

# KRISHNA MURTHY GURUMURTHY

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## EDUCATION

### The University of Texas at Austin, USA

expected August 2020

Doctor of Philosophy in Civil Engineering (*Transportation Engineering*)

GPA: 3.87 / 4.00

Current Courses 'Graduate Research in Statistics'

### The University of Texas at Austin, USA

expected May 2020

Master of Science in Statistics and Data Sciences

GPA: 3.94 / 4.00

Courses 'Design and Analysis of Experiments', 'Mathematical Statistics – II', 'Mathematical Statistics – I', 'Bayesian Statistical Methods', 'Dynamic Traffic Assignment' and 'Public Transportation'

### The University of Texas at Austin, USA

December 2017

Master of Science in Civil Engineering (*Transportation Engineering*)

GPA: 3.81 / 4.00

Thesis [Perceptions and Preferences of Autonomous and Shared Autonomous Vehicles: A Focus on Dynamic Ride-Sharing](#)

Courses 'Statistical Modeling I', 'Advanced Theory of Traffic Flow', 'Optimization I', 'Design and Evaluation of Ground-based Transportation Systems', 'Sensors and Signal Interpretation', 'Transportation Network Analysis', 'Urban Transportation Planning' and 'Linear Regression and Discrete Choice Methods'

### National Institute of Technology Karnataka (NITK), India

May 2016

Bachelor of Technology in Civil Engineering

GPA: 8.92 / 10.00

Courses 'Highway and Traffic Engineering', 'Railways, Tunnels, Harbors and Airports' and 'Traffic Engineering and Management'.

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## EXPERIENCE

### Graduate Research Assistant

Supervisor: Dr. Kara Kockelman

Fall 2016 – Present

Responsible for an ANL project focusing on transportation planning/forecasting for autonomous vehicles *UT Austin*

### Research Aide – Technical

Supervisor: Dr. Joshua Auld

Summer 2018

Tasked with developing algorithms for the control of shared-automated vehicle fleets and implementing the control & optimization algorithms in ANL's POLARIS *Argonne National Laboratory*

### Graduate Teaching Assistant

Course Instructor: Dr. Kara Kockelman

Spring '19

Responsible for students' performance in designing, implementing, collecting and modeling survey data focused on transportation engineering and policy. *UT Austin*

### Graduate Teaching Assistant

Course Instructor: Dr. Kara Kockelman & Ms. Heidi Ross\*

Spring '17, '18\* & '19

Responsible for students' performance, grading, lab lectures (on MicroStation and GEOPAK) and final design-project outcome in a capstone course for transportation engineering *UT Austin*

### Project Research Intern

Supervisors: Drs. Tom V Mathew & Gowri Asaithambi

Spring 2016 – Summer 2016

Tasked with devising incorporating traffic models into existing simulation software *IIT Bombay*

### Summer Research Intern

Supervisor: Dr. Tom V Mathew

Summer 2015

Tasked with devising and programming microscopic traffic model and simulation software in MATLAB *IIT Bombay*

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## PUBLICATIONS

- **Gurumurthy, K.M.**, Kockelman, K. and Simoni, M.D. 2018. Benefits & Costs of Ride-Sharing in Shared Automated Vehicles Across Austin, Texas: Opportunities for Congestion Pricing. *Transportation Research Record* 2673 (6): 548-556.
  - Simoni, Michele D., Kockelman, K., **Gurumurthy, K.M.** and Bischoff, J. 2018. Congestion Pricing in a World of Self-Driving Vehicles: An Analysis of Different Strategies in Alternative Future Scenarios. *Transportation Research Part C: Emerging Technologies* 98: 167-185.
  - **Gurumurthy, K.M.** and Kockelman, K. 2018. Analyzing the Dynamic Ride-Sharing Potential for Shared Autonomous Vehicle Fleets using Cellphone Data from Orlando, Florida. *Computers, Environment and Urban Systems* 71: 177-185.
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## CONFERENCE PAPERS

