

Computer Assignment 4

For Scientific Computing MA3012/MA7012

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Task №1.

1. [10 marks] Given a vector of n data points $x = (x_0, x_1, \dots, x_{n-1})^T$, the Discrete Fourier transform (DFT) is defined as

$$y_k = \sum_{l=0}^{n-1} x_l \omega_n^{kl}, \quad k = 0, \dots, n-1.$$

where $\omega_n = e^{-\frac{2\pi i}{n}}$ is the primitive n^{th} root of unity. Write a Matlab function `fastfft.m` which implements the Fast Fourier Transform (FFT) algorithm for computing the DFT. Your function should have x as the input and $y = (y_0, y_1, \dots, y_{n-1})^T$ as the output. Use the algorithm in Chapter 12 slide 16 of Heath's lecture notes as a template for your function. Note that in Heath's template n and ω are also specified as input variables. This is not necessary, since n can be determined from the length of the input vector x and ω can be calculated according to its definition with the given value of n . Test your function by calculating the DFT of the input vector $x = (0, 3, 3, 1, -2, 1, -3)^T$. The result should be the same as that obtained with the Matlab intrinsic function `fft`.

```
function [y]= fastfft(x)
n=length(x);
w=exp((-2*pi)*1i)/n);
m=n/2;
y=zeros(n,1)
    if n == 1
        y(n)=x(n);
    else

        even=zeros(m,1);
        odd=zeros(m,1);

        for k = 0: (m-1)
            even(k+1)=x(2*k+2);
            odd(k+1)=x(2*k+1);
        end
        t=fastfft(even);
        q=fastfft(odd);
        for k=0 : (n-1)
            l=mod(k,(n/2))+1;
            y(k+1)=q(l)+(w.^k*t(l));
        end
    end
end
```

Task N^o2.

2. [20 marks]

a) Composite Simpson's rule with n intervals has the form

$$\int_a^b f(x)dx \approx \frac{h}{6} \left[f(a) + f(b) + 4 \sum_{i=1}^n f\left(a + \left(i - \frac{1}{2}\right)h\right) + 2 \sum_{i=1}^{n-1} f(a + ih) \right],$$

where $h = \frac{b-a}{n}$. Write a Matlab function with the header line `function S = simpson(f, a, b, n)` to

compute this. Test your function on the following example:

```
>> format long
>> S = simpson(@(x) 1./(1-sin(x)), 0, pi/3, 16)
S =
    2.732058440959821
```

```
function [S] = simpson(f, a, b, n)
h=(b-a)/n
```

```
for i=1:n
    s1(i)=f(a+(i-1/2)*h)
end
for i=1:n-1
    s2(i)=f(a+i*h)
end
```

```
S=(h/6) * (f(a) + f(b) + 4 * sum(s1) + 2 * sum(s2))
```

```
end
```

b) Write a Matlab function `gaussquad.m` which calculates approximate value of the integral $\int_a^b f(x)dx$ using the Gaussian Quadrature with up to 3 nodes. The function header should be

`function G = gaussquad(f, a, b, k)`, where k can take values 1, 2, or 3. The nodes and weights can be found in the table on p. 112 of Pav's lecture notes (note that $k = n + 1$). You should get the following results for the test example:

```
>> G = gaussquad(@(x) 1./(1-sin(x)), 0, pi/3, 1)
G =
    2.094395102393195
>> G = gaussquad(@(x) 1./(1-sin(x)), 0, pi/3, 2)
G =
    2.647865728063311
>> G = gaussquad(@(x) 1./(1-sin(x)), 0, pi/3, 3)
G =
    2.723239447875524
```

```
function [G] = gaussquad(f, a, b, k)
for i=1:k
    if k==1
        x(1)=0
        A(1)=2
    elseif k==2
        x(1)=-sqrt(1/3)
        x(2)=sqrt(1/3)
        A(i)=k-1
    elseif k==3
        x(1)=-sqrt(3/5);
        x(2)=0;
        x(3)=sqrt(3/5);
        A(1)=5/9;
        A(2)=8/9;
        A(3)=5/9;
    end
end
G=sum(A.*((b-a)/2) .* f((b-a).*x+(b+a)/2))
end
```

- c) Write a Matlab function with a header line `function G = compgaussquad(f, a, b, k, n)`, which uses the function from part b), or otherwise, to approximate the integral $\int_a^b f(x)dx$ using a *composite* Gaussian quadrature with n intervals. Test your function with the following example:

```
>> G = compgaussquad(@(x) 1./(1-sin(x)), 0, pi/3, 3, 16)
G =
    2.732050802516621
```

```
function CP = copmgaussquad(f,a,b,k,n)
iappx = 0;
x(1)=a;
for i=2:n
    x(i) = a + (b-a) * i / n;
end
x
for i=1:n-1
    iappx(i) = gaussquad(f,x(i),x(i+1),k);
end
CP=sum(iappx)
end
```

