week03-02-00-network-flows

January 27, 2024

- 1 George McNinch Math 87 Spring 2024
- 2 Week 3
- 3 § Network flows and linear programming
- 4 Overview

So far we have looked at a few examples of linear programs. The key step in modeling these problems is to write down the linear program itself.

As we saw, for simple linear programs – such as the carpenter example – we can figure it out geometrically. In that case, there were only a few variables and a few obvious constraints, and it was easy to find and check all the "vertices".

5 Network flows

We are going to consider some more complex situations for which we will use a *network flow* to help produce the corresponding *linear program.

Let's recall that a directed graph is a pair G = (V, E) where the elements of the set V are the vertices of the graph, and where $E \subset V \times V$ are the edges of G. Thus, an element $e = (a, b) \in E$ represents a directed edge from vertex a to vertex b.

We can produce diagrams for directed graphs using the program graphviz (and a corresponding python library python-graphviz).

Let's look at a simple graph:

```
[1]: from graphviz import Digraph as GVDigraph

dot = GVDigraph("example")
    dot.attr(rankdir='LR')

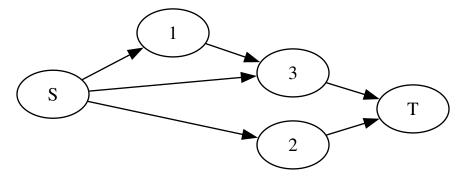
vertices = ['S', '1', '2', '3', 'T']
    edges = [('S','1'),('S','2'),('1','3'),('S','3'),('2','T'),('3','T')]

for v in vertices:
    dot.node(v)
```

```
for (a,b) in edges:
  dot.edge(a,b)

dot
```

[1]:



A vertex is a source if it only appears in outgoing edges, and a vertex is a sink if it only appears in incoming edges.

In the preceding example, S is a source and T is a sink.

```
[2]: from graphviz import Digraph as GVDigraph
     import numpy as np
     from scipy.optimize import linprog
     import math
     from dataclasses import dataclass, field
     ## "standard basis vector"
     ##
     def sbv(index,size):
        return np.array([1.0 if i == index else 0.0 for i in range(size)])
     def from_indices(dat,length):
        ## dat is a list [(c,i),,,] of pairs; the pair (c,i) determines
         ## the vector c*e_i where e_i is the ith standard basis vector
        ## from_indices(dat,length) function returns the sum of the vectors
         ## specified by the list dat
        return sum([c*sbv(i,length) for (c,i) in dat],np.zeros(length))
     ## >>> from_indices([(2,3),(3.5,6)],7)
     ## array([ 0., 0., 2., 0., 0., 3.5, 0.])
```

```
def flatten(ll : list[list[any]]) -> list[any]:
    return [ i for 1 in 11 for i in 1 ]
@dataclass
class UpperBound:
    bound: int = math.inf
@dataclass
class LowerBound:
    bound: int = -math.inf
@dataclass
class Edge:
    vp: (str,str)
    label: str
    val: float = 0.0
    bd: UpperBound | LowerBound = field(default=UpperBound)
@dataclass
class Digraph:
    vertices: list[list[str]]
    edges: list[Edge]
    title: str
    def drawGraph(self):
        dot = GVDigraph(self.title)
        dot.attr(rankdir='LR')
        for vg in self.vertices:
            with dot.subgraph() as c:
                c.attr(rank='same')
                for x in vg:
                    c.node(x)
        vv = flatten(self.vertices)
        for e in self.edges:
            a,b = e.vp
            if (a in vv) and (b in vv):
                dot.edge(a,b,label=format(e.label))
        return dot
```

```
def drawSubgraph(self,vertices:list[str] = None):
      dot = GVDigraph(self.title)
      dot.attr(rankdir='LR')
      vs = vertices if vertices else flatten(self.vertices)
      for x in vs:
          dot.node(x)
      for e in self.edges:
          a,b = e.vp
          if (a in vs) and (b in vs):
              dot.edge(a,b,label=format(e.label))
      return dot
  def getIncoming(self,vertex: str):
      return filter(lambda e: e.vp[1] == vertex, self.edges)
  def getOutgoing(self,vertex: str):
      return filter(lambda e: e.vp[0] == vertex, self.edges)
  def edgeVector(self,edge: Edge):
      i = self.edges.index(edge)
      N = len(self.edges)
      return sbv(i,N)
  def conservationVector(self, vertex: str):
      ivect = np.sum([self.edgeVector(e) for e in self.

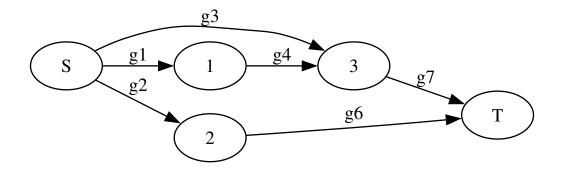
¬getIncoming(vertex)],axis=0)
      ovect = np.sum([self.edgeVector(e) for e in self.

¬getOutgoing(vertex)],axis=0)
      return ivect - ovect
  def conservationLaw(self, vertex: str):
      ii = list(map(lambda x: x.label,self.getIncoming(vertex)))
      oo = list(map(lambda x: x.label,self.getOutgoing(vertex)))
      return "".join([ii.__repr__(),
                       0 = 0.
                       oo.__repr__(),
                       " = 0"
  def edgeBounds(self,edge: Edge):
      match edge.bd:
          case LowerBound(bound):
```

```
if bound > -math.inf:
                    return ((-1)*self.edgeVector(edge),(-1)*bound)
            case UpperBound(bound):
                if bound < math.inf:</pre>
                    return (self.edgeVector(edge),bound)
    def describeEdgeBound(self,edge):
        match edge.bd:
            case LowerBound(bound):
                if bound > -math.inf:
                    return edge.label + ">=" + f"{bound}"
            case UpperBound(bound):
                if bound < math.inf:</pre>
                    return edge.label + "<=" + f"{bound}"
    def allbounds(self):
        info = [self.edgeBounds(e) for e in self.edges ]
        A_ub = np.array([c[0] for c in info if c is not None])
        b_ub = np.array([c[1] for c in info if c is not None])
        return (A_ub,b_ub)
    def describeBounds(self):
        dd = map(lambda e: self.describeEdgeBound(e),self.edges)
        return [d for d in dd if not d is None]
    def objectiveVector(self):
        return np.sum([ e.val * self.edgeVector(e)
                        for e in self.edges if e.val is not None],
                      axis=0)
@dataclass(kw_only=True)
class networkFlow(Digraph):
    source: str
    sink: str
    def __post_init__(self):
        Digraph.__init__(self,vertices=self.vertices,edges=self.
 ⇔edges,title=self.title)
    def internalVertices(self):
        return [ v for v in flatten(self.vertices) if not v in [ self.source, u
 ⇔self.sink]]
    def conservationMatrix(self):
```

We can describe our previous example using this code:

[3]:



[4]: nf.runLinProgr()

```
ValueError
                                          Traceback (most recent call last)
Cell In[4], line 1
----> 1 nf.runLinProgr()
Cell In[2], line 175, in networkFlow.runLinProgr(self, maximize)
    173 else:
    174
            c = self.objectiveVector()
--> 175 return linprog(c,
    176
                       A_eq=A_eq,
                       b_eq=np.zeros(len(self.internalVertices())),
    177
    178
                       A_ub=A_ub,
    179
                       b ub = b ub
File ~/miniforge3/lib/python3.11/site-packages/scipy/optimize/_linprog.py:628,__
 oin linprog(c, A ub, b ub, A eq, b eq, bounds, method, callback, options, x0,
 ⇔integrality)
            integrality = np.broadcast_to(integrality, np.shape(c))
    625
    627 lp = LPProblem(c, A ub, b_ub, A_eq, b_eq, bounds, x0, integrality)
--> 628 lp, solver_options = _parse_linprog(lp, options, meth)
    629 tol = solver_options.get('tol', 1e-9)
    631 # Give unmodified problem to HiGHS
File ~/miniforge3/lib/python3.11/site-packages/scipy/optimize/_linprog_util.py:
 →1026, in _parse_linprog(lp, options, meth)
   1023 solver_options, A_ub, A_eq = _check_sparse_inputs(solver_options, meth,
   1024
                                                           lp.A_ub, lp.A_eq)
   1025 # Convert lists to numpy arrays, etc...
-> 1026 lp = _clean_inputs(lp._replace(A_ub=A_ub, A_eq=A_eq))
   1027 return lp, solver_options
File ~/miniforge3/lib/python3.11/site-packages/scipy/optimize/_linprog_util.py:
 →320, in _clean_inputs(lp)
```

```
318 n_ub = A_ub.shape[0]
    319 if len(A_ub.shape) != 2 or A_ub.shape[1] != n_x:
--> 320
            raise ValueError(
                "Invalid input for linprog: A_ub must have exactly two "
    321
                "dimensions, and the number of columns in A ub must be "
    322
                "equal to the size of c")
    323
    324 if (sps.issparse(A_ub) and not np.isfinite(A_ub.data).all()
    325
                or not sps.issparse(A_ub) and not np.isfinite(A_ub).all()):
    326
            raise ValueError(
                "Invalid input for linprog: A_ub must not contain values "
    327
                "inf, nan, or None")
    328
ValueError: Invalid input for linprog: A_ub must have exactly two dimensions, __
 wand the number of columns in A ub must be equal to the size of c
```

6 Restaurant Example

Suppose that you are opening a new restaurant and need to make sure you have enough clean tablecloths to meet expected demand in the first week. On each day, you can buy new tablecloths for \\$ 5. Used tablecloths can be laundered and returned the next day for \\$2 or the following day for \\$1.

Your expected tablecloth demands are:

Day	1	2	3	4	5	6	7
tablecloths needed	10	10	15	20	40	40	30

Let's try to formulate a linear program to minimize the costs.

Let's name the quantities from the table.

• $t_i = \text{expected } \# \text{ of table cloths required on day } i$.

Now introduce variables:

- $b_i = \#$ tablecloths bought on day $i, 1 \le i \le 7$.
- $f_i = \#$ dirty tablecloths sent to fast laundry on day i

First, let's write down the objective (assuming we only care about week 1):

The goal is to minimize the quantity

$$5\sum_{i=1}^{7} b_i + 2\sum_{i=1}^{6} f_i + \sum_{i=1}^{5} s_i.$$

What are the constraints? On day i, we must have at least t_i tablecloths available.

• day 1

we need enough tablecloths for day 1, so

$$t_1 \leq b_1$$

• day 2

demand must be met from purchases on day 2, plus surplus from day 1, plus fast laundry from day 1. note that the use on day 1 is equal to $f_1 + s_1$ and thus $b_1 - f_1 - s_1$ counts the surplus from day 1. So we need

$$t_2 \leq b_2 + (b_1 - f_1 - s_1) + f_1$$

• day 3

demand must again be met from purchases on day 3, plus leftover from the previous days, plus those laundered from the fast service on day 2, and those laundered via the slow service on day 1. The total used in the first two days is equal to $f_1 + s_1 + f_2 + s_2$, so the surplus from the first two days is $b_1 + b_2 - f_1 - s_1 - f_2 - s_2$. So we need

$$t_3 \leq b_3 + (b_1 + b_2 - f_1 - s_1 - f_2 - s_2) + f_2 + s_1$$

etc.

This becomes increasingly hard to keep track of and formulate.

So, instead, we build what's called a network model and we track the flow of tablecloths!

Let's use a tool called graphviz to draw part of a diagram:

```
for d in range(6)
       ],
      *[ Edge((used[d],clean[d+2]), label=f"s{d}", val=1) # slow laundry
        for d in range(5)
       ]
      ]
def report(nf: networkFlow) -> str:
    lp=nf.runLinProgr()
    x = lp.x
    costs = lp.fun
    return "\n".join(
        [f"linprog succeeded? {lp.success}",
         f"Optimal tablecloth expenses for the week are ${costs:.2f}",
         "This is achieved by the following strategy:",
         *[f"purchase on day {i}: {x[i]:.2f}" for i in range(7)],
         *[f"use on day {i+1}: {x[6+i]:.2f}" for i in range(7)],
         *[f"carry-over from day {i} to day {i+1}: \{x[13+i]: .2f\}" for i in_\(\)
 \hookrightarrowrange(6)],
         шп.
         *[f"fast laundry on day {i}: \{x[19+i]:.2f\}" for i in range(6)],
         *[f"slow laundry on day {i}: \{x[25+i]:.2f\}" for i in range(5)],
         ])
nf = networkFlow(vv,ee,title="Restaurant",source='source',sink='d6 used')
nf.makeGraph().render()
print(report(nf))
```

```
[]: from graphviz import Digraph

## https://www.graphviz.org/
## https://graphviz.readthedocs.io/en/stable/index.html

def clean_node(day):
    return f"d{day}c"

def used_node(day):
    return f"d{day}u"

def make_network_model(last):
```

```
dot = Digraph('tablecloth network model')
   dot.attr(rankdir='LR')
   dot.node('s','source of new tablecloths')
   days = range(1, last + 1)
   with dot.subgraph(name='clean') as c:
     c.attr(rank='same')
     for day in days:
        if day == last:
            c.node(clean_node(day), "etc...")
        else:
            c.node(clean_node(day), f"day {day} clean")
   with dot.subgraph(name='used') as u:
     u.attr(rank='same')
     for day in days:
        if day == last:
            u.node(used_node(day), 'etc...')
        else:
            u.node(used_node(day), f"day {day} used")
   for day in days:
     dot.edge('s',clean_node(day),label='cost=5')
     if day < last:</pre>
        dot.edge(clean_node(day),clean_node(day+1), label = "cost=0")
     dot.edge(clean_node(day),used_node(day),label=f"cost=0, =t_{day}")
     if day < last:</pre>
        dot.edge(used_node(day),clean_node(day+1),label="cost=2") ## fast_
 \hookrightarrow laundry
     if day < last -1:
        dot.edge(used_node(day),clean_node(day+2),label="cost=1") ## slow_
 \hookrightarrow laundry
   return dot
make_network_model(last=5)
```

(extrapolate the diagram for the remaining days...)

How do we make a linear program of this??

The above diagram represents a directed graph. The edges in this graph – i.e. the arrows between

nodes – track the "flow" of tablecloths.

- We introduce a variable for each arrow. The value of the variable represents the number of tablecloths that move from the start to finish of the arrow.
- Some arcs have lower bounds (e.g. ℓ = t_1). If no lower bound is mentioned, there is an implied lower bound of 0.
- Some arcs have upper bounds. These model maximum supply or throughput. Nothing implies a bound of ∞ .
- Each "internal" node has conservation i.e. outputs inputs = 0.
- Each arc has a cost. The Objective function is the sum of the quantities (arc costs × flow variable).

Remember that we write

• $t_i = \#$ tablecloths needed on day i.

(these aren't variables for our linear program – they are values given to us by the problem).

Since we are to have one variable for each arrow in the above diagram, we write:

- $b_i = \#$ tablecloths bought on day $i, 1 \le i \le 7$.
- $u_i = \#$ table cloths used on day $i, 1 \le i \le 7$.
- $c_i = \#$ tablecloths carried over from day i to i+1 for $0 \le i \le 6$
- $f_i = \#$ dirty tablecloths sent to fast laundry on day i for $0 \le i \le 6$
- $s_i = \#$ dirty tablecloths sent to slow laundry on day i for $0 \le i \le 5$

Now the objective equation has the form:

$$5\sum_{i=1}^{7}b_{i}+0\sum_{i=1}^{7}u_{i}+0\sum_{i=1}^{6}c_{i}+2\sum_{i=1}^{6}f_{i}+\sum_{i=1}^{5}s_{i}$$

We require $t_i \leq u_i$ for $1 \leq i \leq 7$ (lower bounds). These lower bounds arise from the arrows from "Day i clean" to "Day i used" with the label $\ell = t_i$.

We impose no upper bounds on the variables.

For each node, we get a conservation equation:

- node "day 1 clean": $u_1 + c_1 b_1 = 0$
- node "day 1 used": $s_1 + f_1 u_1 = 0$
- node "day 2 clean": $u_2 + c_2 b_2 c_1 f_1 = 0$
- node "day 2 used": $s_2 + f_2 u_2 = 0$
- node "day 3 clean": $u_3 + c_3 b_3 c_2 f_2 s_1 = 0$
- node "day 3 used": $s_3 + f_3 u_3 = 0$
- and so on...

Note for example that 2 arrows leave and 3 arrows arrive at the node "Day 2 clean", while 2 arrows leave and 4 arrows arrive at the node "Day 3 clean". The above equations reflect these counts.

6.1 Remarks:

- There are $2 \times 7 + 2 \times 6 + 5 = 31$ variables. So the objective function is given by a vector $\mathbf{c} \in \mathbb{R}^{1 \times 31}$.
- there are 13 "equality constraints" arising from the conservation equation at each node (note that there is no conservation at the node "day 7 used", since it is a terminal node). Thus the equality constraints are given by a 13×31 matrix A (they amount to the condition $A\mathbf{x} = \mathbf{0}$ for $\mathbf{x} \in \mathbb{R}^{31} = \mathbb{R}^{31 \times 1}$).
- there are 7 inequality constraints, given by the condition $B\mathbf{x} \leq \mathbf{b}$ for a 7×31 matrix B and a vector $\mathbf{b} \in \mathbb{R}^7 = \mathbb{R}^{7 \times 1}$.

6.2 Implementation (sketch)

The main task in solving this model via python is producing the matrices A and B.

For example, the conservation at the node

• node "day 3 clean": $u_3 + c_3 - b_3 - c_2 - f_2 - s_1 = 0$

results in a row of the matrix A.

Let's order the variables as follows:

$$b_1, b_2, \dots, b_7, u_1, \dots, u_7, c_1, \dots, c_6, f_1, \dots, f_6, s_1, \dots, s_5$$

We want to write rows of A in the form

$$(\heartsuit) \quad \begin{bmatrix} \mathbf{\tilde{b}} & \mathbf{\tilde{u}} & \mathbf{\tilde{c}} & \mathbf{\tilde{f}} & \mathbf{\tilde{s}} \end{bmatrix} \in \mathbb{R}^{1 \times 31}$$

where

$$\tilde{\mathbf{b}}, \tilde{\mathbf{u}} \in \mathbb{R}^{1 \times 7}, \quad \tilde{\mathbf{c}}, \tilde{\mathbf{f}} \in \mathbb{R}^{1 \times 6}, \quad \tilde{\mathbf{s}} \in \mathbb{R}^{1 \times 5},$$

the row vector (\heartsuit) is to be understood as obtained by "concatenation" of these vectors, and we have:

$$\mathbf{\tilde{b}} = \begin{bmatrix} 0 & 0 & -1 & 0 & 0 & 0 & 0 \end{bmatrix} = -\mathbf{e}_3, \quad \mathbf{\tilde{u}} = \mathbf{e}_3,$$

$$\mathbf{\tilde{c}} = \begin{bmatrix} 0 & -1 & 1 & 0 & 0 & 0 \end{bmatrix} = \mathbf{e}_3 - \mathbf{e}_2, \quad \mathbf{\tilde{f}} = \begin{bmatrix} 0 & -1 & 0 & 0 & 0 \end{bmatrix} = -\mathbf{e}_2, \quad \mathbf{\tilde{s}} = -\mathbf{e}_1$$

