

Question 1

Given: $R = 5 \text{ km}$
 $V = 2.5 \text{ km/h}$
 $T = 1 \text{ hour}$

$$P_e = 300 \text{ kr/kg}$$

$$P_{c_0} = 10 \text{ kr/kg}$$

$$P_f = P_e = 300 \text{ kr/kg at time } t = T$$

Also given:

"price decrease linearly with x " $\rightarrow \frac{\partial P}{\partial x} = f(t) = at + b$

"price change linearly with t " $\frac{\partial P}{\partial t} = g(x) = cx + d$

ALSO given: (BC's)

$$\left. \frac{\partial P}{\partial t} \right|_{x=0} = 0 \quad \forall t \Rightarrow d = 0$$

$$\left. \frac{\partial P}{\partial t} \right|_{x=R} = \frac{P_e - P_{c_0}}{T} \Rightarrow c = \frac{P_e - P_{c_0}}{RT}$$

$$\Rightarrow \left| \frac{\partial P}{\partial t} = \frac{P_e - P_{c_0}}{RT} x \right|$$

$$\left. \frac{\partial P}{\partial x} \right|_{t=0} = -\frac{(P_e - P_{c_0})}{R} \Rightarrow b = -\frac{(P_e - P_{c_0})}{R}$$

$$\left. \frac{\partial P}{\partial x} \right|_{t=T} = 0 \Rightarrow a = \frac{P_e - P_{c_0}}{RT}$$

$$\Rightarrow \left| \frac{\partial P}{\partial x} = \frac{P_e - P_{c_0}}{RT} (t - T) \right|$$

Question 1 cont...

using the notion of "material derivative" with our little man walk ~~at~~ having trajectory $x = vt$ (at $t=0$, $x=0$
constant velocity)
 $\frac{\partial x}{\partial t} = v$

we have $\frac{dP}{dt} = \frac{\partial P}{\partial t} + \frac{\partial x}{\partial t} \times \frac{\partial P}{\partial x}$

$$= \frac{\partial P}{\partial t} + v \frac{\partial P}{\partial x}$$

$$= \frac{P_e - P_{co}}{RT} x + v \left(\frac{P_e - P_{co}}{RT} \right) (t - T)$$

$$= \frac{P_e - P_{co}}{RT} vt + v \left(\frac{P_e - P_{co}}{RT} \right) (t - T)$$

$$\boxed{\frac{dP}{dt} = \frac{v(P_e - P_{co})}{RT} (2t - T)}$$

max/min @ $\frac{dP}{dt} = 0 \Rightarrow t = T/2$

we can also see by ~~subbing~~ $\frac{d^2P}{dt^2} = \frac{2v(P_e - P_{co})}{RT} > 0 \Rightarrow \min$

$$\boxed{\text{cheapest price @ } t = T/2, x = \frac{vT}{2}}$$

$$P = \int \frac{v(P_e - P_{co})}{RT} (2t - T) dt = \frac{v(P_e - P_{co})}{RT} [t^2 - Tt] + C$$

@ $t=0$, $P = P_e$

$$\rightarrow P = \frac{v(P_e - P_{co})}{RT} [t^2 - Tt] + P_e$$

@ $t = T/2$ and subbing in values $P = 263.75 \text{ kr/kg}$

$$\boxed{\text{with 100kr little man buys } 0.3791 \dots \text{ kg}}$$

Question 2

① Single : 1.1921×10^{-7}
double : 2.2204×10^{-16}

② I would interpret "Machine accuracy" (based on the Matlab code) to be the smallest number such that the computer can't tell what the next nearest number is. I.e., the continuous number line must be discretized by a computer (to be ^{described} stored in memory)

continuous #'s

discretized #'s



Question 3

① In Matlab plot
(with $f'(x) = -\frac{1}{(x+2)^2} + 2x$)

