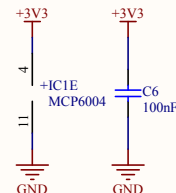
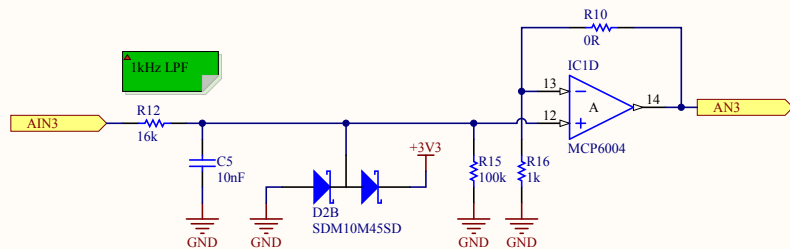
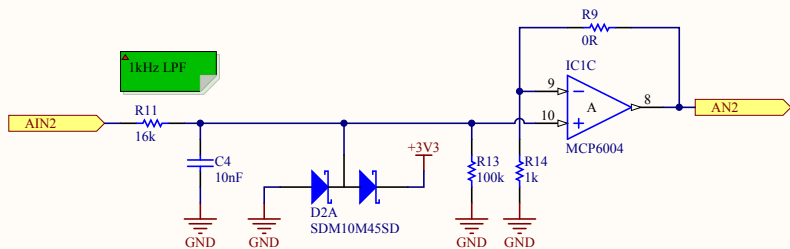
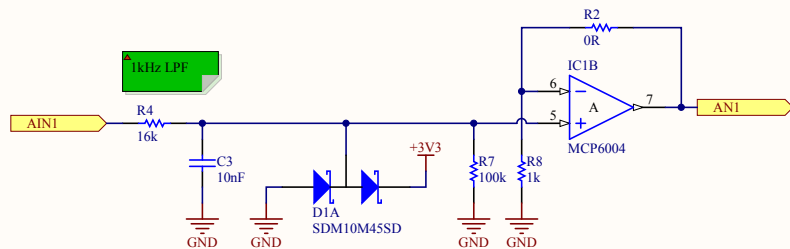
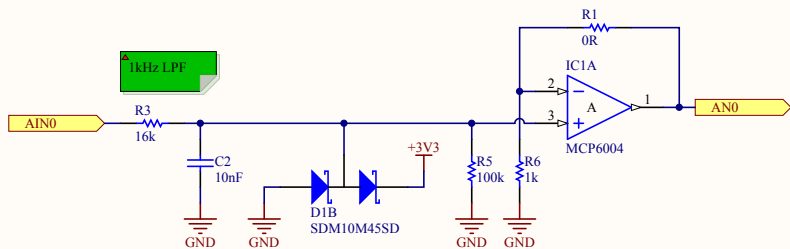


<http://projetvue.com/>  
<http://openecosys.sf.net/>



Title				<i>[VUE32 - Main]</i>			
Size A4		Number			Revision 1.0		
Date:		2012-10-11		08:22:21		Sheet of	
File:		C:\Dropbox\...VUE PIC32 v1 0.SchDoc			Drawn By:		JFDuval

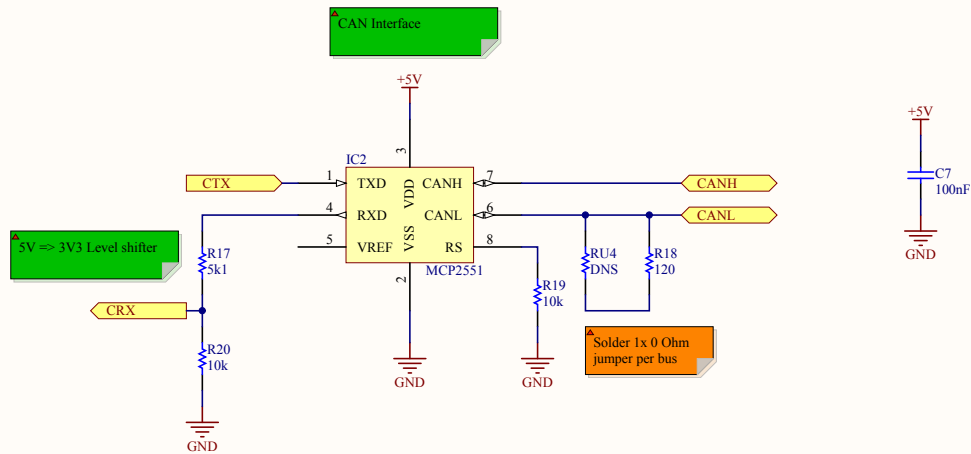


By default the gain is 1. To change it, change the 0R feedback resistors.  
 $G = 1 + R_f/R_g$

With 100k pull-downs, the gain is  $G = 100k/(100k + 16k) = 0.86$ . Using 470k is recommended ( $G = 0.97$ ).

From v0.1:  
 + 100k pull-downs  
 X Lower  $f_c$  (800Hz)

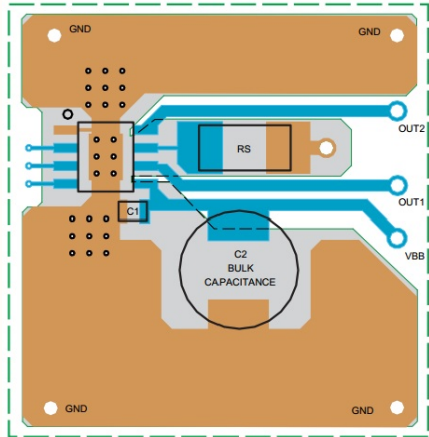
Title		
[VUE32 - 4 ch. analog inputs]		
Size	Number	Revision
A4		1.0
Date:	2012-10-11	08:22:21
File:	C:\Dropbox\...\VUE PIC32 v1.0 Analog	Sheet of 4
		JFDuval



From v0.1:  
Identical.

Title			
<b>[VUE32 - CAN 2.0]</b>			
Size	Number		Revision
A4			1.0
Date:	2012-10-11	08:22:21	Sheet of
File:	C:\Dropbox\...VUE PIC32 v1.0 CAN Schematic		Drawn By: JFDuval

Recommended layout:



Current sensor:  
 $1A * 0.150\Omega = 150mV$   
 $150mV * 7.2V/V = 1.08V$   
 $1.08V / 3.3V = 0.327$   
 $0.327 * 4096 = 1340 \text{ bits/A}$   
 $\Rightarrow 1 \text{ bit} = 746\mu A$

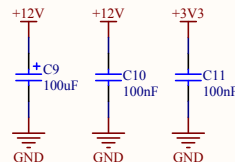
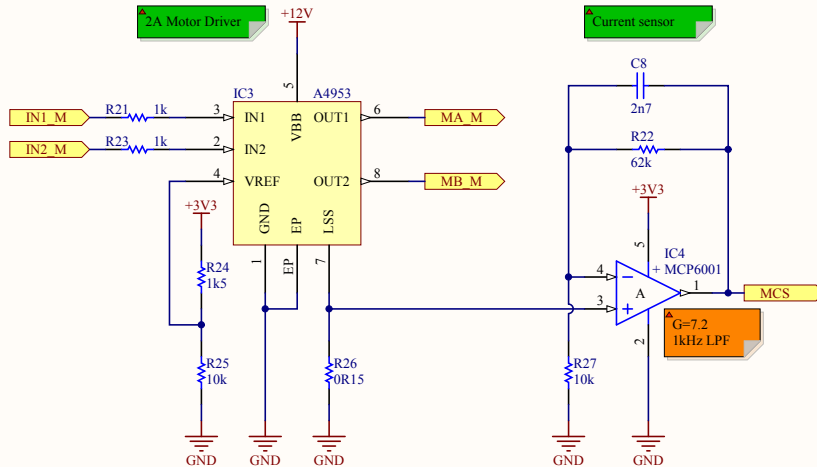
Datasheet: "100nF Electrolytic + 220nF X5R"

Truth table:

[IN1]	[IN2]	
0	0	= Coast
1	0	= CW
0	1	= CCW
1	1	= Brake to VCC

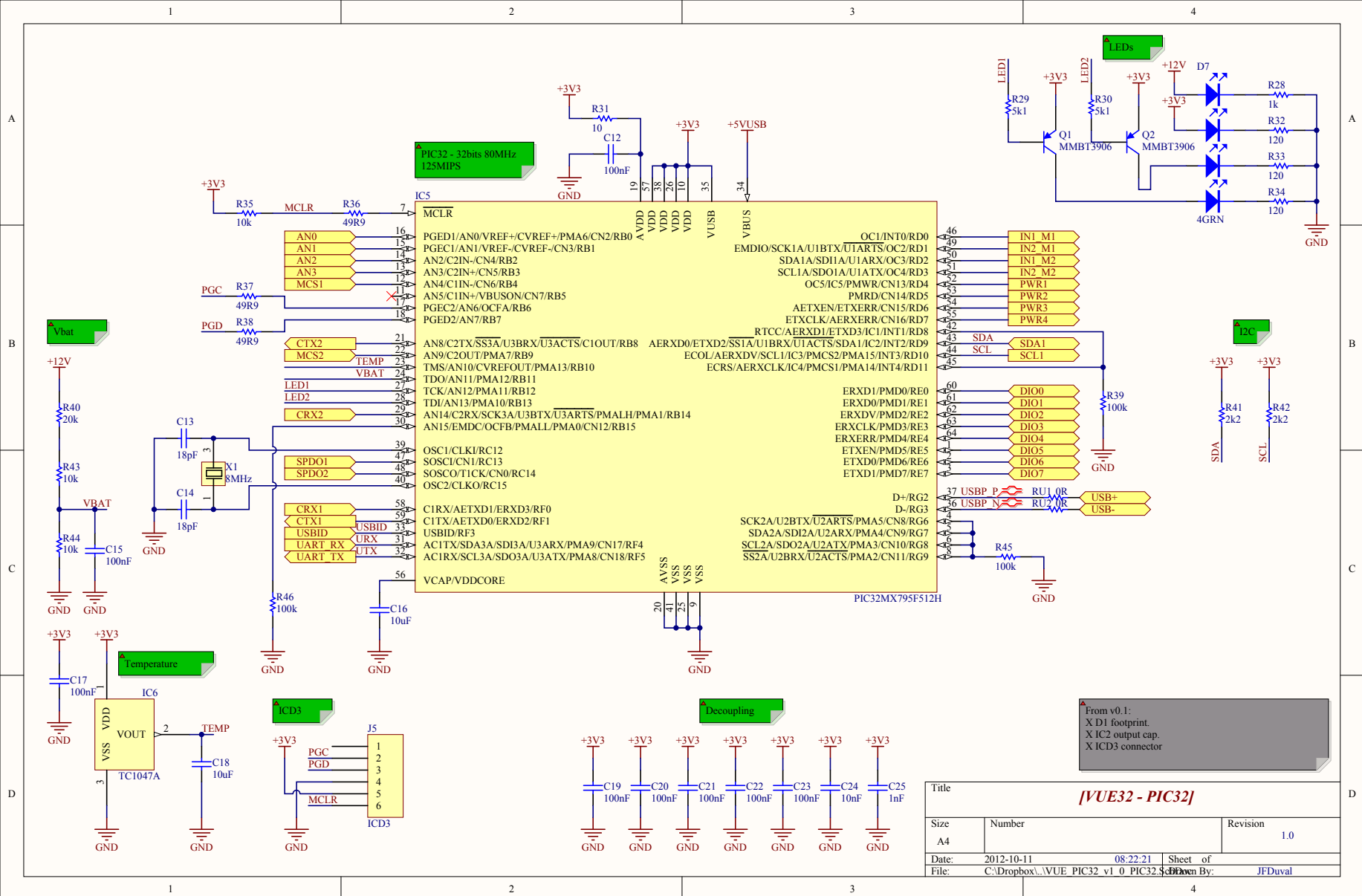
PWM Max Freq: 30kHz

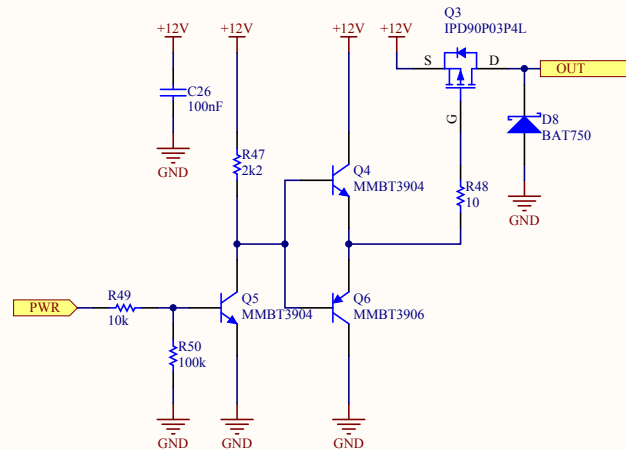
$L_{Trip\_Max} = V_{ref} / (A_v * R_s)$   
 $V_{ref} = 2A * (9.5 * 0.150\Omega) = 2.85V$   
 $(10k / (1.5k + 10k)) * 3.3 = 2.87V \Rightarrow 2.01A$



From v0.1:  
Identical.

Title		
[VUE32 - 2A H-Bridge motor driver]		
Size	Number	Revision
A4		1.0
Date:	2012-10-11	08:22:21
File:	C:\Dropbox\...\VUE PIC32 v1.0 Motor	Sheet of 2
		JFDuval





Max RDSon : 4.1mOhm  
DPAK: 62C/W  
 $P = R \cdot I^2 = 0.0041 \cdot 10A^2 = 410mW$   
