OpenGL Sphere

Related Topics: OpenGL Cylinder, Prism & Pipe, Cone & Pyramid, Torus

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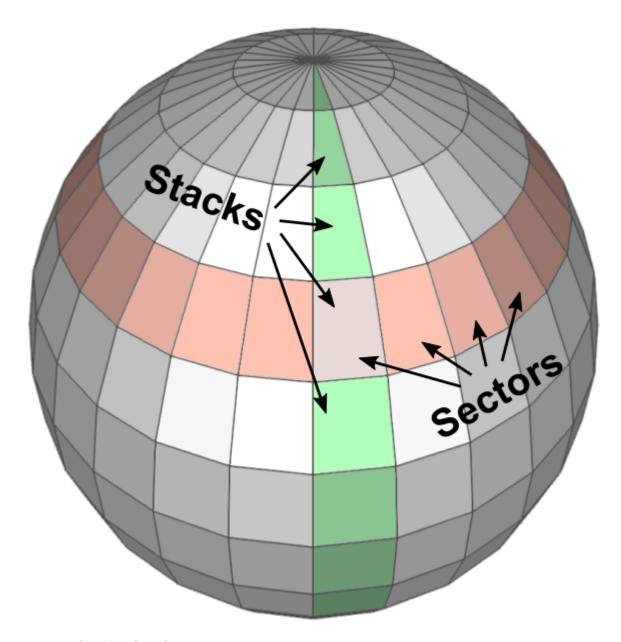
This page describes how to generate various spherical geometries using C++ and how to draw them with OpenGL.

Sphere

The definition of sphere is a 3D closed surface where every point on the sphere is same distance (radius) from a given point. The equation of a sphere at the origin is $x^2+y^2+z^2=r^2$.

Since we cannot draw all the points on a sphere, we only sample a limited amount of points by dividing the sphere by sectors (longitude) and stacks (latitude). Then connect these sampled points together to form surfaces of the sphere.





Sectors and stacks of a sphere

An arbitrary point (x, y, z) on a sphere can be computed by parametric equations with the corresponding sector angle θ and stack angle ϕ .

$$x = (r \cdot \cos \phi) \cdot \cos \theta$$

$$y = (r \cdot \cos \phi) \cdot \sin \theta$$

$$z = r \cdot \sin \phi$$

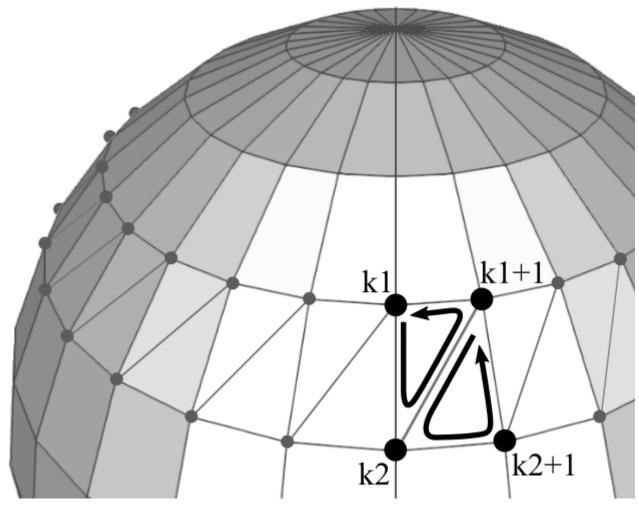
The range of sector angles is from 0 to 360 degrees, and the stack angles are from 90 (top) to -90 degrees (bottom). The sector and stack angle for each step can be calculated by the following; $\theta = 2\pi \cdot \frac{\text{sectorStep}}{\text{sectorCount}}$

$$\theta = 2\pi \cdot \frac{\text{sectorStep}}{\text{sectorCount}}$$

$$\phi = \frac{\pi}{2} - \pi \cdot \frac{\text{stackStep}}{\text{stackCount}}$$

The following C++ code generates all vertices of the sphere for the given radius, sectors and stacks. It also creates other vertex attributes; surface normals and texture coordinates. For more details, please refer to **buildVerticesSmooth()** or **buildVerticesFlat()** functions in **Sphere.cpp** class.

```
// clear memory of prev arrays
std::vector<float>().swap(vertices);
std::vector<float>().swap(normals);
std::vector<float>().swap(texCoords);
                                                        // vertex position
float x, y, z, xy;
float nx, ny, nz, lengthInv = 1.0f / radius;
                                                       // vertex normal
float s, t;
                                                        // vertex texCoord
float sectorStep = 2 * PI / sectorCount;
float stackStep = PI / stackCount;
float sectorAngle, stackAngle;
for(int i = 0; i <= stackCount; ++i)</pre>
    stackAngle = PI / 2 - i * stackStep;
xy = radius * cosf(stackAngle);
z = radius * sinf(stackAngle);
                                                         // starting from pi/2 to -pi/2
                                                        // r * cos(u)
// r * sin(u)
    // add (sectorCount+1) vertices per stack
     // first and last vertices have same position and normal, but different tex coords
     for(int j = 0; j <= sectorCount; ++j)</pre>
         sectorAngle = j * sectorStep;
                                                        // starting from 0 to 2pi
         // vertex position (x, y, z)
         x = xy * cosf(sectorAngle);
y = xy * sinf(sectorAngle);
                                                        // r * cos(u) * cos(v)
                                                        // r * cos(u) * sin(v)
         vertices.push_back(x);
         vertices.push_back(y);
         vertices.push_back(z);
         // normalized vertex normal (nx, ny, nz)
         nx = x * lengthInv;
ny = y * lengthInv;
         nz = z * lengthInv;
         normals.push_back(nx);
         normals.push_back(ny);
         normals.push_back(nz);
         // vertex tex coord (s, t) range between [0, 1]
         s = (float)j / sectorCount;
t = (float)i / stackCount;
         texCoords.push_back(s);
         texCoords.push_back(t);
    }
}
```



