

SymIntegration

DS GLANZSCHE¹

FREYA

2025 Edition

¹A thank you or further information

Contents

Preface	3
1 Introduction Story	7
2 Symbolic Integral Computation with SymIntegration	13
I Build and Install SymIntegration in GFrey OS	14
II Techniques of Integration	16
III Integration by Parts	17
IV Fraction Integral	21
V Trigonometry Integral	24
3 SymIntegration to Solve Ordinary Differential Equations for Engineering Problems	27
I First Order Ordinary Differential Equations	28
II Higher Order Linear Equations	29
III Boundary Value Problems and Sturm-Liouville Theory	30

Preface

For my Wife Freya, and our daughters Solreya, Mithra, Catenary, Iyzumrae and Zefir.

For Lucrif and Znane too along with all the 8 Queens.

For Albert Silverberg, Camus and Miklotov who left TREVOCALL to guard me.

To Nature(Kala, Kathmandu, Big Tree, Sentinel, Aokigahara, Hoia Baci, Jacob's Well, Mt Logan, etc) and my family Berlin: I have served, I will be of service.

To my dogs who always accompany me working in Valhalla Projection, go to Puncak Bintang or Kathmandu: Sine Bam Bam, Kecil, Browni Bruncit, Sweden Sexy, Cambridge Klutukk, Milan keng-keng, Piano Blutut and more will be adopted. To my cat who guard the home while I'm away with my dogs: London.

The one who moves a mountain begins by carrying away small stones - Confucius

A book to explained how we create C++ library from forking / branching out SymbolicC++ 3.35 to improve its' symbolic integral computation.

a little about GlanzFreya:

Freya the Goddess is (DS Glanzsche') Goddess wife. We get married on Puncak Bintang on November 5th, 2020 after we go back from Waghete, Papua. My wife birthday (Freya the Goddess) is on August 1st. After not working with human anymore since 2019, I (DS Glanzsche) work in a forest, shaping a forest into a natural wonder / like a canvas for painting, and also clean up trashes that are thrown in the forest. Thus after 6 years working with Nature I have found what can makes me waltz to work, it is going to the forest in the morning then go back home again and study / learn science, engineering, computer programming.



Figure 1: *Freya, thank you for everything, I am glad I marry you and I could never have done it without you.*



Figure 2: *I paint her 3 days before Christmas in 2021.*

Chapter 1

Introduction Story

On top of the mountain a heart shaped stone waiting for You, my eyes can't see, my body can't touch, but my heart knows it's You. Forever only You. - Glanz to Freya

This book is written on May 9th, 2025, it is exactly 1 month after I finish with the algorithms and C++ codes for $\int \sin^n x dx$, $\int \cos^n x dx$, $\int \tan^n x dx$, $\int \sec^n x dx$, $\int \csc^n x dx$.

SymIntegration itself is a C++ library that is branching out from SymbolicC++3.35. We don't really need to start from scratch. The main idea is to improve its symbolic integration codes. Our main focus is to make it able to compute:

1. All kinds of standard integral form (trigonometry, inverse trigonometry, polynomial, transcendental, hyperbolic).
2. The sum, product and divide combination of the standard functions.
3. To be able to compute improper integrals with cases (e.g. computing mean and variance for exponential distribution)

On April 9th, Sentinel, a Nature residing in a big robust tree in VP (Valhalla Projection) forest told me to start creating C++ library that can do integration like what SymPy able to do, or Mathematica. Around April 2025, GiNaC cannot handle integration by parts, and SymbolicC++ also returns $\int \sin^n x dx$ with $\frac{1}{n+1} \sin^{n+1}$. So then we decided to branching out / forking from SymbolicC++ version 3.35. Fixing the C++ codes there so the computation will be made right.

We will cover mostly tons of integral problems, how to find its patterns then how to create the C++ code so SymIntegration will be able to return the integral correctly, thus there will be a lot of technical writings after this chapter. The requirement to comprehend SymIntegration mathematical background is you should at least self learn, read by yourself a Calculus book [3]. No need to go to college, it is expensive and only add more loan to your life.

