Eigenvalue Algorithms

Numerical Strategies Providing for the Time and Resource Efficient Computation of Eigenvalues for Any General Square Matrix

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The Problem

How can we find the eigenvalues of any $n \times n$ matrix A?

$$A\mathbf{x} = \lambda \mathbf{x}$$

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Section 1

Power Method

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- **3** Iterate the above process for m steps. Now, we have have calculated x_m , which is parallel to $A^m x_0$.
- Calculate the dominant eigenvalue

$$\lambda_1 = \frac{\|AA^m x_0\|}{\|A^m x_0\|} = \frac{\|Ax_m\|}{\|x_m\|} = \frac{Ax_m \cdot x_m}{x_m \cdot x_m}.$$

Reference: [Koc25].



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• Now, if $|\lambda_1| > |\lambda_2| \ge ... \ge |\lambda_n|$, then $\lambda_i/\lambda_1 < 1$ for all $i \ne 1$.

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$$A^k v = \lim_{k \to \infty} \lambda_1^k \left(\left(\frac{\lambda_1}{\lambda_1} \right)^k v_{0_1} p_1 + \left(\frac{\lambda_2}{\lambda_1} \right)^k v_{0_2} p_2 + \sum_{i=3}^n \left(\frac{\lambda_i}{\lambda_1} \right)^k v_{0_i} p_i \right)$$

$$A^{k}v = \lim_{k \to \infty} \lambda_{1}^{k} \left(v_{0_{1}}p_{1} + v_{0_{2}}p_{2} \right)$$

is not an eigenvector of A if $\lambda_1 \neq \lambda_2$.



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- Can use shifts (calculate eigenvalues of A cI), but that is complicated.
- Even worse: only calculates dominant eigenvalue.
- Speed of convergence depends on choice of starting vector.

Section 2

Schur form

Let A be an $n \times n$ real matrix. The **Schur form** of A is:

$$A = QUQ^T = QUQ^{-1}$$

where Q is orthogonal and U is upper triangular. A and U are similar so they share the same eigenvalues, which are the diagonal entries of U.

• Set
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Proof is hard and complicated. We will "prove" by example.

Example of the Basic QR Algorithm (1)

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 1 \end{bmatrix}$$

Eigenvalues

$$\lambda_1 \approx 12.4542$$

$$\lambda_2 \approx -5.0744$$

$$\lambda_3 \approx -0.379762$$

Example of the Basic QR Algorithm (2)

$$A_1 = \begin{bmatrix} 1.00 & 2.00 & 3.00 \\ 4.00 & 5.00 & 6.00 \\ 7.00 & 8.00 & 1.00 \end{bmatrix}$$

Example of the Basic QR Algorithm (2)

$$A_{1} = \begin{bmatrix} 1.00 & 2.00 & 3.00 \\ 4.00 & 5.00 & 6.00 \\ 7.00 & 8.00 & 1.00 \end{bmatrix}$$

$$Q_{1} = \begin{bmatrix} -0.12 & 0.90 & 0.41 \\ -0.49 & 0.30 & -0.82 \\ -0.86 & -0.30 & 0.41 \end{bmatrix}$$

$$R_{1} = \begin{bmatrix} -8.12 & -9.60 & -4.19 \\ 0.00 & 0.90 & 4.22 \\ 0.00 & 0.00 & -3.27 \end{bmatrix}$$

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$$A_{2} = \begin{bmatrix} 9.33 & -8.98 & 2.81 \\ -4.08 & -1.00 & 0.98 \\ 2.81 & 0.98 & -1.33 \end{bmatrix}$$

Example of the Basic QR Algorithm (3)

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$$Q_2 = \begin{bmatrix} -0.88 & -0.47 & 0.02 \\ 0.39 & -0.70 & 0.60 \\ -0.27 & 0.54 & 0.80 \end{bmatrix}$$

$$R_2 = \begin{bmatrix} -10.57 & 7.28 & -1.75 \\ 0.00 & 5.44 & -2.73 \\ 0.00 & 0.00 & -0.42 \end{bmatrix}$$

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$$A_{3} = \begin{bmatrix} 12.61 & -1.09 & 2.74 \\ 2.83 & -5.28 & 1.08 \\ 0.11 & -0.22 & -0.33 \end{bmatrix}$$

