Building a Yocto Image

Advanced Embedded Linux Development

with **Dan Walkes**



Learning objectives:

Yocto build by example
Overview of yocto build helper scripts



Building your Custom Image

- •Run ./build.sh
 - Initializes your poky submodule
 - source poky/oe-init-build-env (note: creates/changes directory to the build dir!)
 - Checks whether your build/conf/local.conf file already contains your MACHINE definition, if not adds it
 - Checks whether your meta-aesd layer is already included, if not adds it
 - Runs bitbake core-image-aesd
 - All commands after source command are run from the build dir!

```
git submodule init
git submodule sync
git submodule update
```

source poky/oe-init-build-env

echo "Adding meta-aesd laver"

bitbake-layers add-layer ../meta-aesd

bitbake core-image-aesd



Running your custom image

- source poky/oe-init-build-env
- runqemu nographic
 - Uses environment info to find MACHINE, and location of image.
 - Use runqemu --help to find additional argument options
- Default login is root with no password
 - Modified for you to set to "root" to match buildroot setup



rungemu.sh

```
You can also run generated qemu images with a command like 'runqemu qemux86'
runqemu - INFO - Running bitbake -e...
runqemu - INFO - Continuing with the following parameters:

KERNEL: [/home/aesdbuildbot/yocto-complete-private/build/tmp/deploy/images/qemuarm64/Image--5.0.19+git0+31de88e51d_00638c
dd8f-r0-qemuarm64-20200522201347.bin]

MACHINE: [qemuarm64]
FSTYPE: [ext4]
ROOTFS: [/home/aesdbuildbot/yocto-complete-private/build/tmp/deploy/images/qemuarm64/core-image-aesd-qemuarm64-2020052220
1347.rootfs.ext4]
CONFFILE: [/home/aesdbuildbot/yocto-complete-private/build/tmp/deploy/images/qemuarm64/core-image-aesd-qemuarm64.qemuboot.conf]

runqemu - INFO - Port forward: hostfwd=tcp::10022-:22 hostfwd=tcp::9000-:9000
```

- Sets up slirp network interface for you, does not require root access (as opposed to tap interface default)
 - Matches what we used for buildroot assignments
- All target ports will now be available at 10.0.2.15 (localhost)
 - Use sockettest.sh to reach the target qemu

Adding your recipe (already done for you)

- Easiest option use devtool
- Source the build script from the poky folder
 - source poky/oe-init-build-env
- Add the recipe using devtool
 - devtool add aesd-assignments <path to your aesd assignments repo>
 - Generates a recipe based on content of git repo in build/workspace/recipes/recipes-aesd-assignments /aesd-assignments_git.bb

Adding your recipe (already done for you)

- devtool build aesd-assignments
 - Builds the source, verifies it builds successfully
- devtool finish aesd-assignments ../../meta-aesd/
 - Places the .bb file in your yocto recipes tree within your layer.



Modifying your Makefile

- Yocto expects to completely override your
 - makefile variables
 - \circ CC
 - LDFLAGS
 - CFLAGS

- CC ?= \$(CROSS_COMPILE)gcc
 CFLAGS ?= -g -Wall -Werror
 TARGET ?= aesdsocket
 LDFLAGS ?= -lpthread -lrt
- Set these with ?= to allow overrides
- Use CC, CFLAGS, INCLUDES, LDFLAGS IN YOUR
 - **COMPILE STEP**

\$(CC) \$(CFLAGS) \$^ -0 \$@ \$(INCLUDES) \$(LDFLAGS)

Implementing/Finishing your Recipe



- Implement TODOs in aesd_assignments_git.bb
 - Setup your assignments repo
 - Important to use ssh-agent with yocto, builds will fail if you need interactive login for your SSH password.
- Setup your commit hash in SRCREV

Implementing/Finishing your Recipe



- Include files you will be adding to the rootfs in FILES:\${PN}
- Add LDFLAGS from your makefile into TARGET LDFLAGS
- Customize do_install() step to install your files

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Start Script Implementation in Yocto