The name is chosen as SymIntegration, not only it has a great Chaldean numerology of 46 (on purpose), a king of success number / Nobel winner number / President / richest person number, but also it is in accordance with the main purpose, to be able to compute all kinds of integration with C++. Which still dominated by SymPy, Mathematica or MATLAB. Mathematica and MATLAB are using license, and I am not working with human anymore, thus I do not have salary / stable income like I used to, so I cannot lean on that (MATLAB / Mathematica), SymPy is

free, can be called from JULIA too besides Python, but then, I read that Game Engine (CryEngine, Genie Engine, Godot, Unreal Engine) that is able to create amazing game with beautiful graphics, animation, real life graphics, you name all the game with best graphics (I can say from Age of Empires, Call of Duty, Crysis, Cyberpunk 2077, Death Stranding, Dota, Grand Theft Auto, Final Fantasy, Metro 2033, Pokemon Go, The Witcher), and I can say it is made with C++. It is the near hardware and one of the fastest programming language if you have a mind on creating something better in the future, like Science and Engineering simulator, e.g. Bullet, Project Chrono, HySys, Autodesk Civil Engineering. Let say if you have time you can create your own Autodesk instead of paying for its license, basically the brain behind them are derivative, integral, statistics and algebra.

Basically we choose C++ so we can create something long lasting in the future, and then I (DS Glanzsche) dedicate everyday of my life to eat and breathe C++ to be able to achieve this stage, hopefully it can be developed further till we can get practical use, like having a simulation for fluid flow, pharmacokinetics (to compute how drugs are metabolized by the body), simulation for human' organ, or to create a stable bridge or skycraper, since the basic of calculus, integral, linear algebra, statistics can be covered nicely by SymIntegration. The front end looks for plot and simulation can be done by third party C++ library like ImGui, MatplotPlusPlus or OpenGL.

Symbolic integration is basically harder than differentiation, differentiation has rigid rules: sum rule, product rule, chain rule, divide rule. While integration has only method of substitution and integration by parts, which back to the method itself. We can obtain different results for integration, but same result for differentiating different functions with respect to the same variable, like this case:

$$\begin{aligned}D_x \frac{-\cos^2(nx)}{2n} &= \cos(nx) \sin(nx) \\D_x \frac{\sin^2(nx)}{2n} &= \cos(nx) \sin(nx)\end{aligned}$$

Depending on the method of substitution, which one we substitute, if we reverse the equations above into integral problems, then we will obtain:

$$\begin{aligned}\int \cos(nx) \sin(nx) dx &= \frac{-\cos^2(nx)}{2n} + C \\ \int \cos(nx) \sin(nx) dx &= \frac{\sin^2(nx)}{2n} + C\end{aligned}$$

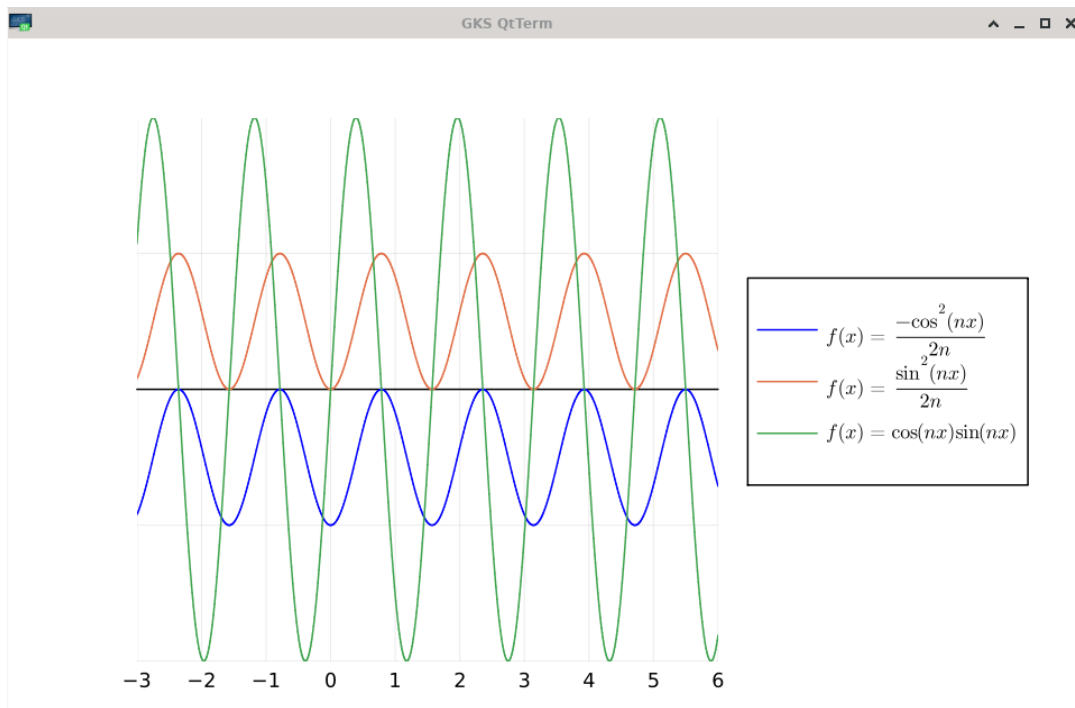


Figure 1.1: Integrating a function with different method can result in at least two different functions.