(here \mathbf{e}_i represents the appropriate standard basis vector in \mathbb{R}^7 , \mathbb{R}^6 or \mathbb{R}^5).

```
[]: ## This code represents a preliminary implementation
## it just gives the row in the equality constraint corresponding
## to a single row. See the next cell for a "full implementation"

import numpy as np
```

```
def sbv(index,length):
         return np.array([1.0 if i == index-1 else 0.0 for i in range(length)])
     ## produce the row corresponding to the "day 3 clean" node.
     row = np.block([(-1)*sbv(3,7), ## bb]
                      sbv(3,7),
                      (-1)*sbv(2,6) + sbv(3,6), ## cc
                      (-1)*sbv(2,6),
                                          ## ff
                      (-1)*sbv(1,5)
                                          ## ss
                    1)
     ## Note that if you had constructed the following rows -- row1, row2, row3, ...
     →, row7 -- you'd produce the matrix A via
     ## A = np.array([row1, row2, row3, ..., row7])
     print(row.shape)
     print(row)
[]: ## This cell represents one possible way of creating the equality and inquality u
     \hookrightarrow constraints
     ## for the "tablecloth" problem
     import numpy as np
     from scipy.optimize import linprog
     float_formatter = "{:.2f}".format
     np.set_printoptions(formatter={'float_kind':float_formatter})
     ## "standard basis vector"
     ##
     def sbv(index,size):
         return np.array([1.0 if i == index-1 else 0.0 for i in range(size)])
     def from_indices(dat,length):
         ## dat is a list [(c,i),,,] of pairs; the pair (c,i) determines
         ## the vector c*e_i where e_i is the ith standard basis vector
         ## from indices(dat,length) function returns the sum of the vectors
         ## specified by the list dat
         return sum([c*sbv(i,length) for (c,i) in dat],np.zeros(length))
     ## >>> from_indices([(2,3),(3.5,6)],7)
     ## array([ 0., 0., 2., 0., 0., 3.5, 0.])
     def row(b=□.
             u=[],
             c=[],
```

```
f=[],
       s=[]):
   bb = from_indices(b,7)
   uu = from_indices(u,7)
   cc = from_indices(c,6)
   ff = from_indices(f,6)
   ss = from_indices(s,5)
   return np.block([bb,uu,cc,ff,ss])
## >>> row(bp=[1],un=[2])
## array([ 1., 0., 0., 0., 0., 0., 0., -1., 0., 0., 0.,
         ##
         0., 0., 0., 0., 0.])
