



GEOF-322

A brief Introduction to Doppler Wind Lidars

22 February 2022, Christiane Duscha

Outcomes of this Lecture

- 1) What is the potential and what are the shortcomings of different Lidar systems?
- 2) What does a Lidar observe?
- 3) How can we utilise these observations?

Types of Doppler Wind Lidar

Wind Profiling Lidar



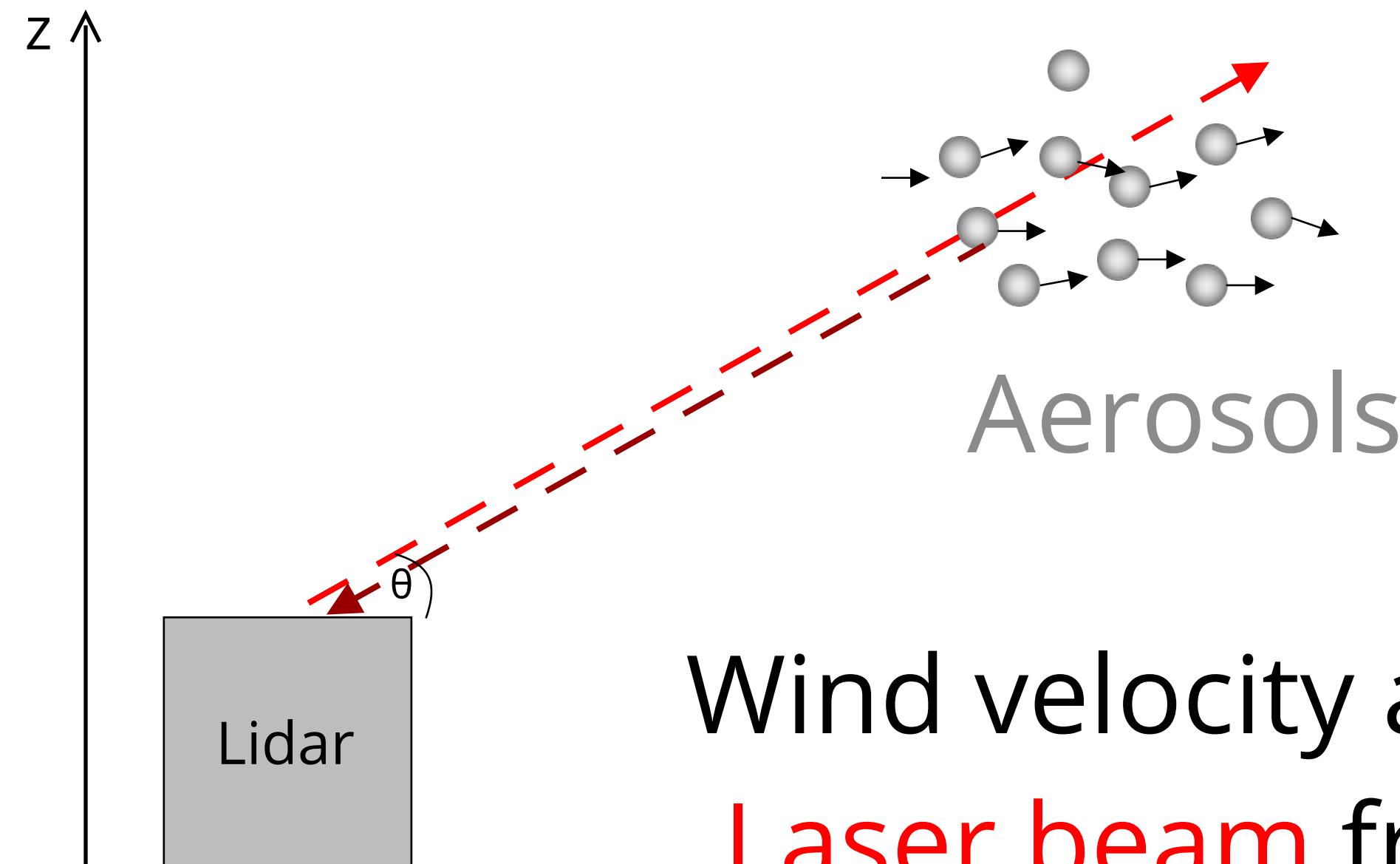
Wind Scanning Lidar



- + mobile
- short range (~200 -300m)
- + cheap
- fixed measurement pattern
(only wind profiles)

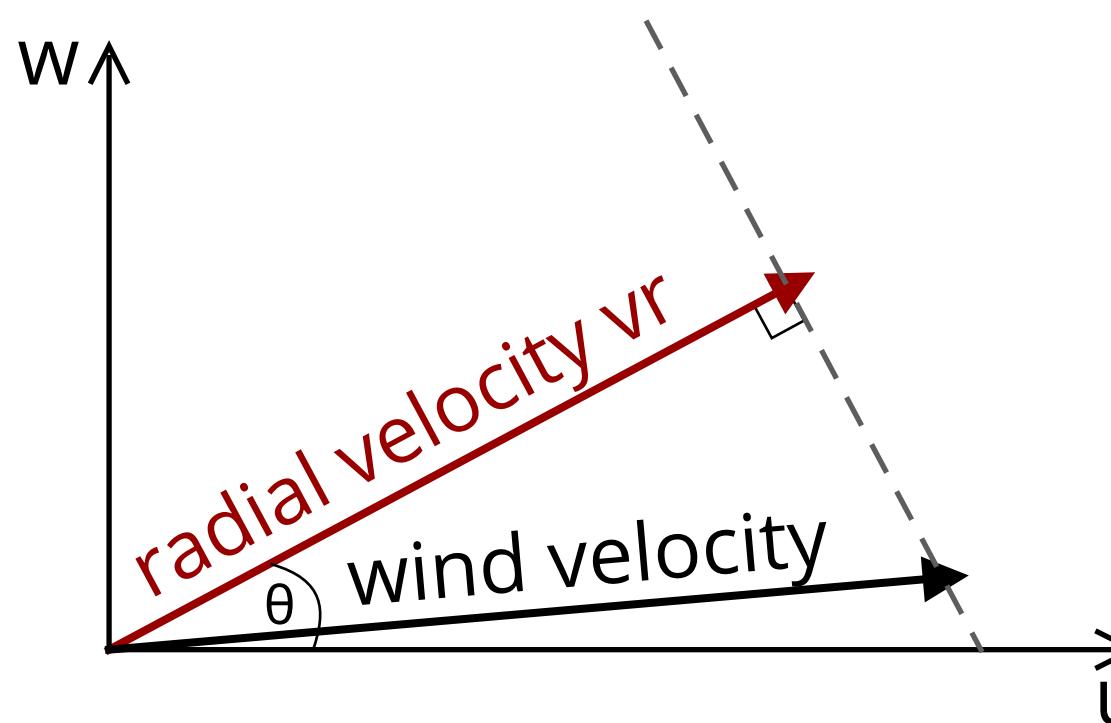
- + long range
- heavy (~ 300kg)
- + programmable
- expensive

