MXB326 Group Project - Reservoir Simulation

 $\begin{array}{c} {\rm MXB326_23se1~Computational~Methods~2} \\ {\rm Due~26-05-2023} \end{array}$

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Contents

| 1 | Introduction | 1 |
|---|--------------------------|---|
| 2 | Mathematical Model | 2 |
| 3 | Semi-Analytical Solution | 2 |
| 4 | Numerical Solution | 2 |
| 5 | Analysis and Findings | 2 |
| 6 | Conclusions | 2 |
| 7 | References | 2 |

1 Introduction

Oil is a natural resource which is used abundantly in modern society. Necessary for the creation of fuels which transport us around the world, to materials in products we use hundreds of times a day, and many applications in between, it is no stretch to say that civilisation as we know it relies on oil. But the production of oil can be a slow and costly process. One method commonly used in the oil industry to improve production is called water-flooding. This processes uses the injection of water into the porous rock structure of an oil reservoir to increase the pressure, driving more oil out. Modelling this process mathematically is a key interest of a field of research known as reservoir engineering, and is of vital importance to ensure that the process of water-flooding runs smoothly.

This modelling, involving the simultaneous flow of two viscous fluids through a horizontal reservoir in three dimensions, is quite complex. Fortunately, the model can be substantially simplified when considering a homogeneous, one-dimensional reservoir. This simplification in turn reduces what would be a coupled system of partial differential equations into a single, one-dimensional PDE. To describe the mechanics of the system, the conservation of mass of oil and water assuming immiscibility and incompressibility, are given by the transport equations:

$$\phi \frac{\partial S_w}{\partial t} + \frac{\partial q_w}{\partial x} = 0 \tag{1}$$

$$\phi \frac{\partial S_o}{\partial t} + \frac{\partial q_o}{\partial x} = 0 \tag{2}$$

In this system, ϕ indicates how porous the medium of the reservoir is, and S_w and q_w , S_o and q_o indicate the saturation and flow rate of the water and oil respectively. We relate the pressure in each fluid as the capillary pressure: $P_c = p_o - p_w$, and assume that the capillary pressure is positive. Furthermore, the saturations of the oil and water can be related as $S_w + S_o = 1$, allowing a single saturation, $S = S_o$ to be the sole variable to be modelled. Also defined are the minimum, irreducible saturations S_{or} and S_{wr} .

For a comprehensive description of the mathematical system, it is also necessary to define the conditions at the boundaries of the domain. Figure 1 demonstrates the domain of the problem.

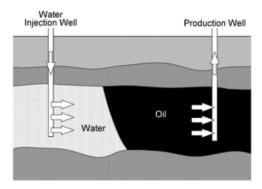


Figure 1: Schematic of the oil injection process.

Assuming a constant injection of water at x = 0 at rate q:

$$q_w(0,t) = q$$
 and $q_o(0,t) = 0$ (3)

And assuming oil saturation begins at its maximum value:

$$S(x,0) = 1 - S_{wr} (4)$$

Finally, assuming a semi-infinite reservoir:

$$\lim_{x \to \infty} S(x, t) = 1 - S_{wr} \tag{5}$$

For an efficient and cost-effective water-flooding operation, it is critical to prevent the water from mixing with the oil in the well-bore (extraction point). We thus define the breakthrough time as $T_B = 1 - S_{or} - S_{wr}$, the time taken for the water to reach the well-bore during the water-flooding. Specification of a suitable injection rate q is capable of preventing this issue from arising.

This report contains a pilot study of the simplified system above, including a mathematical model with a semi-analytic solution and a numerical solution. These solutions will be analysed thoroughly, with the goal of demonstrating the capability of a fully detailed study in the future.

2 Mathematical Model

It is possible to derive an exact solution for the system described above using methods from Fokas and Yortsos, in the case of constant injection rates when the water to oil viscosity ratio F has the form

$$F = \frac{1 - S_{wr} + \frac{\gamma}{\beta}}{S_{or} + \frac{\gamma}{\beta}} \tag{6}$$

Applying this, the following one-dimensional initial boundary value problem can be derived for the oil saturation:

$$\frac{\partial S}{\partial t} = \frac{\partial}{\partial x} \left[g(S) \frac{\partial S}{\partial x} + f(S) \right],$$

$$S(x,0) = 1 - S_{wr},$$
(8)

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$$\frac{\partial S}{\partial x}(0,t) = \frac{\alpha}{\beta}(\beta S(0,t) + \gamma) + \frac{\omega}{\beta}(\beta S(0,t) + \gamma)^2, \tag{9}$$

$$\lim_{x \to \infty} S(x, t) = 1 - S_{wr}. \tag{10}$$

By specifying $S_{wr}, S_{or}, F, \text{and}\beta$, the remaining parameters can be determined from (6) as well as the relations

$$\frac{\alpha}{\beta^2} = -\frac{\left(S_{or} + \frac{\gamma}{\beta}\right)\left(1 - S_{wr} + \frac{\gamma}{\beta}\right)}{1 - S_{wr} - S_{or}},\tag{11}$$

$$\omega = \beta - \frac{\alpha}{\beta - \beta S_{wr} + \gamma}. (12)$$

Furthermore, the functions f(S) and g(S), called the capillary-hydraulic properties of the fluidporous system are given by

$$f(S) = \frac{\alpha}{\beta^2} \left[\frac{1}{1 - S_{wr} + \frac{\gamma}{\beta}} - \frac{1}{S + \frac{\gamma}{\beta}} \right], \quad g(S) = \frac{1}{(\beta S + \gamma)^2}.$$

These functions allow for an exactly solvable PDE (7), and also correspond to a physically meaningful model.

- 3 Semi-Analytical Solution
- **Numerical Solution** 4
- 5 Analysis and Findings
- Conclusions 6
- 7 References