

ELEC 221 Lecture 18

CT/DT conversion and sampling DT signals

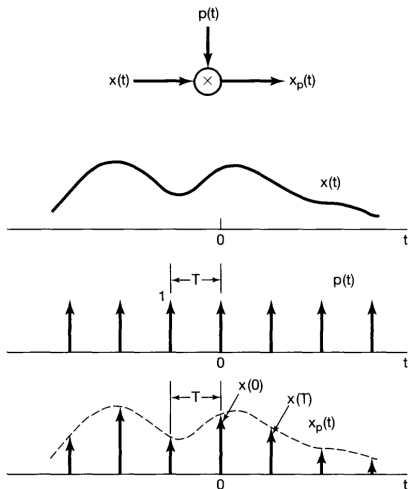
Thursday 14 November 2024

Announcements

- Quiz 8 on Tuesday (L17 and L18)
- Assignment 4 due Saturday 23 Nov at 23:59 (do 4.2, 4.3, 4.4 after today; can try 4.5)
- Tutorial assignment 4 in Monday's tutorial (image processing)

Last time

We modeled **sampling** of CT signals as multiplication of a (band-limited) signal with a periodic impulse train:



Last time

We went to the frequency domain to get a better understanding:

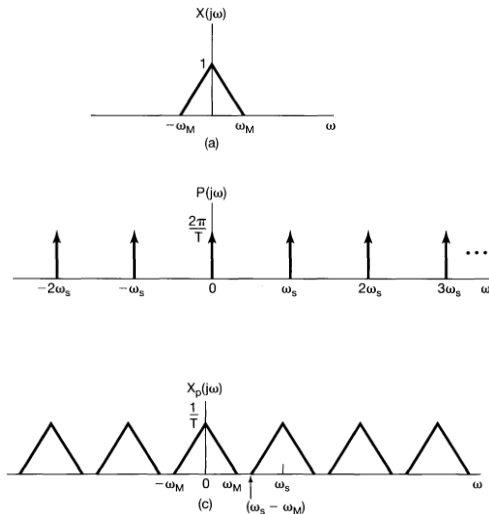


Image credit: Oppenheim 7.1

Last time

We recovered the original signal by applying a low pass filter

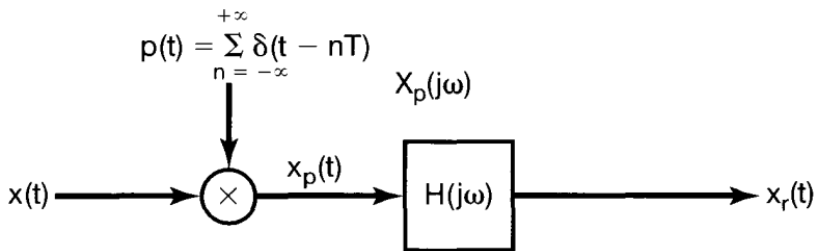
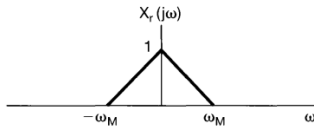
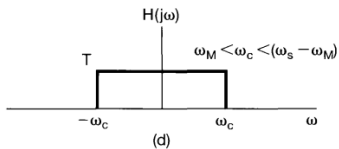
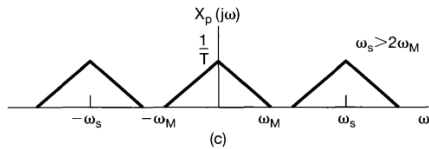


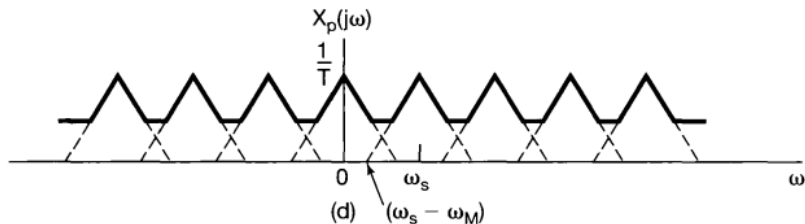
Image credit: Oppenheim 7.1

Last time



Last time

This only works if the sampling rate is higher than the **Nyquist rate**, i.e., $\omega_s > 2\omega_m$



Last time

If the frequency isn't high enough, **aliasing** occurs.