② we have X_1 with uncertainty ϵ_1 and $g(X_1, X_2) = X_1 + X_2$
 X_2 ϵ_2

$$\frac{\partial g}{\partial X_1} = 1, \quad \frac{\partial g}{\partial X_2} = 1$$

$$\Delta_p = \sum_{j=1}^n \left| \frac{a_j}{g} \frac{\partial g}{\partial a_j} \right| \epsilon_j$$

$$= \left| \frac{X_1}{g(X_1, X_2)} \times \frac{\partial g}{\partial X_1} \right| \epsilon_1 + \left| \frac{X_2}{g(X_1, X_2)} \times \frac{\partial g}{\partial X_2} \right| \epsilon_2$$

$$= \left| \frac{X_1}{X_1 + X_2} \right| \epsilon_1 + \left| \frac{X_2}{X_1 + X_2} \right| \epsilon_2$$

$$\Delta_p = \frac{|X_1|}{|X_1 + X_2|} \epsilon_1 + \frac{|X_2|}{|X_1 + X_2|} \epsilon_2$$

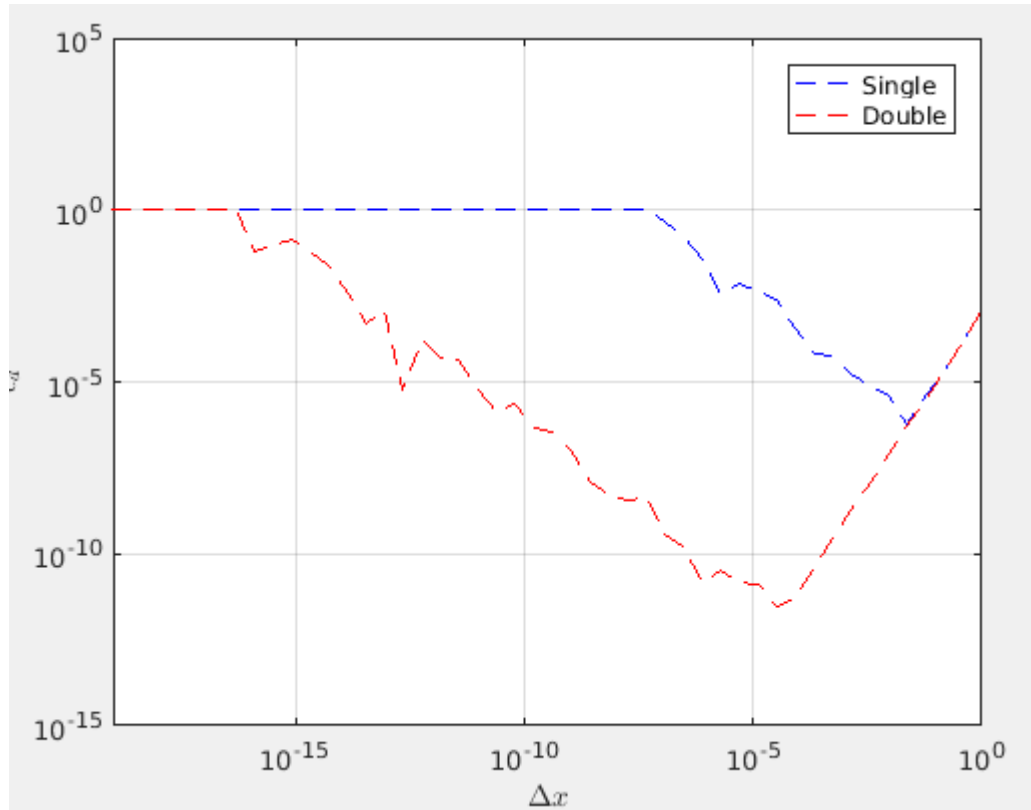


Figure 1: Loglog plot of Δx against relative discretization error for both single and double precision.

It can be seen that $\epsilon = 1$ for very small Δx (indicating Matlab has evaluated $f'_n(x) = 0$). It is clear that the notion of “very small Δx ” is dependent on whether single or double precision is used. As Δx increases, ϵ decreases. This trend continues until a certain minimum at which point the relative discretization error increases again.