- Mahmoud, J., Auld, J., and **Gurumurthy, K.M.** 2018. Intra-Household Fully Automated Vehicles Assignment Problem: Model Development and Case Study. Presented at the 98<sup>th</sup> Annual Meeting of the Transportation Research Board.
  - **Gurumurthy, K.M.** and Kockelman, K. 2018. Modeling Americans' Autonomous Vehicle Preferences: A Focus on Dynamic Ride-Sharing, Privacy & Long-Distance Mode Choices. Presented at the 98<sup>th</sup> Annual Meeting of the Transportation Research Board and under review for publication in *Technological Forecasting and Social Change*.
  - Kotagi, P., Asaithambi, G. and **Gurumurthy, K.M.** 2018. Development of Microscopic Simulation Model for Bidirectional Mixed Traffic on Urban Roads. Presented at the 97<sup>th</sup> Annual Meeting of the Transportation Research Board in Washington, D.C.
  - **Gurumurthy, K.M.**, Munigety, C.R., Peeta, S., Mathew, T.V. and Asaithambi, G. 2017. An Integrated Pedestrian Crossing Behavioural Model Using Spring-mass-damper Dynamics. Presented at the 96<sup>th</sup> Annual Meeting of the Transportation Research Board in Washington, D.C.
  - **Gurumurthy, K.M.**, Singh, V. and Asaithambi, G. 2016. Microscopic Analysis of Lateral and Longitudinal Gaps in Mixed Traffic Conditions with Weak Lane Discipline. Presented at the 12<sup>th</sup> International Conference on Transportation Planning and Implementation Methodologies for Developing Countries in Mumbai, India.
  - Munigety, C.R., Gupta, P.A., **Gurumurthy, K.M.**, Peeta, S. and Mathew, T.V. 2016. Vehicle-type Dependent Car following Model Using Spring-mass-damper Dynamics for Heterogeneous Traffic. Presented at the 95<sup>th</sup> Annual Meeting of the Transportation Research Board in Washington, D.C.
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## PRESENTATIONS

- Invited Speaker, at the SESYNC Pursuit: People, Land, Water and Fish - Integrating Social and Environmental Models in the Chesapeake Watershed held in Annapolis, Maryland, presentation titled "Modeling Emerging Modes and Advanced Policies in MATSim", 21-22 February, 2019.
  - Selected Speaker, at the TRB Workshop on Doctoral Research in Transportation Modeling and Travel Behavior held in Washington, D.C., presentation titled "A System of Shared Autonomous Vehicles for Chicago: Anticipating Impacts at Multiple Stages of Adoption", 13 January, 2019.
  - Invited Speaker, at the Machine Intelligence in Autonomous Vehicles Summit held in San Francisco, presentation titled "Anticipating a World of Shared Fully-Automated Vehicles" on behalf of Dr. Kara Kockelman, 23-24 March, 2017.
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## WORKING PAPERS

- **Gurumurthy, K.M.**, Auld, J., and Kockelman, K.M. A System of Shared Autonomous Vehicles for Chicago: Understanding the Effect of Geofencing the Service. *Working Paper*.
  - **Gurumurthy, K.M.**, Kockelman, K.M., and Zuniga-Garcia, N. First-Mile-Last-Mile Collector-Distributor System using Shared Autonomous Mobility. *Working Paper*.
  - Yan, H., Kockelman, K.M., and **Gurumurthy, K.M.** Agent-based Simulation for Shared Autonomous Vehicle Use across the Minneapolis-Saint Paul Region. *Working Paper*.
  - Becker, H., Becker, F., Abe, R., Bekhor, S., Belgiawan, P.F., Compostella, J., Frazzoli, E., Fulton, L.M., Garrick, N., Bicuda, D.G., **Gurumurthy, K.M.**, Hensher, D.A., Joubert, J.W., Kockelman, K.M., Kroger, L., Kuhnimhof, T., Vine, S.L., Malik, J., Marczuk, K., Nasution, R.A., Rich, J., Carrone, A.P., Shen, D., Shiftan, Y., Tirachini, A., Verdis, D., Wong, Y.Z., Zhang, M., Bosch, P.M. and Axhausen, K.W. 2018. Impact of Vehicle Automation and Electric Propulsion on Production Costs for Mobility Services Worldwide. Under review for publication in *Transportation Research Part A: Policy and Practice*.
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## BOOK CHAPTERS & TECHNICAL REPORTS