 $T = 25C + P \cdot 62C/W = 25C + 25.42C$   
 $T = 50.42C$  Good

Tested on v1.0:  
PowerOut 4 w/ full enclosure

t(s)	I(A)	T(C)
0	0.0	22
60	9.6	22
420	9.6	40
3120	9.6	57
3600	9.6	58
End		

For detailed results, refer to the QA sheet.

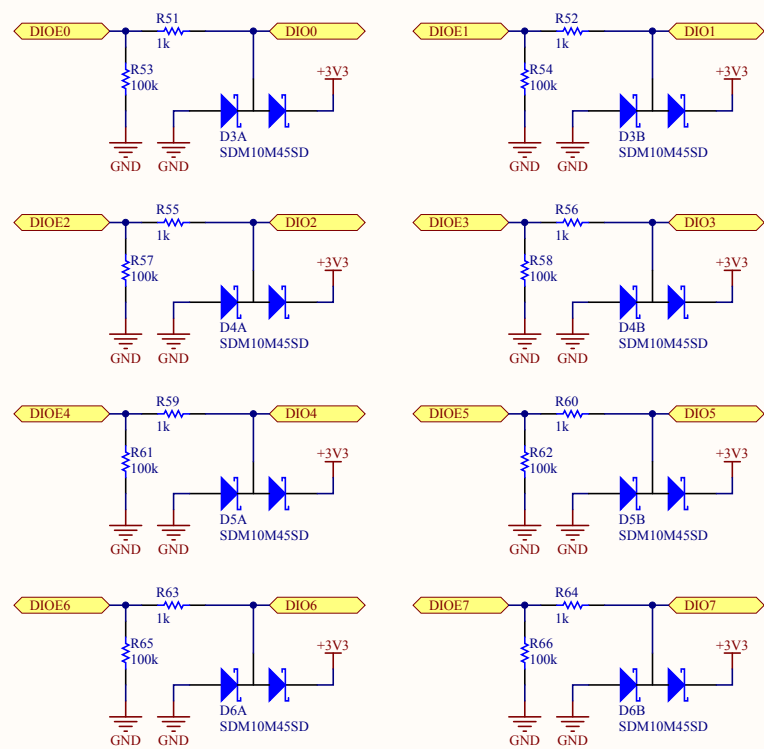
Maximum current determined by layout.  
As a rule of thumb, #1 is rated for 10A and Out1 > Out2 > Out3 > Out4. Now that this is said, Out4 was fully tested at 9.6A and was below 60C after an hour.

Connect the load between OUT and GND.  
When PWR = 1, OUT = 12V. For additional information see LTSpice : high\_side\_p\_mos\_switch\_0\_1.asc.