Question 3 cont...

$$\textcircled{3} \quad f(x+\Delta x) = f(x) + \Delta x f'(x) + \frac{\Delta x^2}{2} f''(x) + \frac{\Delta x^3}{3!} f'''(x) + O(\Delta x^4)$$

$$f(x-\Delta x) = f(x) - \Delta x f'(x) + \frac{\Delta x^2}{2} f''(x) - \frac{\Delta x^3}{3!} f'''(x) + O(\Delta x^4)$$

$$\frac{f(x+\Delta x) - f(x-\Delta x)}{2\Delta x} = \frac{2\Delta x f'(x) + 2\frac{\Delta x^3}{3!} f'''(x) + \dots}{2\Delta x}$$

$$= f'(x) + \frac{\Delta x^2}{3!} f'''(x) + O(\Delta x^4)$$

$$\boxed{\epsilon_d = \left| \frac{f'(x) - f'_n(x)}{f'(x)} \right|}$$

$$= \left| \frac{\cancel{f'(x)} - \cancel{f'(x)} - \frac{\Delta x^2}{3!} f'''(x)}{f'(x)} \right|$$

$$= \left| \frac{-\frac{\Delta x^2}{3!} f'''(x)}{f'(x)} \right| = \frac{\Delta x^2}{6} \frac{|f'''(x)|}{|f'(x)|}$$

~~$f'_n(x)$~~

$$f'_n(x) = \frac{f(x+\Delta x)}{2\Delta x} - \frac{f(x-\Delta x)}{2\Delta x}$$

$\downarrow \qquad \qquad \downarrow$
 $X_1 \qquad \qquad X_2$

this minus is included in X_2

$$\mathcal{I}_p = \frac{|X_1|}{|X_1 + X_2|} \epsilon_1 + \frac{|X_2|}{|X_1 + X_2|} \epsilon_2$$

but each has the same machine accuracy.

$$\Rightarrow \epsilon_1 = \epsilon_2 = \epsilon$$

Question 3 cont...

Note: $|X_1 + X_2| = \frac{1}{2\Delta x} \left[2\Delta x f'(x) + \frac{2\Delta x^3}{3!} f'''(x) + \dots \right]$ as before

$$|X_1| + |X_2| = \frac{1}{2\Delta x} \left[|f(x) + \Delta x f'(x) + \frac{\Delta x^2}{2} f''(x) + \dots| + |f(x) - \Delta x f'(x) + \frac{\Delta x^2}{2} f''(x) + \dots| \right]$$

since Δx is small we only take leading terms

$$|X_1 + X_2| \approx \frac{1}{2\Delta x} |2\Delta x f'(x)| = |f'(x)|$$

$$|X_1| + |X_2| \approx \frac{1}{2\Delta x} [|f(x)| + |f(x)|] = \frac{|f(x)|}{\Delta x}$$

now $\boxed{\mathcal{L}_p} = \frac{\varepsilon [|X_1| + |X_2|]}{|X_1 + X_2|} \quad (\text{as } \varepsilon_1 = \varepsilon_2 = \varepsilon)$

$$\approx \frac{\varepsilon \left[\frac{|f(x)|}{\Delta x} \right]}{|f'(x)|} = \boxed{\frac{|f(x)| \varepsilon}{|f'(x)| \Delta x}}$$

Question 3 cont.

$$L_g = J_d + J_p = \frac{\Delta x^2 |f'''(x)|}{6 |f'(x)|} + \frac{|f(x)| \varepsilon}{|f'(x)| \Delta x}$$

Want to find min:

$$\frac{\partial L_g}{\partial \Delta x} = \frac{\Delta x |f'''(x)|}{3 |f'(x)|} - \frac{|f(x)| \varepsilon}{|f'(x)| \Delta x^2}$$

$$\text{solve } \frac{\partial L_g}{\partial \Delta x} = 0$$

$$\Rightarrow \Delta x^3 = \frac{|f(x)| \varepsilon \times 3 |f'(x)|}{|f'(x)| \times |f'''(x)|}$$

$$\Delta x^* = \sqrt[3]{\frac{|f(x)|}{|f'''(x)|} \times 3\varepsilon}$$

$$\text{now } \frac{\partial^2 L_g}{\partial \Delta x^2} = \frac{|f'''(x)|}{3 |f'(x)|} + \frac{2 |f(x)| \varepsilon}{|f'(x)| \Delta x^3} > 0 \quad \forall \Delta x, \varepsilon > 0$$

\Rightarrow min!