Measurement principle lidar



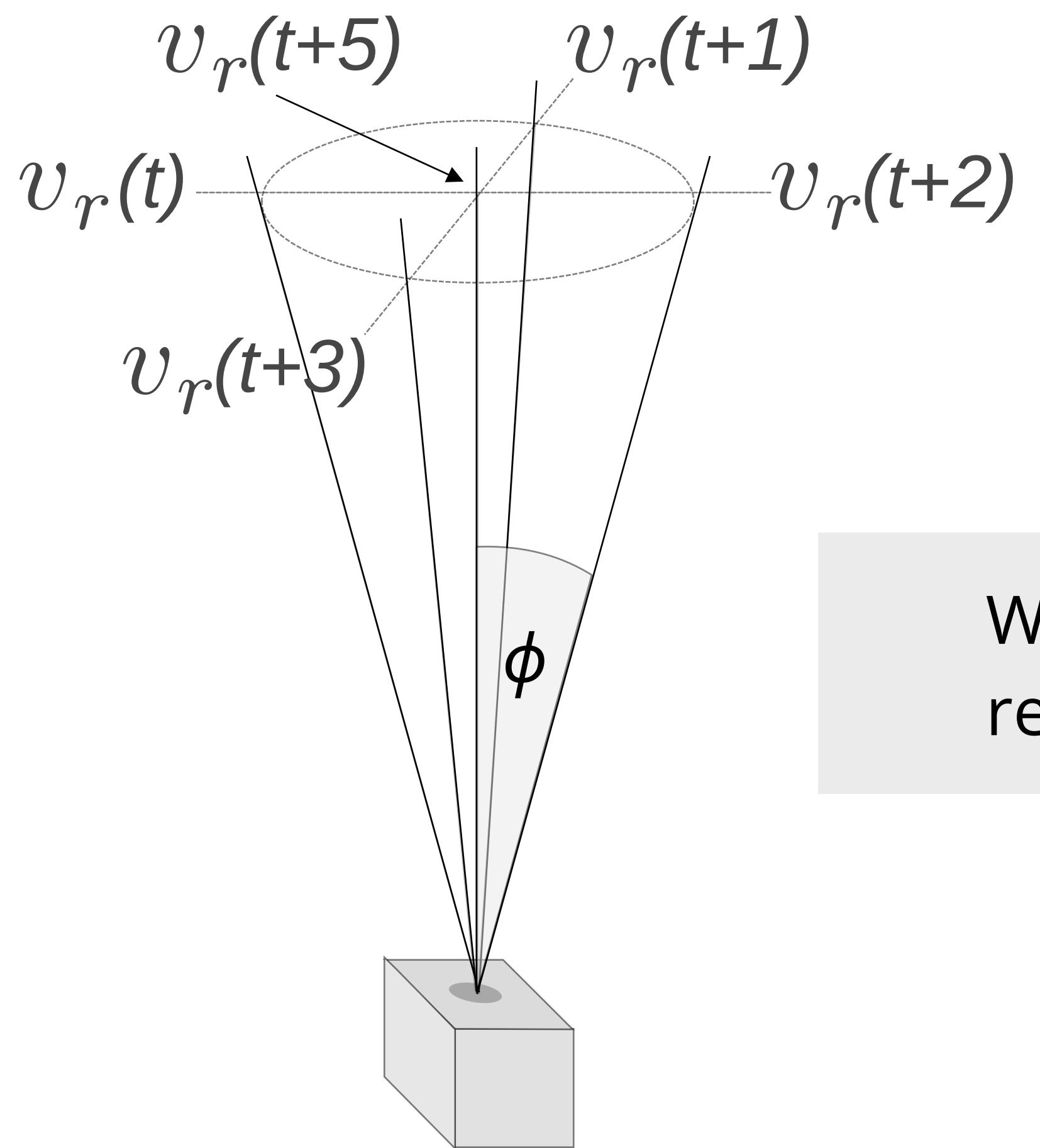
Interaction of **Laser beam** at distance r with Aerosol particles, which are transported by the wind

Wind velocity along the **line of sight** (LOS) of the **Laser beam** from **doppler shift (radial velocity)**

