# DRAFT: Discrete differential geometry in homotopy type theory

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## Motivation

Introduction

To use HoTT to study connections and explain their applicability to algebraic topology, via

- the Gauss-Bonnet theorem
- its vast generalization, Chern-Weil theory

## Plan

Introduction

- Manifolds
- Classifying maps
- Connections and curvature
- Theorems

# HoTT background

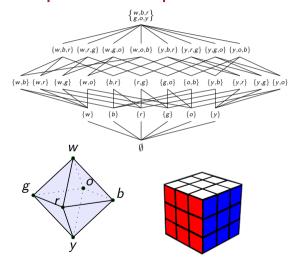
Introduction

- Bezem, M., Buchholtz, U., Cagne, P., Dundas, B. I., and Grayson, D. R., (2021-) Symmetry. https://github.com/UniMath/SymmetryBook.
- Buchholtz, U., Christensen, J. D., Flaten, J. G. T., and Rijke, E. (2023) Central H-spaces and banded types. arXiv:2301.02636
- Scoccola, L. (2020) Nilpotent types and fracture squares in homotopy type theory, MSCS 30(5). arXiv:1903.03245

## Discrete manifolds in HoTT

- Recall the classical theory of simplicial complexes
- Define a realization functor to turn them into homotopy pushouts

# Simplicial complexes



A Hasse diagram of a simplicial complex (vertices named for the colors on a Hungarian Cube)

Form a pushout of edges to create a 1-type.

$$egin{aligned} \mathcal{M}_1 imes \partial \Delta^1 & \stackrel{\mathrm{pr}_1}{\longrightarrow} \mathcal{M}_1 \ & & \downarrow_{h_1} & \downarrow_{*_{\mathbb{M}_1}} \ & \mathcal{M}_0 = \mathbb{M}_0 & \longrightarrow & \mathbb{M}_1 \end{aligned}$$

 $\partial \Delta^1$  is a 0-sphere: the set  $\{a, b\}$ .

#### **Definition**

An n-gon  $\mathbb{C}(n)$  is the realization of a complex C(n):

$$C(n)_0 = \{v_1, \dots, v_n\}$$
  
 $C(n)_1 = \{e_1 = \{v_1, v_2\}, \dots, e_{n-1} = \{v_{n-1}, v_n\}, e_n = \{v_n, v_0\}\}$ 

Toss in two non-complexes

$$\mathbb{C}(1) \stackrel{\mathrm{def}}{=} S^1, \quad \mathbb{C}(2) \stackrel{\mathrm{def}}{=} \ell_{12} \stackrel{\mathbf{v}_1}{\bigcirc} r_{21}$$

Then push out faces o from a 2-dim type.

$$egin{aligned} \mathcal{M}_1 imes \partial \Delta^1 & \stackrel{\operatorname{pr}_1}{\longrightarrow} \mathcal{M}_1 \ & & \downarrow^{st_{\mathbb{M}_1}} & \downarrow^{st_{\mathbb{M}_1}} \ \mathcal{M}_0 &= & \mathbb{M}_0 & \stackrel{\operatorname{pr}_1}{\longrightarrow} & \mathbb{M}_1 & \stackrel{h_2}{\longrightarrow} & \uparrow^{st_{\mathbb{M}_2}} \ & & & \downarrow^{h_2} & \uparrow^{st_{\mathbb{M}_2}} \ \mathcal{M}_2 imes \partial \Delta^2 & \stackrel{\operatorname{pr}_1}{\longrightarrow} & \mathcal{M}_2 \end{aligned}$$

 $\partial \Delta^2$  is a 1-sphere, i.e.  $\mathbb{C}(3)$ .

#### Lemma

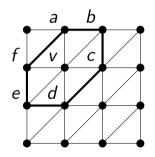
 $\mathbb{C}(2) \simeq \mathbb{C}(1)$  and in general  $\mathbb{C}(n) \simeq \mathbb{C}(n-1)$ .

