week14-02-springs-bridges

April 14, 2025

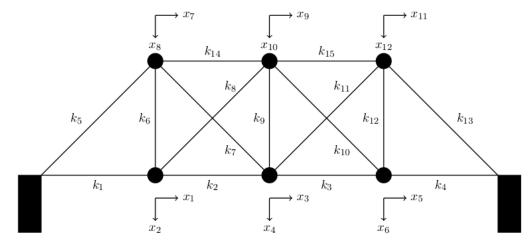
- 1 George McNinch Math 87 Spring 2025
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```
[1]: import numpy as np
import numpy.linalg as la

def sbv(i,n):
    return np.array([1 if j == i else 0 for j in range(n)])

def makeK(kar):
    n = len(kar)
    return np.array([kar[i]*sbv(i,n) for i in range(n)])
```

Suppose we are building a bridge, which we'll view as a spring-system as before:



For simplicity we are going to assume that all angles in the diagram are $\pi/2$ or $\pi/4$.

Using the same material for each "beam" of the bridge, the spring constants are inversely proportional to their length.

There are 15 springs/beams in total, and we take them as follows:

$$k_i = \begin{cases} 9.7500 \cdot 10^6 \, \text{N/m} & \text{for } i = 1, 2, 3, 4, 6, 9, 12, 14, 15 \\ 6.8943 \cdot 10^6 \, \text{N/m} & \text{for } i = 5, 7, 8, 10, 11, 13 \end{cases}$$

In order to test the bridge for structural integrity, we load the three lower masses (where traffic would be) individually with forces of $2 \cdot 10^6$ N, and measure the resulting displacements.

Remark The average car in the US weighs about 4,000 lbs ($\approx 1,814$ kg), which corresponds to $\approx 1.778 \cdot 10^4$ N. The average semi-truck weighs about 80,000 lbs ($\approx 36,287$ kg), which corresponds to $\approx 3.556 \cdot 10^5$ N.

```
[7]: # The matrix B with Bx = e is given as follows:
     def sbv(i,n):
         return np.array([1 if i == j else 0 for j in range(n)])
     def sbvarray(x,1):
         return sbv(l.index(x),len(l))
     a = list(range(1,13))
     k = np.sqrt(2)/2
     B bridge = np.array([ sbvarray(1,a),
                                                                                   # e1 =
      -r.1
                                                                           \# e2 = x3 - x1
                     sbvarray(3,a) - sbvarray(1,a),
                                                                           \# e3 = x5 - x3
                     sbvarray(5,a) - sbvarray(3,a),
                                                                           \# e4 = x5
                     sbvarray(5,a),
                     k*(sbvarray(7,a) - sbvarray(8,a)),
                                                                           \# e5 = k*x7 -
      \hookrightarrow k*x8
                     sbvarray(2,a) - sbvarray(8,a),
                                                                           \# e6 = x2 - x8
                     k*(sbvarray(3,a) + sbvarray(4,a)
                        - sbvarray(7,a) - sbvarray(8,a)),
                                                                           \# e7 = k*x3 + 1
      4 k*x4 - k*x7 - k*x8
                     k*(-sbvarray(1,a) + sbvarray(2,a)
                        + sbvarray(9,a) - sbvarray(10,a)),
                                                                           \# e8 = -k*x1 + \dots
      4k*x2 + k*x9 - k*x10
                     sbvarray(4,a) - sbvarray(10,a),
                                                                           \# e9 = x4 -
      \hookrightarrow x10
                     k*(sbvarray(5,a) + sbvarray(6,a)
                        - sbvarray(9,a) - sbvarray(10,a)),
                                                                           \# e10 = k*x5 +
      4k*x6 - k*x9 - k*x10
                     k*(-sbvarray(3,a) + sbvarray(4,a)
                        + sbvarray(11,a) - sbvarray(12,a)),
                                                                          \# e11 = -k*e3
      →+ k*e4 + k*e11 - k*e12
                     sbvarray(6,a) - sbvarray(12,a),
                                                                           \# e12 = x6 -
       \rightarrow x12
```

```
k*(-sbvarray(11,a) - sbvarray(12,a)),  # e13 = -k*x11_{\square}
-sbvarray(7,a) + sbvarray(9,a),  # e14 = -x7 +_{\square}
-sbvarray(9,a) + sbvarray(11,a)  # e15 = -x9 +_{\square}
-x11
))
np.set_printoptions(suppress=True, linewidth=1000)
B_bridge
```

