2.8.- Plantillas

2.8.1.- Variables auxiliares

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$$\frac{a_{[1]^{2}}}{a_{1}^{2}} \left(*c \text{Linemattica directas} \right) \\ \left\{ 31 \rightarrow 1 + g^{2}, \text{ bit } \rightarrow -2 \text{ fg * gif } 5 + 2 \text{ gil Los [61] * 211 Sin[61] }, \text{ ci } \rightarrow f^{2} + 11^{2} - 12^{2} - f 15 + \frac{15^{2}}{4} + 11 \text{ (-2 f * 15) Cos [61]} \right\}; \\ \left\{ f \rightarrow \frac{11^{2} - 12^{2} + 13^{2} - 14^{2} + 1115 \text{ Cos [61] * 1415 Cos [64]}}{2 \text{ (15 + 11 Cos [61] * 14 Cos [64])}}, \text{ g } \rightarrow \frac{(-2 \text{ 11 Sin[61] * 2 145 Sin[64])}}{2 \text{ (15 + 11 Cos [61] * 14 Cos [64])}} \right\}; \\ \left\{ 61 \rightarrow 11^{2} - 12^{2} - 1115 + \frac{15^{2}}{4} + 2 11 \text{ X3 - 15 X3 + X3^{2} * V3^{2}}, \text{ bit } \rightarrow -4 11 \text{ Y3 , ci} \rightarrow 11^{2} - 12^{2} + 1115 + \frac{15^{2}}{4} - 2 11 \text{ X3 - 15 X3 + X3^{2} * V3^{2}} \right\}; \\ \left(*644 \right) \\ \left\{ 62 \rightarrow -13^{2} + 14^{2} + 14 15 + \frac{15^{2}}{4} + 2 14 \text{ X3 + 15 X3 + X3^{2} * V3^{2}}, \text{ bit } \rightarrow -4 14 \text{ Y3 , ci} \rightarrow 11^{2} - 12^{2} + 14^{2} - 14 15 + \frac{15^{2}}{4} - 2 14 \text{ X3 + 15 X3 + X3^{2} * V3^{2}} \right\}; \\ 2.8.2.- \text{ Cinemattica directa} \\ \left[(*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [61] + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [61] + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 14 \text{ Cos } [64] \right) \right) \right) \left(2 \text{ (15 + 11 Cos } [61] - 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 11 \text{ Cos } [61] - 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 11 \text{ Cos } [61] - 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 11 \text{ Cos } [61] + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + 11 \text{ Cos } [61] + 14 \text{ Cos } [64] \right) \\ \left((*s) \left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}$$

$$\left(15 - \frac{11^2 - 12^2 + 13^2 - 14^2 + 11 \, 15 \, \mathsf{Cos} \, [\theta 1] + 14 \, 15 \, \mathsf{Cos} \, [\theta 4]}{15 + 11 \, \mathsf{Cos} \, [\theta 1] - 14 \, \mathsf{Cos} \, [\theta 4]}\right)\right) \left(1 + \frac{\left(-2 \, 11 \, \mathsf{Sin} \, [\theta 1] + 2 \, 14 \, \mathsf{Sin} \, [\theta 4] \,\right)^2}{4 \, \left(15 + 11 \, \mathsf{Cos} \, [\theta 4] \,\right)}\right)\right)\right)$$

$$\left(4 \, \left(15 + 11 \, \mathsf{Cos} \, [\theta 1] - 14 \, \mathsf{Cos} \, [\theta 4] \,\right) \left(1 + \frac{\left(-2 \, 11 \, \mathsf{Sin} \, [\theta 1] + 2 \, 14 \, \mathsf{Sin} \, [\theta 4] \,\right)^2}{4 \, \left(15 + 11 \, \mathsf{Cos} \, [\theta 4] \,\right)^2}\right)\right);$$