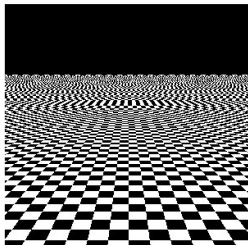
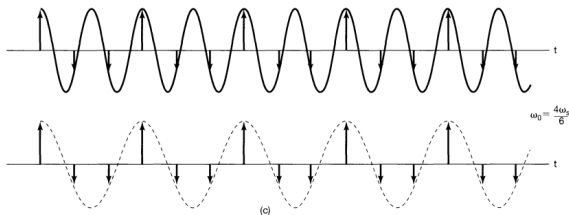


Image credit: Oppenheim 7.3, <https://textureingraphics.wordpress.com/what-is-texture-mapping/anti-aliasing-problem-and-mipmapping/>

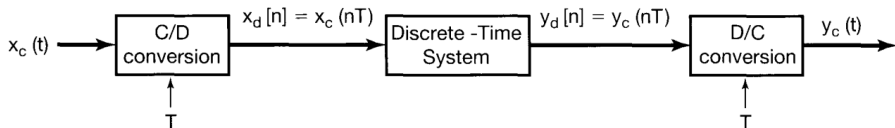
[//textureingraphics.wordpress.com/what-is-texture-mapping/anti-aliasing-problem-and-mipmapping/](https://textureingraphics.wordpress.com/what-is-texture-mapping/anti-aliasing-problem-and-mipmapping/)

Learning outcomes:

- describe the frequency domain effects of sampling from a discrete signal
- decimate and interpolate a DT signal
- determine how decimation and interpolation affect the spectrum of a DT signal

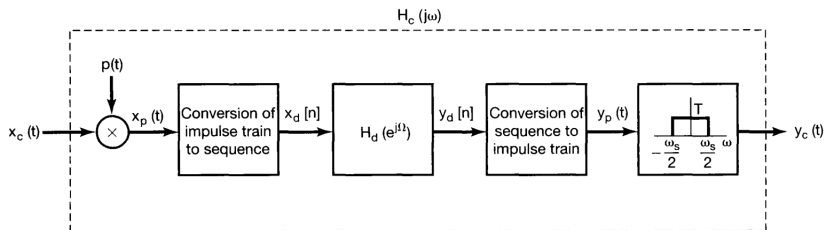
Converting between DT \leftrightarrow CT

Often convenient to process CT signals by first converting to DT, processing, then converting back.



What is the theory that makes this possible?

Converting between DT \leftrightarrow CT



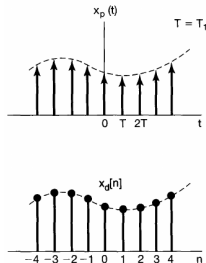
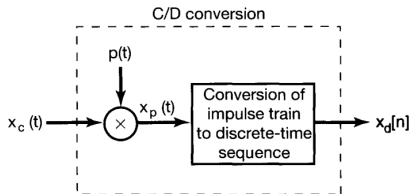
Let's explore what happens at the level of the spectra

Note: we have *two frequencies*, one in CT, one in DT. Write:

$$\begin{aligned} X_c(j\omega), \quad Y_c(j\omega) \\ X_d(e^{j\Omega}), \quad Y_d(e^{j\Omega}) \end{aligned}$$

Converting between DT \leftrightarrow CT

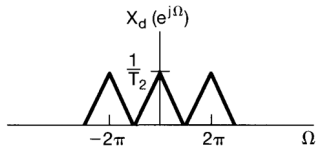
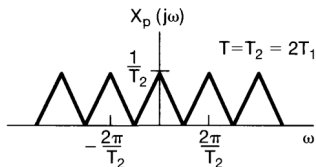
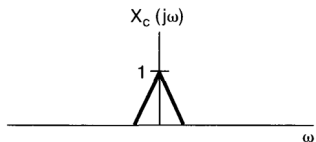
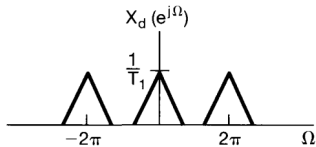
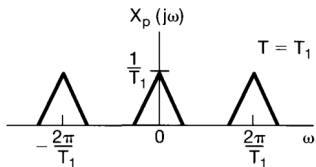
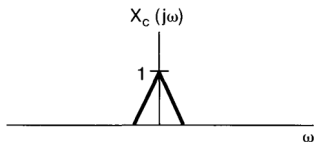
First: how are $X_p(j\omega)$ and $X_d(e^{j\Omega})$ related?



