctx, heap, hctx) \leftarrow

REACHABLE(meth, ctx), ALLOC(var, heap, meth).
```





to = from

 $\begin{aligned} & \mathsf{VARPOINTSTO}(\textit{to, ctx, heap, hctx}) \leftarrow \\ & \mathsf{VARPOINTSTO}(\textit{from, ctx, heap, hctx}), \ \mathsf{MOVE}(\textit{to, from}). \end{aligned}$



to = from

 $\begin{aligned} \mathsf{VARPOINTSTO}(\textit{to, ctx, heap, hctx}) \leftarrow \\ & \mathsf{VARPOINTSTO}(\textit{from, ctx, heap, hctx}), \ \mathsf{MOVE}(\textit{to, from}). \end{aligned}$





to = from

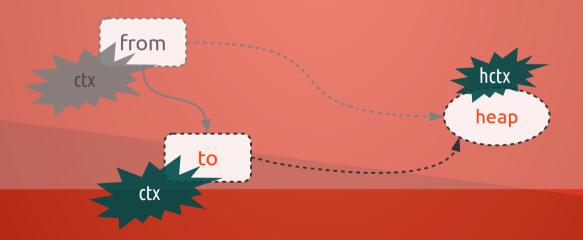
$$\label{eq:VarPointsTo} \begin{split} \text{VarPointsTo}(\textit{to, ctx, heap, hctx}) \leftarrow \\ \text{VarPointsTo}(\textit{from, ctx, heap, hctx}), \ \texttt{MoVE}(\textit{to, from}). \end{split}$$





to = from

 $\begin{aligned} & \text{VARPOINTSTO}(\textit{to, ctx, heap, hctx}) \leftarrow \\ & \text{VARPOINTSTO}(\textit{from, ctx, heap, hctx}), \ \text{MOVE}(\textit{to, from}). \end{aligned}$





to = from

VARPOINTSTO(to, ctx, heap, hctx) \leftarrow Recursion! VARPOINTSTO(from, ctx, heap, hctx), MOVE(to, from).



to ≈ from

```
VARPOINTSTO(to, toCtx, heap, hctx) ←
    INTERPROCASSIGN(to, toCtx, from, fromCtx),
    VARPOINTSTO(from, fromCtx, heap, hctx).
```



to ≈ from

VARPOINTSTO(to, toCtx, heap, hctx) ←
 INTERPROCASSIGN(to, toCtx, from, fromCtx),
 VARPOINTSTO(from, fromCtx, heap, hctx).

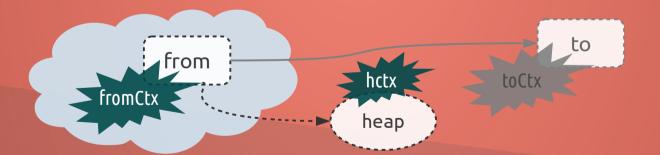






to ≈ from

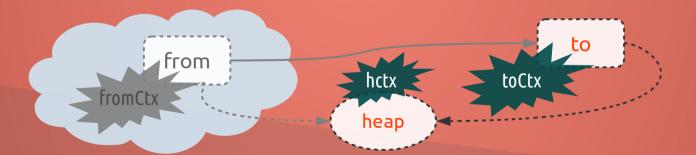
VARPOINTSTO(to, toCtx, heap, hctx) ←
 INTERPROCASSIGN(to, toCtx, from, fromCtx),
 VARPOINTSTO(from, fromCtx, heap, hctx).





to ≈ from

VARPOINTSTO(to, toCtx, heap, hctx) ←
 INTERPROCASSIGN(to, toCtx, from, fromCtx),
 VARPOINTSTO(from, fromCtx, heap, hctx).





base.fld = from

```
FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx) ←
    VARPOINTSTO(from, ctx, heap, hctx),
    STORE(base, fld, from), VARPOINTSTO(base, ctx, baseH, baseHCtx).
```



base.fld = from

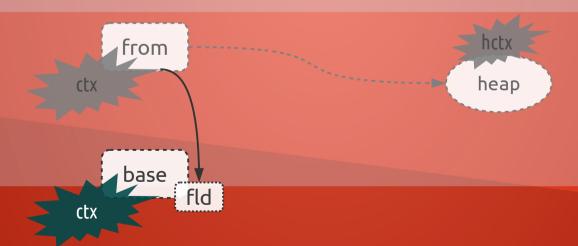
```
FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx) ←
    VARPOINTSTO(from, ctx, heap, hctx),
    STORE(base, fld, from), VARPOINTSTO(base, ctx, baseH, baseHCtx).
```





base.fld = from

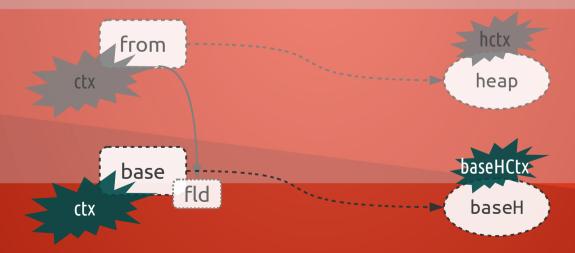
```
FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx) ←
    VARPOINTSTO(from, ctx, heap, hctx),
    STORE(base, fld, from), VARPOINTSTO(base, ctx, baseH, baseHCtx).
```





base.fld = from

FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx) ←
 VARPOINTSTO(from, ctx, heap, hctx),
 STORE(base, fld, from), VARPOINTSTO(base, ctx, baseH, baseHCtx).



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base.fld = from

FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx) ←
 VARPOINTSTO(from, ctx, heap, hctx),
 STORE(base, fld, from), VARPOINTSTO(base, ctx, baseH, baseHCtx).



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to = base.fld

