

## Problem 1

Under the assumption that  $X^T X$  is singular where  $X^T X y = 0$  can have solutions where,  $y \neq 0$ :

$$\begin{aligned} X^T X y &= 0 \\ y^T X^T X y &= 0 \\ (yX)^T X y &= 0 \\ \|Xy\|^2 &= 0 \\ Xy &= 0 \end{aligned}$$

Since  $y \neq 0$  is a valid solution,  $X$  must have linearly dependent columns. Conversely, if we start off with  $X^T X y = 0$  having only the trivial solution  $y = 0$ , then we find that  $Xy = 0$  where only  $y = 0$  is a valid solution. We can see that  $X^T X y = 0$  iff  $X$  has linearly independent columns.

## Problem 2

- a) A symmetric matrix is a matrix where  $A^T = A$ . We first note that the inverse of a transpose is the transpose of an inverse,  $(A^T)^{-1} = (A^{-1})^T$ .

$$\begin{aligned} H^T &= (X(X^T X)^{-1} X^T)^T \\ &= (X^T)^T ((X X^T)^{-1})^T X^T \\ &= X((X X^T)^T)^{-1} X^T \\ &= X(X^T X)^{-1} X^T \\ &= H \end{aligned}$$

Where we see that  $H$  is symmetric.

- b) Suppose that  $H^K = H$ , if we then consider  $H^{K+1}$ :

$$\begin{aligned} H^{K+1} &= H H \\ &= X(X^T X)^{-1} X^T X (X^T X)^{-1} X^T \end{aligned}$$

Where we find  $X^T X (X^T X)^{-1} = I$

$$\begin{aligned} &= X (X^T X)^{-1} X^T \\ &= H \end{aligned}$$

We know that this is true for  $K = 1$ , and thus, is true for  $K = 2, 3, \dots$  for all positive integer  $K$ .

c) Suppose that  $(I - H)^K = I - H$ , if we then consider  $(I - H)^{K+1}$ :

$$\begin{aligned} (I - H)^{K+1} &= (I - H)(I - H) \\ &= II - IH - HI + HH \\ &= I - 2H + HH \end{aligned}$$

Where we have already proved that  $H^n = H$

$$= I - H$$

We know that this is true for  $K = 1$ , and thus, is true for  $K = 2, 3, \dots$  for all positive integer  $K$ .

d)

$$\begin{aligned} \text{Tr}(H) &= \text{Tr}(X(X^T X)^{-1} X^T) \\ &= \text{Tr}((X^T X)^{-1} X^T X) \\ &= \text{Tr}(I) \end{aligned}$$

Where  $I$  has dimension  $M \times M$

$$= M$$

## Problem 3

Given:

$$J(w_0, w_1) = \sum_{n=1}^N \alpha_n (w_0 + w_1 x_{n,1} - y_n)^2$$

We take the derivatives with respect to  $w_0$  and  $w_1$ :

$$\begin{aligned}
 \frac{\partial J}{\partial w_0} &= \frac{\partial}{\partial w_0} \sum_{n=1}^N \alpha_n (w_0 + w_1 x_{n,1} - y_n)^2 \\
 &= \sum_{n=1}^N \alpha_n \frac{\partial}{\partial w_0} (w_0 + w_1 x_{n,1} - y_n)^2 \\
 &= \boxed{2w_0 \sum_{n=1}^N \alpha_n (w_0 + w_1 x_{n,1} - y_n)}
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial J}{\partial w_1} &= \frac{\partial}{\partial w_1} \sum_{n=1}^N \alpha_n (w_0 + w_1 x_{n,1} - y_n)^2 \\
 &= \sum_{n=1}^N \alpha_n \frac{\partial}{\partial w_1} (w_0 + w_1 x_{n,1} - y_n)^2 \\
 &= \boxed{2 \sum_{n=1}^N \alpha_n x_{n,1} (w_0 + w_1 x_{n,1} - y_n)}
 \end{aligned}$$

Having each index  $n$  have different weights in the form of  $\alpha_n$ , items with lower  $\alpha_n$  values do not contribute as strongly to the summation, while items with higher  $\alpha_n$  values affect the derivative more.

## Problem 4

First we take the derivative of  $h_w(x)$ :

$$\begin{aligned}
 \frac{\partial h_w(x)}{\partial w_j} &= \frac{\partial}{\partial w_j} \left( \frac{1}{1 + e^{-w^T x}} \right) \\
 &= (-x_j e^{-w^T x}) (1 + e^{-w^T x})^{-2} \\
 &= x_j h_w(x) (1 - h_w(x))
 \end{aligned}$$

