| Desktop — -bash — 80×24 | | | | | |
|-------------------------|------|---------|------------------|-----------|-------------|
| 893 | 8.93 | 636.706 | 1.39172 -9.81 | 8.76783 | 0.0350713 |
| 894 | 8.94 | 636.719 | 1.29327 -9.81 | 8.14759 | 0.0325904 |
| 895 | 8.95 | 636.732 | 1.19484 -9.81 | 7.52751 | 0.03011 |
| 896 | 8.96 | 636.744 | 1.09644 -9.81 | 6.90758 | 0.0276303 |
| 897 | 8.97 | 636.755 | 0.998066 -9.81 | 6.28781 | 0.0251513 |
| 898 | 8.98 | 636.765 | 0.899714 -9.81 | 5.6682 | 0.0226728 |
| 899 | 8.99 | 636.774 | 0.801387 -9.81 | 5.04874 | 0.020195 |
| 900 | 9 | 636.782 | 0.703085 -9.81 | 4.42944 | 0.0177178 |
| 901 | 9.01 | 636.789 | 0.604808 -9.81 | 3.81029 | 0.0152412 |
| 902 | 9.02 | 636.795 | 0.506556 -9.81 | 3.1913 | 0.0127652 |
| 903 | 9.03 | 636.8 | 0.408328 -9.81 | 2.57247 | 0.0102899 |
| 904 | 9.04 | 636.805 | 0.310125 -9.81 | 1.95379 | 0.00781516 |
| 905 | 9.05 | 636.808 | 0.211947 -9.81 | 1.33527 | 0.00534107 |
| 906 | 9.06 | 636.81 | 0.113794 -9.81 | 0.7169 | 0.0028676 |
| 907 | 9.07 | 636.811 | 0.0156651 -9.81 | 0.0986898 | 0.000394759 |
| 908 | 9.08 | 636.811 | -0.0824389 -9.81 | -0.519365 | -0.00207746 |
| 909 | 9.09 | 636.81 | -0.180518 -9.81 | -1.13726 | -0.00454906 |
| 910 | 9.1 | 636.808 | -0.278573 -9.81 | -1.75501 | -0.00702003 |
| 911 | 9.11 | 636.806 | -0.376602 -9.81 | -2.3726 | -0.00949038 |
| 912 | 9.12 | 636.802 | -0.474608 -9.81 | -2.99003 | -0.0119601 |
| 913 | 9.13 | 636.797 | -0.572588 -9.81 | -3.6073 | -0.0144292 |
| 914 | 9.14 | 636.791 | -0.670544 -9.81 | -4.22442 | -0.0168977 |
| 915 | 9.15 | 636.785 | -0.768475 -9.81 | -4.84139 | -0.0193656 |
| 916 | 9.16 | 636.777 | -0.866381 -9.81 | -5.4582 | -0.0218328 |

Columns: "Index", "Timestamp", "Position (m)", "Velocity m/s", "Gravity (m/s/s)", "ARF kg*(m/s^2)", "d(t)"

1.) According to the table the maximum height that the object reaches is 636.808 meters at 9.05 seconds. (I used an interval of 0.01 seconds but technically I could have gone as accurate as I wanted by changing the "interval" variable in the code.

```
🔳 Desktop — -bash — 80×24
2092
      20.92
                         -100.497 -9.81
                                             -633.13
                                                         -2.53252
               12.3634
2093
      20.93
               11.3585
                          -100.57 -9.81
                                            -633.588
                                                         -2.53435
      20.94
               10.3528
                                           -634.046
2094
                         -100.642 - 9.81
                                                         -2.53619
2095
      20.95
               9.34634
                         -100.715 - 9.81
                                           -634.505
                                                         -2.53802
2096
      20.96
               8.33919
                         -100.788 - 9.81
                                            -634.963
                                                         -2.53985
2097
      20.97
               7.33131
                           -100.86 -9.81
                                            -635.421
                                                         -2.54168
2098
      20.98
               6.32271
                         -100.933 -9.81
                                           -635.879
                                                         -2.54351
      20.99
2099
               5.31337
                         -101.006 -9.81
                                           -636.337
                                                         -2.54535
2100
         21
               4.30332
                         -101.078 -9.81
                                           -636.794
                                                         -2.54718
2101
      21.01
               3.29253
                         -101.151 -9.81
                                           -637.252
                                                         -2.54901
                         -101.224 -9.81
2102
                                            -637.709
                                                         -2.55084
      21.02
               2.28102
                         -101.296 -9.81
2103
      21.03
               1.26878
                                           -638.167
                                                         -2.55267
                                                         -2.55449
2104
      21.04
              0.255822
                         -101.369 -9.81
                                           -638.624
      21.05 -0.757867
                         -101.441 -9.81
                                           -639.081
                                                         -2.55632
2105
2106
      21.06
             -1.77228
                         -101.514 -9.81
                                            -639.538
                                                         -2.55815
                         -101.586 -9.81
2107
      21.07
             -2.78742
                                            -639.995
                                                         -2.55998
2108
      21.08
             -3.80328
                         -101.659 -9.81
                                           -640.451
                                                         -2.56181
                         -101.731 -9.81
2109
      21.09
             -4.81987
                                           -640.908
                                                         -2.56363
                         -101.804 -9.81
                                            -641.365
2110
       21.1
             -5.83719
                                                         -2.56546
      21.11
2111
              -6.85523
                         -101.876 -9.81
                                            -641.821
                                                         -2.56728
                         -101.949 -9.81
2112
      21.12
             -7.87399
                                            -642.277
                                                         -2.56911
      21.13
2113
             -8.89348
                         -102.021 -9.81
                                            -642.733
                                                         -2.57093
2114
      21.14
             -9.91369
                         -102.094 -9.81
                                             -643.19
                                                         -2.57276
2115
      21.15 -10.9346
                         -102.166 -9.81
                                           -643.645
                                                         -2.57458
```