Example of the Basic QR Algorithm (4)

$$A_4 = \begin{bmatrix} 12.15 & -4.87 & -3.01 \\ -1.07 & -4.77 & -0.65 \\ 0.00 & 0.02 & -0.38 \end{bmatrix}$$

Example of the Basic QR Algorithm (4)

$$A_4 = \begin{bmatrix} 12.15 & -4.87 & -3.01 \\ -1.07 & -4.77 & -0.65 \\ 0.00 & 0.02 & -0.38 \end{bmatrix}$$
$$A_5 = \begin{bmatrix} 12.54 & -3.34 & 2.96 \\ 0.46 & -5.16 & 0.93 \\ 0.00 & -0.00 & -0.38 \end{bmatrix}$$

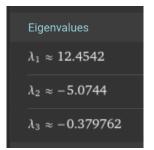
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$$A_{11} = \begin{bmatrix} 12.45 & -3.79 & 2.98 \\ 0.00 & -5.07 & 0.85 \\ 0.00 & -0.00 & -0.38 \end{bmatrix}$$

Example of the Basic QR Algorithm (5)

$$A_{11} = \begin{bmatrix} 12.45 & -3.79 & 2.98 \\ 0.00 & -5.07 & 0.85 \\ 0.00 & -0.00 & -0.38 \end{bmatrix}$$



We found <u>EVERY</u> eigenvalue!

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- Similar convergence problems to Power Method: only guaranteed to work if $|\lambda_1| > |\lambda_2| > \ldots > |\lambda_n|$
- Needs modifications to find complex eigenvalues.
- Could be faster: runs in $\mathcal{O}(n^3)$ time for $n \times n$ matrix.

Bad Example (1)

$$A = \begin{bmatrix} 1 & 5 \\ -1 & -3 \end{bmatrix}$$

Eigenvalues $\lambda_1 = -1 + i$ $\lambda_2 = -1 - i$

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$$|\lambda_1| = \sqrt{(-1)^2 + 1^2} = \sqrt{2}$$

 $|\lambda_2| = \sqrt{(-1)^2 + (-1)^2} = \sqrt{2}$

Bad Example (2)

$$A_{1} = \begin{bmatrix} 1.00 & 5.00 \\ -1.00 & -3.00 \end{bmatrix}$$

$$A_{2} = \begin{bmatrix} -3.00 & -5.00 \\ 1.00 & 1.00 \end{bmatrix}$$

$$A_{3} = \begin{bmatrix} -1.40 & 5.80 \\ -0.20 & -0.60 \end{bmatrix}$$

$$A_{4} = \begin{bmatrix} -0.60 & -5.80 \\ 0.20 & -1.40 \end{bmatrix}$$

Bad Example (2)

$$A_{1} = \begin{bmatrix} 1.00 & 5.00 \\ -1.00 & -3.00 \end{bmatrix} \qquad A_{5} = \begin{bmatrix} 1.00 & 5.00 \\ -1.00 & -3.00 \end{bmatrix}$$

$$A_{2} = \begin{bmatrix} -3.00 & -5.00 \\ 1.00 & 1.00 \end{bmatrix} \qquad A_{6} = \begin{bmatrix} -3.00 & -5.00 \\ 1.00 & 1.00 \end{bmatrix}$$

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 $\lim_{k\to\infty} A_k$ will not converge onto a triangular matrix.

$$A = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

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$$\lambda_1 = 1, \lambda_2 = -1, \lambda_3 = 1, \lambda_4 = -1$$

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$$A_1 = A = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = A_1 I$$

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$$A_2 = R_1 Q_1 = I A_1 = A_1$$

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This will never converge to a triangular matrix, since $A_i = A$ for all i.

Section 3

Improved QR Algorithm

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Lapack Algorithm

• Reduce A to an upper Hessenberg form by calculating $A = QHQ^T$, where Q is orthogonal and H is an upper Hessenberg matrix. H and A are similar and share the same eigenvalues.

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Reference: [Bla99].

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Used by the Linear Algebra PACKage (LAPACK), which is used by NumPy and SciPy behind the scenes.

References

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