## Corollary

All n-gons are equivalent to  $S^1$ .

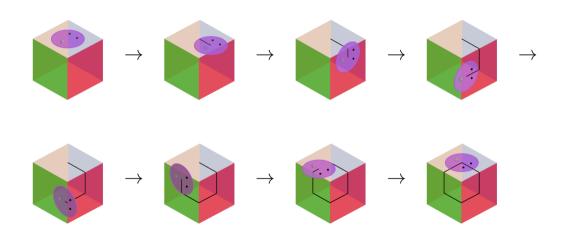
 $*_{\mathbb{M}_1}$ ,  $*_{\mathbb{M}_2}$  provide hubs.  $h_1$ ,  $h_2$  provide spokes.

$$M_1 imes \partial \Delta^1 \stackrel{\operatorname{pr}_1}{\longrightarrow} M_1$$
 $A_0 \downarrow \qquad \qquad \downarrow^{*_{\mathbb{M}_1}} \downarrow^{*_{\mathbb{M}_1}}$ 
 $M_0 = \mathbb{M}_0 \stackrel{\longrightarrow}{\longrightarrow} \mathbb{M}_1 \stackrel{h_2}{\longrightarrow} \mathbb{M}_2$ 
 $A_1 \uparrow \qquad \qquad \downarrow^{h_2} \uparrow^{*_{\mathbb{M}_2}}$ 
 $M_2 imes \partial \Delta^2 \stackrel{\operatorname{pr}_1}{\longrightarrow} M_2$ 



The link of a vertex v in a 2-complex is the polygon of edges not containing v but whose union with v is a face.

This will be our model of the tangent space.



## Rotation

Let  $R : [abcd] \rightarrow [abcd]$  send  $a \mapsto b, b \mapsto c, c \mapsto d, d \mapsto a$ .

Extend R to edges.

#### Lemma

 $[\![R]\!]$ :  $[\![abcd]\!] \to [\![abcd]\!]$  is homotopic to the identity, i.e. we have  $\prod_{x:[\![abcd]\!]} x = [\![R]\!](x)$ .

### Proof.

Use edges.

Let G be a group with identity element e. A G-set is a set X equipped with a homomorphism  $\phi:(G,e)\to \operatorname{Aut}(X)$ . If we have

$$\mathsf{is\_torsor}(X,\phi) \stackrel{\mathrm{def}}{=} ||X||_{-1} \times \prod_{x:X} \mathsf{is\_equiv}(\phi(-,x) : (G,e) \to (X,x))$$

we say  $(X, \phi)$  is a G-torsor. Denote the type of G-torsors by BG.

#### Lemma

Point BG at  $G_{reg}$ , the G-torsor G acting on itself on the right. Then  $\Omega_{G_{reg}}BG \simeq G$ , so BG is a  $\mathrm{K}(G,1)$ .

- $S^1 \cdot \mathcal{U}$  is not an Aut  $S^1$ -torsor
- It's a torsor for  $(S^1 = S^1)_{(id)}$ , the identity component.
- This omits the flip, the reversal of orientation.

Torsors 000

• See the Buchholtz et. al. H-spaces paper for more.

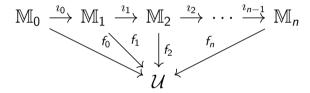
$$\mathrm{EM}(G,n)\stackrel{\mathrm{def}}{=} \mathsf{BAut}(\mathrm{K}(G,n))\stackrel{\mathrm{def}}{=} \sum_{Y:\mathcal{U}}||Y\simeq \mathrm{K}(G,n)||_{-1}$$

#### Definition

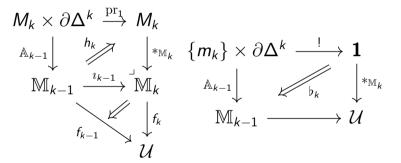
A K(G, n)-bundle on a type M is a map  $f: M \to EM(G, n)$ .