^{2.)} According to the table the object hits the ground at 21.04 seconds at a velocity of -101.369 m/s.

```
import math
import pandas as pd
import matplotlib.pyplot as plt

pd.set_option('display.max_rows', None)
pd.set_option('display.max_columns', None)
pd.set_option('display.max_columns', None)

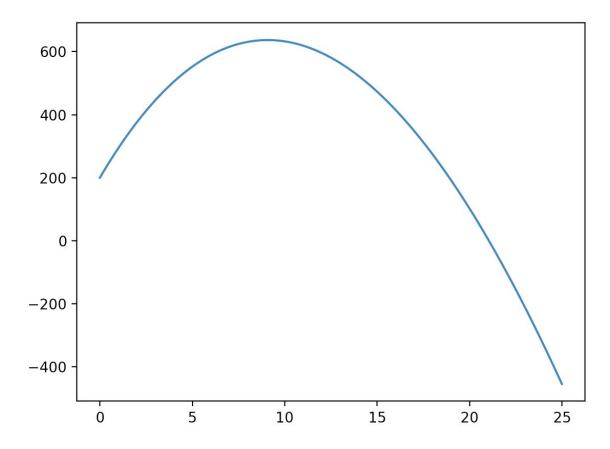
pt.set_option('display.width', None)

thing = pd.DataFrame(columns = ['t','st','vt','at','ARF','dt'])
thing.loc(0,'t'] = 0
thing.loc(0,'st'] = 200
thing.loc(0,'st'] = 100
thing.loc(0,'at'] = -9.81
thing.loc(0,'ARF'] = 0
thing.loc(0,'ARF'] = 0
thing.loc(i,'at'] = 0
interval = 0.01
for i in range(2500):
    thing.loc(i,'at'] = -9.81
    thing.loc(i,'at'] = -9.81
    thing.loc(i,'at'] = -9.81
    thing.loc(i,'at'] = thing.loc(i,'ARF'] / 250
    thing.loc(i,'at'] = thing.loc(i,'dt']*interval + thing.loc(i,'at']*interval + thing.loc(i+1,'st') = -thing.loc(i,'dt']*interval + thing.loc(i,'at']*interval

thing.loc(i+1,'st') = -thing.loc(i,'dt']*interval + thing.loc(i,'at']*interval

thing.loc(i+1,'st','st','vt','at','ARF','dt']]
print(max(thing('st')))
print(max(thing('st')))
print(thing)
plt.figure(1)
```

-Code for project



-Graph of Position vs Time over 25 seconds (sampling every 0.01 seconds)

3.)

- a.) The procedure I used to calculate the data for each row is as follows:
 - Calculate ARF for current row: multiply 6.3 (constant of air resistance) to the velocity of the current row.
 - Calculate d(t) for the current row: divide ARF (current row) by the weight of the object (250 kg).
 - Calculate the velocity of the NEXT row: d(t) * time interval + a(t) * time interval + previous velocity.
 - Calculate position of the next row: current position + current velocity * time interval.
- b.) The advantage of solving this problem numerically is that it is easier to do and requires less thinking than solving it algebraically.
- c.) The disadvantage of solving this problem numerically is that no matter how small you set your time interval you will never get a perfect answer. However if you were able to solve this problem algebraically you would be able to arrive at an exact answer.

- d.) Making a table with a smaller time interval (longer table) would increase accuracy and mostly solve the disadvantage of solving this numerically. However a longer table requires more computing power. There are no disadvantages that could not be solved by making a longer table.
- e.) The way you would go about creating a table accounting for the decrease in air resistance and force of gravity is by changing each of their equations. EX:

The equation for force of gravity is:

$$a(t) = -9.81$$

It is a constant since we are assuming that it is not changing as height increases. In order to model the change you would have to use an equation that calculation that predicts the force of gravity with respect to position.

The equation would look more like this:

$$a(p) = -9.81/p$$

As position increases the force of gravity decreases. You would incorporate this into the table by adding one extra step: Creating a new column with the instantaneous acceleration due to gravity & instantaneous acceleration due to air resistance.

Note: This program can be used as a calculator for problems like this. As long as you change your starting velocity, position, weight, and time interval you can generate a graph of the position vs time of the object. Further, the more you decrease the time interval the more accurate your guess, therefore the maximum accuracy of your answer is proportional to the computing power you have at your disposal.

Full code for this project is on github: