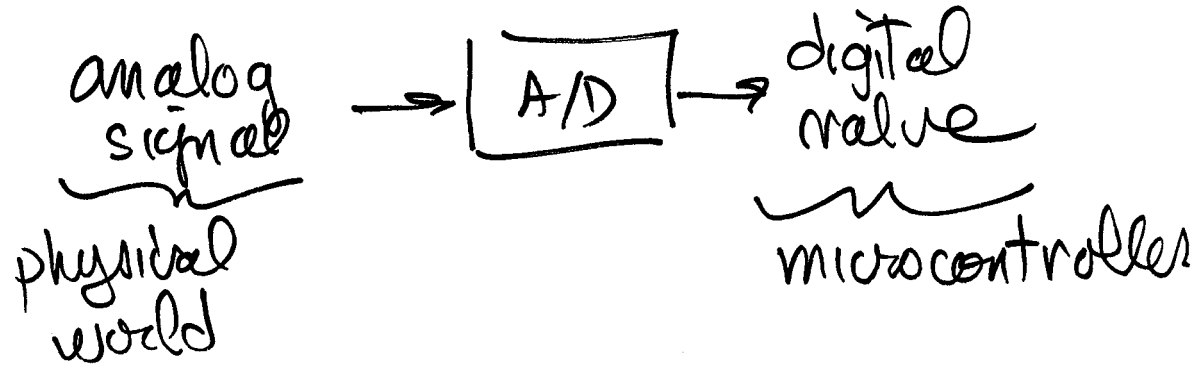


EE2361 - Lecture 28

11/14/16

A/D converter
module:

A/D converter module



A/D { resolution
range
precision

How to build an A/D ?

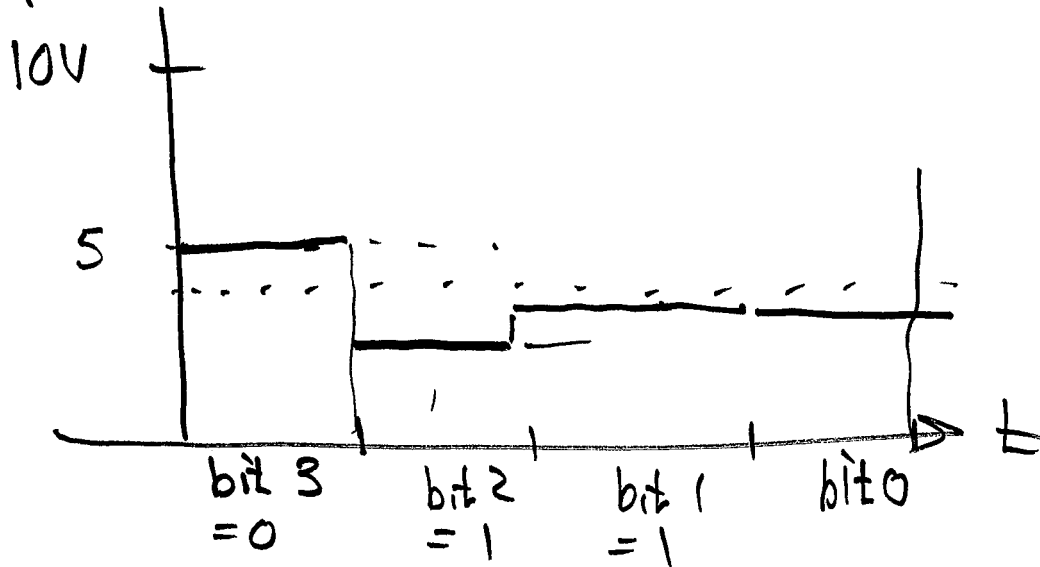
⇒ several technologies/methods can be used

- Flash or Parallel A/D
- Single and Dual Slope A/D
- Sigma-Delta A/D
- Successive Approximation (SAR) A/D