Not characterized for PWM!

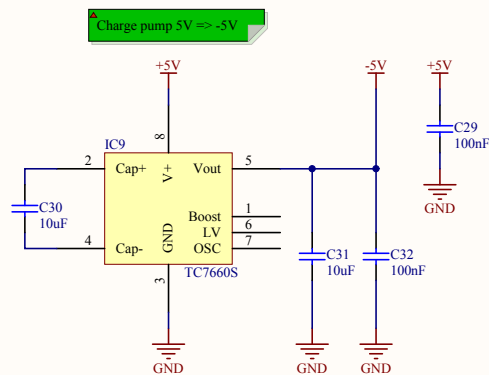
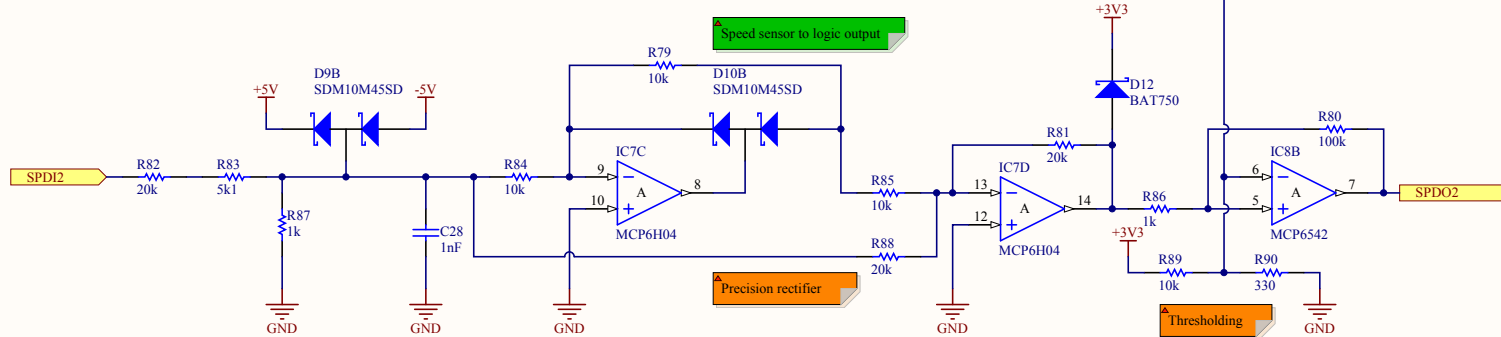
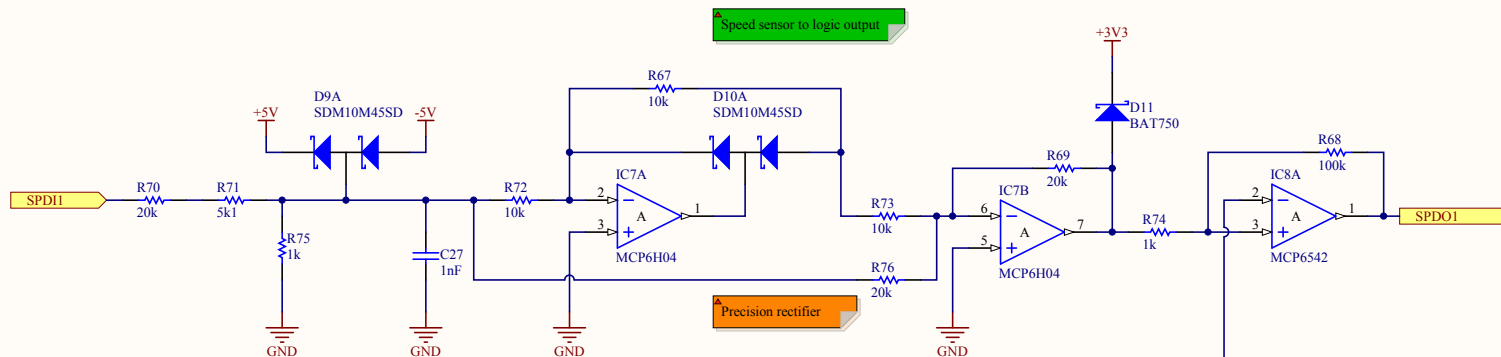
From v0.1:  
Identical.