To compute the definite integral of a function in an interval you have to know how it behaves on the entire interval, and to compute the indefinite integral you have to know how it behaves on all intervals. While differentiation is a "local" operation, it computes the derivative of a function at a point you only have to know how it behaves in a neighborhood; distance, speed and acceleration from basic physics is the example of differentiation and integral. Computing integral / antiderivative often requires clever algebraic manipulation and technique and there are no universal rules for integration like there are for differentiation.

Integrals are fundamental in all science and engineering fields for solving problems involving area, volume, and other accumulations, some specific applications of integrals in science and engineering:

1. To calculate the area of irregular shapes, the volume of solids, and the surface area of objects.
2. To determine center of mass and moments of inertia for various shapes, they are crucial for structural analysis and design.
3. To calculate work done by a variable force, which is essential in mechanics and thermodynamics.
4. To calculate energy, power, and signal properties over time in electrical and computer engineering.
5. To determine stresses and strains analysis in structures under various loads.
6. To calculate fluid flow, pressure distributions, and forces exerted by fluids.

7. To compute probability distributions and statistical calculations.
8. To predict the trajectory of satellites and other objects in motion, ensuring they follow the intended path.
9. To calculate drug accumulation and half-life in a body, it is crucial for understanding how drugs are metabolized and eliminated by the body in Pharmacokinetics.
10. To model how diseases spread through a population with Susceptible-Infectious-Removed (SIR) model.
11. To understand better the complex processes of modeling tumor growth and metastasis.
12. To understand how reactions progress and their rates for reaction kinetics in chemistry.
13. To calculate work done during processes like gas expansion and changes in internal energy or enthalpy. These calculations are crucial for understanding the energetics of chemical reactions and processes.
14. To solve problems related to process design, optimization and understanding reaction kinetics in building a plant in Chemical Engineering.
15. To determine the volume of concrete needed for a structure, the area of a road surface, or the volume of soil required for an excavation in building bridges and structures.
16. To find the deflection (bending) and slope of a beam under load, which is crucial for ensuring structural stability.
17. To determine the velocity of a fluid flow, which is important in designing hydraulic structures like dams and pipelines.
18. To calculate the pressure distribution in fluids, which is essential for understanding the forces exerted on structure by fluids.
19. To understand the behavior of capacitors and inductors. The voltage across a capacitor is the integral of the current flowing through it, and the current through an inductor is the integral of the voltage across it.
20. To compute total charge and energy in Electrical Engineering.
21. To determine the circuit's voltage, current, or other parameters as a function of time by using integration to solve differential equations for many kind of circuit behaviors.

Now we will take a look at the applications of the integration in computer science:

1. Mathematics and computing.
2. Block chain method.
3. Quantum computing.
4. Big data analytics.
5. Neural Networking.
6. Artificial Intelligence.

7. Machine Learning.

Integration, calculus, linear algebra are the brain behind the applications above.

Triple integrals are used in physics, engineering, and even finance. If we get ahold of the C++, we can do the integral computation right, then it is only a matter of presentation, create the plot / simulation / computation for our goal, e.g. to create a stable bridge that can handle earthquake with magnitude of 10 SR. It takes simulation first, before constructing the real product.

The Operating System and Softwares in Use:

1. GFreya OS version 1.8 (based on LFS and BLFS version 11.0 System V books)
2. GCC version 11.2.0 (to compile C++ codes in Box2D)
3. SymIntegration version 1.51

