Approximating likelihood ratios with calibrated classifiers

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Joint work with



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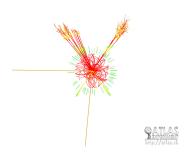


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See paper (Cranmer et al., 2015) for full details.

Likelihood-free setup

- Complex simulator p parameterized by θ ;
- Samples $\mathbf{x} \sim p$ can be generated on-demand;
- ... but the likelihood $p(\mathbf{x}|\theta)$ cannot be evaluated!



Simple hypothesis testing

- Assume some observed data $\mathcal{D} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$;
- Test a null $\theta = \theta_0$ against an alternative $\theta = \theta_1$;
- The Neyman-Pearson lemma states that the most powerful test statistic is

$$\lambda(\mathcal{D}; \theta_0, \theta_1) = \prod_{\mathbf{x} \in \mathcal{D}} \frac{\rho_{\mathbf{X}}(\mathbf{x}|\theta_0)}{\rho_{\mathbf{X}}(\mathbf{x}|\theta_1)}.$$

• ... but neither $p_{\mathbf{X}}(\mathbf{x}|\theta_0)$ nor $p_{\mathbf{X}}(\mathbf{x}|\theta_1)$ can be evaluated!

Straight approximation

- 1. Approximate $p_{\mathbf{X}}(\mathbf{x}|\theta_0)$ and $p_{\mathbf{X}}(\mathbf{x}|\theta_1)$ individually, using density estimation algorithms;
- 2. Evaluate their ratio $r(\mathbf{x}; \theta_0, \theta_1)$.

Works fine for low-dimensional data, but because of the curse of dimensionality, this is in general too difficult a problem!

$$\frac{p_{\mathbf{x}}(\mathbf{x}|\theta_0)}{p_{\mathbf{x}}(\mathbf{x}|\theta_1)} = r(\mathbf{x};\theta_0,\theta_1)$$

When solving a problem of interest, do not solve a more general problem as an intermediate step. – Vladimir Vapnik

Approximating likelihood ratios with classifiers

• Theorem: The likelihood ratio is invariant under the change of variable $\mathbf{U} = s(\mathbf{X})$, provided $s(\mathbf{x})$ is monotonic with $r(\mathbf{x})$.

$$r(\mathbf{x}; \theta_0, \theta_1) = \frac{p_{\mathbf{X}}(\mathbf{x}|\theta_0)}{p_{\mathbf{X}}(\mathbf{x}|\theta_1)} = \frac{p_{\mathbf{U}}(s(\mathbf{x})|\theta_0)}{p_{\mathbf{U}}(s(\mathbf{x})|\theta_1)}$$

- Well, a classifier trained to distinguish $\mathbf{x} \sim p_0$ from $\mathbf{x} \sim p_1$ yields a decision function $s(\mathbf{x})$ which is monotonic with $r(\mathbf{x})$.
- Estimating $p(s(\mathbf{x})|\theta)$ is now easy, since the change of variable $s(\mathbf{x})$ projects \mathbf{x} in a 1D space, where only the informative content of the ratio is preserved.
- Disentangle training from calibration.

Inference and composite hypothesis testing

Approximated likelihood ratios can be used for inference, since

$$\begin{split} \hat{\theta} &= \arg\max_{\theta} p(\mathcal{D}|\theta) \\ &= \arg\max_{\theta} \prod_{\mathbf{x} \in \mathcal{D}} \frac{p(\mathbf{x}|\theta)}{p(\mathbf{x}|\theta_1)} \\ &= \arg\max_{\theta} \prod_{\mathbf{x} \in \mathcal{D}} \frac{p(s(\mathbf{x};\theta,\theta_1)|\theta)}{p(s(\mathbf{x};\theta,\theta_1)|\theta_1)} \end{split} \tag{1}$$

where θ_1 is fixed and $s(\mathbf{x}; \theta, \theta_1)$ is a family of classifiers parameterized by (θ, θ_1) .