- Co-author of Chapter 18 in "Smart Transport for Cities & Nations: The Rise of Self-Driving & Connected Vehicles". 2018. Kara Kockelman and Stephen Boyles (Eds). Published by CreateSpace on Amazon.com, August 2018. ISBN-10:0692121501, ISBN-13: 978-0692121504.
- Kockelman, K., Boyles, S., Sturgeon, P., Claudel, C., ... **Gurumurthy, K.M.**, He, D., ... and Yarmohammadisatri, S. "Phase 2 - Bringing Smart Transport to Texans: Ensuring the Benefits of a Connected and Autonomous Transport System in Texas - Final Report". Technical Report FHWA/TX-18/0-6838-3, TxDOT, CTR, UT Austin, TX, July 2018.
- Kockelman, K., Loftus-Otway, L., Stewart, D., Nichols, A., Wagner, W., Boyles, S., Levin, M., Liu, J., Perrine, K., Kilgore, S., and **Gurumurthy, K.M.** "Best Practices for Modifying Transportation Design, Planning, and Project Evaluation in Texas." Report 0-6847-P1, TxDOT, CTR, UT Austin, TX, March 2017.

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## SOFTWARE SKILLS

MATLAB • TransCAD • Java • Microsoft Office Suite • R • ArcGIS • C# • C++ • Python

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## RESEARCH PROJECTS

### **Implementing Shared Autonomous Vehicles in POLARIS and Assessing the Impact of Dynamic Ride-Sharing in Chicago**

Fall 2018 – Present

*UT Austin*

Supervisor: Dr. Kara Kockelman (Sponsored by Argonne National Laboratory)

POLARIS, an agent-based discrete event simulator developed by the Argonne National Laboratory, is being enhanced to simulate shared autonomous vehicles with dynamic ride-sharing capabilities. Policies such as geofencing the service, pre-determined pick-up and drop-off spots, and congestion pricing are being analyzed to understand the future of mobility.

### **First-Mile-Last-Mile Collector-Distributor System Using Shared Autonomous Mobility**

Fall 2018

*UT Austin*

Supervisor: Dr. Randy Machemehl (In a graduate course: CE 392M)

An agent-based simulator, MATSim, was used to analyze an SAV fleet serving as a first-mile-last-mile collector-distributor system. The outcome of the analysis is expected to be a set of parameters (like SAV fares, transit fares and SAV service characteristics) that demarcates between SAVs complementing and supplementing transit.

### **Agent-Based Microsimulations of Shared Autonomous Vehicles in Austin using Dynamic Ride-Sharing on MATSim**

Fall 2016 – Summer 2018

*UT Austin*

Supervisor: Dr. Kara Kockelman (Sponsored by TxDOT)

MATSim (Multi-agent Transport Simulation), an agent-based simulation model was studied to include shared autonomous vehicle simulations. Tolling and AVs were incorporated into an existing SAV module. Several scenarios were run based on different congestion-pricing and fare policies with dynamic ride-sharing being an integral part of the analysis.

### **Nationwide Survey on the Implications of Autonomous Vehicles in the United States**

Spring 2017 – Spring 2018

*UT Austin*

Supervisor: Dr. Kara Kockelman (Sponsored by TxDOT)

A survey with around 70 questions was created to address various issues regarding autonomous vehicles. The main topics targeted in this survey were privacy, security and ethics and questions regarding dynamic ride-sharing. 2,588 respondents were acquired using a panel of Americans by Survey Sampling International.