By May 9th, 2025 SymIntegration is able to compute

1. The integral of $\sin(ax + b)$, $\cos(ax + b)$, $\tan(ax + b)$, $\cot(ax + b)$, $\sec(ax + b)$, $\csc(ax + b)$ with $ax + b$ is a polynomial of order 1.
2. The integral of $\frac{1}{(ax+b)}$, $\frac{1}{ax^2+bx+c}$.
3. The integral and derivative of $\operatorname{asin}(ax + b)$, $\operatorname{acos}(ax + b)$, $\operatorname{atan}(ax + b)$, $\operatorname{acot}(ax + b)$, $\operatorname{asec}(ax + b)$, $\operatorname{acsc}(ax + b)$ with $ax + b$ is a polynomial of order 1.
4. The integral and derivative of all hyperbolic trigonometry functions $\sinh(ax + b)$, $\cosh(ax + b)$, $\tanh(ax + b)$, $\coth(ax + b)$, $\operatorname{sech}(ax + b)$, $\operatorname{csch}(ax + b)$.
5. The integral with the form of $x^b e^{ax}$, $x^b e^{cx}$ with integration by parts method.
6. The integral of $\sin(ax) \cos(bx)$, $\cos(ax) \cos(bx)$, $\sin(ax) \sin(bx)$

We are really appreciate those who spend time to write constructing critics, not hate words without reason that will only add more good luck and karma to me, write their opinions on what should be added in SymIntegration or if there is an incorrect C++ codes or algorithm to compute the integrals. We cannot provide the readers who send nice feedbacks with anything now, but if we have money, when someone send / email me a very good feedbacks then we will send you either cookies, doughnuts or parcel of foods. Feedbacks can be sent to **dsglantzsche@gmail.com**.

Chapter 2

Symbolic Integral Computation with SymIntegration

"The best and most beautiful things in the world cannot be seen or even touched - they must be felt with the heart" - Helen Keller

W^E will first learn how to create the shared library for C++ library in a very simple and manual way, then we will see the source code that composing this C++ library, SymIntegration.

I. BUILD AND INSTALL SYMINTEGRATION IN GFREYA OS

We are using GFreya OS as it is a custom Linux-based Operating System, your distro your rules. Building applications from scratch instead of using package manager, you learn more from mistakes than just depending on package manager.

To download SymIntegration, open terminal / xterm then type:

```
git clone https://github.com/glanzkaiser/SymIntegration.git
```

Enter the directory then type:

```
cd src
```

```
bash dynamiclibrary.sh
```

or you can also type from the main parent directory of SymIntegration repository:

```
cd src
g++ -fPIC -c *.cpp
g++ -shared -o libsymintegration.so *.o
```

Code 1: *Create dynamic library*

It will create the dynamic library **libsymintegration.so** with a very manual way, instead of using CMake, we are using less space.

Assuming you are using Linux-based OS, you can then copy / move the dynamic library to **/usr/lib**.

Then open terminal and from the current working directory / this repository main directory:

```
cd include
cp -r * /usr/include
```

Code 2: *Move include folder*

When we want to create the shared library it will look for this header files in the default path where the include files are usually located. In Linux OS **usr/include** is the basic / default path.

All files, examples codes and source codes used in this books can be found in this repository: <https://github.com/glanzkaiser/SymIntegration>

We are using less, minimal amount of code to create the library, if you compare it with the original SymbolicC++ that has **.configure** and **Makefile** that will be spawn after you configure it, we don't use any of that.

Two simple commands with **g++** can already make a shared symbolic integration computation library, with limitation still.

If you are using Windows OS or MacOS then you are on your own.

The C++ codes are only located in the **/src** directory , it is designed to contain all the '.cpp' files, then inside the **/include/** we have header files and another folder **/include/symintegral/** is

also a folder that contain header files too.

You can open them one by one, read them and making sense of it based on the function that you are looking for.

There are total of 27 **.cpp** files and 26 **.h** / header files. So it won't take a long time for someone to learn it.

II. TECHNIQUES OF INTEGRATION

- Integration by Parts

[SI*] From the analogue of the product rule for differentiation. Suppose we have two functions $f(x)$ and $g(x)$ with

$$\frac{d}{dx} f(x)g(x) = f(x)\frac{dg(x)}{dx} + g(x)\frac{df(x)}{dx} \quad (2.1)$$

Integrating both sides and rearranging the terms, we will get the integration by parts formula:

$$\int f(x)\frac{dg(x)}{dx} dx = f(x)g(x) - \int g(x)\frac{df(x)}{dx} dx \quad (2.2)$$

This formula is only useful if $\int g(x)\frac{df(x)}{dx} dx$ or $\int f(x)\frac{dg(x)}{dx} dx$ is easier to integrate than $\int f(x)g(x) dx$.

The application for integration by part is very useful in statistics, e.g. to be able to compute the mean and variance for exponential distribution.