We further assume f factors through K(G, n+1) and so is principal.

If  $\mathbb{M} \stackrel{i_0}{=} \mathbb{M}_0 \xrightarrow{i_0} \cdots \xrightarrow{i_{n-1}} \mathbb{M}_n$  is a cellular type and all the triangles commute in the diagram:



- The map  $f_k$  is a k-bundle on  $\mathbb{M}$ .
- The pair given by the map  $f_k$  and the proof  $f_k \circ i_{k-1} = f_{k-1}$ , i.e. that  $f_k$  extends  $f_{k-1}$  is called a k-connection on the (k-1)-bundle  $f_{k-1}$ .

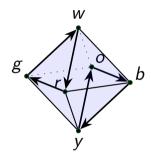


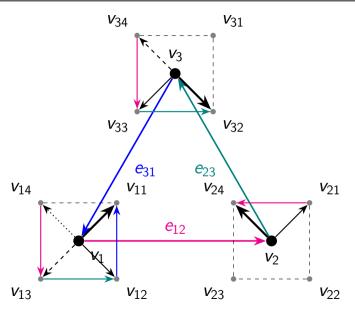
the filler  $\flat_k$  is called a flatness structure for the face  $m_k$ , and its ending path is called curvature at the face  $m_k$ .

## Vector fields

Let  $T: \mathbb{M}_2 \to \mathrm{K}(\mathbb{Z},2)$  be an oriented tangent bundle on an oriented 2-dim cellular type

- A vector field is a term  $X : \prod_{m:\mathbb{M}_1} Tm$ .
- It's a nonvanishing vector field on the 1-skeleton.
- We model classical zeros by omitting the faces.





- $\partial F \stackrel{\text{def}}{=} e_{12} \cdot e_{23} \cdot e_{31}$
- We access pathovers asymmetrically:  $X_{12}: T_{12}X_1 = X_2$
- $X(\partial F)$  is 3-sided

inside a square

• To make a loop we cat with  $\flat(\partial F)$ 

holonomy

flatness

$$\operatorname{\sf tr}_F \stackrel{\mathrm{def}}{=} \operatorname{\sf tr}(\partial F)$$
 :  $Tm = Tm$ 

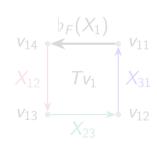
$$b_F \stackrel{\text{def}}{=} b(\partial F) \quad : \text{id} =_{Tm=Tm} \text{tr}(\partial F)$$

$$X_F \stackrel{\text{def}}{=} X(\partial F)$$
 :  $\operatorname{tr}(\partial F)(X(m)) =_{T_m} X(m)$  swirling

## Definition

The index of the vector field X on the face F is the integer

$$I_F^X \stackrel{\mathrm{def}}{=} \Omega(\flat_F(X(m)) \cdot X_F) : \Omega(X(m) =_{Tm} X(m)).$$



holonomy

flatness

$$\operatorname{\sf tr}_F \stackrel{\operatorname{def}}{=} \operatorname{\sf tr}(\partial F) : Tm = Tm$$

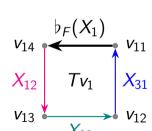
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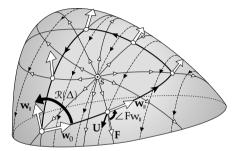
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# Classical proof



**[26.2]** The difference  $\Re(\Delta) - 2\pi \Im_F(s)$  can be found by summing over the edges  $K_j$  the change  $\Phi(K_j)$  in the illustrated angle  $\angle FW_{||}$  i.e., the rotation of  $\mathbf{w}_{||}$  relative to  $\mathbf{F}$ .

Figure: Needham, T. (2021) Visual Differential Geometry and Forms.

- The classical proof is discrete-flavored
- " $\angle Fw_{||}$ " looked a lot like a pathover.
- Hopf's Φ is defined on edges, not loops. We imitated that too.