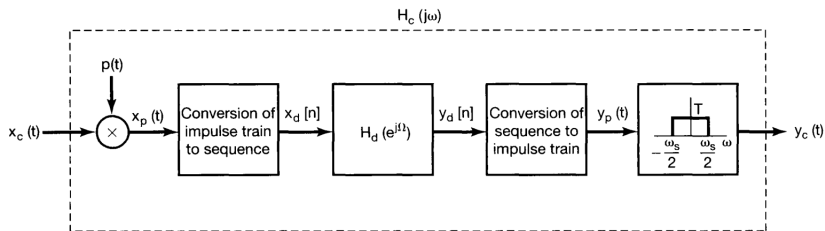
Converting between DT \leftrightarrow CT

Relate $X_d(e^{j\Omega})$ back to the original spectrum $X_c(j\omega)$

Converting between DT \leftrightarrow CT

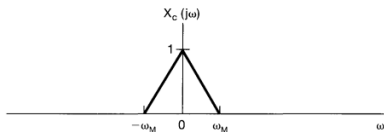


Converting between DT \leftrightarrow CT

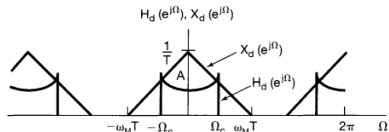


The converted signal $x_d[n]$ enters a DT system:

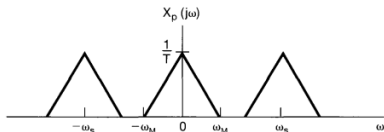
Converting between DT \leftrightarrow CT



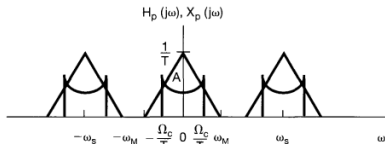
(a)



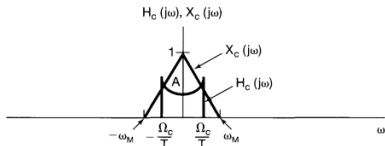
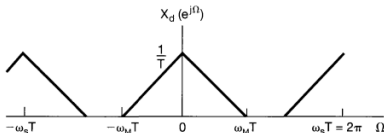
(d)



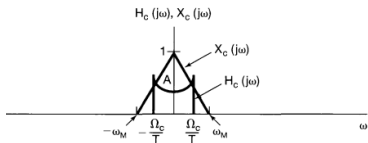
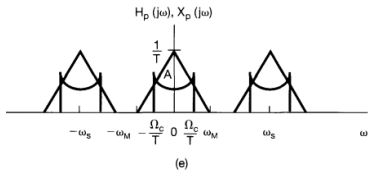
(b)



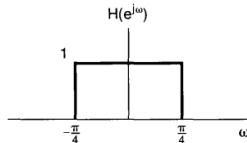
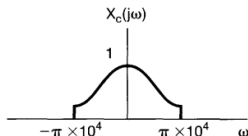
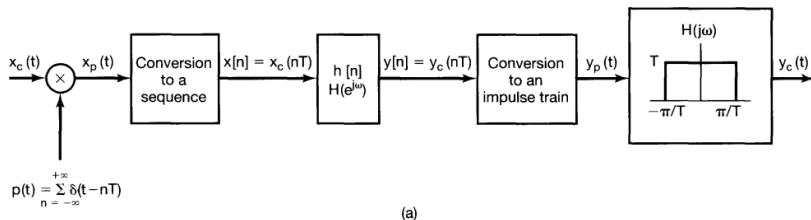
(e)



Sampling of DT signals

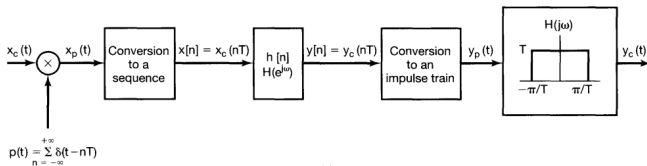


Example

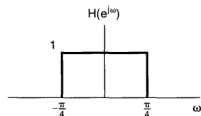
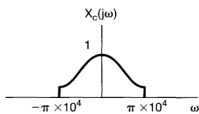


Sketch: $X_p(j\omega)$, $X(e^{j\omega})$, $Y(e^{j\omega})$, $Y_p(j\omega)$, $Y_c(j\omega)$ if $1/T = 20\text{kHz}$.