- Substitution

[SI*] .

III. INTEGRATION BY PARTS

• Example: Exponential Distribution

[SI*] The exponential distribution, which is sometimes used to model the lifetimes of electrical or mechanical components, has probability density function

$$f(x) = \begin{cases} \lambda e^{-\lambda x}, & \text{if } 0 \leq x \\ 0, & \text{otherwise} \end{cases}$$

where λ is some positive constant. Compute the mean μ and the variance σ^2 .

Solution:

To compute for the mean we will have

$$\begin{aligned} E(X) &= \int_{-\infty}^{\infty} x f(x) dx \\ &= \int_{-\infty}^0 x \cdot 0 dx + \int_0^{\infty} x \lambda e^{-\lambda x} dx \end{aligned}$$

We apply integration by parts in the second integral with

$$\begin{aligned} u &= x \\ dv &= \lambda e^{-\lambda x} dx \\ du &= dx \\ v &= -e^{-\lambda x} \end{aligned}$$

Thus

$$\begin{aligned} E(X) &= [-x \lambda e^{-\lambda x}]_0^{\infty} - \int_0^{\infty} (-e^{-\lambda x}) dx \\ &= (-0 + 0) + \left[-\frac{1}{\lambda} e^{-\lambda x} \right]_0^{\infty} \\ &= \frac{1}{\lambda} \end{aligned}$$

The variance is

$$\begin{aligned} \sigma^2 &= E(X^2) - \mu^2 \\ &= \int_{-\infty}^{\infty} x^2 f(x) dx - \left(\frac{1}{\lambda} \right)^2 \\ &= \int_{-\infty}^0 x^2 \cdot 0 dx + \int_0^{\infty} x^2 \lambda e^{-\lambda x} dx - \frac{1}{\lambda^2} \\ &= [-x^2 e^{-\lambda x}]_0^{\infty} - \int_0^{\infty} (-e^{-\lambda x}) 2x dx - \frac{1}{\lambda^2} \\ &= (-0 + 0) + 2 \int_0^{\infty} x e^{-\lambda x} dx - \frac{1}{\lambda^2} \\ &= 2 \frac{1}{\lambda^2} - \frac{1}{\lambda^2} \\ &= \frac{1}{\lambda^2} \end{aligned}$$

[SI*] When they say integration is an art it is true, you need more practice to be able to handle all kinds of integral problems.

If we are facing this kind of equation:

$$f(x) = x\lambda e^{-\lambda x}$$

then what we need to do is learning the pattern

$$\int x e^x dx = (x - 1)e^x + C$$

$$\int x^2 e^x dx = (x^2 - 2x + 2)e^x + C$$

$$\int x^3 e^x dx = (x^3 - 3x^2 + 6x - 6)e^x + C$$

$$\int x^4 e^x dx = (x^4 - 4x^3 + 12x^2 - 24x + 24)e^x + C$$

⋮

so for the general function of

$$f(x) = x^n e^x$$

The algorithm will be like this:

```
Symbolic sgn = 1;
int k = 1;
Symbolic integral;
for (int i = 0; i <= n; i++)
{
    integral += k * sgn * (x^(n-i)) * exp(x)
    sgn = -sgn;
    k *= n-i;
}
return integral;
```

The C++ file to handle cases of integration by parts is located in **src/integrate.cpp**

```
Symbolic integrate(const Symbolic &f, const Symbolic &x)
{
    list<Equations> eq;
    list<Equations>::iterator i;
    UniqueSymbol a, b, c;
    ...
    ...
```

Code 3: *src/integrate.cpp*

Now for the case of $f(x) = x^n e^x$, it is handled at this part of codes

```
Symbolic integrate(const Symbolic &f, const Symbolic &x)
{
```

```

...
...
eq = ((x^b)*exp(x)).match(f, (a,b)); // case for x^b
    * exp(x)
for(i=eq.begin(); i!=eq.end(); ++i)
try {
    Symbolic bp = rhs(*i, b);
    if(bp.type() == typeid(Numeric)
    && Number<void>(bp)->numericity() == typeid(
        int)
    && Number<void>(bp)>Number<int>(0))
    {
        int n = CastPtr<const Number<int> >(bp
            )->n, sgn = 1;
        Symbolic integral, nf = 1;
        for(; n>=0; nf*=n, --n, sgn=-sgn)
            integral += sgn*nf*(x^n)*exp(x);
        return integral;
    }
} catch(const SymbolicError &se) {}
}