vertex indices to draw triangles of a sphere

In order to draw the surface of a sphere in OpenGL, you must triangulate adjacent vertices to form polygons. It is possible to use a single triangle strip to render the whole sphere. However, if the shared vertices have different normals or texture coordinates, then a single triangle strip cannot be used.

Each sector in a stack requires 2 triangles. If the first vertex index in the current stack is k1 and the next stack is k2, then the counterclockwise orders of vertex indices of 2 triangles are;

$$k1 \longrightarrow k2 \longrightarrow k1+1$$

 $k1+1 \longrightarrow k2 \longrightarrow k2+1$

But, the top and bottom stacks require only one triangle per sector. The code snippet to generate all triangles of a sphere may look like;

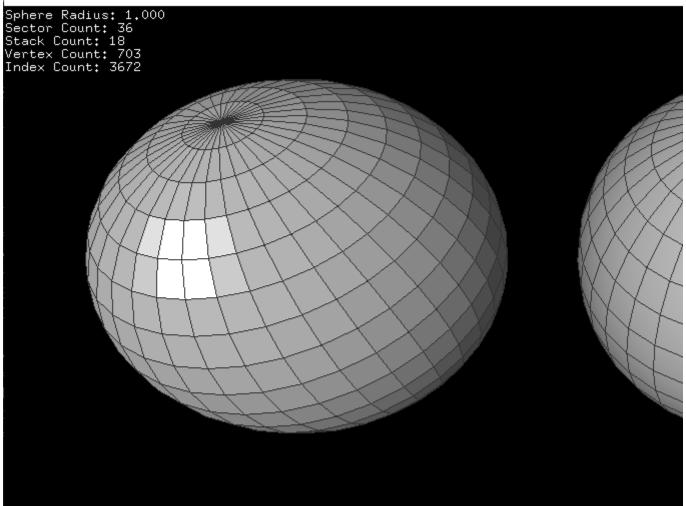
```
// generate CCW index list of sphere triangles
// k1--k1+1
// | / |
// | / |
// k2--k2+1
std::vector<int> indices;
std::vector<int> lineIndices;
int k1, k2;
for(int i = 0; i < stackCount; ++i)</pre>
     k1 = i * (sectorCount + 1);
                                           // beginning of current stack
     k2 = k1 + sectorCount + 1;
                                           // beginning of next stack
     for(int j = 0; j < sectorCount; ++j, ++k1, ++k2)
         // 2 triangles per sector excluding first and last stacks // k1 => k2 => k1+1 if(i != 0)
              indices.push_back(k1);
              indices.push back(k2);
              indices.push_back(k1 + 1);
         // k1+1 => k2 => k2+1
LOG
```

```
if(i != (stackCount-1))
{
    indices.push_back(k1 + 1);
    indices.push_back(k2);
    indices.push_back(k2 + 1);
}

// store indices for lines
// vertical lines for all stacks, k1 => k2
lineIndices.push_back(k1);
lineIndices.push_back(k2);
if(i != 0) // horizontal lines except 1st stack, k1 => k+1
{
    lineIndices.push_back(k1);
    lineIndices.push_back(k1);
    lineIndices.push_back(k1 + 1);
}
}
```

Example: Sphere

C:\song\scripts\cpp\opengl\sphere\bin\sphere.exe



Download: sphere.zip, <a href="mai

This example constructs spheres with 36 sectors and 18 stacks, but with different shadings; flat, smooth or textured. Sphere.cpp class provides pre-defined functions; draw(), drawWithLines() and drawLines(), to draw a sphere using OpenGL VertexArray.

By default, the north pole of the sphere is facing to +Z axis. But, it can be changed by the last parameter of Sphere class contructor (X=1, Y=2, or Z=3), or by calling **setUpAxis()** function after it is constructed.

```
// create a sphere with radius=1, sectors=36, stacks=18,
// smooth=true(default), up-axis=Z(default)
Sphere sphere(1.0f, 36, 18);
Sphere sphere(1.0f, 36, 18, true, 3); // same as above
LOG
```

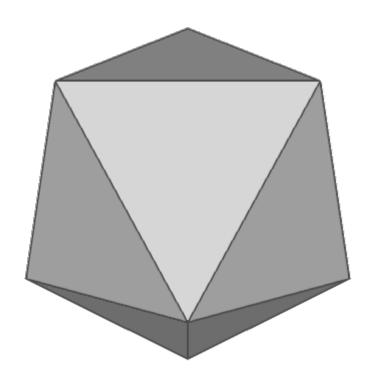
This C++ class also provides **getVertices()**, **getIndices()**, **getInterleavedVertices()**, etc. in order to access the vertex data in GLSL. The following code draws a sphere with interleaved vertex data using <u>VBO</u>, VAO and GLSL. Or, download <u>sphereShader.zip</u> (with GLFW) for more details.