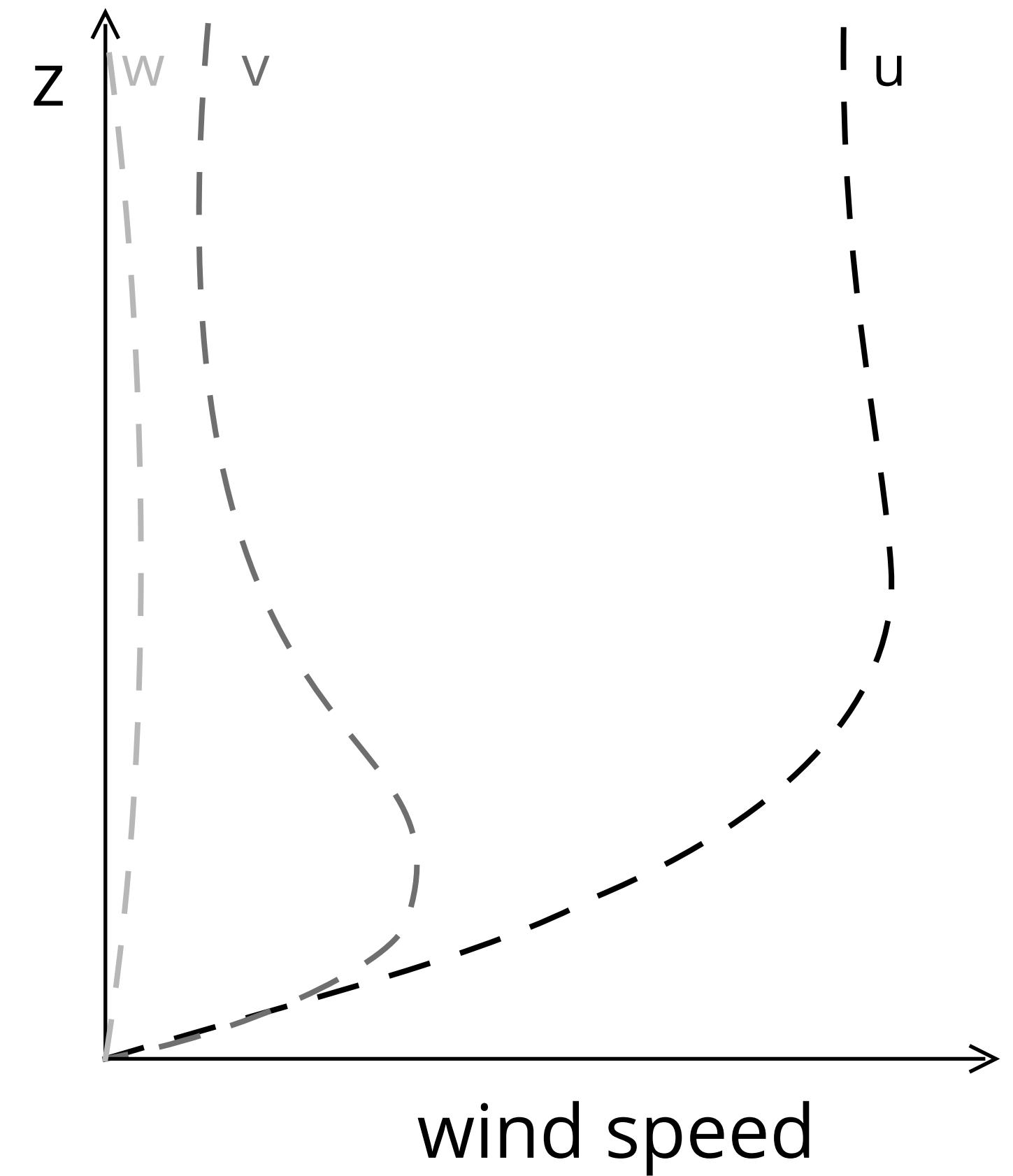


$$v_r(r, \theta) = u(r, \theta) \cos\theta + w(r, \theta) \sin\theta$$

Profiling lidar



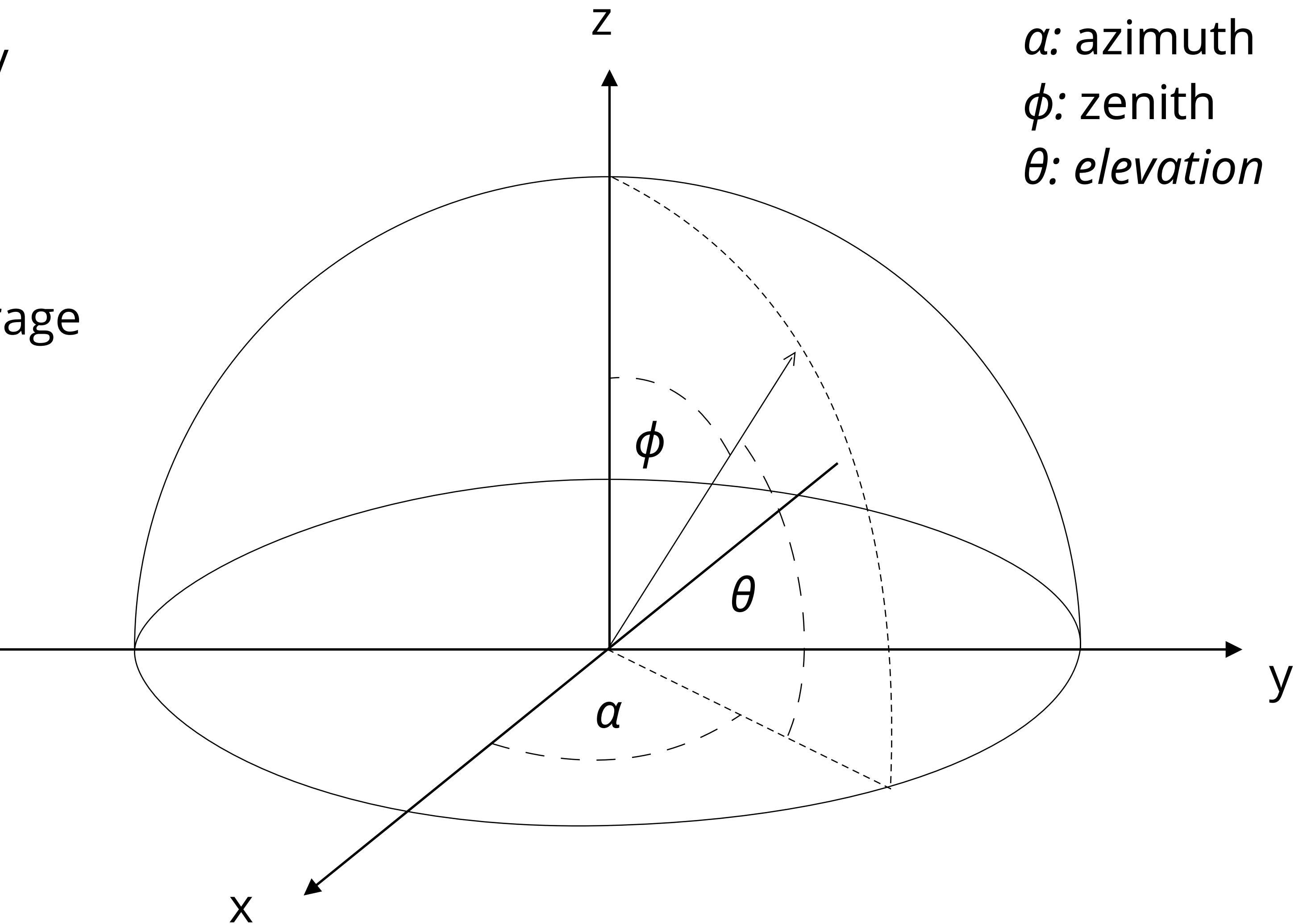
Wind profile
(3 wind speed components)



Scanning lidar

Are not limited to a single strategy
(e.g. observing the wind profile)