↪ used in PIC24F family

Successive Approximation Register scheme

Example



For the PIC24F 10-bit A/D

2 steps

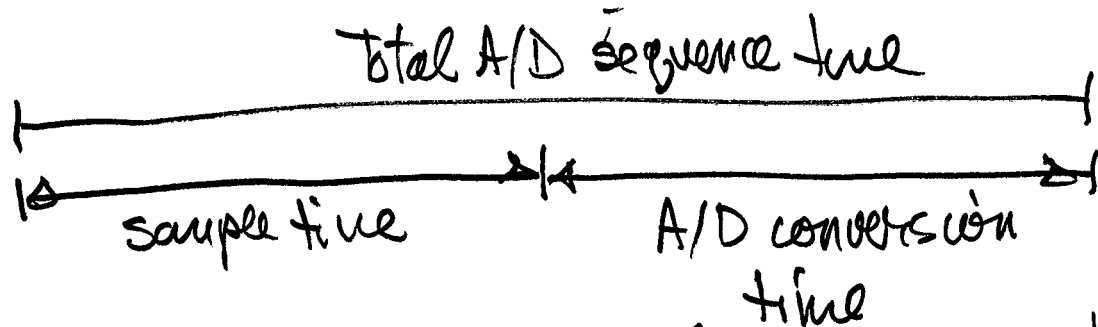
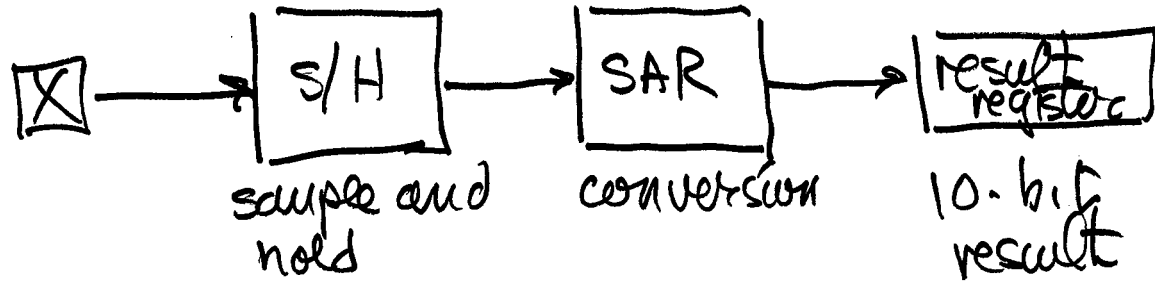
- Sample and Hold Step

sample the input signal and use it to charge a capacitor.

- Conversion

Disconnect cap from input pin and connect it to the SAR A/D converter

We have



Conversion process is controlled by a number of registers

Fig 21-1 in PIC24FJ64GA002
datasheet

(PIC24F FRM Section 17)
10-bit

What Registers do you use

• 3 control registers

ADICON1, ADICON2, ADICON3

• ADICHS (channel select register)

• ADIPCFG (port configuration)

• ADICSSL (scan select register)

• ADCIBUFD (~~register~~ result buffer)

Details for configuring and using
the A/D are in the FRM (sec 17)

Configurations

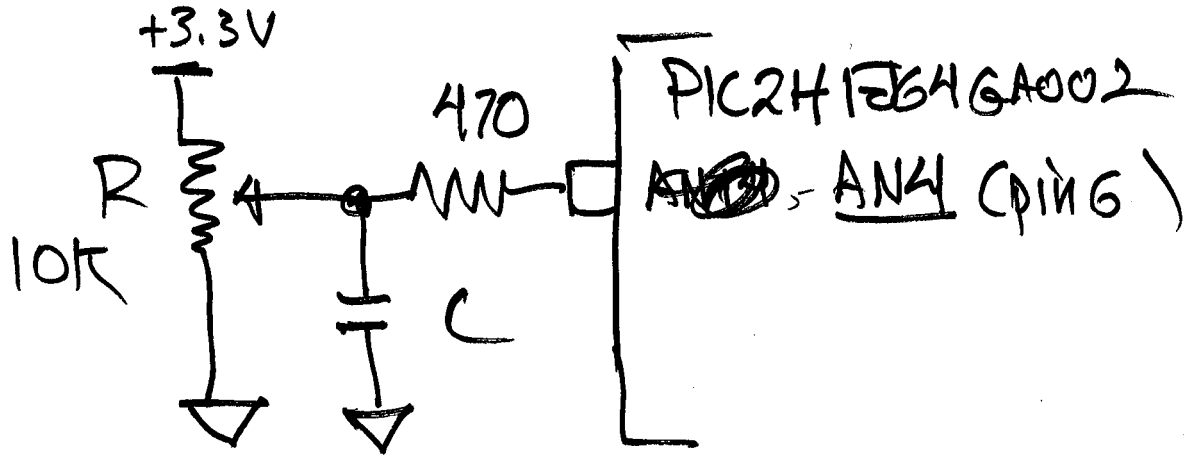
Example Codes

Datasheet also walks through the
configuration bit settings

Do an example

Based on example in Datasheet

Sample a potentiometer



Digitize the Voltage on the pot

Example

Resolution 10-bits or $2^{10} = 1024$ levels

Range is 0 to 3.3V

$$\text{Precision } \frac{3.3\text{V}}{2^{10}} = 3.22\text{mV}$$

Initialization

AD1PCFG = 0xffef; // AN4

AD1CON1 = 0;

AD1CSSL = 0;

AD1CON2 = 0;

AD1CON3 = 0x1F01; // AD timing

AD1CON1bits.ADON = 1; // turn on

manually do 1 channel

↖ analog
1111 1111 1110 1111