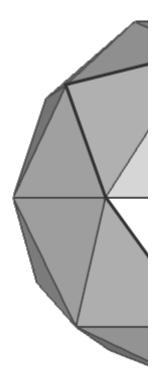
```
// create a sphere with default params;
// radius=1, sectors=36, stacks=18, smooth=true
Sphere sphere:
// create VAO to store all vertex array state to VAO
GLuint vaoId;
glGenVertexArrays(1, &vaoId);
glBindVertexArray(vaoId);
// create VBO to copy interleaved vertex data (V/N/T) to VBO
GLuint vboId;
glGenBuffers(1, &vboId);
glBindBuffer(GL ARRAY BUFFER, vboId);
                                                // for vertex data
glBufferData(GL_ARRAY_BUFFER,
                                                // target
             sphere.getInterleavedVertexSize(), // data size, # of bytes
                                               // ptr to vertex data
             sphere.getInterleavedVertices(),
             GL STATIC_DRAW);
                                                // usage
// create VBO to copy index data to VBO
GLuint iboId;
glGenBuffers(1, &iboId);
glBindBuffer(GL_ELEMENT_ARRAY_BUFFER, iboId);
                                                // for index data
glBufferData(GL_ELEMENT_ARRAY_BUFFER,
                                                // target
             sphere.getIndexSize(),
                                                // data size, # of bytes
                                               // ptr to index data
             sphere.getIndices(),
             GL STATIC DRAW);
                                                // usage
// activate attrib arrays
glEnableVertexAttribArray(attribVert);
glEnableVertexAttribArray(attribNorm);
glEnableVertexAttribArray(attribTex);
// set attrib arrays with stride and offset
int stride = sphere.getInterleavedStride();
                                                // should be 32 bytes
glVertexAttribPointer(attribVert, 3, GL_FLOAT, false, stride, (void*)0);
glVertexAttribPointer(attribNorm, 3, GL_FLOAT, false, stride, (void*)(sizeof(float)*3));
glVertexAttribPointer(attribTex, 2, GL_FLOAT, false, stride, (void*)(sizeof(float)*6));
  unbind VAO and VBOs
glBindVertexArray(0);
glBindBuffer(GL ARRAY BUFFER, 0);
glBindBuffer(GL ELEMENT ARRAY BUFFER, 0);
// draw a sphere with VAO
glBindVertexArray(vaoId);
glDrawElements(GL_TRIANGLES,
                                                // primitive type
               sphere.getIndexCount(),
                                                // # of indices
               GL_UNSIGNED_INT,
                                                // data type
               (void*)0):
                                                // offset to indices
// unbind VAO
glBindVertexArray(0);
```

Since this C++ class uses cylindrical texture mapping, there is a squeeze/distortion at the north and south pole area. This problem can be solved using <u>lcosphere</u> or <u>Cubesphere</u>.

Icosphere / Geosphere

Another way to create a spherical geometry is subdividing an icosahedron multiple times. Icosahedron is a regular polyhedron with 12 vertices and 20 equilateral triangles (the first left image below). Each triangle of an icosa' is divided into multiple equal sub-triangles per subdivision. If the subdivision frequency is 3, it becomes a so like grometry, with 20 hexgonal surfaces and 12 pentagonal surfaces by combining multiple triangles.

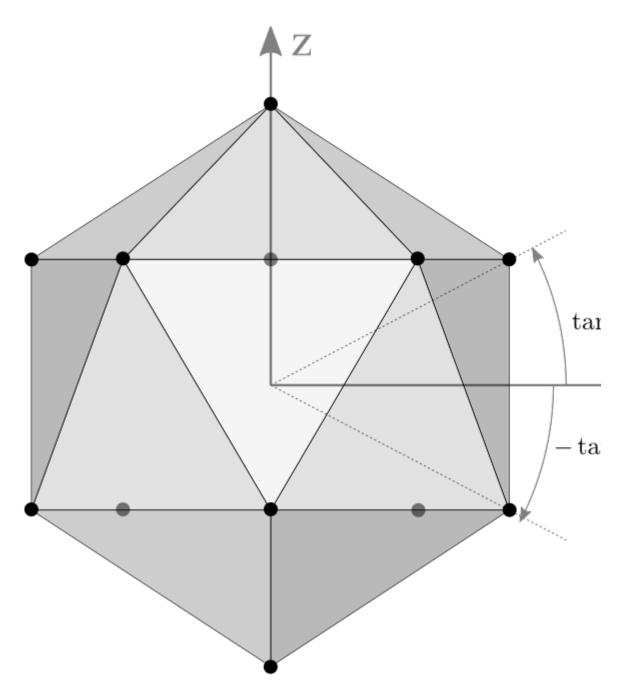




Icosphere at subdivision 1

Icosphere at subdivision 2

One way to construct 12 vertices of an icosahedron is using spherical coordinates; aligning 2 vertices at the north and south poles, and the other 10 vertices are placed at latitude $\pm \tan^{-1}(\frac{1}{2})$ degrees and 72° aside on the same latitude. Please see the following orthogonal projection images of icosahedron.



