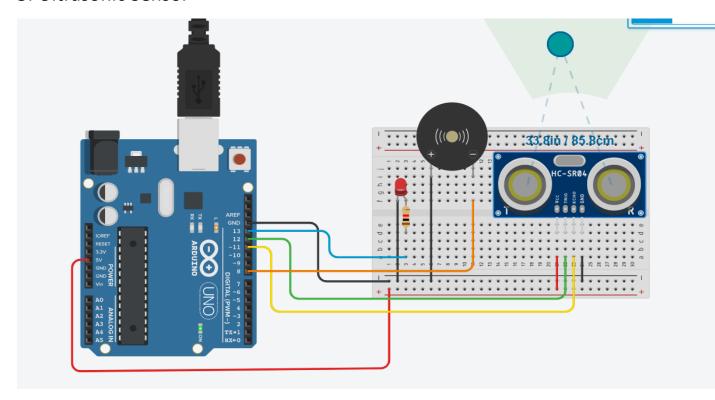
5. Ultrasonic Sensor



```
long duration, dist_cm;
void setup()
{
   pinMode(13, OUTPUT);
   pinMode(12, OUTPUT);
   pinMode(11, INPUT);
   pinMode(8, OUTPUT);
}

void loop()
{
   digitalWrite(12, LOW);
      delayMicroseconds(5);
      digitalWrite(12, HIGH);
      delayMicroseconds(10);
      digitalWrite(12, LOW);
```

```
//pinMode(11, INPUT);
    duration = pulseIn(11, HIGH);

    dist_cm = (duration/2) / 29;

if(dist_cm>0 && dist_cm<300){
    digitalWrite(13,HIGH);
    digitalWrite(8,HIGH);
}

else {
    digitalWrite(8,LOW);
    digitalWrite(13,LOW);
}</pre>
```