Title			
[VUE32 - (Up to) 10A switched output]			
Size	Number		Revision
A4			1.0
Date:	2012-10-11	08:22:21	Sheet of
File:	C:\Dropbox\...VUE PIC32 v1.0 PowerOutSchDoc		JFDuval

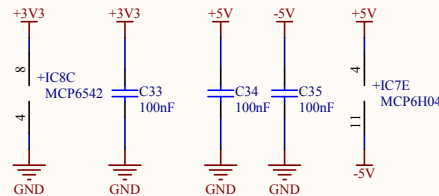


From v0.1:  
Identical.

Title			<b>[VUE32 - Digital I/Os]</b>	
Size	Number		Revision	
A4			1.0	
Date:	2012-10-11	08:22:21	Sheet of	
File:	C:\Dropbox\...VUE PIC32 v1.0 Signals		Sheet By:	JFDuval



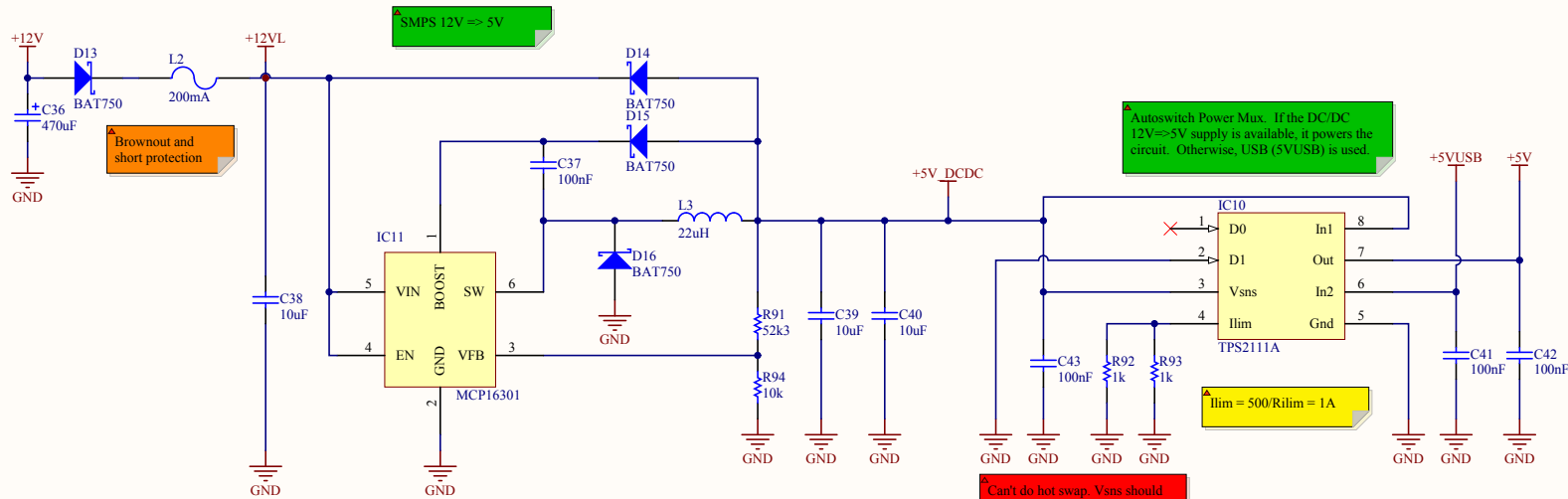
Details: the input is a sine-like waveform. It gets rectified by the precision rectifier. The comparator then transforms the analog signal to a 0-3V3 digital pulse train.