Then taking the derivative of  $J(w)$ :

$$\begin{aligned}
 \frac{\partial J(w)}{\partial w_j} &= \frac{\partial}{\partial w_j} \left[ -\sum_{n=1}^N [y_n \log(h_w(x_n)) + (1 - y_n) \log(1 - h_w(x_n))] + \frac{1}{2} \sum_i w_i^2 \right] \\
 &= -\sum_{n=1}^N \left[ y_n \frac{\partial \log(h_w(x))}{\partial w_j} + (1 - y_n) \frac{\partial \log(1 - h_w(x_n))}{\partial w_j} \right] + w_j \\
 &= -\sum_{n=1}^N \left[ y_n \frac{x_j h_w(x_n)(1 - h_w(x_n))}{h_w(x_n)} + (1 - y_n) \frac{-x_j h_w(x_n)(1 - h_w(x_n))}{(1 - h_w(x_n))} \right] + w_j \\
 &= -\sum_{n=1}^N [y_n x_j (1 - h_w(x_n)) - (1 - y_n) x_j h_w(x_n)] + w_j \\
 &= \boxed{x_j \sum_{n=1}^N [h_w(x_n) - y_n] + w_j}
 \end{aligned}$$

Where we define the change in error to be

$$\begin{aligned}
 \nabla E_{in}(w_t)_j &= \frac{\partial J(w)}{\partial w_j} \\
 &= x_j \sum_{n=1}^N [h_w(x_n) - y_n] + w_j
 \end{aligned}$$

For the update rule:

$$w_{t+1} = w_t - \eta \frac{\nabla E_{in}(w_t)}{\|\nabla E_{in}(w_t)\|}$$

## Problem 5

We first want to take the maximum likelihood product to the log space. Since log is a monotonically increasing function, finding the maximum of the log is the same as finding the maximum of the function itself.

$$\operatorname{argmax}_w \prod_{i=1}^n P(y_i | x_i, w) f(w) \rightarrow \operatorname{argmax}_w \sum_{i=1}^n \log(P(y_i | x_i, w) f(w))$$

For the binary classification done in logistic regression, the conditional probabilities can be written as probabilities of Bernoulli random variables:

$$P(y_i|x_i, w) = \sigma(w^T x_i)^{y_i} (1 - \sigma(w^T x_i))^{1-y_i}$$

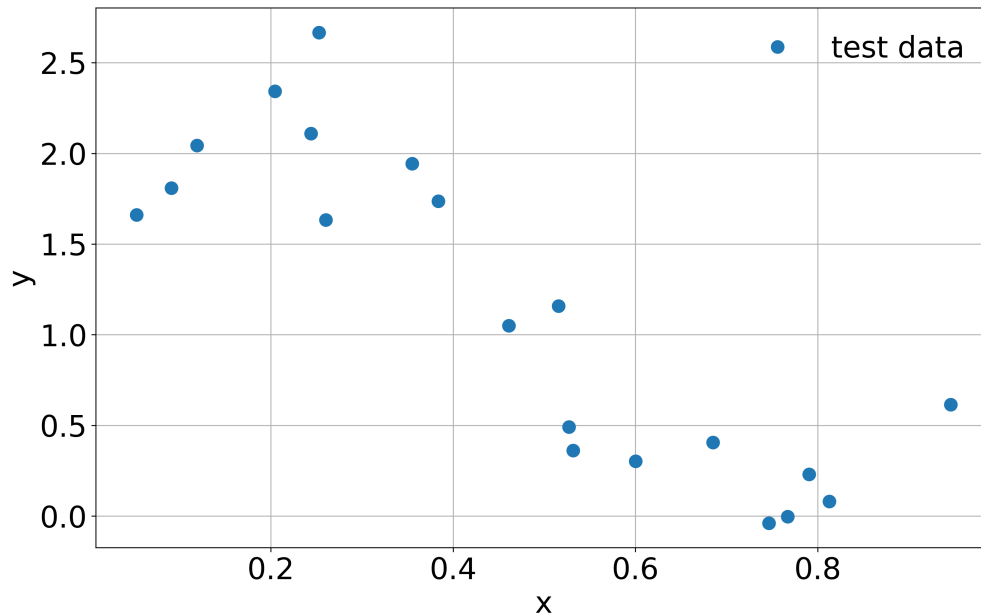
Considering  $\operatorname{argmax}_w \sum_{i=1}^n \log(P(y_i|x_i, w)f(w))$ , we find:

$$\begin{aligned} &\rightarrow \operatorname{argmax}_w \sum_{i=1}^n \log \left[ \sigma(w^T x_i)^{y_i} (1 - \sigma(w^T x_i))^{1-y_i} \frac{1}{(2\pi)^{\frac{m}{2}}} e^{-\sum_{j=1}^m \frac{w_j^2}{2}} \right] \\ &= \operatorname{argmax}_w \sum_{i=1}^n \left[ y_i \log(\sigma(w^T x_i)) + (1 - y_i) \log(1 - \sigma(w^T x_i)) - \frac{m}{2} \log(2\pi) - \sum_{j=1}^m \frac{w_j^2}{2} \right] \\ &= \operatorname{argmin}_w \left( - \sum_{i=1}^n [y_i \log(h_w(x_i)) + (1 - y_i) \log(1 - h_w(x_i))] + \frac{1}{2} \sum_{j=1}^m w_j^2 \right) \end{aligned}$$

