# Nonlinear Equations Bisection and Regula Falsi

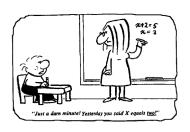
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#### References

- S. Chapra and R. Canale, Numerical Methods for Engineers
- A. Greenbaum and T. Chartier, Numerical Methods: Design, Analysis, and Computer Implementation of Algorithms
- ► M. Heath, Scientific Computing: An Introductory Survey Check out the interactive educational modules\* associated with "nonlinear equations"

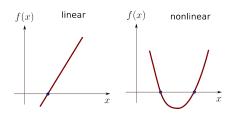


<sup>\*</sup>http://www.cse.illinois.edu/iem/

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- Nonlinear equations, f(x) = 0, arise in numerous applications
- ▶ Unlike linear equations, f(x) = mx + c = 0, they can have multiple solutions or *roots*



- ▶ Often we are after one of the many solutions
- We specify which one by prescribing a range (bisection and regula falsi), or an initial guess (Newton's and secant methods)

Consider the problem of the sky-diver. We found:

$$v(t) = \sqrt{\frac{mg}{c_d}} \tanh\left(\sqrt{\frac{gc_d}{m}}t\right)$$

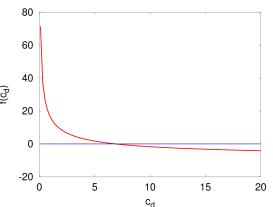
- ▶ Suppose, you are a parachute company (interested in controlling  $c_d$ ). You want to ensure that the velocity after 20 seconds is v(t = 20s) = 10 m/s.
- ▶ Assume m = 70 kg, and g = 9.8 m/s<sup>2</sup>. Substituting:

$$10 = \sqrt{\frac{70 \times 9.8}{c_d}} \tanh\left(\sqrt{\frac{9.8c_d}{70}}20\right)$$

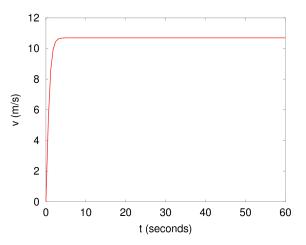
▶ That is, we want to solve the nonlinear equation:

$$f(c_d) = \frac{26.1916}{\sqrt{c_d}} \tanh(7.4833\sqrt{c_d}) - 10 = 0$$

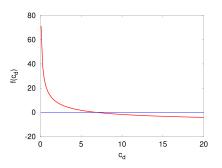
• Let us first plot  $f(c_d)$ 



Let us double check that these numbers make sense. Hence replot v(t) with  $c_d=6$ 

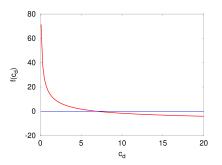


#### **Bisection Method**



- ▶ Observe from the example that the function changes signs near the root (say  $x^*$ )
- As the x changes from a=1 to b=20, the function f(x) goes from being positive to negative.
- ▶ We say that the root  $x^*$  of f(x) is *bracketed* by a and b.

#### **Bisection Method**



- ▶ More formally, a root  $x^*$  of a continuous function f(x) is bracketed by a and b, if for  $a \le x^* \le b$ , f(a)f(b) < 0
- $\blacktriangleright$  Bisection proceeds by dividing the interval [a,b] by half in every iteration
- ► Once the root is bracketed, bisection is guaranteed to converge to the solution

## Bisection Algorithm

- 1. Get the bracketing interval [a,b] by numerical experimentation or prior knowledge of the behavior of f(x).
- 2. Propose initial estimate of the root as

$$x_r = a + \frac{b-a}{2} = \frac{a+b}{2}.$$

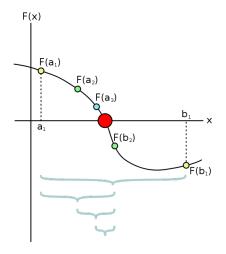
3. To determine which subinterval ( $[a, x_r]$  or  $[x_r, b]$ ) evaluate  $f(a)f(x_r)$ 

if 
$$f(a)f(x_r)$$
 
$$\begin{cases} <0, &\Longrightarrow x^* \in [a, x_r], \text{ set } b=x_r \\ =0, &\Longrightarrow x^*=x_r \\ >0, &\Longrightarrow x^* \in [x_r, b], \text{ set } a=x_r \end{cases}$$