- d) Use your functions from a) and c) to find approximate value of the integral $\int_0^{\pi/3} 1/(1 - \sin x) dx$ using $n = 2^m$ intervals with $m = 2, 3, \dots, 10$ and $k = 1, 2$, and 3 in case of the composite Gaussian quadrature. Given that the exact value of the integral is $1 + \sqrt{3}$, plot the absolute error for each method as a function of $h = (b - a)/n$ on a log-log scale. From the obtained plots, determine the order of accuracy of each method, i.e., you should

observe that the error is $O(h^p)$ and determine p . Comment on the observed order of accuracy of the four methods compared to the theoretical prediction.

```
function [P]=plotgaussererror()
f=@(x)1./(1-sin(x));
a=0; b=pi/3;
m=(2:10);
k=(1:3);
EXV=1+sqrt(3);
for i=1:length(m)
    n(i)=2^m(i);
    h(i)=(b-a)/n(i);
end
for i=1:length(k)
    for j=1:length(n)
        CP(j,i) = compgaussquad(f,a,b,k(i),n(j));
        SP(j) = simpson(f, a, b, n(j));
        ERR1(i,j)=abs(EXV-CP(j,i));
        ERR2(j)=abs(EXV-SP(j));
    end
end
for i=1:length(k)
    for j=1:length(n)-1
        p1(i,j)=(log(ERR1(i,j))-log(ERR1(i,j+1)))/(log((b-a)/n(j))-log((b-a)/n(j+1)));
        p2(j)=(log(ERR2(j))-log(ERR2(j+1)))/(log((b-a)/n(j))-log((b-a)/n(j+1)));
    end
end
p1%compgaussquad k=1
p2%simpson
P1=min(p1)
P2=min(p2)
loglog(h,ERR1(1,:),h,ERR1(2,:),h,ERR1(3,:),h,ERR2);
xlabel('h');ylabel('Error')
legend('compgaussquad k=1','compgaussquad k=2','compgaussquad k=3','simpsons')
end
```

3. [10 marks] Consider the initial value problem $du/dt = u(1 - u^2)$, $u(0) = 0.1$.

- Write a Matlab function `flowmap.m` which calculates the flow map of this initial value problem. *Hint:* The function should output the value of the exact solution $u(t)$ of this IVP.
- Write a Matlab program which computes the local and global errors of Euler's method along the solution from $t = 0$ to $t = 5$. Plot the local and global errors as functions of t for the numerical solutions with step sizes $h = 0.2$ and $h = 0.1$. Comment on how the local and global errors scale with the step size.
- Same as b), but for the explicit midpoint method (see bottom of p. 10 of my lecture notes on Numerical Solution of ODEs).

File `flowmap.m`

```
function [U] = flowmap(u0,t)
U=u0*exp(t)/(sqrt(-
u0^2+(1+u0^2*exp(2*t))))
end
```

File `exact.m`

```
function [UE,UE2,t,t2]=exact(u0)
t=0:0.1:5
t2=0:0.2:5
UE(1)=u0
UE2(1)=u0

for k=2:length(t)
    UE(k)=flowmap(u0,0.1)
end
for k=2:length(t2)
    UE2(k)=flowmap(u0,0.2)
end
end
```

File euler.m

```
function U=euler(f,a,b,u0,N)
h=(b-a)/N;
U=zeros(1,N);
U(1)=u0;
for j=1:N
    U(j+1)=U(j)+h*f(U(j));
end
end
```

File err.m

```
function [LER,GER] = err(E,T,h)

LER(1)=0.1-E(1);
for i=2:length(T)
LER(i)=flowmap(E(i-1),h)-E(i);
end

for i=1:length(T)
GER(i)=flowmap(0.1,T(i))-E(i);
end
GER=GER'
```

File ploterror.m

```
function [P]=ploterror(u0)

[UE,UE2,t,t2]=exact(u0);

E=euler(@(u)u*(1-u^2),0,5,u0,50);
E2=euler(@(u)u*(1-u^2),0,5,u0,25);

[LER,GER] = err(E,t,0.1);
[LER2,GER2] = err(E2,t2,0.2);

figure(1)
xlabel('t'), ylabel('Error');
plot(t,GER,t,LER);
title('Local and Global Error h=0.1');
legend('Global error','Local error');

figure(2);
xlabel('t'), ylabel('Error');
plot(t2,GER2,t2,LER2);
legend('Global error','Local error');
title('Local and Global Error h=0.2')

end
```

File midpoint.m

```
function UM=midpoint(f,a,b,u0,N)
h=(b-a)/N;
UM=zeros(1,N);
UM(1)=u0;
for j=1:N
    UU(j)=UM(j)+h/2*f(UM(j))
    UM(j+1)=UM(j)+h*f(UU(j))
end
end
```


File ploterror_midpoint.m

```
function [P]=ploterror_midpoint(u0)

[UE,UE2,t,t2]=exact(u0);

E=midpoint(@(u)u*(1-u^2),0,5,u0,50);
E2=midpoint(@(u)u*(1-u^2),0,5,u0,25);

[LER,GER] = err(E,UE,t);
[LER2,GER2] = err(E2,UE2,t2);

figure(1)
xlabel('t'), ylabel('Error');
plot(t,LER,t,GER);
title('Local and Global Error h=0.1');
legend('local error','global error');

figure(2);
xlabel('t'), ylabel('Error');
plot(t2,LER2,t2,GER2);
legend('local error','global error');
title('Local and Global Error h=0.2')

end
```