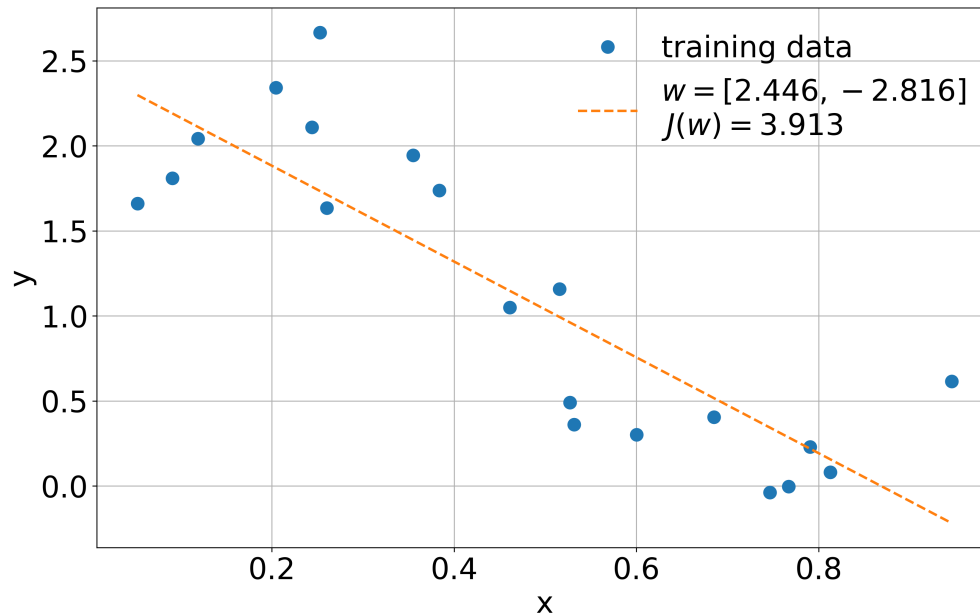
Where we see that the minimization of the argument is the same as the logistic regression object with L2 regularization.

## Problem 6

- a) The training data looks like it has a distinctive downward linear trend. I would believe that the linear regression will make a good prediction on this data set. As long as the test data is not vastly different, it will be a good model.



b) Plotted data shown here

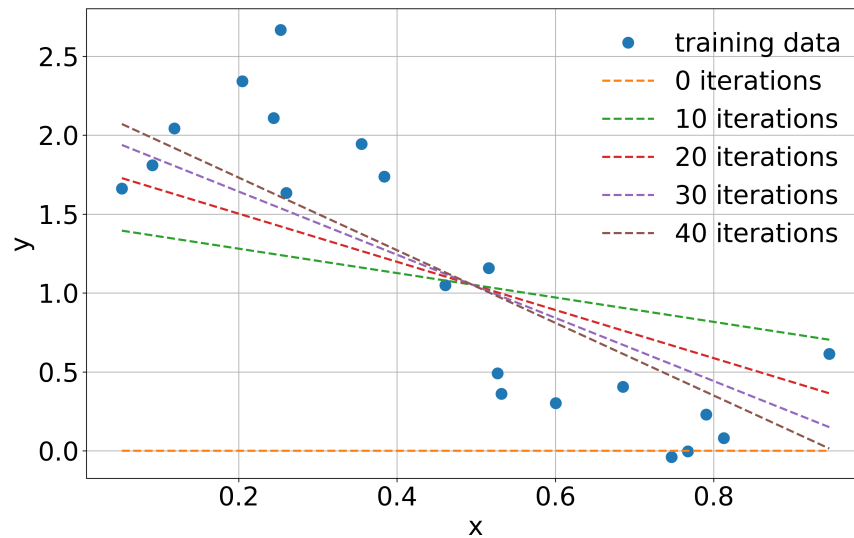


c) As the learning rate  $\eta$  is decreased, the gradient descent fares worse and worse to the point that it does not converge. The non-convergence just means more iterations are needed, but the ones that do converge still are farther away than ones of larger  $\eta$  values. I believe this is due to the fact that making the algorithm stop when the absolute value of the  $J(w)$  difference is not a good stopping condition; this terminates the program when the change is small, not when an equilibrium has been reached.

$\eta$	iterations	$J(w)$
0.0407	104	3.914
0.01	364	3.917
0.001	2609	3.958
0.0001	10000	5.494

d) We find that the greater number of iterations used, the closer the values of  $w$  and  $J(w)$  tend towards the closed form values found in part b).

iterations	$w$	$J(w)$
0	$[0, 0]$	40.234
10	$[1.436, -0.773]$	9.646
20	$[1.808, -1.526]$	6.199
30	$[2.043, -2.002]$	4.824
40	$[2.192, -2.302]$	4.276



- e) From the plot of RMSE, I would say that the  $m = 5$  results in the best fit to the data as it yields the lowest RMSE on the test data. For  $m < 3$ , we find that in general, adding more degrees lowers the RMSE for both training and test data, which seems like under-fitting. When  $m > 8$ , we see the test data's RMSE drastically rise, while the test data's RMSE continues to fall, which is indicative of overfitting.