##
## this result has a 1 in the "1st entry of the b-group" and a -1 in
## the "2nd entry of the u-group"
## here is a textual description of the "equality constraint" matrix.
## We then proceed to implement this description using the function `row`
## defined above.
##
## day1 clean: b1 - u1 - c1 = 0
## day2 clean: b2 + c1 + f1 - u2 - c2 = 0
## day3 clean: b3 + c2 + s1 + f2 - u3 - c3 = 0
## day4 clean: b4 + c3 + s2 + f3 - u4 - c4 = 0
## day5 clean: b5 + c4 + s3 + f4 - u5 - c5 = 0
## day6 clean: b6 + c5 + s4 + f5 - u6 - c6 = 0
## day7 clean: b7 + c6 + s5 + f6 - u7 = 0
## day1 used: u1 - s1 - f1 = 0
## day2 used: u2 - s2 - f2 = 0
## day3 used: u3 - s3 - f3 = 0
## day4 used: u4 - s4 - f4 = 0
## day5 used: u5 - s5 - f5 = 0
## day6 used: u6 - f6 = 0
## Note that day7 used is a "terminal node" so doesn't have a conservation_
⇔equation.
## the rc are rows corresponding to conservation laws for "clean" nodes
rc1 = row(b=[(1,1)], c=[(-1,1)],
                                               u = [(-1,1)]
rc2 = row(b=[(1,2)], c=[(1,1), (-1,2)], f=[(1,1)], u=[(-1,2)])
rc3 = row(b=[(1,3)],c=[(1,2),(-1,3)],s=[(1,1)],f=[(1,2)],u=[(-1,3)])
rc4 = row(b=[(1,4)],c=[(1,3),(-1,4)],s=[(1,2)],f=[(1,3)],u=[(-1,4)])
rc5 = row(b=[(1,5)], c=[(1,4), (-1,5)], s=[(1,3)], f=[(1,4)], u=[(-1,5)])
```

```
rc6 = row(b=[(1,6)], c=[(1,5), (-1,6)], s=[(1,4)], f=[(1,5)], u=[(-1,6)])
rc7 = row(b=[(1,7)], c=[(1,6), (-1,7)], s=[(1,5)], f=[(1,6)], u=[(-1,7)])
## the ru are rows corresponding to conservation laws for "used" nodes
ru1 = row(u=[(1,1)], s=[(-1,1)], f=[(-1,1)])
ru2 = row(u=[(1,2)],s=[(-1,2)],f=[(-1,2)])
ru3 = row(u=[(1,3)],s=[(-1,3)],f=[(-1,3)])
ru4 = row(u=[(1,4)],s=[(-1,4)],f=[(-1,4)])
ru5 = row(u=[(1,5)],s=[(-1,5)],f=[(-1,5)])
ru6 = row(u=[(1,6)],
                              f = [(-1, 6)]
## the rc and ru determined the rows of the matrix defining
Aeq = np.array([rc1,rc2,rc3,rc4,rc5,rc6,rc7,
                ru1,ru2,ru3,ru4,ru5,ru6])
Alb = np.array([row(u=[(1,i)]) for i in range(1,8)])
## objective function
c = row(b=[(5,1),(5,2),(5,3),(5,4),(5,5),(5,6),(5,7)],
        f=[(2,1),(2,2),(2,3),(2,4),(2,5),(2,6)],
        s=[(1,1),(1,2),(1,3),(1,4),(1,5)])
tt = np.array([10,10,15,20,40,40,30]) ## these are the ti entries taken from
→the "tablecloths needed" table
## use linprog to find the point which minimizes the objective function
## we impose equality constraints Aeg*x=0.
## we also want the inequality constraint Ax \ge tt, so we use -Ax < -tt.
result = linprog(c,A_eq=Aeq,b_eq=np.zeros(13),A_ub=(-1)*Alb,b_ub=(-1)*tt)
def report(result):
    ## the argument ``result`` should be an instance of the class ``scipy.
 ⇔optimize.OptimizeResult`` --
    ## i.e. a value of the form returned by ``linprog``
    ##
    x = result.x
    costs = result.fun
    return "\n".join(
        [f"linprog succeeded? {result.success}"]
        [f"Optimal costs on tablecloths for the week are ${costs:.2f}"]
```