4. Goto step 2 and repeat until  $x^* = x_r$  or b - a is small enough.

## Bisection Algorithm

► Graphically,<sup>†</sup>



<sup>†</sup>wikipedia.org

### Example

Let us use this method to solve our equation (sub: x for  $c_d$ ), with a=1 and b=20

$$f(x) = \frac{26.1916}{\sqrt{x}} \tanh \left(7.4833\sqrt{x}\right) - 10 = 0$$

i	a	b	$x_r$	$\epsilon_a$	$\epsilon_t$
0	1.0000	20.0000	10.5000		53.06
1	1.0000	10.5000	5.7500	82.61	16.18
2	5.7500	10.5000	8.1250	29.23	18.44
3	5.7500	8.1250	6.9375	17.12	1.13
4	5.7500	6.9375	6.3438	9.36	7.53
5	6.3438	6.9375	6.6406	4.47	3.20
7	6.7891	6.9375	6.8633	1.08	0.05
12	6.8586	6.8633	6.8610	0.03	0.01

## Example

 $ightharpoonup \epsilon_t$  is the true relative error:

$$\epsilon_t = 100 \times \left| \frac{x_r^{new} - x^*}{x_r^{new}} \right|$$

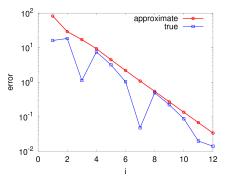
▶ However,  $x^*$  is not known in advance, hence compute the approximate relative error:

$$\epsilon_a = 100 \times \left| \frac{x_r^{new} - x_r^{old}}{x_r^{new}} \right|$$

 $\blacktriangleright$  Can use these estimates of error to determine stopping criterion, say  $\epsilon_a < 10^{-4}$ 

## Example

▶ Note the linear "convergence" of  $\epsilon_a$ 



ullet  $\epsilon_t$  generally is not as smooth, but here  $\epsilon_t < \epsilon_a$ . So using  $\epsilon_a$  to prescribe a stopping criteria is conservative.

#### Bisection: Convergence

- ▶ Let us say that we set  $\epsilon_{stop}$  as the stopping criteria.
- ▶ That is we stop interval halving, when the root has been narrowed down to a subinterval of size  $2\epsilon_{stop}$ .
- After i steps the size of the subinterval is  $(b-a)/2^i$ . Hence we want:

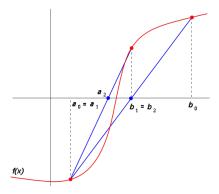
$$\frac{|b-a|}{2^{i}} \leq 2\epsilon_{stop}$$

$$\frac{|b-a|}{\epsilon_{stop}} \leq 2^{i+1}$$

$$i \geq \log_2\left(\frac{|b-a|}{\epsilon_{stop}}\right) - 1$$

- ▶ In bisection method, we do not use the actual magnitudes of f(x), only the signs
- ▶ Can we use the magnitudes to improve convergence?
- This idea leads to Regula Falsi, or the method of false position
- Like bisection, we first need an interval [a, b] that brackets the root  $x^*$ .
- ▶ Instead of halving the interval every iteration, we "connect" the end-points (a, f(a)) and (b, f(b)) and use the point at which the line intersects the x-axis as the guess  $x_r$ .