Side View of Icosahedron

2 vertices are at north/south pole and 10 vertices are at elevation ±26.565°

A typical point at latitude 26.565° and radius r can be computed by;

$$x = r \cdot \cos\left(\tan^{-1}\left(\frac{1}{2}\right)\right) \cdot \cos(72 * n)$$
$$y = r \cdot \cos\left(\tan^{-1}\left(\frac{1}{2}\right)\right) \cdot \sin(72 * n)$$

$$z = r \cdot \sin\left(\tan^{-1}\left(\frac{1}{2}\right)\right)$$

Note that $r \cdot \sin\left(\tan^{-1}\left(\frac{1}{2}\right)\right)$ is the elevation (height) of the point and $r \cdot \cos\left(\tan^{-1}\left(\frac{1}{2}\right)\right)$ is the length of the projected line segment on XY plane.

(Reference: Spherical Coordinates of Regular Icosahedron from Wikipedia)

The following C++ code is to generate 12 vertices of an icosahedron for a given radius, or you can find the implementation of Icosahedron.cpp or <a href="

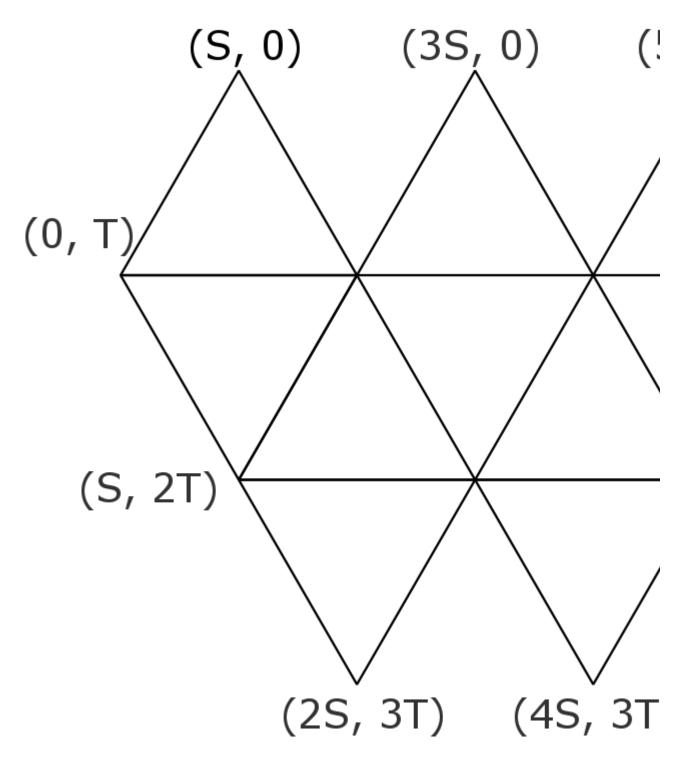
```
// constants
const float PI = 3.1415926f;
const float H_ANGLE = PI / 180 * 72;
                                              // 72 degree = 360 / 5
const float V_ANGLE = atanf(1.0f / 2); // elevation = 26.565 degree
std::vector<float> vertices(12 * 3);
                                              // array of 12 vertices (x,y,z)
int i1, i2;
                                               // indices
float z, xy;
                                               // coords
float hAngle1 = -PI / 2 - H ANGLE / 2; // start from -126 deg at 1st row
float hAngle2 = -PI / 2;
                                              // start from -90 deg at 2nd row
// the first top vertex at (0, 0, r)
vertices[0] = 0;
vertices[1] = 0;
vertices[2] = radius;
// compute 10 vertices at 1st and 2nd rows
for(int i = 1; i \le 5; ++i)
     i1 = i * 3;
                           // index for 1st row
     i2 = (i + 5) * 3; // index for 2nd row
    z = radius * sinf(V_ANGLE);
xy = radius * cosf(V_ANGLE);
                                                   // elevaton
                                                   // length on XY plane
    vertices[i1] = xy * cosf(hAngle1);
                                                   // x
    vertices[i1] = xy * cost(nAngle1); // x
vertices[i2] = xy * cosf(hAngle2);
vertices[i1 + 1] = xy * sinf(hAngle1); // y
vertices[i2 + 1] = xy * sinf(hAngle2);
    vertices[i1 + 2] = z;
                                                   // z
    vertices[i2 + 2] = -z;
     // next horizontal angles
     hAngle1 += H ANGLE;
    hAngle2 += H_ANGLE;
}
// the last bottom vertex at (0, 0, -r)
i1 = 11 * 3:
vertices[i1] = 0;
vertices[i1 + 1] = 0;
vertices[i1 + 2] = -radius;
```