and several instruments can be
combined to achieve spatial coverage

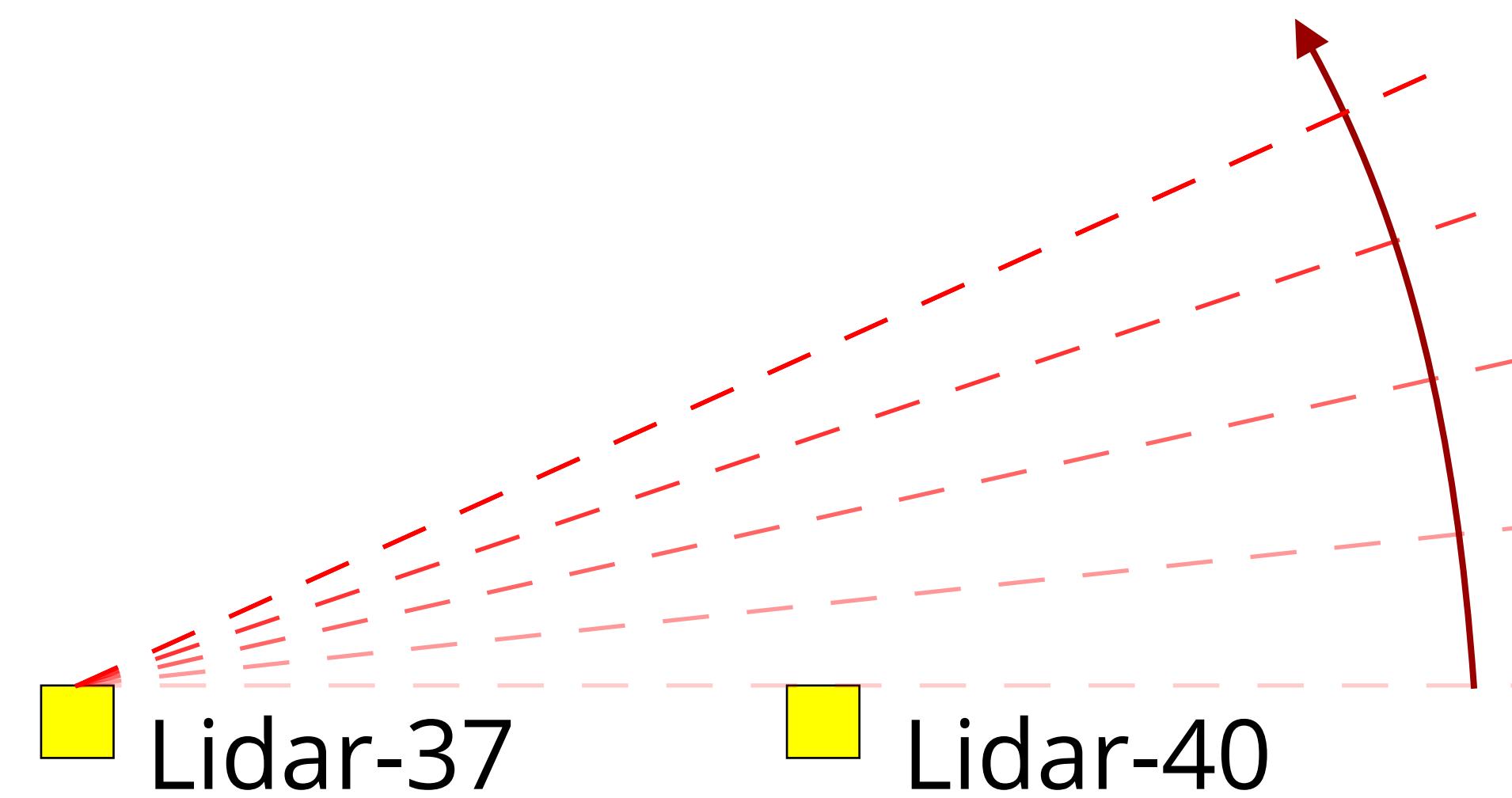


a : azimuth
 ϕ : zenith
 θ : elevation

Scanning strategy

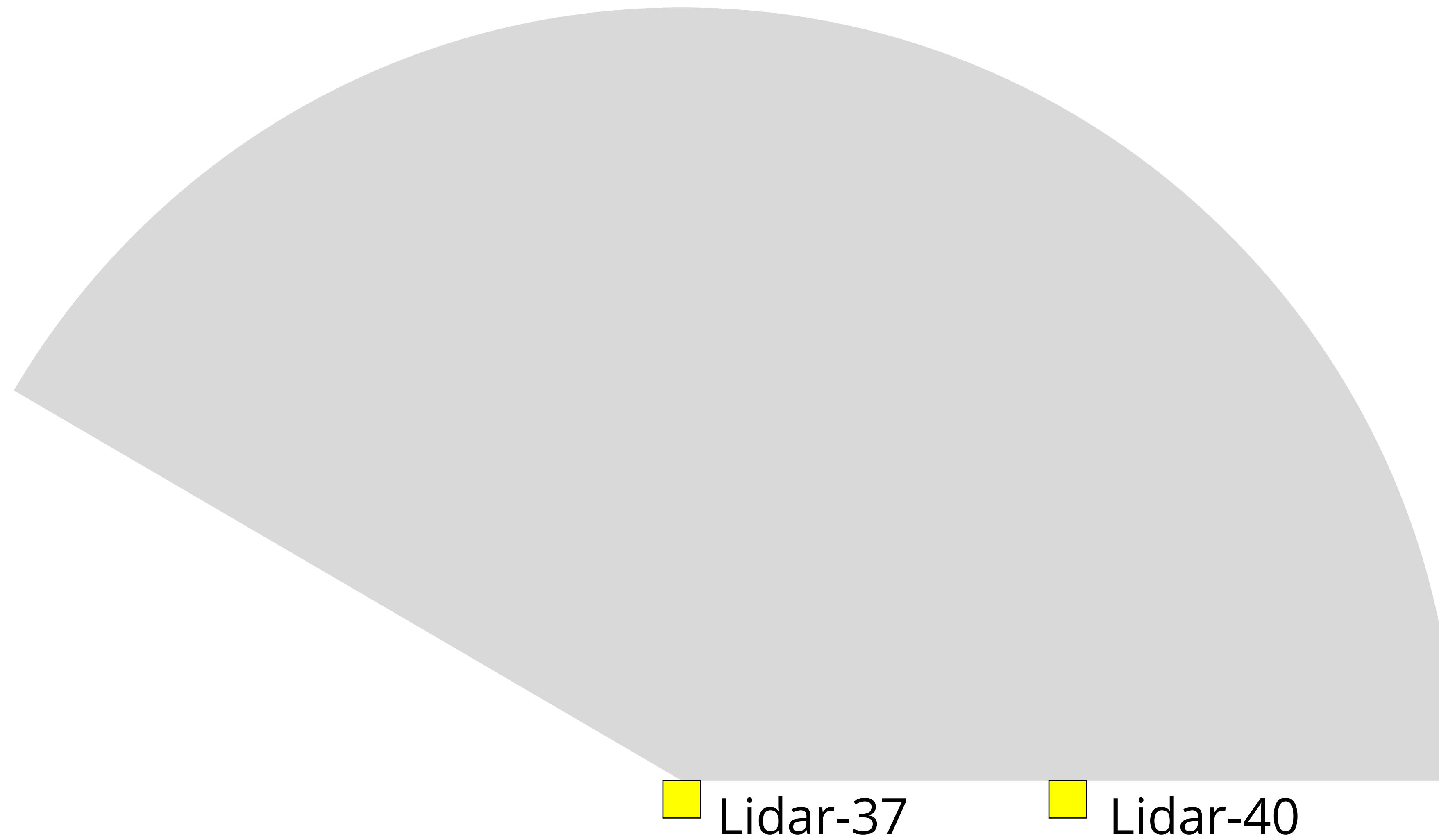
Example: combine two scanning Lidars

Rotate the lidar beam with increasing elevation angle, θ , within the vertical cross-section between the lidar



Scanning strategy

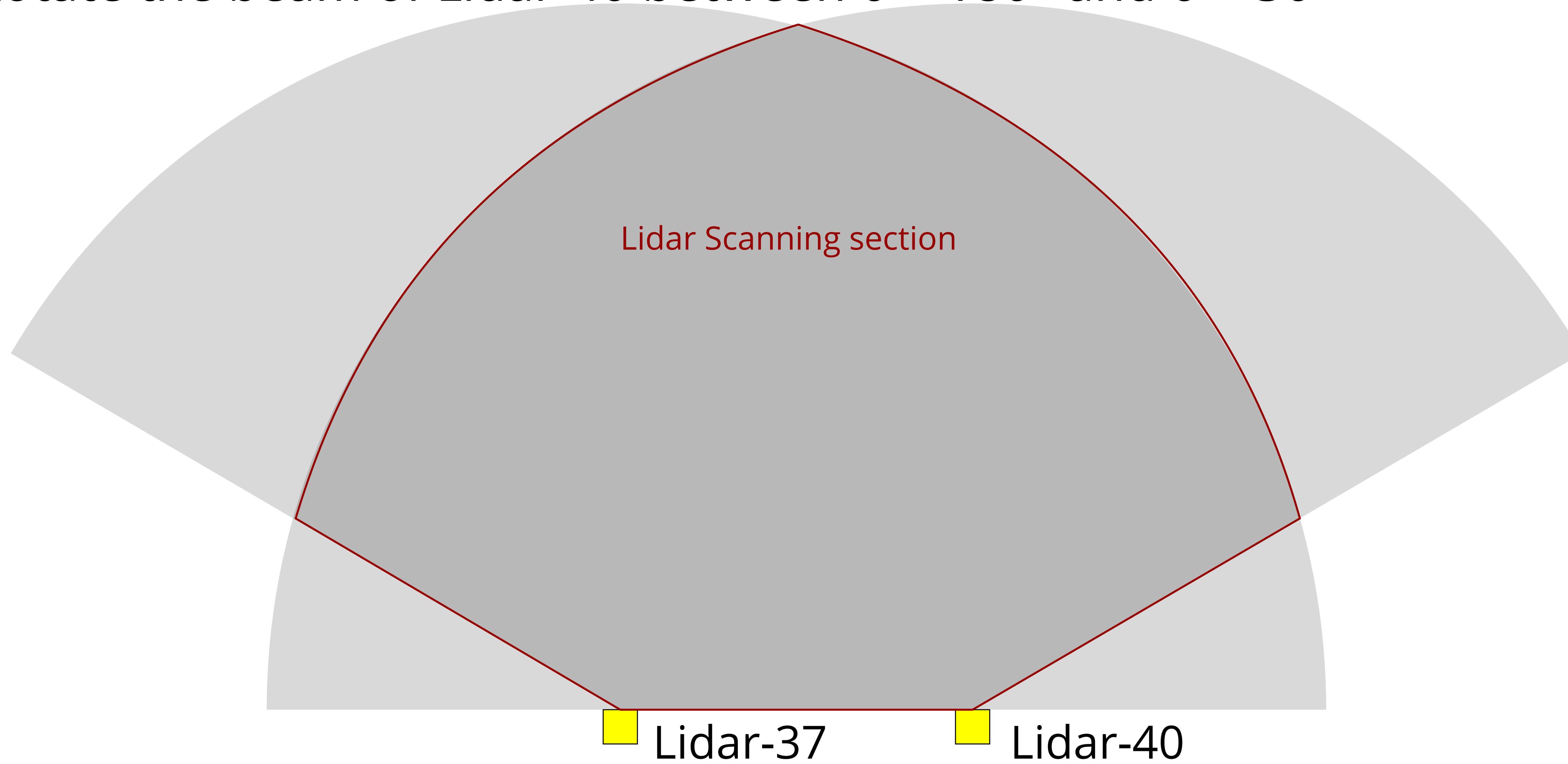
Rotate the beam of Lidar-37 between $\theta = 0^\circ$ and $\theta = 150^\circ$