```

Code 4: *src/integrate.cpp* to handle $x^n e^x$

For the computation of mean and variance of exponential distribution with SymIntegration we will get this raw result, where the e^{-inf} is still as it is, and not returning to 0, we will work on it in the future.

```

#include <iostream>
#include "symintegrationc++.h"

using namespace std;

int main(void)
{
    Symbolic x("x"), l("l"), Inf("Inf"), y, Ex,
        Varx, u, dv, v, du;

    y = l*exp(-l*x);
    u = x;
    dv = l*exp(-l*x);
    du = df(u,x);
    v = integrate(dv,x);

    cout << "f(x) = " << y << endl;

    for(int i=1;i<=1;i++)
    {
        y = integrate(y,x);
    }
}

```

```
        cout << i << "-st integral of f(x) = "
        << y << endl;
    }
    cout << "int_{0}^{Inf} f(x) = " << y[x==Inf]
        - y[x==0] << endl;

    Ex = x*l*exp(-l*x);

    cout << "\nx f(x) = " << Ex << endl;
    cout << "\nu = " << u << endl;
    cout << "dv = " << dv << endl;
    cout << "du = " << du << endl;
    cout << "v = " << v << endl;

    Ex = integrate(Ex,x);
    cout << "\nE(x) = int x f(x) = " << Ex <<
        endl;
    cout << "int_{0}^{Inf} x f(x) = " << Ex[x==
        Inf] - Ex[x==0] << endl;

    Varx = x*x*l*exp(-l*x);
    Varx = integrate(Varx,x);

    cout << "\nint x^{2} f(x) = " << Varx << endl
        ;
    cout << "int_{0}^{Inf} x^{2} f(x) = " << Varx
        [x==INFINITY, l==1] - Varx[x==0] << endl;
    cout << "\nVar(x) = int x^{2} f(x) - mu^{2} =
        " << Varx[x==INFINITY, l==1] - Varx[x
        ==0] - (1/l^2) << endl;

    return 0;
}
```

Code 5: *Integration by Parts*

IV. FRACTION INTEGRAL

• Fraction Level 1

[SI*] Suppose we have this function that we want to integrate toward x .

$$f(x) = \frac{1}{ax + b}$$

a and b are constants.

The integral will be

$$\int \frac{1}{ax + b} dx = \frac{\ln(ax + b)}{a} + C \quad (2.3)$$

For the integrate function alone in SymIntegration we do not include the constant C that is obtained after integration.

[SI*] The C++ code to handle this fraction level 1 integral problem to make sure the integral will return the correct result is located in **src/functions.cpp** under the function **Symbolic Power::integrate(const Symbolic &s) const**

```
Symbolic Power::integrate(const Symbolic &s) const
{
    const Symbolic &a = parameters.front();
    const Symbolic &b = parameters.back();
    ...
    ...
}
```

```
Symbolic Power::integrate(const Symbolic &s) const
{
    ...
    ...

    if(b == -1 && parameters.front().coeff(s,2) == 0)
        return ln(parameters.front()) * (1/ parameters.
            front().df(s));
    ...
    ...
}
```

Code 6: *fraction level 1 integral*

The **if** statement above is a condition: if the input of a function meets the criteria that the power is -1 / a fraction ($f(x)^{-1} = \frac{1}{f(x)}$) then we will return it as **ln(parameters.front()) * (1/ parameters.front().df(s))**. The symbolic s is used to replace the variable in the integration problem.

I will introduce to the reader here about **parameters.front()** and **parameters.back()**, suppose we have a function

$$f(x) = (ax^2 + bx + c)^d \quad (2.4)$$

with a, b, c as constants.

- * The **parameters.front()** of the function from equation (2.4) is $ax^2 + bx + c$.
parameters.front().coeff(s,2) is a .
parameters.front().coeff(s,1) is b .
parameters.front().coeff(s,0) is c .

- * The **parameters.back()** of the function from equation (2.4) is d .

With this knowledge we can create a lot of **if**, **if.. else..** conditions to make the integration computation complete and better.

• Fraction Level 2

[SI*] Suppose we have this function that we want to integrate toward x .

$$f(x) = \frac{1}{ax^2 + bx + c}$$

a, b and c are constants.