Accordingly, generalized (or profile) likelihood ratio tests can be evaluated in the same way.

Parameterized learning

For inference, we need to build a family $s(\mathbf{x}; \theta, \theta_1)$ of classifiers.

- One could build a classifier s independently for all θ, θ_1 . But this is computationally expensive and would not guarantee a smooth evolution of $s(\mathbf{x}; \theta, \theta_1)$ as θ varies.
- Solution: build a single parameterized classifier instead, where parameters are additional input features (Baldi et al., 2016).

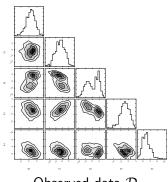
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 \begin{split} \mathcal{T} &:= \{\}; \\ \text{while } & \operatorname{size}(\mathcal{T}) < \textit{N} \  \  \, \text{do} \\ & \operatorname{Draw} \  \, \theta_0 \sim \pi_{\Theta_0}; \\ & \operatorname{Draw} \  \, \mathbf{x} \sim p(\mathbf{x}|\theta_0); \\ & \mathcal{T} := \mathcal{T} \cup \{((\mathbf{x},\theta_0,\theta_1),y=0)\}; \\ & \operatorname{Draw} \  \, \theta_1 \sim \pi_{\Theta_1}; \\ & \operatorname{Draw} \  \, \mathbf{x} \sim p(\mathbf{x}|\theta_1); \\ & \mathcal{T} := \mathcal{T} \cup \{((\mathbf{x},\theta_0,\theta_1),y=1)\}; \\ & \text{end while} \\ & \operatorname{Learn a single classifier} \  \, \mathbf{s}(\mathbf{x};\theta_0,\theta_1) \  \, \text{from } \mathcal{T}. \end{split}
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Example: Inference from multidimensional data

Let assume 5D data x generated from the following process p_0 :

- 1. $\mathbf{z} := (z_0, z_1, z_2, z_3, z_4)$, such that $z_0 \sim \mathcal{N}(\mu = \alpha, \sigma = 1)$, $z_1 \sim \mathcal{N}(\mu = \beta, \sigma = 3)$, $z_2 \sim \mathsf{Mixture}(\frac{1}{2}\,\mathcal{N}(\mu = -2, \sigma = 1), \frac{1}{2}\,\mathcal{N}(\mu = 2, \sigma = 0.5))$, $z_3 \sim \mathsf{Exponential}(\lambda = 3)$, and $z_4 \sim \mathsf{Exponential}(\lambda = 0.5)$;
- x := Rz, where R is a fixed semi-positive definite 5 × 5 matrix defining a fixed projection of z into the observed space.

Our goal is to infer the values α and β based on \mathcal{D} .



Observed data $\mathcal D$

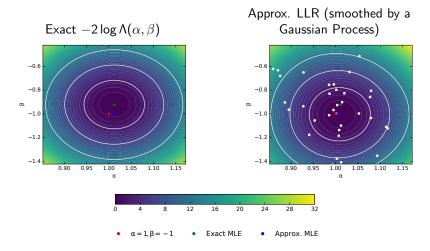
• Check out (Louppe et al., 2016) to reproduce this example.

Example: Inference from multidimensional data

Recipe:

- 1. Build a single parameterized classifier $s(\mathbf{x}; \theta_0, \theta_1)$, in this case a 2-layer NN trained on 5+2 features, with the alternative fixed to $\theta_1 = (\alpha = 0, \beta = 0)$.
- 2. Find the approximated MLE $\hat{\alpha}, \hat{\beta}$ by solving Eqn. 1.
 - Solve Eqn. 1 using likelihood scans or through optimization.
 - Since the generator is inexpensive, $p(s(\mathbf{x}; \theta_0, \theta_1)|\theta)$ can be calibrated on-the-fly, for every candidate (α, β) , e.g. using histograms.
- 3. Construct the log-likelihood ratio (LLR) statistic

$$-2\log\Lambda(\alpha,\beta) = -2\log\frac{p(\mathcal{D}|\alpha,\beta)}{p(\mathcal{D}|\hat{\alpha},\hat{\beta})}$$