Scanning strategy

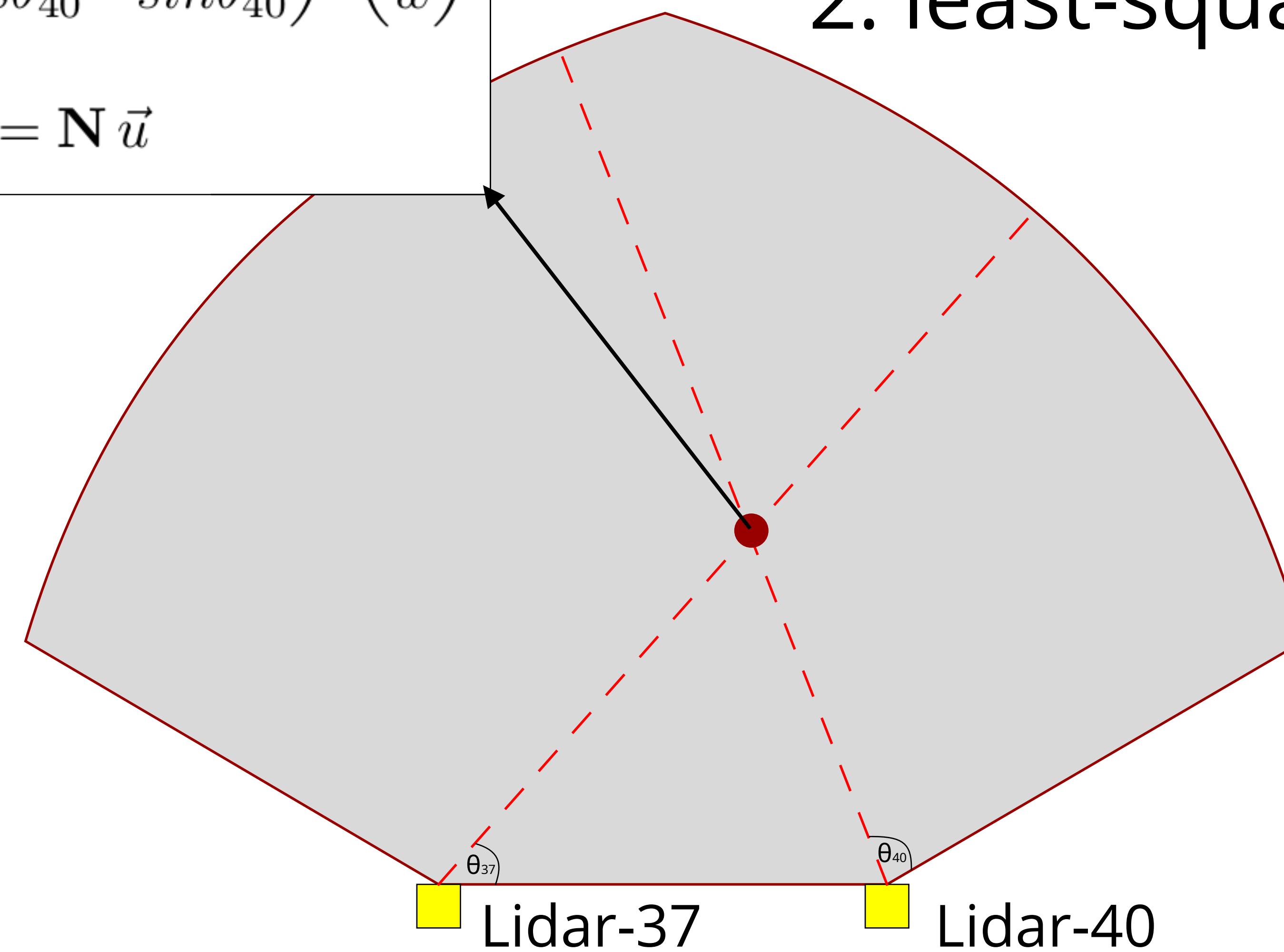
Rotate the beam of Lidar-37 between $\theta = 0^\circ$ and $\theta = 150^\circ$

Rotate the beam of Lidar-40 between $\theta = 180^\circ$ and $\theta = 30^\circ$



Reconstruction of wind field

$$\begin{pmatrix} v_{r37} \\ v_{r40} \end{pmatrix} = \begin{pmatrix} \cos\theta_{37} & \sin\theta_{37} \\ \cos\theta_{40} & \sin\theta_{40} \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix}$$
$$\vec{v}_r = \mathbf{N} \vec{u}$$



1. to cartesian grid
2. least-squares approach

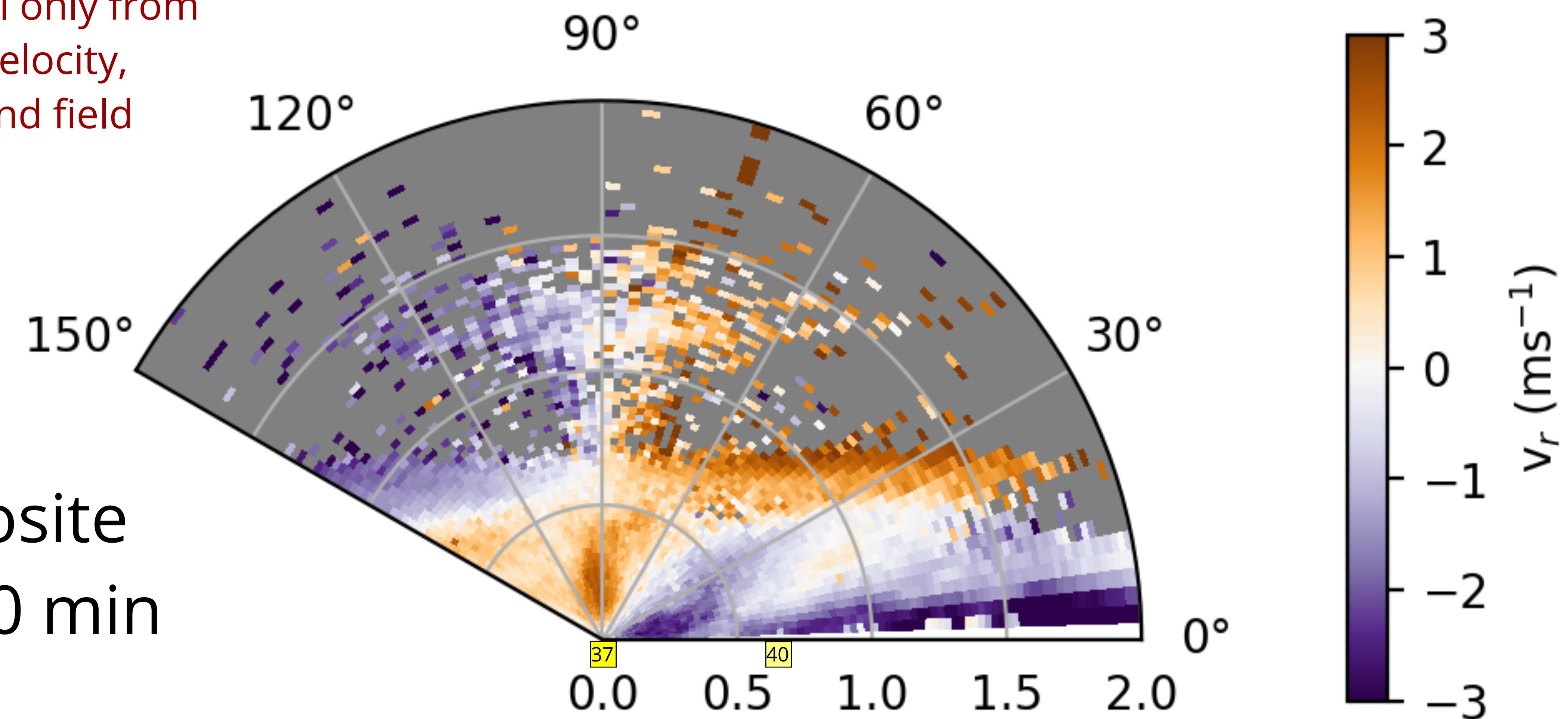
$$\hat{\vec{u}} = (\mathbf{N}^T \mathbf{N})^{-1} \mathbf{N}^T \vec{v}_r$$