$$\left(* \frac{b + \sqrt{-4 \, a \, b + o^2}}{4 \, a \, b + o^2} *\right)$$

$$\begin{aligned} &\left(\star^{\frac{b-\sqrt{-4 \text{ o } h + o^2}}{2 \text{ o }}}\star\right) \\ &\text{Ymenos} = \frac{1}{2\left(1 + \frac{\left(-211\sin(o_1) + 214\sin(o_4)\right)^2}{4\left(15 + 11\cos(o_1) - 14\cos(o_4)\right)^2}\right)} \\ &\left(211\sin[o_1] + \frac{15\left(-211\sin(o_1) + 214\sin(o_4)\right)}{2\left(15 + 11\cos(o_1) - 14\cos(o_4)\right)} + \frac{11\cos[o_1]\left(-211\sin[o_1] + 214\sin[o_4]\right)}{15 + 11\cos[o_1] - 14\cos[o_4]} - \frac{\left(\left(11^2 - 12^2 + 13^2 - 14^2 + 1115\cos[o_1] + 1415\cos[o_4]\right)\right) \left(-211\sin[o_1] + 214\sin[o_4]\right)\right)}{\left(2\left(15 + 11\cos[o_1] - 14\cos[o_4]\right)^2\right)} - \sqrt{\left(\left(211\sin[o_1] + \frac{11\cos[o_1] + 214\sin[o_4]\right)\right)\right)} \\ &\left(2\left(15 + 11\cos[o_1] - 14\cos[o_4]\right)^2\right) - \sqrt{\left(\left(211\sin[o_1] + \frac{11\cos[o_1] - 14\cos[o_1]}{15 + 11\cos[o_1] - 14\cos[o_4]}\right)} \\ &\left(\left(15 - \frac{11^2 - 12^2 + 13^2 - 14^2 + 1115\cos[o_1] + 1415\cos[o_4]}{15 + 11\cos[o_1] - 14\cos[o_4]}\right) \left(-211\sin[o_1] + 214\sin[o_4]\right)\right)\right)} \\ &\left(2\left(15 + 11\cos[o_1] - 14\cos[o_4]\right)\right)^2 - \\ &\left(411^2 - 412^2 + 15^2 - \frac{215\left(11^2 - 12^2 + 13^2 - 14^2 + 1115\cos[o_1] + 1415\cos[o_1] + 1415\cos[o_1]}{15 + 11\cos[o_1] - 14\cos[o_4]}\right)} \\ &\left(\frac{\left(11^2 - 12^2 + 13^2 - 14^2 + 1115\cos[o_1] + 1415\cos[o_4]\right)}{15 + 11\cos[o_1] - 14\cos[o_4]}\right)}{(15 + 11\cos[o_1] - 14\cos[o_1]} + 411\cos[o_1] + 214\sin[o_1]^2} \\ &\left(15 - \frac{11^2 - 12^2 + 13^2 - 14^2 + 1115\cos[o_1] + 1415\cos[o_1]}{15 + 11\cos[o_1] - 14\cos[o_1]}\right)\right) \left(1 + \frac{\left(-211\sin[o_1] + 214\sin[o_1]\right)^2}{4\left(15 + 11\cos[o_1] - 14\cos[o_1]\right)^2}\right)\right)\right), \end{aligned}$$