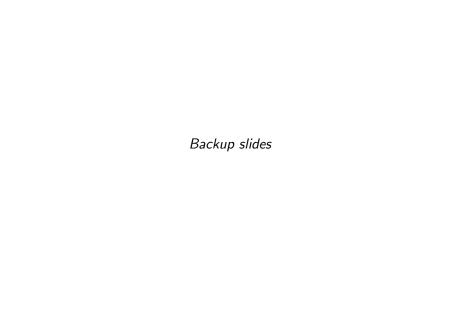


Summary

- We proposed an approach for approximating LR in the likelihood-free setup.
- Evaluating likelihood ratios reduces to supervised learning.
 Both problems are deeply connected.
- Alternative to Approximate Bayesian Computation, without the need to define a prior over parameters.

References

- Baldi, P., Cranmer, K., Faucett, T., Sadowski, P., and Whiteson, D. (2016). Parameterized Machine Learning for High-Energy Physics. arXiv preprint arXiv:1601.07913
- Cranmer, K., Pavez, J., and Louppe, G. (2015). Approximating likelihood ratios with calibrated discriminative classifiers. arXiv preprint arXiv:1506.02169.
- Louppe, G., Cranmer, K., and Pavez, J. (2016). carl: a likelihood-free inference toolbox. http://dx.doi.org/10.5281/zenodo.47798, https://github.com/diana-hep/carl.



Likelihood ratio of mixtures

For models defined as known mixtures of several components, i.e. when $p(\mathbf{x}|\theta)$ can be written as

$$p(\mathbf{x}|\theta) = \sum_{c} w_{c}(\theta) p_{c}(\mathbf{x}|\theta),$$

the target likelihood ratio can be formulated in terms of pairwise approximations of likelihood ratios. Specifically, we can write

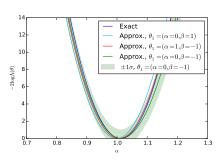
$$\begin{split} \frac{\rho(\mathbf{x}|\theta_0)}{\rho(\mathbf{x}|\theta_1)} &= \frac{\sum_c w_c(\theta_0) p_c(\mathbf{x}|\theta_0)}{\sum_{c'} w_{c'}(\theta_1) p_{c'}(\mathbf{x}|\theta_1)} \\ &= \sum_c \left[\sum_{c'} \frac{w_{c'}(\theta_1)}{w_c(\theta_0)} \frac{p_{c'}(\mathbf{x}|\theta_1)}{p_c(\mathbf{x}|\theta_0)} \right]^{-1} \\ &= \sum_c \left[\sum_{c'} \frac{w_{c'}(\theta_1)}{w_c(\theta_0)} \frac{p_{c'}(\mathbf{s}_{c,c'}(\mathbf{x};\theta_0,\theta_1)|\theta_1)}{p_c(\mathbf{s}_{c,c'}(\mathbf{x};\theta_0,\theta_1)|\theta_0)} \right]^{-1}. \end{split}$$

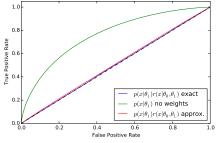
This allows to focus the capacity of the classifiers on simpler problems, resulting in better approximations.

Diagnostics

In practice $\hat{r}(\hat{s}(\mathbf{x}; \theta_0, \theta_1))$ will not be exact. Diagnostic procedures are needed to assess the quality of this approximation.

- 1. For inference, the value of the MLE $\hat{\theta}$ should be independent of the value of θ_1 used in the denominator of the ratio.
- 2. Train a classifier to distinguish between unweighted samples from $p(\mathbf{x}|\theta_0)$ and samples from $p(\mathbf{x}|\theta_1)$ weighted by $\hat{r}(\hat{s}(\mathbf{x};\theta_0,\theta_1))$.





Applications in High Energy Physics