```
VARPOINTSTO(to, ctx, heap, hctx) ←
    VARPOINTSTO(base, ctx, baseH, baseHCtx),
    FLDPOINTSTO(baseH, baseHCtx, fld, heap, hctx), LOAD(to, base, fld).
```



to = base.fld

```
\label{eq:VarPointsTo} \begin{split} \text{VarPointsTo}(\textit{to, ctx, heap, hctx}) \leftarrow \\ & \quad \text{VarPointsTo}(\textit{base, ctx, baseH, baseHCtx}), \\ & \quad \text{FLDPointsTo}(\textit{baseH, baseHCtx, fld, heap, hctx}), \, \text{LOAD}(\textit{to, base, fld}). \end{split}
```





to = base.fld

```
\label{eq:VarPointsTo} $$ VARPOINTSTO(\textit{base}, \textit{ctx}, \textit{baseH}, \textit{baseHCtx}), $$ $$ FLDPOINTSTO(\textit{baseH}, \textit{baseHCtx}, \textit{fld}, \textit{heap}, \textit{hctx}), LOAD(\textit{to}, \textit{base}, \textit{fld}). $$
```



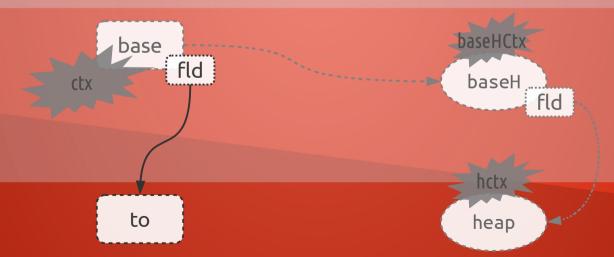






to = base.fld

```
\label{eq:VarPointsTo} $$ VARPOINTSTO(\textit{base}, \textit{ctx}, \textit{baseH}, \textit{baseHCtx}), $$ FLDPOINTSTO(\textit{baseH}, \textit{baseHCtx}, \textit{fld}, \textit{heap}, \textit{hctx}), LOAD(\textit{to}, \textit{base}, \textit{fld}). $$
```

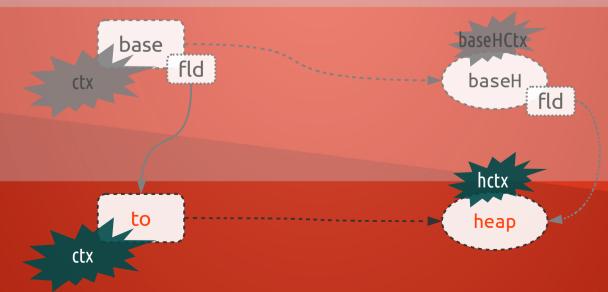


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to = base.fld

 $\begin{aligned} & \text{VARPOINTSTO}(\textit{to, ctx, heap, hctx}) \leftarrow \\ & \text{VARPOINTSTO}(\textit{base, ctx, baseH, baseHCtx}), \\ & \text{FLDPOINTSTO}(\textit{baseH, baseHCtx, fld, heap, hctx}), \text{ LOAD}(\textit{to, base, fld}). \end{aligned}$



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A::toMeth()

```
MERGESTATIC(invo, callerCtx) = calleeCtx,

REACHABLE(toMeth, calleeCtx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

SCALL(toMeth, invo, inMeth), REACHABLE(inMeth, callerCtx).
```



A::toMeth()

```
MERGESTATIC(invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
SCALL(toMeth, invo, inMeth), REACHABLE(inMeth, callerCtx).
```

inMeth
invo: A::toMeth(..)
callerCtx

toMeth



A::toMeth()

```
MERGESTATIC(invo, callerCtx) = calleeCtx, new context!