The subdivision algorithm is splitting the 3 edge lines of each triangle into N segments, then extruding the new point outward, so its length (the distance from the center) is the same as sphere's radius.

```
std::vector<float> tmpVertices;
std::vector<float> tmpIndices;
std::vector<float> newVs((subdivision+1) * (subdivision+2) / 2 * 3); const float *v1, *v2, *v3; // ptr to original vertices of a
const float *v1, *v2, *v3; // ptr to original vertices of a triangle float newV1[3], newV2[3], newV3[3]; // new vertex positions
unsigned int index = 0;
int i, j, k;
float a:
                                          // lerp alpha
unsigned int i1, i2;
                                          // indices
// copy prev arrays
tmpVertices = vertices;
tmpIndices = indices;
// iterate each triangle of icosahedron
for(i = 0; i < tmpIndices.size(); i += 3)</pre>
     // get 3 vertices of a triangle of icosahedron
    v1 = &tmpVertices[tmpIndices[i] * 3];
v2 = &tmpVertices[tmpIndices[i + 1] *
     v3 = &tmpVertices[tmpIndices[i + 2] * 3];
     // add top vertex (x,y,z)
    newVs.clear();
    newVs.insert(newVs.end(), v1, v1+3);
     // find new vertices by subdividing edges
     for(j = 1; j \le subdivision; ++j)
         a = (float)j / subdivision; // lerp alpha
         // find 2 end vertices on the edges of the current row
                                      //
// if N = 3,
         //
                       v1
         //
                      / \
                                                                                                                                 1
         //
                                      // lerp alpha = 1 / N
         // /\ /\ /\ //
// newV1*---*--* newV2 // lerp alpha = 2 / N
                / \newV3/ \
                                    //
                v2--*---v3
LOG
         Icosphere::interpolateVertex(v1, v2, a, radius, newV1);
```

```
Icosphere::interpolateVertex(v1, v3, a, radius, newV2);
         for(k = 0; k \le j; ++k)
             if(k == 0)
                               // new vertex on the left edge, newV1
                  newVs.insert(newVs.end(), newV1, newV1+3);
             else if(k == j) // new vertex on the right edge, newV2
                 newVs.insert(newVs.end(), newV2, newV2+3);
                               // new vertices between newV1 and newV2
                  a = (float)k / j;
                  Icosphere::interpolateVertex(newV1, newV2, a, radius, newV3);
                  newVs.insert(newVs.end(), newV3, newV3+3);
         }
    }
    // compute sub-triangles from new vertices
    for(j = 1; j <= subdivision; ++j)</pre>
         for(k = 0; k < <; ++k)
         {
             // indices
             i1 = (j - 1) * j / 2 + k; // index from prev row i2 = j * (j + 1) / 2 + k; // index from curr row
             v1 = \&newVs[i1 * 3];
             v2 = &newVs[i2 * 3];
v3 = &newVs[(i2+1) * 3];
             addVertices(v1, v2, v3);
              // add indices
             addIndices(index, index+1, index+2);
             index += 3; // next index
             // if K is not the last, add adjacent triangle
             if(k < (j-1))
                  i2 = i1 + 1; // next of the prev row
                  v2 = &newVs[i2 * 3];
addVertices(v1, v3, v2);
                  addIndices(index, index+1, index+2);
                  index += 3;
             }
        }
    }
}
```

In order to generate a texture map of an icosphere, you need to unwrap the 3D geometry on a plane (paper model). I use the following texture coordinates of vertices instead of normalized coordinates from 0 to 1, so the coordinate of each vertex can be snapped to an exact pixel on the image. For example, if a texture size is 2048x1024, then the horizontal step is 186 pixels and the vertical step is 322 pixels.

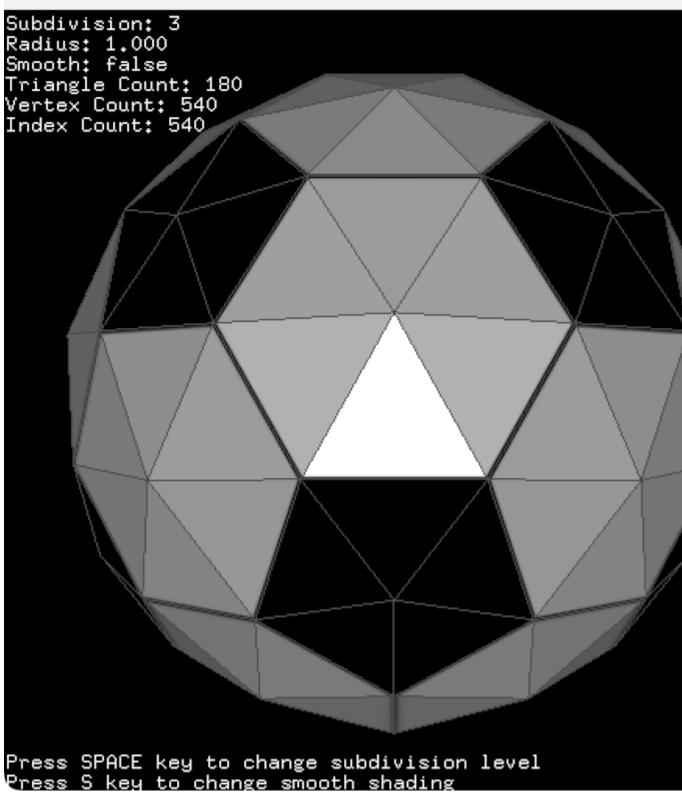


Texture coordinates of Icosphere, where S=186/2048, T=322/1024

Example: Icosphere







This example is to draw an icosphere with a texture. Press the spacebar key to change the subdivision level. If the subdivision frequency is 3, the icosphere consists of 180 triangles, and if the subdivision is 6, it has 720 triangles. It includes a texture template of soccer ball which consists of 20 hexagon surfaces and 12 pentagon surfaces. **Download:** icosphere.zip, icosphereShader.zip (GLFW), icosahedron.zip (Updated: 2024-09-02)