### **Analyzing the Dynamic Ride-Sharing Potential for Shared Autonomous Vehicle Fleets Using Cellphone Data from Orlando, Florida**

Spring 2017 – Spring 2018

*UT Austin*

Supervisor: Dr. Kara Kockelman (Sponsored by TxDOT)

Cellphone data obtained for Orlando was spatially and temporally disaggregated to have a resolution of one minute and intersection-level detail. Disaggregated data was used to assess the dynamic ride-sharing potential for the region by comparing origin-destination versus en route dynamic ride-sharing. A simulation of a fleet of autonomous vehicles was used to estimate optimal fleet sizes for the region.

### **Estimating a Car-Following Model Based on Spring-Mass-Damper Dynamics using NGSIM Data**

Fall 2017

*UT Austin*

Supervisor: Dr. Christian Claudel (In a graduate course: CE 391F)

An open-source dataset for vehicle trajectories by NGSIM has been used to develop a microscopic car-following model. Model formulation was carried out based on an existing Spring-Mass-Damper based dynamics with certain alterations. Then, data fitting was carried out using non-linear optimization in MATLAB.

### **Evaluating Traffic Characteristics by Mining IMU Data: An Exploratory Study**

Spring 2017

*UT Austin*

Supervisor: Dr. Christian Claudel (In a graduate course: CE 397)

Inertial Measurement Unit (IMU) fitted with a GPS device was used to collect 3-4 hours' worth of data over a period of 7 days. Data was cleaned and processed to ensure segmented continuity and an unsupervised machine learning model was applied. The predictive power of certain pitch and acceleration variables from the IMU was high. The project concluded that better data collection efforts and data tagging can ensure high prediction of traffic characteristics using an IMU.

### **Travel Demand Modeling using TransCAD**

Fall 2016

*UT Austin*

Supervisor: Dr. Kara Kockelman (In a graduate course: CE 391H)

CAMPO Data was used to carry out Travel Demand Modeling in the 6-county region of Austin. Various scenarios were developed and their feasibility was tested. Increasing parking costs in the Central Business District was concluded as a viable scenario to mitigate congestions.

### **A Path-Based Incentive Approach to Achieving System Optimum**

Fall 2016

UT Austin

Supervisor: Dr. Stephen Boyles (In a graduate course: CE 392C)

A mathematical model with equilibrium constraints was developed to achieve system optimum. Budgeted allocation of path-based incentives was analyzed. Significant reductions in travel times based on economic use of funds was the typical end product.

### **Framework for Various Traffic Models under Mixed Traffic Conditions**

Fall 2015 – Spring 2016

NITK & IIT Bombay

Supervisors: Dr. Gowri Asaithambi & Dr. Tom V Mathew

Previous simulation models under mixed traffic conditions were studied to identify important parameters affecting similar conditions. Models for pedestrian crossing, uncontrolled intersections were formulated and executed.

### **Quantitative Determination of Vehicle Influence in Mixed Traffic Conditions**

Fall 2015

NITK

Supervisor: Dr. Gowri Asaithambi

Open access mixed traffic trajectory data collected in Chennai, India was used in this project. Vehicle type dependency and factors affecting the influence was analyzed. Sensitivity analysis was conducted to check the effect of influential parameters.

### **Modeling Mid-Block Sections under Mixed Traffic Conditions**

Summer 2015

IIT Bombay

Supervisor: Dr. Tom V Mathew

The traffic model was theorized based on spring-mass-damper dynamics for integrated movement. Microscopic model for a single vehicle was implemented in Excel and then extrapolated as a Simulator using MATLAB. Extensive test cases were conducted to verify the robustness of the model.