REACHABLE(toMeth, calleeCtx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

SCALL(toMeth, invo, inMeth), REACHABLE(inMeth, callerCtx).
```

inMeth
invo: A::toMeth(..)
callerCtx





A::toMeth()

```
MERGESTATIC(invo, callerCtx) = calleeCtx,

REACHABLE(toMeth, calleeCtx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

SCALL(toMeth, invo, inMeth), REACHABLE(inMeth, callerCtx).
```





```
base.sig(..)
```

```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
VARPOINTSTO(this, calleeCtx, heap, hctx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
    REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),
    VARPOINTSTO(base, callerCtx, heap, hctx),
    HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),
    THISVAR(toMeth, this).
```



```
base.sig(..)
```

```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
VARPOINTSTO(this, calleeCtx, heap, hctx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
    REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),
    VARPOINTSTO(base, callerCtx, heap, hctx),
    HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),
    THISVAR(toMeth, this).
```

inMeth

invo: base.sig(..)

callerCtx **3**



```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,

REACHABLE(toMeth, calleeCtx),

VARPOINTSTO(this, calleeCtx, heap, hctx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),

VARPOINTSTO(base, callerCtx, heap, hctx),

HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),

THISVAR(toMeth, this).
```

inMeth

callerCtx heap

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```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,

REACHABLE(toMeth, calleeCtx),

VARPOINTSTO(this, calleeCtx, heap, hctx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),

VARPOINTSTO(base, callerCtx, heap, hctx),

HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),

THISVAR(toMeth, this).
```

invo: base.sig(..)

inMeth

heap

this

toMeth

erCtx

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```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx, new context!

REACHABLE(toMeth, calleeCtx),

VARPOINTSTO(this, calleeCtx, heap, hctx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),

VARPOINTSTO(base, callerCtx, heap, hctx),

HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),

THISVAR(toMeth, this).
```

invo: base.sig(..)

callerCtx

inMeth

heap

this

toMeth

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```
base.sig(..)
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
VARPOINTSTO(this, calleeCtx, heap, hctx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
    REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),
    VARPOINTSTO(base, callerCtx, heap, hctx),
    HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),
    THISVAR(toMeth, this).
   inMeth.
                                            → toMeth
```

invo: base.sig(..) callerCtx 3 heap George Kastrinis ~ University of Athens ~ PLAST lab

calleeCtx.

this



inMeth

Datalog Rules

```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,

REACHABLE(toMeth, calleeCtx),

VARPOINTSTO(this, calleeCtx, heap, hctx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),

VARPOINTSTO(base, callerCtx, heap, hctx),

HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),

THISVAR(toMeth, this).
```

rCtx heap calleeCtx

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toMeth

this

#10

Datalog Rules

#10

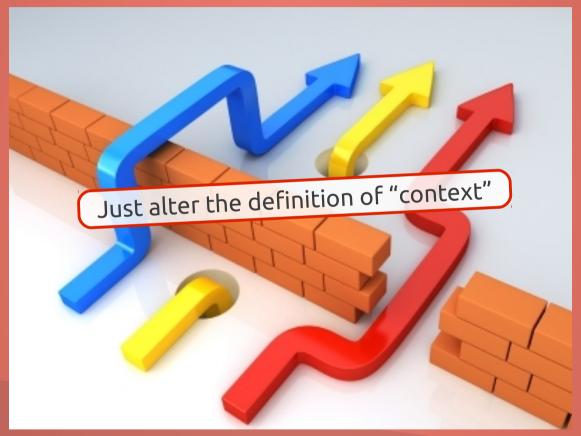
Datalog Rules

9 RULES ARE ENOUGH!

Variety of Analyses



Variety of Analyses



LET'S RECALL WHERE CONTEXTS ARE CREATED

LET'S RECALL WHERE CONTEXTS ARE CREATED

```
RECORD(heap, ctx) = hctx,
VARPOINTSTO(var, ctx, heap, hctx) \leftarrow
REACHABLE(meth, ctx), ALLOC(var, heap, meth).
```

#8

```
MERGESTATIC(invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
SCALL(toMeth, invo, inMeth), REACHABLE(inMeth, callerCtx).
```

```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
VARPOINTSTO(this, calleeCtx, heap, hctx),
CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←
    REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),
    VARPOINTSTO(base, callerCtx, heap, hctx),
    HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),
    THISVAR(toMeth, this).
```

#9

LET'S RECALL WHERE CONTEXTS ARE CREATED

```
RECORD(heap, ctx) = hctx,
```

Object allocation VARPOINTSTO(var, ctx, hear

REACHABLE (ma OC(var, heap, meth).