The integral will be

$$\begin{aligned} \int \frac{1}{ax^2 + bx + c} dx = & -\sqrt{\frac{-1}{4ac - b^2}} \ln \left(x + \frac{-4ac\sqrt{\frac{-1}{4ac - b^2}} + b^2\sqrt{\frac{-1}{4ac - b^2}} + b}{2a} \right) \\ & + \sqrt{\frac{-1}{4ac - b^2}} \ln \left(x + \frac{4ac\sqrt{\frac{-1}{4ac - b^2}} - b^2\sqrt{\frac{-1}{4ac - b^2}} + b}{2a} \right) + C \end{aligned} \quad (2.5)$$

[SI*] The codes for the SymIntegration to handle this integral is located in **src/functions.cpp**

```
...
...

Symbolic Power::integrate(const Symbolic &s) const
{
    ...
    ...
    if(b == -1 && parameters.front().coeff(s,2) != 0)
    {
        double a1 = parameters.front().coeff(s,2);
        double b1 = parameters.front().coeff(s,1);
        double c1 = parameters.front().coeff(s,0);
        double D_inv = sqrt(-1/(4*a1*c1-b1*b1));
```

```
        return - D_inv * ln(s + (-4*a1*c1*D_inv + b1
            *b1*D_inv + b1)/(2*a1)) + D_inv * ln(s +
            (4*a1*c1*D_inv - b1*b1*D_inv + b1)/(2*a1
            )) ;
    }
    ...
    ...
}
...
...
```

Code 7: *fraction level 2 integral*

V. TRIGONOMETRY INTEGRAL

• Trigonometry Level 1

[SI*] We will want to compute integral of trigonometry at the basic level like these:

$$\begin{aligned}\int \sin(x) dx &= -\cos(x) + C \\ \int \sin(3x+5) dx &= -\frac{1}{3} \cos(3x+5) + C \\ \int \cos(x) dx &= \sin(x) + C \\ \int \cos(3x+5) dx &= \frac{1}{3} \sin(3x+5) + C \\ \int \tan(x) dx &= -\ln(\cos(x)) + C \\ \int \tan(3x+5) dx &= \frac{1}{6} \ln(\tan^2(3x+5) + 1) + C \\ \int \cot(x) dx &= \ln(\sin(x)) + C \\ \int \cot(3x+5) dx &= -\frac{1}{6} \ln(\tan^2(3x+5) + 1) + \frac{1}{3} \ln(\tan(3x+5)) + C \\ \int \sec(x) dx &= -\frac{\ln(\cos(x))}{\sin(x)} + C \\ \int \sec(3x+5) dx &= -\frac{1}{3} \frac{\ln(\cos(3x+5))}{\sin(3x+5)} \\ \int \csc(x) dx &= \frac{\ln(\sin(x))}{\cos(x)} + C \\ \int \csc(3x+5) dx &= \frac{1}{3} \frac{\ln(\sin(3x+5))}{\cos(3x+5)}\end{aligned}$$

At first the raw codes from SymbolicC++ 3.35 cannot perform that computation, in the **src/functions.cpp** there are implementations for sin, cos, tan but they are imperfect and if the case is not covered it will have an output of **return Integral(*this,s)**, which means the integral cannot be computed.

So we correct it and put the formula so SymIntegration can compute the integral problems above, which we call them as Level 1 trigonometry problems.

```
...
...

Symbolic Tan::integrate(const Symbolic &s) const
{
    const Symbolic &x = parameters.front();
    if(x == s) return -ln(cos(x)) * (1 / parameters.front().
        df(s));
    if(df(s) == 0) return *this * s;
```



```

        return ln( tan(parameters.front()) * tan(parameters.
                    front() + 1) * ( 1 / (2*parameters.front().df(s)) )
                    ;
    }

    ...

