# **ELEC 221 Lecture 21 The Laplace transform**

Tuesday 26 November 2024

### Announcements

- Quiz 9 today
- Tutorial assignment 5 due Monday 23:59
- First part of A5 released; due 8 Dec 23:59

## Last time

We made frequency-division multiplexing more efficient with single-sideband modulation

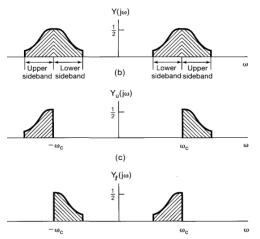
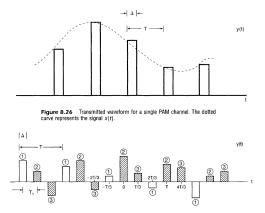


Image credit: Oppenheim 8.4

#### Last time

We saw how AM with a pulse-train carrier can be used for time-division multiplexing, and pulse-amplitude modulation.



You will get to explore this more in A5.

Image credit: Oppenheim 8.6

#### Last time

We discussed how cell phones are radios and how the radio spectrum gets divided (and auctioned off).



https://ised-isde.canada.ca/site/spectrum-management-telecommunications/sites/default/files/attachments/2022/2018\_Canadian\_Radio\_Spectrum\_Chart.PDF

#### The course so far

## Wayyyyy back in lecture 5:

LTI systems and complex exponential functions

To summarize:

$$x(t) = e^{st} \rightarrow y(t) = H(s) \cdot e^{st}$$

Complex exponentials are eigenfunctions of LTI systems.

H(s) is called the **system function**, or *frequency response*, of an LTI system.

## The course so far

## Wayyyyy back in lecture 5:

#### The Fourier series

Let's consider a special set of signals<sup>1</sup>:

$$x(t) = e^{st} = e^{j\omega t}$$

This signal has frequency  $\omega$  and period  $T=2\pi/\omega$ .

We write its system function as  $H(j\omega)$ .

<sup>&</sup>lt;sup>1</sup>We will see the general case at the end of the course.

## Today

#### Learning outcomes:

- distinguish between the Fourier transform and the Laplace transform
- compute the Laplace transform and its region of convergence (ROC) for some basic signals
- represent a ROC using a pole-zero plot
- compute the inverse Laplace transform of basic signals using the ROC

Input a signal into LTI system with impulse response h(t):

If  $s = j\omega$ : Fourier transform

If  $s = \sigma + j\omega$ : (bilateral) **Laplace transform** 

More generally,

We can relate the Laplace and Fourier transforms.

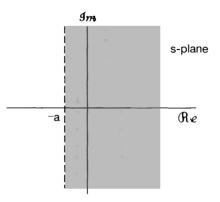
Example: Let 
$$x(t) = e^{-at}u(t)$$
. What is  $X(j\omega)$ ?

Recall: conditions on a?

Example: Let  $x(t) = e^{-at}u(t)$ . What is X(s)?

Conditions on a?

We must specify for which s the Laplace transform is valid.

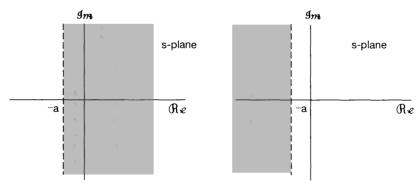


This is called the **region of convergence** (ROC).

Exercise: what is the Laplace transform and ROC of

$$x(t) = -e^{-at}u(-t)$$

Multiple signals can have the same algebraic Laplace transform, but different ROCs.

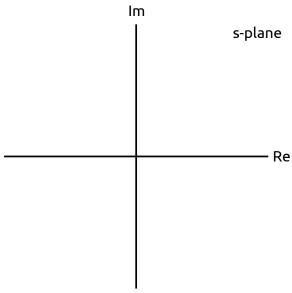


Exercise: what is the Laplace transform and ROC of

$$x(t) = 3e^{-2t}u(t) - 2e^{-t}u(t)$$

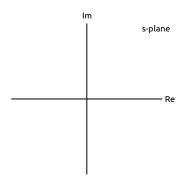
Hint: the Laplace transform is also linear!

Let's draw the ROC:



## Pole-zero plots

X(s) are often rational polynomials of s. Indicate roots on the s-plane using  $\times$  for denominator (poles),  $\circ$  for numerator (zeros):



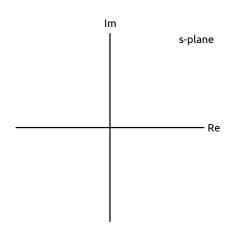
This is a **pole-zero plot**. (May also have poles/zeros at infinity if degree of polynomials is different)

## Pole-zero plots

Exercise: compute the Laplace transform of

$$x(t) = -2e^{-3t}u(t) + 4e^{-4t}u(t)$$

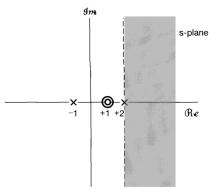
and draw its pole-zero plot.