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## **CO-CURRICULARS & VOLUNTEERING**

**Eno Fellow**, Eno Center for Transportation

Class of 2019

**Core Team Member**, UT Austin Traffic Bowl Team

2017 & 2019

**Marketing Coordinator**, UT Apartment's Tenant Advisory Board

Spring 2019 - Present

**Selection Committee**, UT Graduate Student Assembly's Travel Awards

Spring 2019

**Friend**, TRB's ADB40 Committee on Transportation Demand Forecasting

Spring 2018 - Present

**Volunteer**, Women's Transportation Seminars – Heart of Texas' Annual Gala

Spring 2018

**Member & Ex-Officer**, Women's Transportation Seminars, UT Austin Student Chapter

Fall 2017 – Present

**Member & Past President**, Institute of Transportation Engineers, UT Austin Student Chapter

Fall 2016 – Present

**Member & Ex-Officer**, Intelligent Transportation Society of America, UT Austin Student Chapter

Fall 2016 – Present

**Mentor**, Graduates Linked with Undergraduates in Engineering (GLUE)

Fall 2017

**Lead Event Organizer**, Texas Student Leadership Summit

Fall 2017

**Member**, ASCE UT Austin Chapter

Spring 2017 – Fall 2017

**Volunteer**, Clean-up drive organized by Capital Area Section – ITE

Spring 2017

**Executive Member**, ASCE NITK Students' Chapter

Spring 2014 – Spring 2016

**Joint Convener**, Civil Events Committee in 'ENGINEER'

Fall 2015

**Executive Member**, Institution of Engineers – NITK Chapter

Fall 2013 – Spring 2016

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## **PEER REVIEWER - JOURNALS**

*Transportation Research – Part A, Part B, Part C, Part D • Computers, Environment and Urban Systems • Transport Policy • Transportation • Transportation Research Record: Journal of the Transportation Research Board • European Journal of Operational Research*

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## **AWARDS & ACHIEVEMENTS**

- Received the Conference of Minority Transportation Officials (COMTO) scholarship to attend the 2019 Eno Future Leaders Development Conference in Washington, D.C.
- Awarded the Graduate Research Award by the Airport Cooperative Research Program for the period 2018-19.
- Received the Outstanding Student Award at TexITE Spring Meeting in 2018.
- Awarded the CAS-ITE (2017), ITS Texas (2017, 2018) scholarships, and Texas district ITE fellowship award (2017).

- Part of the UT Austin Traffic Bowl Team that won the Texas district championship in Spring 2017 and came second in the International championships in Summer 2017
- Won the “Best Paper Award” at a student-run symposium called “AAKAAR” at IIT Bombay for presenting a paper titled “Quantitative Determination of Vehicle Influence in Mixed Traffic Conditions”.

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## **MENTEES**

Hyungseung (Jeffrey) Hahm • Evelyn Reyes (GLUE)

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W: [gkmurthy10.github.io](https://gkmurthy10.github.io)

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## BIOGRAPHY

Krishna Murthy Gurumurthy is a doctoral student in transportation engineering at The University of Texas at Austin, pursuing his research under Dr Kara Kockelman. He received his master's in civil engineering from UT Austin in December 2017, and a bachelor's from the National Institute of Technology Karnataka, India in May 2016. He is expected to graduate with a Ph.D. in summer of 2020, along with a master's in statistics.

His research focuses on travel demand modeling & forecasting, especially through the utilization of largescale agent-based simulation tools. He is particularly interested in capturing the impacts of shared and automated vehicles (S/AVs) on travel patterns and congestion and measuring the resulting effects of various policies.

Murthy, as he's often called, is an Eno Fellow from the 2019 class, actively participates in events organized by transportation organizations like ITE, ITS and WTS, and has previously served in leadership roles in their respective student chapters at UT. In addition to several scholarships, he is also the recipient of the 'Outstanding Student' award by Texas ITE. In his free time, he enjoys playing basketball and racquetball, and is interested in photography.