Example observations from last year

28.05.21 9:30 UTC, 2° resolution (Lidar-37)

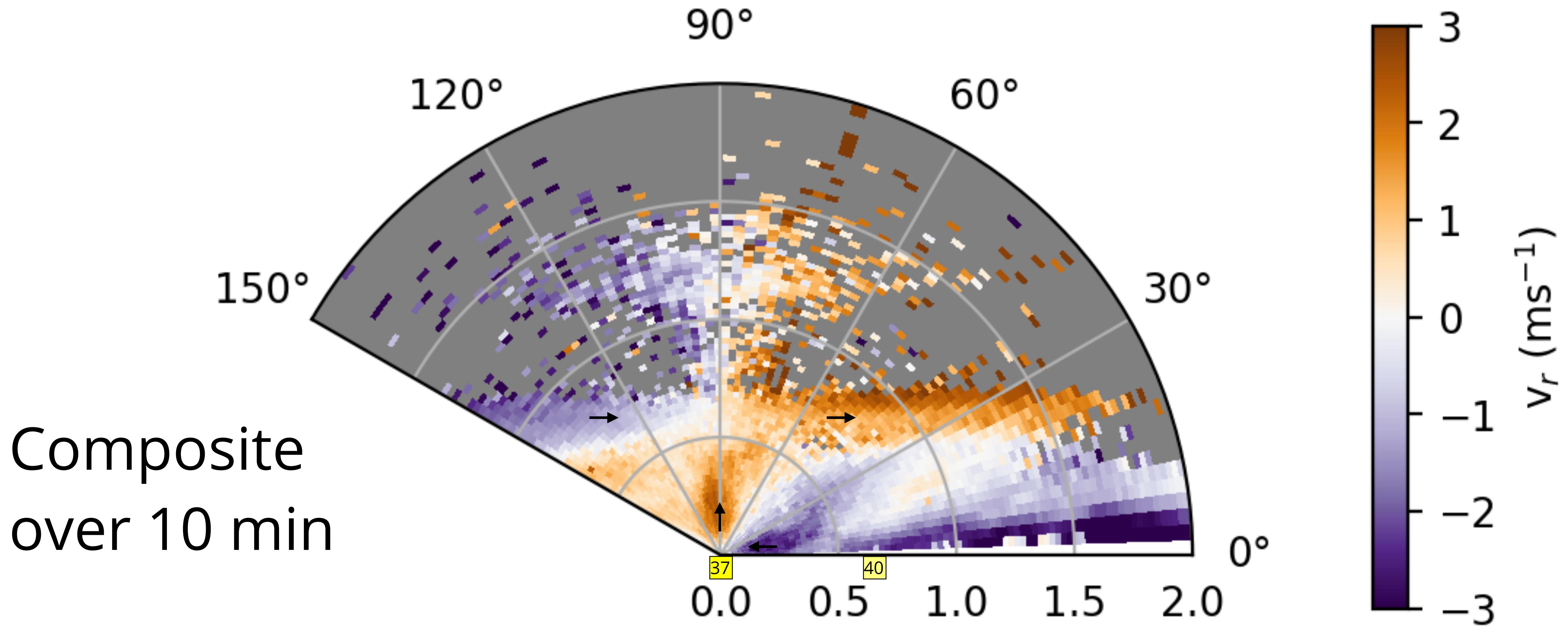
Can you tell only from
the radial velocity,
how the wind field
looks like?

Composite
over 10 min



Example observations from last year

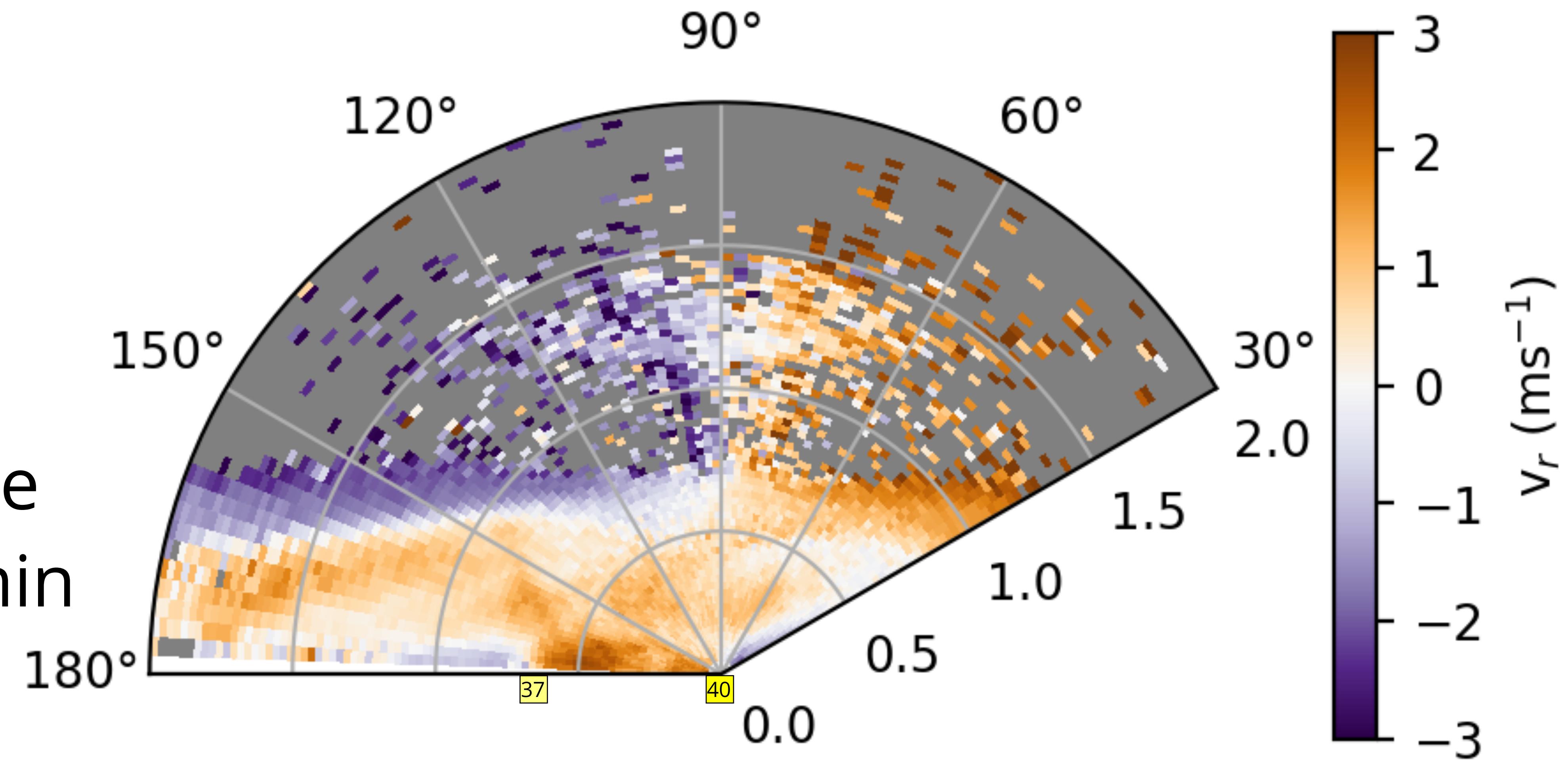
28.05.21 9:30 UTC, 2° resolution (Lidar-37)