Graphically,<sup>‡</sup>



lacktriangle The only difference between this method and bisection is how  $x_r$  is determined

<sup>&</sup>lt;sup>‡</sup>wikipedia.org

▶ By considering "similar triangles"

$$\frac{f(a)}{x_r - a} = \frac{f(b)}{x_r - b}$$

▶ Solving for  $x_r$  leads to

$$x_r = \frac{f(b)a - f(a)b}{f(b) - f(a)}$$

▶ Algorithm is exactly the same as bisection except step 2, where  $x_r$  is determined by the formula above

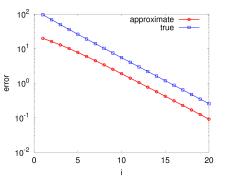
- Guaranteed to converge like bisection
- ► However, convergence can be poor, especially if the same end point is repeatedly selected

Skydiving parachute example:

i	a	b	$x_r$	$\epsilon_a$	$\epsilon_t$
1	1.0000	16.1286	13.4534	19.89	96.11
2	1.0000	13.4534	11.5843	16.13	68.87
3	1.0000	11.5843	10.2655	12.85	49.64
4	1.0000	10.2655	9.3268	10.06	35.96
5	1.0000	9.3268	8.6538	7.78	26.15
10	1.0000	7.3737	7.2371	1.89	5.50
15	1.0000	6.9701	6.9410	0.42	1.18
20	1.0000	6.8838	6.8775	0.09	0.26

#### Error

▶ Decay is slower than bisection and  $\epsilon_t > \epsilon_a$ .



- ► It is possible to combine regula falsi and bisection to create a faster method
- Switch back to bisection if one of the endpoints remains unchanged for a few iterations (also google "Illinios method")

## **Taylor Series**

- ▶ The most-used theorem in numerical analysis
- ▶ A common form involves expanding f(x) around x = a

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^{2} + \frac{f^{(3)}(a)}{3!}(x-a)^{3} + \cdots$$
$$= \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!}(x-a)^{n}$$

▶ Higher derivatives of f(x) at the point a tell me something about the function far away from a. If you know all the (infinite) derivatives at x = a, then you effectively know the "function" f(x)

## Taylor Series with Remainder

A far more useful form is Taylor series with remainder

$$f(x) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \frac{f^{(n+1)}(\xi)}{n+1!}(x-a)^{n+1}$$

for some  $\xi \in (x, a)$ .

▶ An equivalent form which is sometimes also useful is:

$$f(x+h) = f(x) + \frac{f'(x)}{1!}h + \frac{f''(x)}{2!}h^2 + \cdots + \frac{f^{(n)}(x)}{n!}h^n + \frac{f^{(n+1)}(\xi)}{n+1!}h^{n+1}$$

for some  $\xi \in (x, x + h)$ .

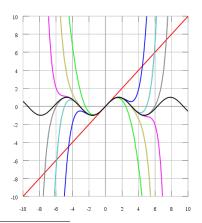
## Taylor Series

- ► For the Taylor series to be written out, the function has to be sufficiently smooth (all the derivatives in the expansion should exist)
- ▶ If h is small, then h<sup>n</sup> rapidly decays to zero. This allows us to approximate functions by truncating the series after a certain number of points
- ► Conversely, the remainder term tells us that as *h* becomes large, the truncated Taylor expansion represents the function poorly

# Taylor Series Example

▶ Consider the Taylor expansion of sin(x)§

$$\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$



# Taylor Series Example 2

Problem: What is the remainder term of a third order Taylor expansion of  $f(x) = e^{2x}$  around a = 0.

Solution: Here a=0 and n=3. Thus, we can write the Taylor expansion as:

$$f(x) = f(0) + \frac{f'(0)}{1!}x + \frac{f''(0)}{2!}x^2 + \frac{f^{(3)}(0)}{3!}x^3 + \frac{f^{(4)}(\xi)}{4!}x^4$$

$$f(0)=e^{2\cdot 0}=1;\ f'(0)=2e^{2\cdot 0}=2;\ f^{(n)}(0)=2^n;\ f^{(n)}(\xi)=2^ne^{2\xi}$$
 Thus,

$$f(x) = 1 + 2x + 2x^2 + \frac{4}{3}x^3 + \frac{4e^{2\xi}}{6}x^4$$