# Regions of convergence

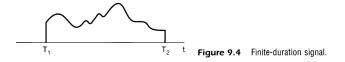
The ROC has many nice properties:

- if ROC doesn't contain  $j\omega$  axis, FT does not converge
- ROC is strips parallel to  $j\omega$  axis
- ROC of rational Laplace transform contains no poles



# Regions of convergence

If x(t) has finite duration and is absolutely integrable, the ROC is the entire s-plane.



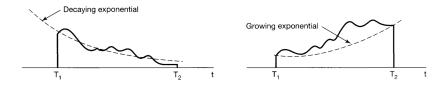
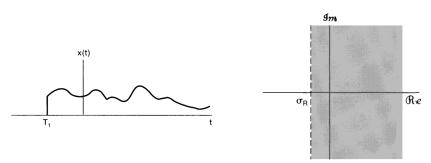


Image credit: Oppenheim 9.2

# Right-sided signals

If x(t) is right sided and  $Re(s) = \sigma_0$  is in the ROC, then all values s.t.  $Re(s) > \sigma_0$  are also in the ROC.

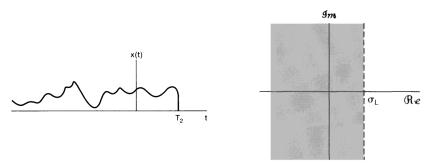


This ROC is called a **right-half plane**.

Intuition: if  $Re(s) = \sigma_1 > \sigma_0$  the exponential in  $x(t)e^{-\sigma t}$  decays even faster and will still converge.

# Left-sided signals

If x(t) is left sided and  $Re(s) = \sigma_0$  is in the ROC, then all values s.t.  $Re(s) < \sigma_0$  are also in the ROC.

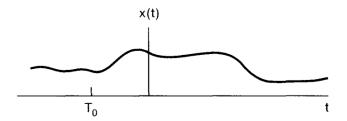


This ROC is called a **left-half plane**.

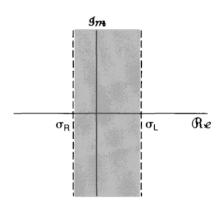
Image credit: Oppenheim 9.2

# Two-sided signals

Any guesses?



# Two-sided signals

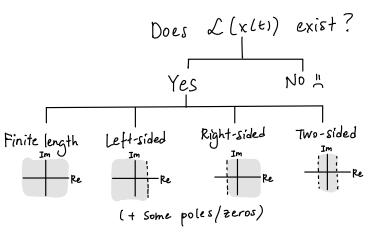


Only works if initial ROCs overlap - otherwise X(s) doesn't exist!

Image credit: Oppenheim 9.2

# Regions of convergence

For any signal x(t)...

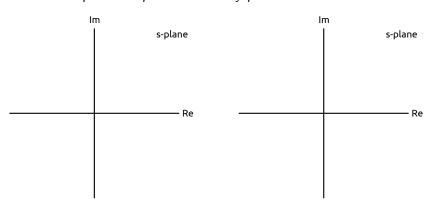


## Regions of convergence

(Oppenheim 9.7) How many signals have a Laplace transform that may be expressed as

$$\frac{s-1}{(s+2)(s+3)(s^2+s+1)}$$

Hint: draw pole-zero plot and identify possible ROCs.





From this, we can invert:

Make a change of variables  $ds = jd\omega$ :

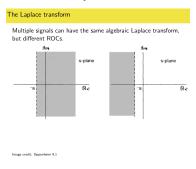
... we are not going to integrate this.

# Inverse Laplace transforms

Suppose

where degree of denominator is higher than numerator.

To invert, we can use our handy identities, BUT the ROC matters.



## Inverse Laplace transforms

Exercise: what is the inverse Laplace transform of

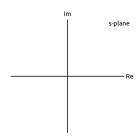
$$X(s) = \frac{s+2}{s^2+7s+12}, \quad -4 < \text{Re}(s) < -3$$

## Inverse Laplace transforms

Exercise: what is the inverse Laplace transform of

$$X(s) = \frac{s+2}{s^2+7s+12}, \quad -4 < \text{Re}(s) < -3$$

Draw the s-plane:



## For next time

#### Content:

properties and system analysis with Laplace transform

#### Action items:

- 1. Thursday class back in person
- 2. Tutorial assignment 5 due Monday 23:59

## Recommended reading:

- From this class: Oppenheim 9.0-9.3, 9.5 (skip 9.4)
- Suggested problems: Oppenheim 9.1-9.9, 9.21, 9.26
- For next class: 9.5-9.8 (skip 9.9)