

Oxiflex - A Constraint Programming Solver for MiniZinc written in Rust

Gianluca Klimmer

University of Basel

15.07.2024

Planning

SAS⁺ Planning Task $\Pi = \langle V, I, O, \gamma \rangle$

- state variables V with finite domain
- initial state I
- operators O
- goal γ

Satisficing planning ignores plan cost.