From v0.1:  
X Hysteresis value  
X Resistor values (cost reduction)

Title			
<b>[VUE32 - Speed Sensor]</b>			
Size	Number	Revision	
A4		1.0	
Date:	2012-10-11	08:22:21	Sheet of
File:	C:\Dropbox\...VUE PIC32_v1.0_Speed_Sensor.doc		JFDuval

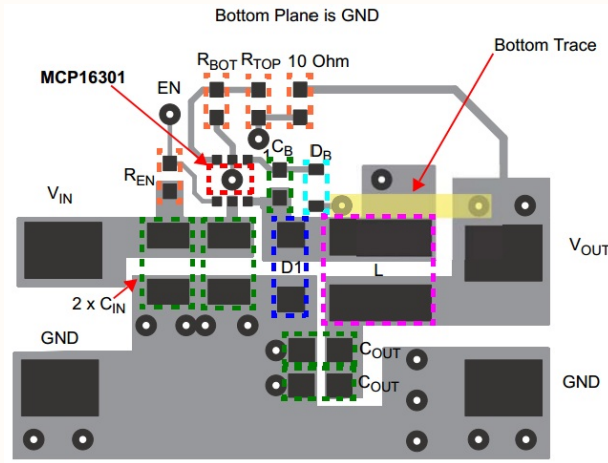
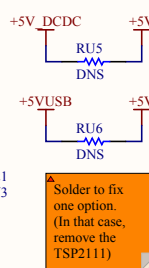
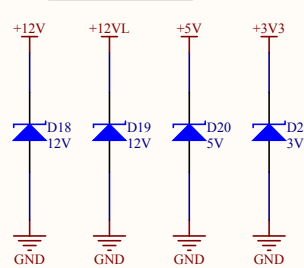
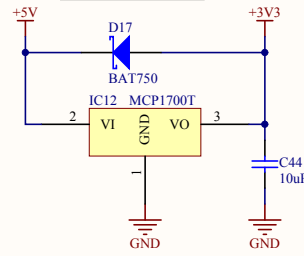




Can't do hot swap. V<sub>ns</sub> should be on a voltage divider. See datasheet's Fig. 14.

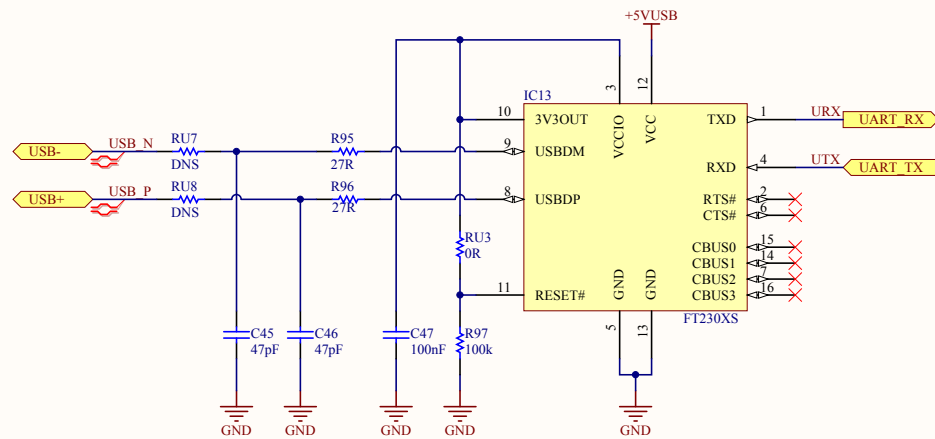
**Linear 5V => 3V3**

**Protections**



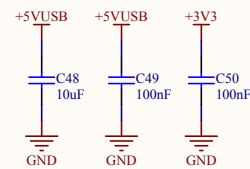
From v0.1: Identical.

Title			
[VUE32 - Supplies]			
Size	Number	Revision	
A4		1.0	
Date:	2012-10-11	08:22:21	Sheet of
File:	C:\Dropbox\...VUE PIC32 v1.0 Supplies	Sheet 3 of 3	JFDuval



To use this FT230X instead of the onboard USB:  
 => Solder RU7 and RU8  
 => Remove RU1, RU2 and RU3

From v0.1:  
 X Cheaper and better FT230XS (rather than FT232)



Title			
[VUE32 - USB-Serial]			
Size	Number		Revision
A4			1.0
Date:	2012-10-11	08:22:22	Sheet of
File:	C:\Dropbox\...VUE PIC32 v1.0 USB-Serial.doc		
	JFDuval		