```
[7]: array([[ 1.
         0.
                        0.
                                                                                                 ],
              [-1.
                                               1.
                                                              0.
                                                                             0.
         0.
                        0.
                                        0.
                                                       0.
                                                                                                 ],
              [ 0.
                               0.
                                                              0.
                                              -1.
                                                                              1.
         0.
                                                                      0.
                                                                                                 ],
              Γ0.
                               0.
                                               0.
                                                                                                 ],
              Γ0.
                               0.
                                               0.
                                                              0.
                                                                             0.
         0.70710678, -0.70710678,
                                       0.
                                                       0.
                                                                      0.
                                                                                      0.
                                                                                                 ],
              [ 0.
                               1.
                                               0.
                                                              0.
                                                                             0.
                     , -1.
                                       0.
                                                       0.
                                                                      0.
                                                                                                 ],
              [ 0.
                               0.
                                               0.70710678,
                                                              0.70710678,
        -0.70710678, -0.70710678,
                                       0.
                                                                                                 ],
                                                       0.
                                                                      0.
              [-0.70710678,
                               0.70710678,
                                               0.
                                                              0.
                                        0.70710678, -0.70710678,
                                                                      0.
                                                                                                 ],
                                                    , -1.
         0.
                        0.
                                       0.
                                                                      0.
                                                                                                 ],
              [ 0.
                               0.
                                               0.
                                                              0.
                                                                             0.70710678,
     0.70710678,
                                                , -0.70710678, -0.70710678,
                     0.
                                    0.
                                                                                                 0.
     ],
                                                              0.70710678, 0.
              Γ0.
                                             -0.70710678,
                               0.
         0.
                        0.
                                       0.
                                                                      0.70710678, -0.70710678,
              [ 0.
                               0.
                                                              0.
                                               0.
         0.
                        0.
                                        0.
                                                       0.
                                                                                                 ],
              [ 0.
                               0.
                                               0.
                                                              0.
                                                                             0.
                                                                   , -0.70710678, -0.70710678],
         0.
                        0.
                                       0.
                                                       0.
              [ 0.
                                               0.
                               0.
                                                              0.
                                                                             0.
      , -1.
                        0.
                                        1.
                                                       0.
                                                                      0.
                                                                                                 ],
              [ 0.
                                               0.
                                                              0.
                                                                             0.
                               0.
                                                                                             0.
         0.
                                                       0.
                                                                      1.
     ]])
```

Let's suppose that f = [0, 2, 0, 2, 0, 0, 0, 0, 0, 0]. (We keep the numbering on the forces is the same as the numbering on the displacements. Thus, these forces are *downward* on all three masses in the bottom row.)

```
[8]: ff = 10**6*np.array([0, 2, 0, 2, 0, 2, 0, 0, 0, 0, 0, 0])

K2 = makeK([ 9.7* 10**6 if i in [1,2,3,4,6,9,12,14,15] else 6.8943 * 10**6 for in range (1,16)])

A2 = B_bridge.transpose() @ K2 @ B_bridge la.solve(A2,ff)
```

4.1 inverse problem

The above shows that, given knowledge of the "spring constants" k_i , and the applied forces f_i , we can estimate the displacements x_i . This is the "forward problem".

The inverse problem is this: given measurements of the displacements x_i , find the spring constants k_i .

There are many applications of such *inverse problems*.

For our bridge problem, note that consider the system

$$B^T K B \mathbf{x} = \mathbf{f}$$

We consider a general case where there are m springs and n/2 masses, so that there are n "displacement components" (in 2 dimensions).

Notice that

$$KB\mathbf{x} = \begin{bmatrix} k_1 & 0 & \cdots & 0 \\ 0 & k_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & k_m \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{m1} & b_{m2} & \cdots & b_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$
$$= \operatorname{diag}(B\mathbf{x}) \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix}$$

where for a vector $\mathbf{w} \in \mathbb{R}^m$, we obtain an $m \times m$ matrix

$$\operatorname{diag}(\mathbf{w}) = \begin{bmatrix} w_1 & 0 & \cdots & 0 \\ 0 & w_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & w_m \end{bmatrix}$$

Thus we have

$$B^T K B \mathbf{x} = B^T \operatorname{diag}(B \mathbf{x}) \mathbf{k} = \mathbf{f}$$

which gives some hope for finding the vector \mathbf{k} given knowledge of \mathbf{x} and \mathbf{f} .

4.2 the difficulty

Note that in the case of our bridge example, the number of "displacement components" we are tracking is n = 12, while the number of springs is m = 15.

Note that B^T is an $n \times m$ matrix, that $B\mathbf{x}$ is in \mathbb{R}^m , so that $B^T \operatorname{diag}(B\mathbf{x})$ is an $n \times m$ matrix.

In our example, the linear equation $B^T \operatorname{diag}(B\mathbf{x})\mathbf{k} = \mathbf{f}$ amounts to a system of 12 linear equations in 15 unknowns.

In general, if n < m, the system is underdetermined. As a consequence, the linear equation does not uniquely determine the spring constants k_i – i.e. the entries in the vector \mathbf{k} .

One way to fix this:

take measurements \mathbf{x} for various different force loads \mathbf{f} .

More precisely, consider different force loads $\mathbf{f}_1, \dots, \mathbf{f}_p$. For each of these force loads, determine the displacement vectors $\mathbf{x}_1, \dots, \mathbf{x}_p$.

We now obtain a $pn \times m$ matrix system

$$\begin{bmatrix} B^T \operatorname{diag}(B\mathbf{x}_1) \\ B^T \operatorname{diag}(B\mathbf{x}_2) \\ \vdots \\ B^T \operatorname{diag}(B\mathbf{x}_p) \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_m \end{bmatrix} = \begin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \\ \vdots \\ \mathbf{f}_p \end{bmatrix}.$$

If we choose p sufficiently large and if we make sure that the $np \times m$ coefficient matrix has rank at least m, we expect to find a solution.