```

Code 8: Implementation of integral for tangent function

```

170
171 Symbolic Acos::integrate(const Symbolic &s) const
172 {
173     const Symbolic &x = parameters.front();
174     if(x == s) return x*acos(x) - sqrt(1-x*x);
175     if(df(s) == 0) return *this * s;
176     return ( - sqrt(1-(parameters.front())*(parameters.front())) / parameters.front().df(s) ) + ( parameters.front()*acos(parameters.front()) ,
177 }
178
179
180 // Implementation of Tan
181 //
182 //
183
184 Tan::Tan(const Tan &s) : Symbol(s) {}
185
186 Tan::Tan(const Symbolic &s) : Symbol(Symbol("tan")[s]) {}
187
188 Simplified Tan::simplify() const
189 {
190     const Symbolic &s = parameters.front().simplify();
191     if(s == 0) return Number<int>(0);
192     if(s.type() == typeid(Product))
193     {
194         CastPtr<const Product> p(s);
195         if(p->factors.front() == -1) return -Tan(-s);
196     }
197     if(s.type() == typeid(Numeric) &&
198        Number<void>(s).numeric_type() == typeid(double))
199     return Number<double>(tan(CastPtr<const Number<double>>(s)->n));
200 return *this;
201 }
202
203 Symbolic Tan::df(const Symbolic &s) const
204 { return tan(parameters.front()) * tan(parameters.front()) * parameters.front().df(s) + parameters.front().df(s) ; }
205
206 Symbolic Tan::integrate(const Symbolic &s) const
207 {
208     const Symbolic &x = parameters.front();
209     if(x == s) return -ln(cos(x)) * (1 / parameters.front().df(s));
210     if(df(s) == 0) return *this * s;
211     return ln( tan(parameters.front()) * tan(parameters.front()) + 1) * ( 1 / (2*parameters.front().df(s)) ) ;
212 }

```

Figure 2.1: The implementation of tangent function to compute its derivative and integral in `src/functions.cpp`.

- [Trigonometry Level 2](#)

[SI*] .

- [Trigonometry Level 3](#)

[SI*] .

Chapter 3

SymIntegration to Solve Ordinary Differential Equations for Engineering Problems

"After Odin's defeat atop Yggdrasil and the revelation of Lezard's true nature, Freya quickly teleports there in a frantic state, telling Odin that Lezard's presence was the distortion she felt at Dipan" - Freya (Valkyrie Profile 2: Silmeria)

"Everyone's favorite fighting fairy godmother is still kicking, taking out Ether Strike hits for her godfather Odin. The heretofore unmatched fury of her scowl derives from her lack of lines in the main story" - Freya (Valkyrie Profile: Covenant of the Plume)

According to Newton's second law of motion, the acceleration a of a body of mass m is proportional to the total force F acting on it, with $1/m$ as the constant of proportionality, so that $a = F/m$ or

$$F = ma \quad (3.1)$$

[SI*] General Remarks and Solutions

The general ordinary differential equation of the n th order is

$$F\left(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}, \dots, \frac{d^ny}{dx^n}\right) = 0$$

or, using the prime notation for derivatives,

$$F(x, y, y', y'', \dots, y^{(n)}) = 0$$

It is normally a simple task to verify that a given function $y = y(x)$ is a solution of an equation above.

* All that is necessary is to compute the derivatives of $y(x)$ and to show that $y(x)$ and these derivatives, when substituted in the equation, reduce it to an identity in x .

I. FIRST ORDER ORDINARY DIFFERENTIAL EQUATIONS

- [Some Basic Mathematical Models](#)

[SI*] .

Direction Fields

[SI*] The independent variables for the example above is t ,

- [Solutions of Some Differential Equations](#)

[SI*] The equation

$$m \frac{dv}{dt} = mg - \gamma v$$

is of the general form

$$\frac{dy}{dt} = ay - b \tag{3.2}$$

II. HIGHER ORDER LINEAR EQUATIONS

- General Theory of n th Order Linear Equations

[SI*] The first
[SI*]

- The Method of Variation of Parameters

[SI*] The first
[SI*]

III. BOUNDARY VALUE PROBLEMS AND STURM-LIOUVILLE THEORY

- [The Occurrence of Two-Point Boundary Value Problems](#)

[SI*] The first
[SI*]

- [Nonhomogeneous Boundary Value Problems](#)

[SI*] The first
[SI*]

Bibliography

- [1] Colley, Susan Jane (2012) Vector Calculus 4th Edition, Pearson, Boston, MA, United States.
- [2] Dorf, Richard C., Bishop, Robert H. (2010) Modern Control Systems 12th Edition, Pearson, New Jersey, United States.
- [3] Purcell, Rigdon, Varberg (2007) Calculus 9th Edition, Pearson, Upper Saddle River, New Jersey, United States.
- [4] Kenneth H. Rosen (2006) Discrete Mathematics and its Applications 6th Edition, McGraw-Hill, Boston, United States.
- [5] Anton, Rorres (2006) Elementary Linear Algebra with Supplemental Applications 10th Edition, Wiley, Boston, United States.
- [6] Anton, Howard, Rorres, Chris, Elementary Linear Algebra with Supplemental Applications 12th edition, Wiley, Hoboken, New Jersey, United States.