Example observations from last year

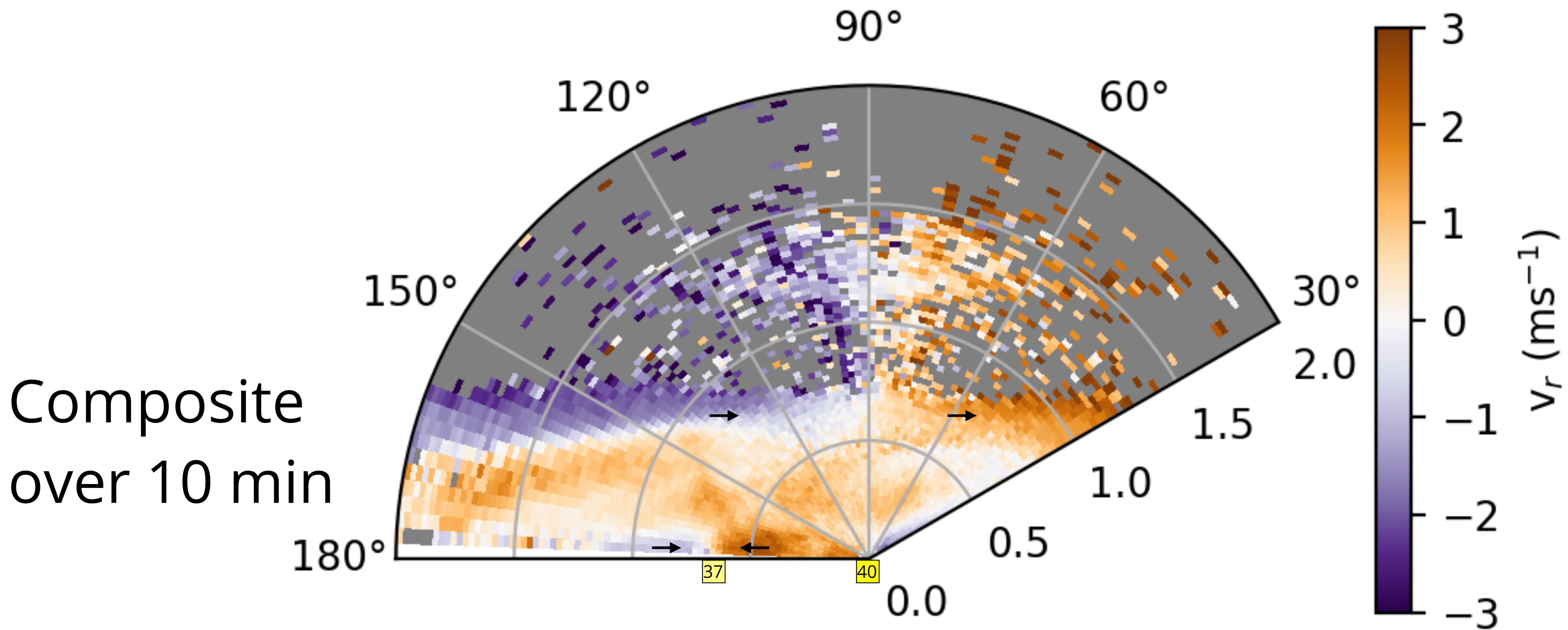
28.05.21 9:30 UTC, 2° resolution (Lidar-40)

Composite
over 10 min



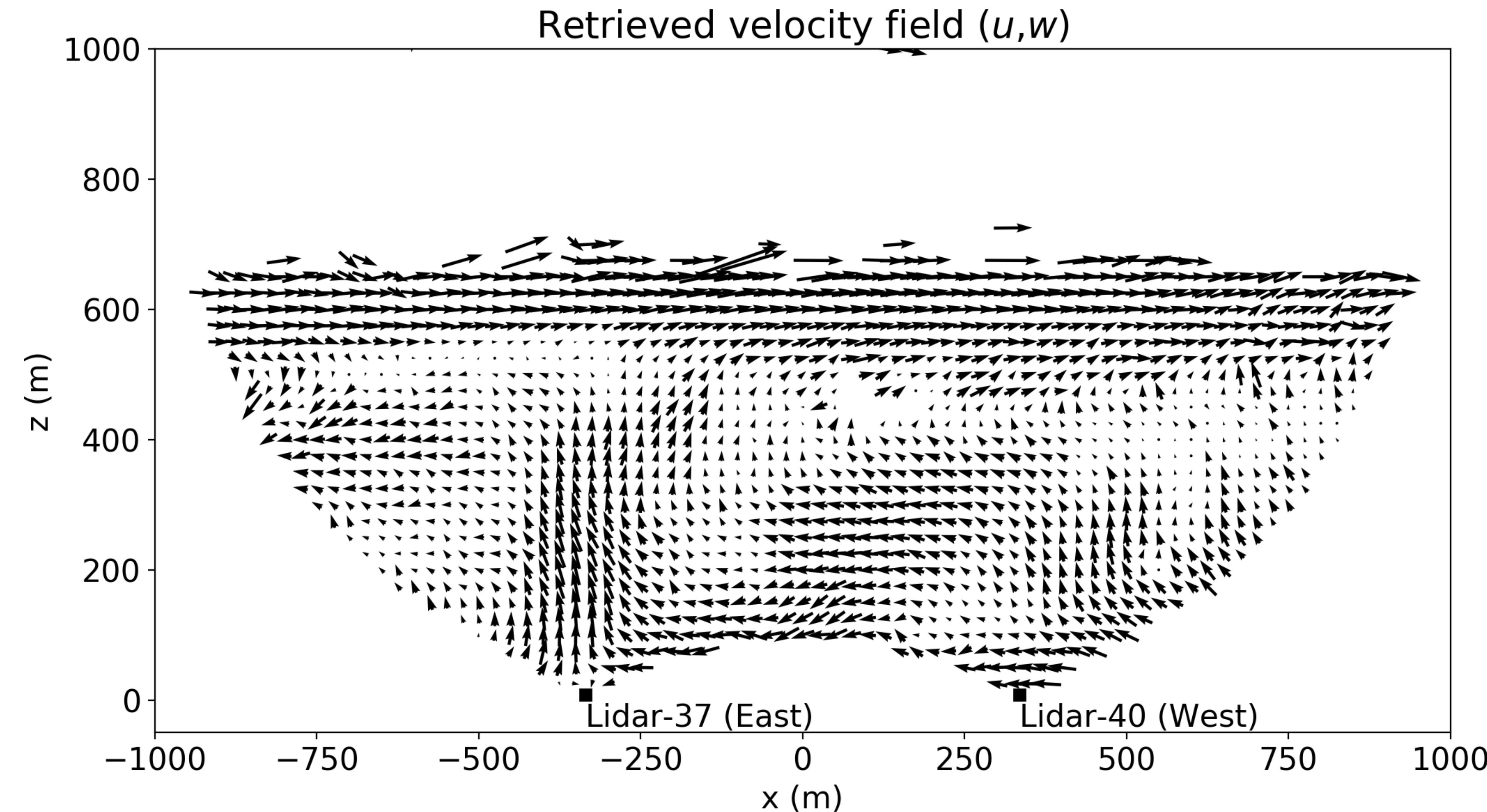
Example observations from last year

28.05.21 9:30 UTC, 2° resolution (Lidar-40)