```
[4]: def diag(w):
    n = len(w)
    return np.array([ w[i]*sbv(i,n) for i in range(n) ])

diag([1,2,3,4])
```

```
[4]: array([[1, 0, 0, 0], [0, 2, 0, 0], [0, 0, 3, 0], [0, 0, 0, 4]])
```

Let's consider some data. We have collected displacement measurements for three different force loads. The displacement measurements are outside of engineering tolerances!

We want to know which spring (=bridge component) is defective.

```
[11]: # measurements
# for these forces
```

```
f1 = 10**6*np.array([0, 2, 0, 0, 0, 0, 0, 0, 0, 0, 0])
     f2 = 10**6*np.array([0, 0, 0, 2, 0, 0, 0, 0, 0, 0, 0])
     f3 = 10**6*np.array([0, 0, 0, 0, 0, 2, 0, 0, 0, 0, 0])
     # measured the following displacements
     x1 = np.array([ 0.04465819,  0.69735727,  0.08117014,  0.49972439,  0.0584346,
             0.29520329, 0.09315958, 0.52830165, -0.04706315, 0.50115528,
            -0.11445688, 0.25950424])
     x2 =np.array([-0.03453953, 0.49972439, 0.01867222, 0.76169019, 0.03453953,
             0.49283618, 0.16411865, 0.45421336, 0.0034441, 0.66577233,
            -0.15233463, 0.44242935])
     x3 = np.array([-0.04465819, 0.29520329, -0.08117014, 0.49283618, -0.0584346]
             0.69735727, 0.11302599, 0.25807335, 0.04706315, 0.49140529,
            -0.09172868, 0.52687076])
     (f1,x1,f2,x2,f3,x3)
                               Ο,
                                        0, 0, 0, 0,
[11]: (array([
                0, 2000000,
                                                                           0,
                      Ο,
                              0]),
      array([ 0.04465819, 0.69735727, 0.08117014, 0.49972439, 0.0584346,
     0.29520329, 0.09315958, 0.52830165, -0.04706315, 0.50115528, -0.11445688,
     0.25950424]),
      array([
                 Ο,
                           0, 0, 2000000, 0, 0,
                                                                    0,
                                                                             0,
                              0]),
                      Ο,
      array([-0.03453953, 0.49972439, 0.01867222, 0.76169019, 0.03453953,
     0.49283618, 0.16411865, 0.45421336, 0.0034441, 0.66577233, -0.15233463,
     0.44242935]),
      array([
                 Ο,
                         0, 0, 0, 2000000, 0,
                                                                             0,
                      Ο,
                              0]),
     0.
      array([-0.04465819, 0.29520329, -0.08117014, 0.49283618, -0.0584346,
     0.69735727, 0.11302599, 0.25807335, 0.04706315, 0.49140529, -0.09172868,
     0.52687076]))
[6]: coeffMatrix = np.concatenate([ B bridge.transpose() @ diag( B bridge @ x ) for
     \rightarrow x in [x1,x2,x3] ])
     kvalues,_,_, = la.lstsq(coeffMatrix , np.concatenate([f1,f2,f3]),rcond=None)
     [ f"k{i+1} = {kvalues[i]}" for i in range(len(kvalues))]
[6]: ['k1 = 9699998.607722549',
      'k2 = 2000000.4090927793',
      'k3 = 9700000.122052612',
      'k4 = 9699998.86756195',
```

```
'k5 = 6894300.281687661',
'k6 = 9700000.126240244',
'k7 = 6894300.249842933',
'k8 = 6894299.831309714',
'k9 = 9699998.96686751',
'k10 = 6894300.258596171',
'k11 = 6894299.903274672',
'k12 = 9700000.298712648',
'k13 = 6894300.008658496',
'k14 = 9700000.174220743',
'k15 = 9700000.624519458']
```

We see that k2 is different than expected and needs to be replaced!