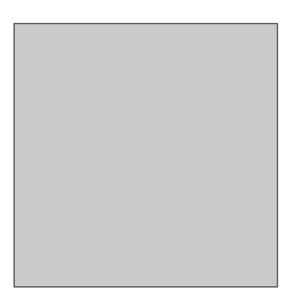
Drawing an icosphere in OpenGL is identical to Sphere C++ class object. Please refer to <u>Sphere example</u> section above. To construct an icosphere object, it requires 3 parameters; radius, subdivision and surface smoothness. You can change the radius and subdivision level after it has been constructed. If the subdivision level is 1, then it is the same as an icosahedron.

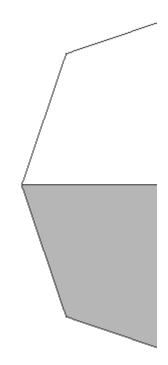
```
// can change parameters later
sphere.setRadius(2.0f);
sphere.setSubdivision(6);
sphere.setSmooth(false);
// draw icosphere using vertexarray
sphere.draw();
// create VAO to store all vertex array state to VAO
GLuint vaoId:
glGenVertexArrays(1, &vaoId);
glBindVertexArray(vaoId);
// copy interleaved vertex data (V/N/T) to VBO
GLuint vboId;
glGenBuffers(1, &vboId);
                                                        // for vertex data
glBindBuffer(GL_ARRAY_BUFFER, vboId);
glBufferData(GL_ARRAY_BUFFER,
                                                        // target
               sphere.getInterleavedVertexSize(), // data size, # of bytes
                                                      // ptr to vertex data
               sphere.getInterleavedVertices(),
               GL STATIC DRAW);
                                                        // usage
// copy index data to VBO
GLuint iboId;
glGenBuffers(1, &iboId);
glBindBuffer(GL_ELEMENT_ARRAY_BUFFER, iboId);
                                                        // for index data
                                                        // target
// data size, # of bytes
glBufferData(GL_ELEMENT_ARRAY_BUFFER,
               sphere.getIndexSize(),
               sphere.getIndices(),
                                                       // ptr to index data
               GL STATIC DRAW);
                                                        // usage
// activate vertex array attributes
glEnableVertexAttribArray(attribVert);
glEnableVertexAttribArray(attribNorm);
glEnableVertexAttribArray(attribTex);
// set vertex array attributes with stride and offset
int stride = sphere.getInterleavedStride();
                                                        // should be 32 bytes
glVertexAttribPointer(attribVert, 3, GL_FLOAT, false, stride, (void*)0);
glVertexAttribPointer(attribNorm, 3, GL_FLOAT, false, stride, (void*)(sizeof(float)*3));
glVertexAttribPointer(attribTex, 2, GL_FLOAT, false, stride, (void*)(sizeof(float)*6));
// unbind VAO and VBOs
glBindVertexArray(0);
glBindBuffer(GL_ARRAY_BUFFER, 0);
glBindBuffer(GL_ELEMENT_ARRAY_BUFFER, 0);
// draw icosphere using VAO, VBO and GLSL \,
glBindVertexArray(vaoId);
{\tt glDrawElements}({\tt GL\_TRIANGLES},
                  sphere.getIndexCount(),
                 GL_UNSIGNED_INT,
                  (void*)0);
```

Cubesphere

Similar to subdividing an icosahedron, a cubesphere is subdividing a cube (a regular polyhedron with 6 faces) N times to construct a sphere geometry. The characteristic of a cubesphere is that the spherical surface of the sphere is decomposed into 6 equal-area regions (+X, -X, +Y, -Y, +Z and -Z faces). It is somewhat related to the cube map, which is a method of environment mapping in computer graphics.