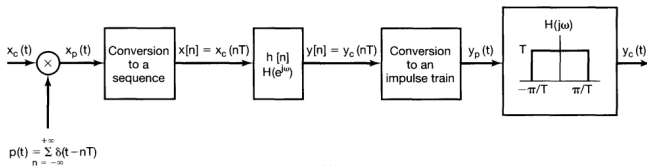
Example



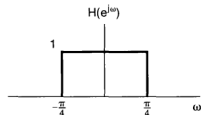
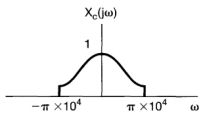
(a)



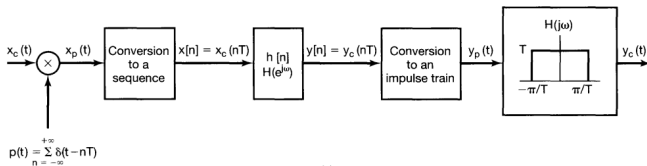
Example



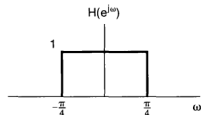
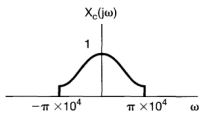
(a)



Example

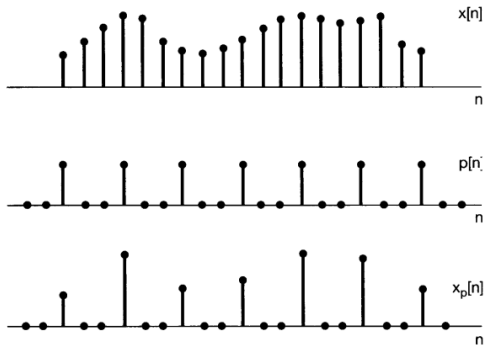


(a)



Sampling of discrete-time signals

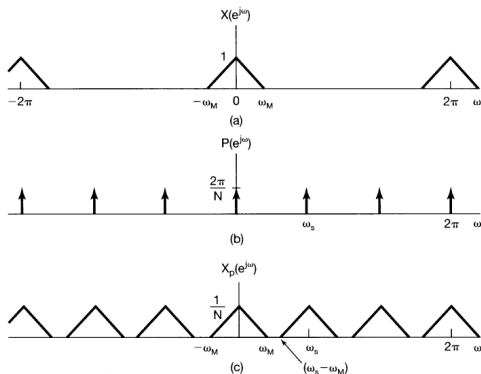
Sample with DT impulse train of period N :



Sampling of discrete-time signals

Take similar approach as we did in CT:

Sampling of discrete-time signals



Sampling of discrete-time signals

Aliasing can happen in DT; some differences due to DT frequency range (π is the highest frequency).

Exercise: suppose $x[n]$ has $X(e^{j\omega})$ that is 0 for $3\pi/7 \leq |\omega| \leq \pi$.
What is the largest sampling period N we can use without aliasing?

Decimation

Sampling and then transmitting a DT signal in this way is inefficient

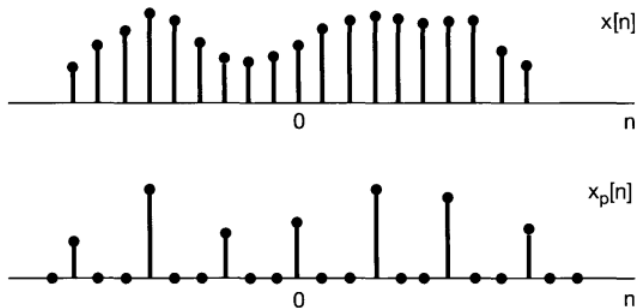
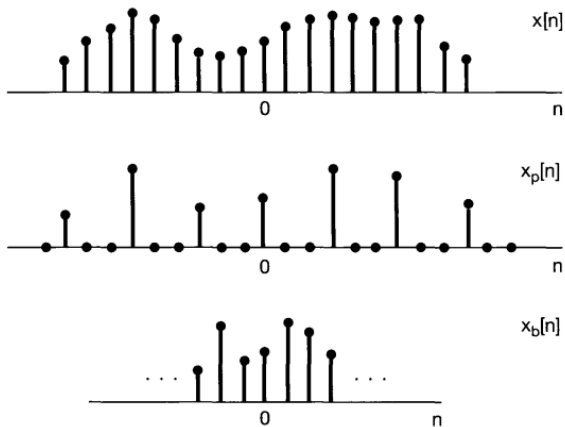


Image credit: Oppenheim 7.31

Decimation

We can *compress* the representation:

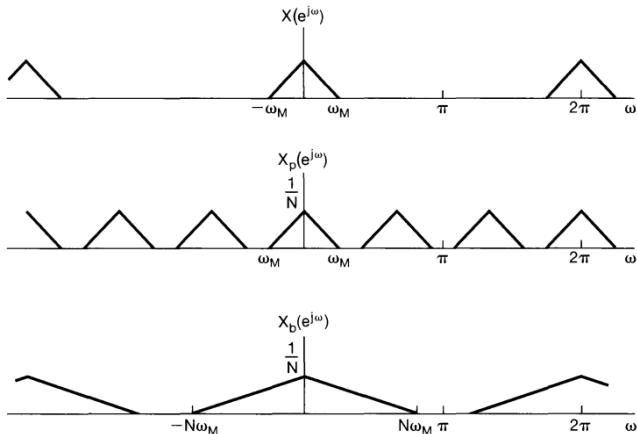


Decimation

Frequency domain effect:

Decimation

Decimation spreads out the spectrum



If original signal was CT, say that decimation has *downsampled* it.