#3

```
MERGESTATIC(invo, callerCtx) = calleeCtx,
REACHABLE(toMeth, calleeCtx),
                 Method invocation (Infleth, callerCtx).
  CALLGRAPH(invo, callerCtx, toMeth, celterCtx) \leftarrow
       SCALL(toMeth, invo, inMe
```

```
MERGE(heap, hctx, invo, callerCtx) = calleeCtx,
```

REACHABLE(toMeth, calleeCtx),

VARPOINTSTO(this, calleeCtx, heap, hctx),

CALLGRAPH(invo, callerCtx, toMeth, calleeCtx) ←

REACHABLE(inMeth, callerCtx), VCALL(base, sig, invo, inMeth),

VARPOINTSTO(base, callerCtx, heap, hctx),

HEAPTYPE(heap, heapT), LOOKUP(heapT, sig, toMeth),

CONTEXT INSENSITIVE IGNORE CONTEXT ALTOGETHER

CONTEXT INSENSITIVE IGNORE CONTEXT ALTOGETHER

```
void foo() { foo::a → new A1()
   b = id(a);
void bar() {
   a = new A2();
   b = id(a);
A id(A a) {
   return a;
```

```
a = new A1(); bar::a → new A2()
                 id::a \rightarrow new A1(), new A2()
                    foo::b \rightarrow new A1(), new A2()
                    bar::b → new A1(), new A2()
```

CONTEXT INSENSITIVE IGNORE CONTEXT ALTOGETHER

```
RECORD(heap, ctx) = *

MERGE(heap, hctx, invo, callerCtx) = *

MERGESTATIC(invo, callerCtx) = *

Use a single context everywhere!
```

CALL-SITE SENSITIVITY USE CALL-SITES AS CONTEXTS

CALL-SITE SENSITIVITY USE CALL-SITES AS CONTEXTS

```
void foo() {
    a = new A1();
    b = id(a);
}

void bar() {
    a = new A2();
    b = id(a);
}

A id(A a) {
    return a;
}
```

```
foo::a → new A1()
bar::a → new A2()
id::a (inv1) → new A1()
id::a (inv2) → new A2()
foo::b → new A1()
bar::b → new A2()
```



1-CALL-SITE SENSITIVE

RECORD(heap, ctx) = *

No context for heap abstractions

1-CALL-SITE SENSITIVE

```
RECORD(heap, ctx) = *
MERGE(heap, hctx, invo, callerCtx) = invo
MERGESTATIC(invo, callerCtx) = invo
```

1-CALL-SITE SENSITIVE+1-HEAP

Context sensitive heap abstractions

1-CALL-SITE SENSITIVE+1-HEAP

RECORD(heap, ctx) = ctx

1-CALL-SITE SENSITIVE+1-HEAP

RECORD(heap, ctx) = ctx

MERGE(heap, hctx, invo, callerCtx) = invo

MERGESTATIC(invo, callerCtx) = invo

Based on the receiver object in a method call

Really good for Object-Oriented languages

```
class C {
    void meth(Object o) { ... }
}

class Client {
    void bar(C c1, C c2) {
        c1.meth(obj1);
        c2.meth(obj2);
    }
}
```

```
class C {
    void meth(Object o) { ... }
}

class Client {
    void bar(C c1, C c2) {
        ...
        c1.meth(obj1);
        ...
        c2.meth(obj2);
    }
}
```

```
class C {
    void meth(Object o) { ... }
}

class Client {
    void bar(C c1, C c2) {
        ...
        c1.meth(obj1);
        ...
        c2.meth(obj2);
}

#contexts for meth::o?

#co
```

RECORD(heap, ctx) = *

No context for heap abstractions

```
RECORD(heap, ctx) = *
MERGE(heap, hctx, invo, callerCtx) = heap
```

Use the allocation-site of the receiver object

```
RECORD(heap, ctx) = *
MERGE(heap, hctx, invo, callerCtx) = heap
MERGESTATIC(invo, callerCtx) = ctx
```

No receiver object to use!

```
RECORD(heap, ctx) = *

MERGE(heap, hctx, invo, callerCtx) = heap

MERGESTATIC(invo, callerCtx) = ctx
```

No receiver object to use!

Copy context from caller

DIFFERENT CONTEXT DEPTHS

- DIFFERENT CONTEXT DEPTHS
- ALTER DEFINITIONS OF RECORD AND MERGE

- DIFFERENT CONTEXT DEPTHS
- ALTER DEFINITIONS OF RECORD AND MERGE
- OTHER TYPES OF CONTEXT

- DIFFERENT CONTEXT DEPTHS
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- OTHER TYPES OF CONTEXT
- COMBINE DIFFERENT CONTEXTS

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- COMBINE DIFFERENT CONTEXTS

What to combine? Where? How?

RECAP

9 Rules x 3 Context Functions = ∞ Analyses

Hope you enjoyed!

George Kastrinis

http://gkastrinis.info