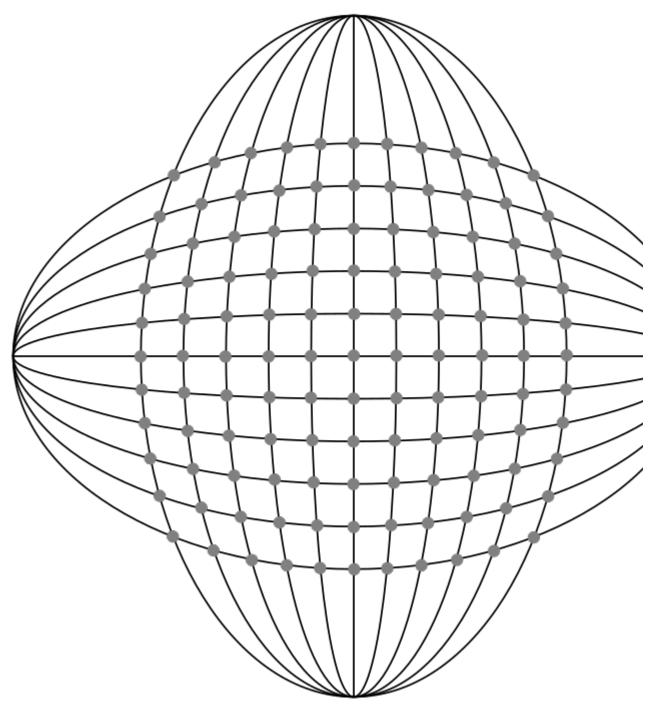


Cubesphere at subdivision 1

Cubesphere at subdivision 2

The following images represent how to construct one of the 6 regions of a cubesphere by intersecting angularly equal-distant longitudinal and latitudinal lines from -45 degree to 45 degree. A vertex on a cubesphere can be computed by the intersection of 2 plane equations. If the normal vector of the latitudinal plane is \vec{n}_1 and the normal of the longitudinal plane is \vec{n}_2 , then the direction vector of the intersect line is $\vec{v}=\vec{n}_1\times\vec{n}_2$. Finally, the vertex on the cubesphere is scaling the normalized direction vector by the radius of the sphere, $r\vec{v}$.





A face of cubesphere by intersecting longitudinal and latitudinal lines from -45 to +45 degree

+X-axis vertices =
$$\begin{cases} \vec{n}_1 &= (-\sin\theta, \, \cos\theta, \, 0), & -\frac{\pi}{4} \le \theta \le \frac{\pi}{4} \\ \vec{n}_2 &= (\sin\phi, \, 0, \, \cos\phi), & -\frac{\pi}{4} \le \phi \le \frac{\pi}{4} \\ \vec{p} &= r(\vec{n}_1 \times \vec{n}_2) \end{cases}$$

The following C++ code is generating a face of a unit cubesphere, which is facing +X axis and the radius is 1.

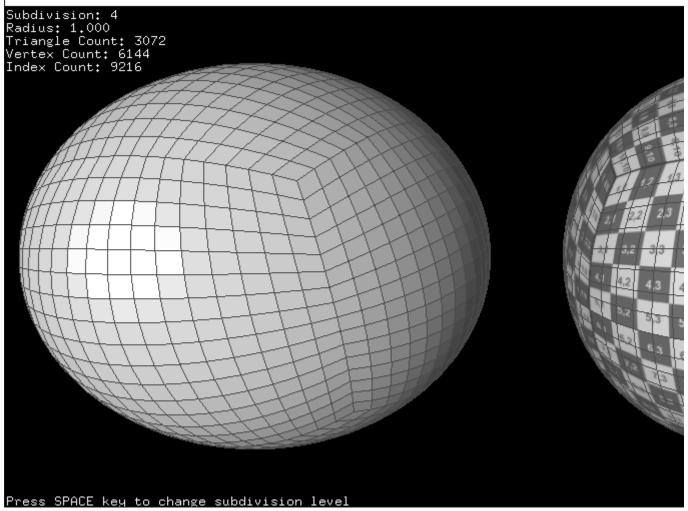
```
// compute the number of vertices per row, N + 1
     int pointsPerRow = subdivision + 1;
     // rotate latitudinal plane from 45 to -45 degrees along Z-axis (top-to-bottom)
     for(unsigned int i = 0; i < pointsPerRow; ++i)</pre>
          // normal for latitudinal plane
         // if latitude angle is 0, then normal vector of latitude plane is n2=(0,1,0)
         // therefore, it is rotating (0,1,0) vector by latitude angle a2 a2 = DEG2RAD * (45.0f - 90.0f * i / (pointsPerRow - 1));
         n2[0] = -\sin(a2);
         n2[1] = cos(a2);
         n2[2] = 0;
          // rotate longitudinal plane from -45 to 45 along Y-axis (left-to-right)
          for(unsigned int j = 0; j < pointsPerRow; ++j)
               // normal for longitudinal plane
              // if longitude angle is 0, then normal vector of longitude is n1=(0,0,-1)
              // therefore, it is rotating (0,0,-1) vector by longitude angle al al = DEG2RAD * (-45.0f + 90.0f * j / (pointsPerRow - 1));
              n1[0] = -\sin(a1);
              n1[1] = 0;
              n1[2] = -cos(a1);
              // find direction vector of intersected line, n1 x n2 v[0] = n1[1] * n2[2] - n1[2] * n2[1]; v[1] = n1[2] * n2[0] - n1[0] * n2[2]; v[2] = n1[0] * n2[1] - n1[1] * n2[0];
               // normalize direction vector
               float scale = 1 / sqrt(v[0]*v[0] + v[1]*v[1] + v[2]*v[2]);
              v[0] *= scale;
v[1] *= scale;
              v[2] *= scale;
               // add a vertex into array
              vertices.push back(v[0]):
              vertices.push_back(v[1]);
              vertices.push_back(v[2]);
         }
    }
     return vertices;
}
```

The other 5 faces can be generated by repeating the above procedure, or swapping and/or negating axis of the vertices of +X face to optimize redundant sine/cosine computations. For example, the vertices of -X face are only negating x and z coordinates of +X face, and +Y face requires swapping $x \rightarrow y$, $y \rightarrow -z$, and $z \rightarrow -x$.

Please see the detail implementation in **buildVerticesFlat()** and **buildVerticesSmooth()** of C++ <u>Cubesphere</u> class to construct all 6 faces.