- Yocto uses a similar but slightly different startup
 - System V vs Busybox init
- Your start script can be installed using the update-rc.d class

```
root@gemuarm64:~# ls -la /etc/rc5.d/
                                       1024 Oct 10 20:01 .
drwxr-xr-x
              2 root
                         root
drwxr-xr-x
             24 root
                                       3072 Oct 10 20:14 ...
                         root
                                         20 Oct 10 20:01 S01networking -> ../init.d/networking
1rwxrwxrwx
             1 root
                         root
                                         16 Oct 10 20:01 502dbus-1 -> ../init.d/dbus-1
Trwxrwxrwx
              1 root
                         root
                                         17 Oct 10 20:01 S12rpcbind -> ../init.d/rpcbind
rwxrwxrwx
              1 root
                         root
                                         21 Sep 10 04:31 S15mountnfs.sh -> ../init.d/mountnfs.sh
rwxrwxrwx
              1 root
                         root
                                         19 Oct 10 20:01 S19nfscommon -> ../init.d/nfscommon
Trwxrwxrwx
              1 root
                         root
                                         31 Oct 10 20:01 S20aesdsocket-start-stop -> ../init.d/aesdsocket-start-stop
Trwxrwxrwx
              1 root
                         root
                                         19 Oct 10 20:01 S20bluetooth -> ../init.d/bluetooth
Trwxrwxrwx
              1 root
                         root
                                         16 Oct 10 20:01 520distcc -> ../init.d/distcc
Trwxrwxrwx
              1 root
                         root
                                         20 Oct 10 20:01 S20hwclock.sh -> ../init.d/hwclock.sh
Trwxrwxrwx
              1 root
                         root
                                         19 Oct 10 20:01 S20nfsserver -> ../init.d/nfsserver
Trwxrwxrwx
              1 root
                         root
                                         16 Oct 10 20:01 S20syslog -> ../init.d/syslog
Trwxrwxrwx
              1 root
                         root
                                         22 Oct 10 20:01 S21avahi-daemon -> ../init.d/avahi-daemon
Trwxrwxrwx
              1 root
                         root
                                         22 Sep 10 04:31 S99rmnologin.sh -> ../init.d/rmnologin.sh
Irwxrwxrwx
              1 root
                         root
                                         23 Sep 10 05:40 S99stop-bootlogd -> ../init.d/stop-bootlogd
Trwxrwxrwx
              1 root
                         root
root@gemuarm64 ...#
```

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Start Script Implementation in Yocto

- Add these lines to your recipe:
- inherit update-rc.d
 - References class which handles install scripts
- INITSCRIPT_PACKAGES = "\${PN}"
 - flag your package as one which uses init scripts
- INITSCRIPT_NAME:\${PN} = "your-start-script-name"
- Then in do_install()
 - install -d \${D}\${sysconfdir}/init.d
 - install -m \${S}/<your-start-script-name> \${D}\${sysconfdir}/init.d



Adding packages to the image

- Add an IMAGE_INSTALL += to your core-image-aesd.bb file referencing your aesd-assignments recipe
 - You can specify other recipes on this line, space separated, to customize your image





Yocto Project Example

- See branch <u>https://github.com/cu-ecen-aeld/yocto-hello-worl</u> <u>d/tree/ecen5013-hello-world</u> for working example.
- See pull request
 https://github.com/cu-ecen-aeld/yocto-hello-worl
 d/pull/1 for changes to support adding hello world
 example package to the base project

Devtool Modify and Iterative Changes

- Equivalent of FOO_OVERRIDE_SRCDIR in buildroot to build based on modified source of a specific component.
 - source poky/oe-init-build-env
 - devtool modify <recipename> (ie aesd-assignments)
 - Will output a workspace location
 - cd to this location and edit source code there

Devtool Modify and Iterative Changes

```
dwalkes@AESD-001:~/yocto-complete-private/build$ devtool modify aesd-assignments

IFO: Source tree extracted to /home/dwalkes/yocto-complete-private/build/workspace/sources/aesd-assignments

IFO: Using source tree as build directory since that would be the default for this recipe

IFO: Recipe aesd-assignments now set up to build from /home/dwalkes/yocto-complete-private/build/workspace/sources/aesd-assignments
```

- Next bitbake run (or build.sh) will use source there instead of at your git repository/commit hash
- git add/ commit/git push to push to your repo (switch to master branch)
- Update commit hash in your .bb file
- devtool reset < recipename > to go back to the settings in your .bb file