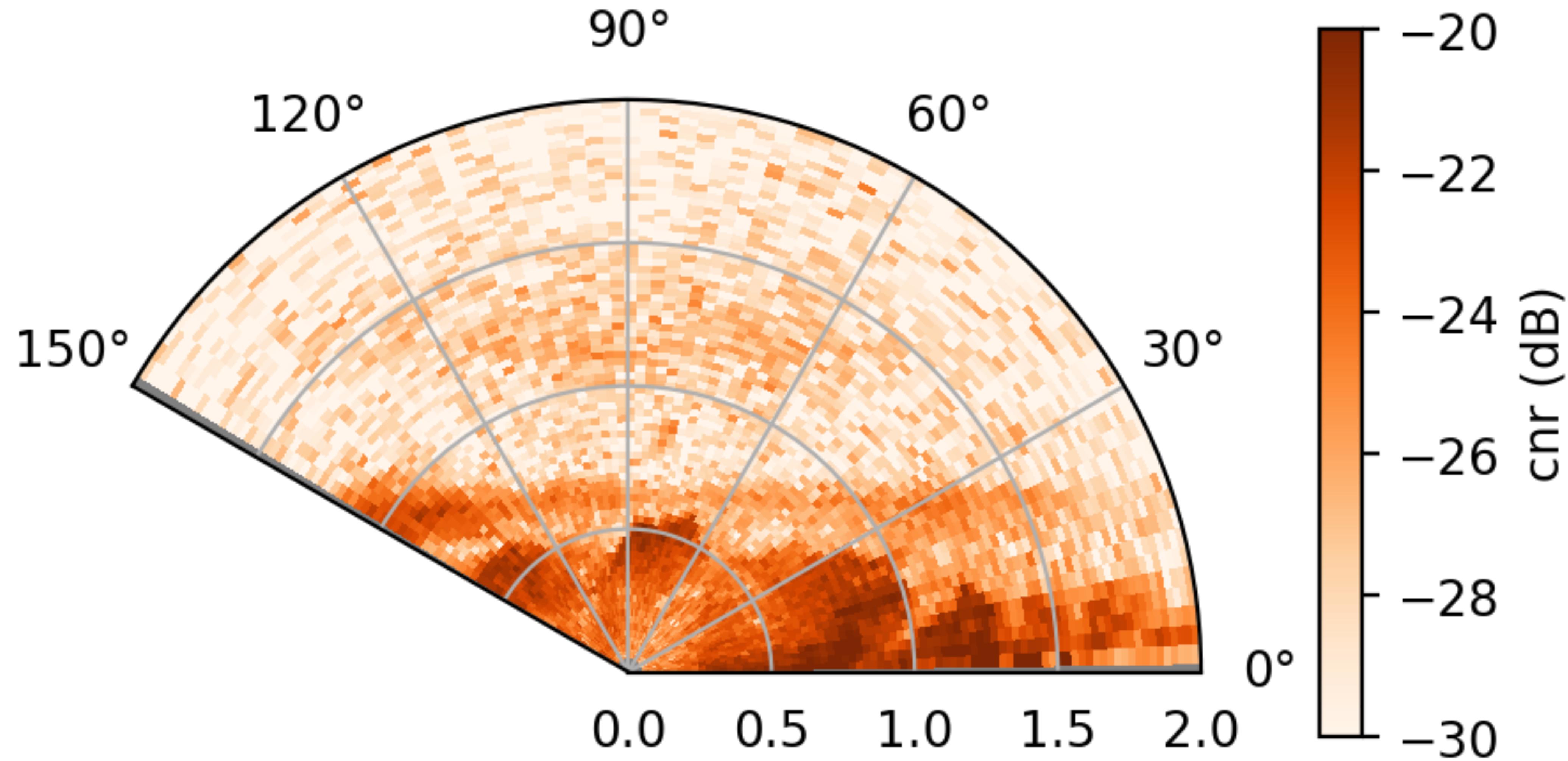
Reconstructed wind field

Example from 28.05.21 9:30 UTC



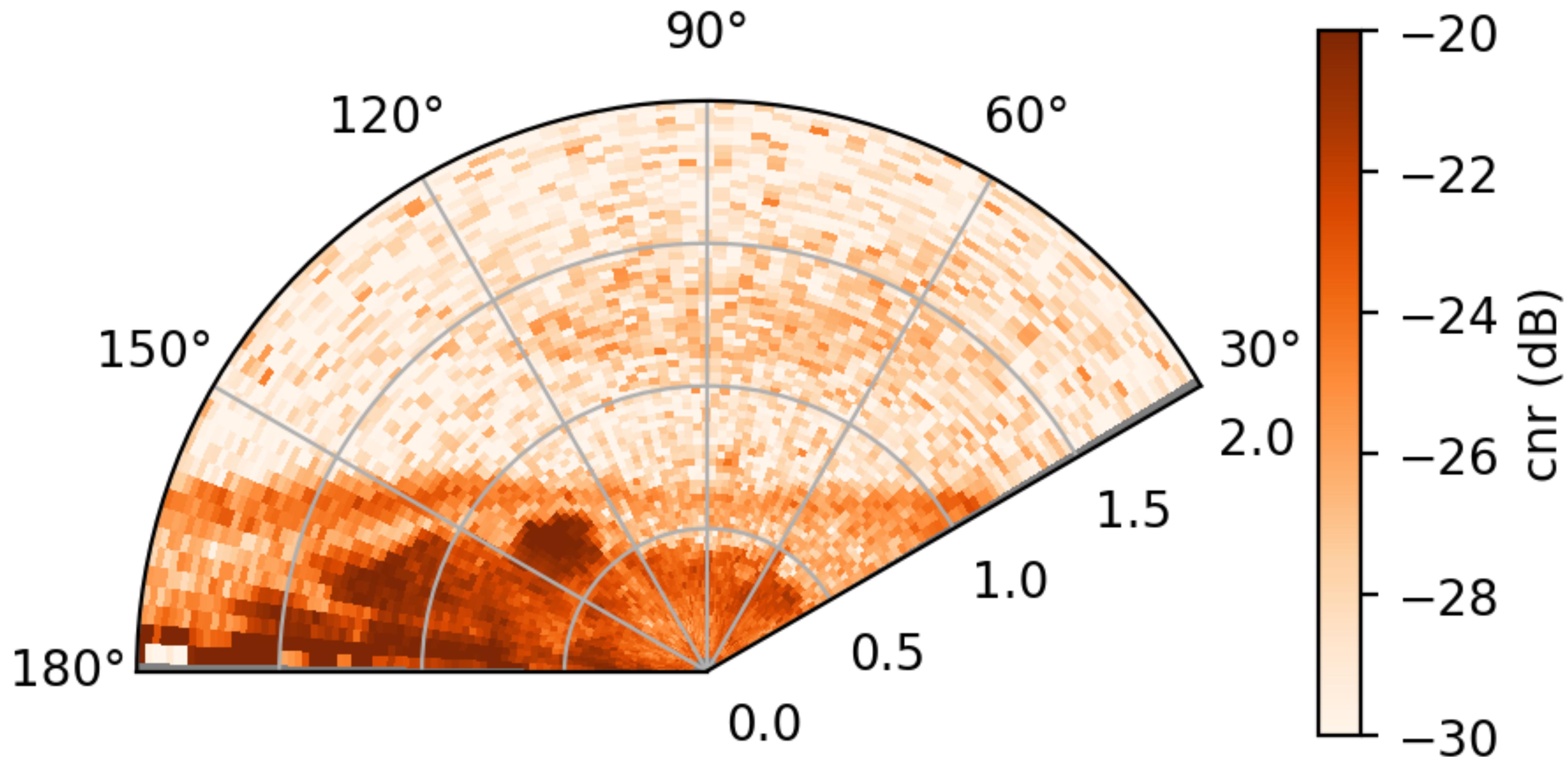
Carrier to noise ratio

A measure for strength of back-scatter from Aerosols



Carrier to noise ratio

A measure for strength of back-scatter from Aerosols



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