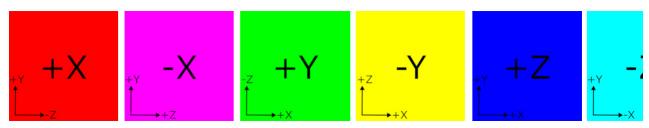
Example: Cubesphere

C:\song\scripts\cpp\opengl\cubesphere\bin\cubesphere.exe



Download: <u>cubesphere.zip</u>, <u>cubesphereShader.zip</u> (GLFW), <u>cubesphereEarth.zip</u>, <u>cubesphereEarthShader.zip</u> (GLFW) (*Updated: 2024-09-07*)

This example is to draw cubespheres with various shadings; the left sphere is without texture, the center sphere is applying a 2D texture to all the 6 faces, and the right sphere is with a cube map texture (GL_ARB_texture_cube_map extension required). Press the space key to change the subdivision levels.



A cubemap has 6 separate images; +X, -X, +Y, -Y, +Z and -Z.

To construct a cubesphere object, it requires 3 parameters; radius, subdivision and surface smoothness. You can change the radius and subdivision level after it has been constructed. If the subdivision is 1, then the shape is a cube.

```
// create cubesphere with default constructor
// radius=1, subdivision=3 and smooth shading=true
Cubesphere sphere;
Cubesphere sphere(1, 3, true); // same as above

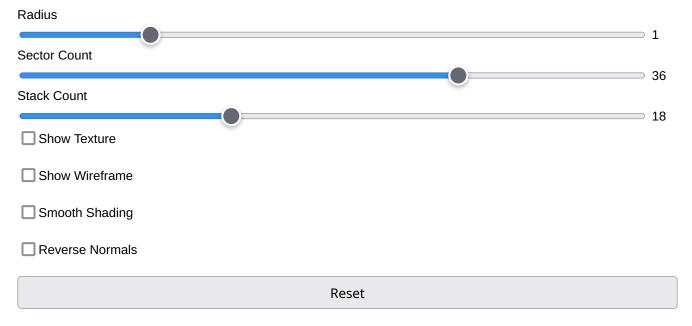
// can change parameters later
sphere.setRadius(2.0f);
sphere.setSubdivision(6);
sphere.setSmooth(false);
...

LOG
aw cubesphere using vertexarray
```

```
sphere.draw();  // draw surface only
sphere.drawWithLines(); // draw surface and lines
sphere.drawFace(0);  // draw only +X face, face index:0~5
...
```

This C++ class provides an additional function, **drawFace()** to draw only the selected face for the given face index. The valid face index is 0 to 5; +X, -X, +Y, -Y, +Z, -Z face respectively.

Example: WebGL Sphere (Interactive Demo)



It is a JavaScript version of Sphere class, <u>Sphere.js</u>, and rendering it with WebGL. Drag the sliders to change the parameters of the sphere. The fullscreen version is available at <u>Sphere Demo</u>.

The following JavaScript code is to create and to render a sphere object.

```
// create a sphere with 4 params: radius, sectors, stacks, smooth
let sphere = new Sphere(gl, 1, 36, 18, false);
...
// change params of sphere later
sphere.setRadius(2);
sphere.setSectorCount(8);
sphere.setStackCount(4);
LOG e.setSmooth(true);
```

```
// draw a sphere with interleaved mode
gl.bindBuffer(gl.ARRAY_BUFFER, sphere.vboVertex);
gl.vertexAttribPointer(gl.program.attribPos, 3, gl.FLOAT, false, sphere.stride, 0);
gl.vertexAttribPointer(gl.program.attribNorm, 3, gl.FLOAT, false, sphere.stride, 12);
gl.vertexAttribPointer(gl.program.attribTex0, 2, gl.FLOAT, false, sphere.stride, 24);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, sphere.vboIndex);
gl.drawElements(gl.TRIANGLES, sphere.getIndexCount(), gl.UNSIGNED_SHORT, 0);
...
```

Example: WebGL Cubesphere (Interactive Demo)



It is a JavaScript version of Cubesphere class for WebGL, <u>Cubesphere.js</u>. Drag the sliders to change the radius and subdivision parameters of the cubesphere. The maximum subdivision value is limited to 52 because the data type of the index array is 16-bit integer (Uint16Array), and it holds upto 65535. The fullscreen version is also available at <u>Cubesphere Demo</u>.

The following JavaScript code is to create and to render a cubesphere object.

```
// create a cubesphere with 3 params: radius, subdivision, smooth
let sphere = new Cubesphere(gl, 1, 3, true); // default cubesphere
...

// change params of cubesphere later
sphere.setRadius(2);
sphere.setSideLength(1);
sphere.setSubdivision(5);
sphere.setSmooth(false);
...

LOG aw a cubesphere with interleaved mode
```

```
gl.bindBuffer(gl.ARRAY_BUFFER, sphere.vboVertex);
gl.vertexAttribPointer(gl.program.attribPos, 3, gl.FLOAT, false, sphere.stride, 0);
gl.vertexAttribPointer(gl.program.attribNorm, 3, gl.FLOAT, false, sphere.stride, 12);
gl.vertexAttribPointer(gl.program.attribTex0, 2, gl.FLOAT, false, sphere.stride, 24);
gl.bindBuffer(gl.ELEMENT_ARRAY_BUFFER, sphere.vboIndex);
gl.drawElements(gl.TRIANGLES, sphere.getIndexCount(), gl.UNSIGNED_SHORT, 0);
...
```

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