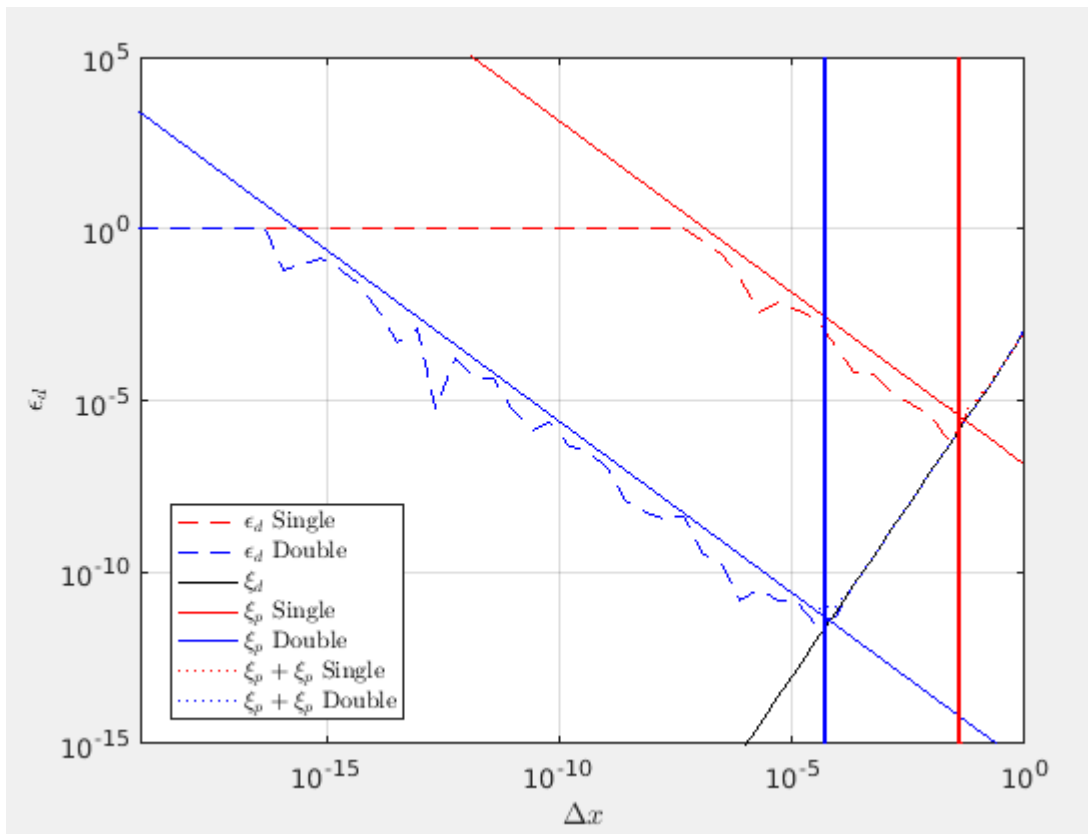


Figure 2: Loglog plot of Δx against relative discretization error for ξ_d ξ_p ξ_g .

The trend in figure 1 is explained in more detail here. A similar trend can be seen for both single and double precision albeit somewhat skewed and shifted.

The decrease in ϵ (with increasing Δx) initially observed can be explain by the propagation error while the subsequent increase in ϵ can be explained by the discretization error.

The trend noticed in figure 1 that “ $\epsilon = 1$ for very small Δx ” is not apparent in the ξ_p plots as $f'_n(x)$ is not being explicitly calculated.