2.8.3.- Cinemática inversa

 $(* \sigma 2 = -1 *)$ ⊖4menos =

$$\begin{aligned} &\text{oflas} = \\ &\text{oflas} = \\ &2 \operatorname{ArcTan} \Big[\left(4 \ 11 \ Y3 + \sqrt{ \left(16 \ 11^2 \ Y3^2 - 4 \left(11^2 - 12^2 + 11 \ 15 + \frac{15^2}{4} - 2 \ 11 \ X3 - 15 \ X3 + X3^2 + Y3^2 \right) } \right) \Big] \cdot \left(11^2 - 12^2 - 11 \ 15 + \frac{15^2}{4} + 2 \ 11 \ X3 - 15 \ X3 + X3^2 + Y3^2 \right) \Big) \Big] ; \\ &(* \ \sigma 1 = -1 \ *) \\ &\text{olimenos} = \\ &2 \operatorname{ArcTan} \Big[\left(4 \ 11 \ Y3 - \sqrt{ \left(16 \ 11^2 \ Y3^2 - 4 \left(11^2 - 12^2 + 11 \ 15 + \frac{15^2}{4} - 2 \ 11 \ X3 - 15 \ X3 + X3^2 + Y3^2 \right) } \right) \Big] \cdot \left(11^2 - 12^2 - 11 \ 15 + \frac{15^2}{4} + 2 \ 11 \ X3 - 15 \ X3 + X3^2 + Y3^2 \right) \Big) \Big] ; \\ &(* \ \sigma 2 = 1 \ *) \\ &\text{o4mas} = \\ &2 \operatorname{ArcTan} \Big[\left(4 \ 14 \ Y3 + \sqrt{ \left(16 \ 14^2 \ Y3^2 - 4 \left(-13^2 + 14^2 - 14 \ 15 + \frac{15^2}{4} - 2 \ 14 \ X3 + 15 \ X3 + X3^2 + Y3^2 \right) } \right) \Big] \cdot \left(11^2 - 12^2 - 11 \ 15 + \frac{15^2}{4} + 2 \ 11 \ X3 - 15 \ X3 + X3^2 + Y3^2 \right) \right) \Big] ; \end{aligned}$$

 $2 \arctan \left[\left(4 \ 14 \ Y3 - \sqrt{\left(16 \ 14^2 \ Y3^2 - 4 \left(-13^2 + 14^2 - 14 \ 15 + \frac{15^2}{4} - 2 \ 14 \ X3 + 15 \ X3 + X3^2 + Y3^2 \right) \right) \left(-13^2 + 14^2 + 14 \ 15 + \frac{15^2}{4} + 14 \ 15$

 $2 14 X3 + 15 X3 + X3^{2} + Y3^{2}$ $\left| \left| \left| \left| \left| \left| \left(2 \left(-13^{2} + 14^{2} + 14 15 + \frac{15^{2}}{4} + 2 14 X3 + 15 X3 + X3^{2} + Y3^{2} \right) \right| \right| \right| \right|$;

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4 PlantillasCinematica_DirectaInversa.nb
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2.8.4 .- Dibujar Barras

```
In[*]:= (*Puntos de las barras*)
      p2S2D = \left\{11 \cos [\theta 1] + \frac{15}{2}, 11 \sin [\theta 1]\right\};
      p4S2D = \left\{14 \cos \left[\theta 4\right] - \frac{15}{2}, 14 \sin \left[\theta 4\right]\right\};
      p1S2D = \left\{\frac{15}{2}, 0\right\};
      p5S2D = \left\{-\frac{15}{2}, 0\right\};
       p3S2D = {Xmas, Ymas};
       DibujarBarrasFunction[P_, c_, text_] := Module[
           {elementos},
           (*Union de los elementos*)
          elementos = \{ \{P[[1]], P[[2]]\}, \{P[[2]], P[[3]]\}, \{P[[4]]\}, \{P[[4]], P[[5]]\}, \{P[[5]], P[[1]]\} \} /.
                \{11 \rightarrow \texttt{c[[1]]}, \ 12 \rightarrow \texttt{c[[2]]}, \ 13 \rightarrow \texttt{c[[3]]}, \ 14 \rightarrow \texttt{c[[4]]}, \ 15 \rightarrow \texttt{c[[5]]} \} \ /. \ \{\theta1 \rightarrow \texttt{c[[6]]}, \ \theta4 \rightarrow \texttt{c[[7]]} \};
          Show [
            Table[Graphics[Line[elementos[k]]]], {k, 1, Length[elementos]}],
            Table [Graphics [Text[Style[StringForm["l``", k], Bold, Red, 15], Mean[elementos[[k]]]]], \{k, 1, 5\}], \\
            Table[Graphics[Text[Style[ToString[k], Bold, Black, 15], elementos[k, 1]]], {k, Length[elementos]}],
            Axes -> True, AxesLabel \rightarrow {x, y}, PlotLabel \rightarrow text,
            GridLines → Automatic, GridLinesStyle → Directive[Gray, Dashed]]
         ]
```