Interpolation (upsampling)

Opposite of decimation: add $N - 1$ points between.

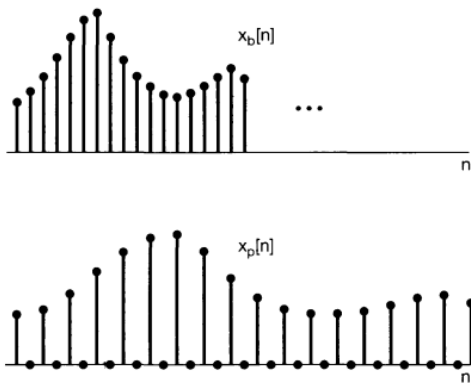


Image credit: Oppenheim 7.5

Interpolation (upsampling)

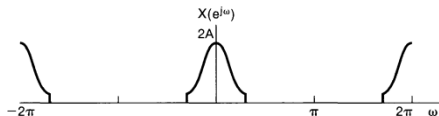
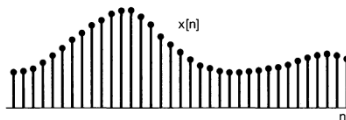
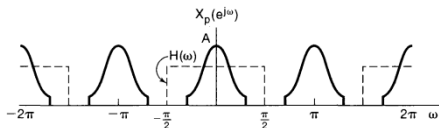
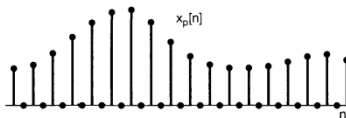
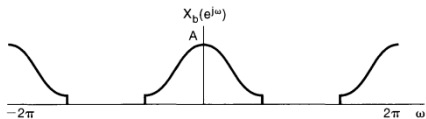
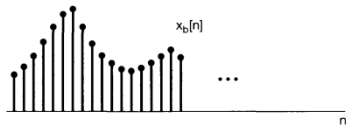


Image credit: Oppenheim 7.5

Example: down/upsampling

Oppenheim problem 7.19,

7.19. Consider the system shown in Figure P7.19, with input $x[n]$ and the corresponding output $y[n]$. The zero-insertion system inserts two points with zero amplitude between each of the sequence values in $x[n]$. The decimation is defined by

$$y[n] = w[5n],$$

where $w[n]$ is the input sequence for the decimation system. If the input is of the form

$$x[n] = \frac{\sin \omega_1 n}{\pi n},$$

determine the output $y[n]$ for the following values of ω_1 :

- (a) $\omega_1 \leq \frac{3\pi}{5}$
- (b) $\omega_1 > \frac{3\pi}{5}$

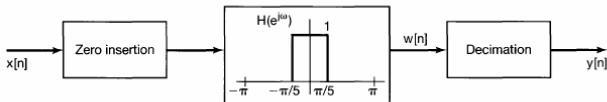


Figure P7.19

Example: down/upsampling

First case: $\omega_1 \leq \frac{3\pi}{5}$

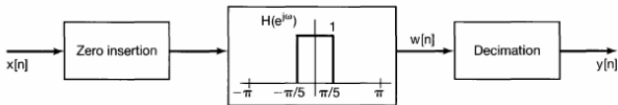


Figure P7.19

Example: down/upsampling

Second case: $\omega_1 > \frac{3\pi}{5}$

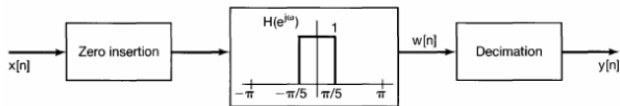


Figure P7.19

For next time

Content:

- moving into topic of modulation / communication systems

Action items:

1. Work on assignment 4
2. Prepare for quiz 8 on Tuesday (L17 and L18 material)
3. Tutorial Assignment 4 Monday

Recommended reading:

- From this class: Oppenheim 7.4-7.6
- Suggested problems: 7.17, 7.18, 7.20, 7.30, 7.32
- For next class: Oppenheim 8.0-8.4