# Exercice 1 - Simplex implementation

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### 1 Introduction

This work solves the following problem:

minimize 
$$z = 2x_1 - 10x_2 + x_3 + 4x_4$$
  
subject to  $3x_1 + 6x_2 3x_4 \le 100$   
 $10_4 + x_2 + 6x_3 \ge 50$   
 $-3x_1 + x_2 + 6x_3 \ge 30$   
 $x > 0$ 

#### 1.1 How it works

This problem is solved by running simplex2 implementation without specifying a feasible base. The function simplex2 calls simplex1 in order to find a feasible base, after that using the found base the function is called again solving problem.

#### 1.2 Results

The optimum result for this problem is:

$$z = -119.0278$$
  
 $x = [0, 14.1667, 2.6389, 5.0000]$ 

#### 1.3 Input parameters

The simplxe2 implementation was configured as follows:

## 2 Source Code

## simplex1.m

```
function [x, z, I, it, tipo] = simplex1(A, b, c, I)
       [ \tilde{ } , n ] = size(A);
2
       J \ = \ 1\!:\! n\,;
4
       J(I) = [];
       it = 0;
        while true
            it = it + 1;
10
11
            Ai = A(:, I) ^ -1;
12
            Aj = A(:, J);
            ci = c(:, I);
            cj = c(:, J);
15
16
            pi = ci * Ai;
17
            ccj = pi * Aj - cj;
19
            z = pi * b;
21
            x = n:1;
            x(I) = Ai * b;
23
            x(J) = 0;
            x = x.;
25
26
            [t,k] = \max(ccj);
27
28
            if ccj == 0
29
                 tipo = 1;
30
                 break;
31
             elseif t <= 0
32
                 tipo = 0;
```

```
break;
34
            else
35
                 xi = Ai * b;
36
                Ak = Ai * A(:, J(k));
38
                byk = xi./Ak;
39
40
                byk(byk \le 0) = inf;
41
                 [t, r] = \min(byk);
42
                 if t = inf
44
                     tipo = -1;
45
                     break;
46
                end
47
                [J(k), I(r)] = deal(I(r), J(k));
49
            \quad \text{end} \quad
50
       end
51
  end
  simplex2.m
   function [x, z, I, it, tipo] = simplex2(A, b, c)
       [m,n] = size(A);
       I = 1:n+m;
3
       ct = zeros(1, n+m);
5
       I(1:n) = [];
       ct(I) = 1;
       B = horzcat(A, eye(m));
10
       [x, z_f1, I_f1, it_f1, ^] = simplex1(B, b, ct, I);
^{11}
12
       if z_-f1 = 0
            [x, z, I, it_f2, tipo] = simplex1(A, b, c, I_f1);
14
            it = it_f2 + it_f1;
16
       end
```

18 end