The idea is that "network flow" graphs are a tool to help formulate the linear program. Here is another example.

7 Grocery example

A fruit wholesaler buys and sells apples according to the following prices and demand:

Month	Aug	Sep	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul
price/kg from	0.80	0.55	0.55	0.65	0.75	0.85	0.95	-	-	-	-	
grower sale price/kg	0.90	0.65	0.65	0.85	1.00	1.00	1.20	1.20	1.20	1.00	0.80	0.80
demand in 1000kg	10	15	15	15	13	10	10	10	9	7	5	5

The wholesaler can store 50,000kg at a cost of \$0.025 per kg per month. Unlimited supplies are available from September to January but only 15,000kg are available in August and February and none during the rest of the year.

We consider the profit for a year (12 months), from August to the next July. We suppose that there are no apples to carry over from the previous month – we begin with no apples.

Our goal: Maximize the profit!

We'll begin by formulating the flow model.

Remember that each edge in the graph corresponds to a variable in our linear program. We are going to label each edge with a symbol $[c, u, \ell]$ representing the "cost" (i.e. the contribution of that variable to the objective function), an upper bound u for that variable, and a lower bound ℓ for that variable.

We are going to construct the diagram using graphviz, though the main point here is the diagram itself rather than the code used to produce it. (I'm including the code so you can copy it if you wish).

```
[]: from graphviz import Digraph
     ## https://www.graphviz.org/
     ## https://graphviz.readthedocs.io/en/stable/index.html
     dot = Digraph('fruit wholesaler model')
     dot.attr(rankdir='LR')
     dot.node('g','grower')
     with dot.subgraph(name='months') as c:
         c.attr(rank='same')
         c.node('aug')
         c.node('sep')
         c.node('oct')
         c.node('nov')
         c.node('feb')
         c.node('mar')
     dot.node('d','demand')
     dot.edge('g','aug',label='[-.8,15000,0]')
     dot.edge('g', 'sep', label='[-.55, \omega, 0]')
     dot.edge('g','oct',label='[-.55,\omega,0]')
     dot.edge('g','nov',label='[-.65,\omega,0]')
     dot.edge('g','feb',label='[-.95,15000,0]')
     dot.edge('aug','sep',label='[-0.025,50K,0]')
     dot.edge('sep','oct',label='[-0.025,50K,0]')
     dot.edge('oct','nov',label='[-0.025,50K,0]')
     dot.edge('feb','mar',label='[-0.025,50K,0]')
     dot.edge('aug','d',label='[0.9,10000,0]')
     dot.edge('sep','d',label='[0.65,15000,0]')
```

```
dot.edge('oct','d',label='[0.65,15000,0]')
dot.edge('nov','d',label='[0.85,15000,0]')
dot.edge('feb','d',label='[1.20,10000,0]')
dot.edge('mar','d',label='[1.20,10000,0]')

dot
#dot.format='png'
#dot.render()
```

Now let's formulate the linear program.

Let's number our months in a slightly odd way. Our year starts in august, so we number as follows:

aug	sep	oct	nov	dec	jan	feb	mar	apr	may	jun	jul
1	2	3	4	5	6	7	8	9	10	11	12

We need to name our variables; we'll use the above numbering:

- $g_i = \#$ kg bought in month i, for $1 \le i \le 12$.
- $d_i = \# \text{ kg sold in month } i$

All of our variables are assumed to be non-negative: $g_i \geq 0, s_i \geq 0, d_i \geq 0$ for all i.

We've been told the following:

Unlimited supplies are available (from the grower) from September to January but only 15,000kg are available in August and February and none during the rest of the year.

This gives us some "upper bound" inequalities:

$$\begin{bmatrix} g_1 \\ g_2 \\ g_3 \\ g_4 \\ g_5 \\ g_6 \end{bmatrix} \le \begin{bmatrix} 1500 \\ \infty \\ \infty \\ \infty \\ \infty \\ \infty \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} g_7 \\ g_8 \\ g_9 \\ g_{10} \\ g_{11} \\ g_{12} \end{bmatrix} \le \begin{bmatrix} 15000 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

(since $g_i \ge 0$ is non-negative, the above conditions for $8 \le i \le 12$ amount to an equality condition of $g_i = 0$ for these i, but we'll enter it as an inequality condition for uniformity).

We've also been told:

The wholesaler can store 50,000kg at a cost of \$0.025 per kg per month.

This yields the upper bound - $s_i \leq 50000$ for $1 \leq i \leq 12$

Now, we know from table the demand for each month. Remember what we are doing: with the linear program, we are trying to decide the optimal values of our decision variables – i.e. how many

apples do we buy each month? and how many apples do we store each month? According to the model, the number of apples we expect to sell depends on these choices (via the conservation laws). So to be sensible, our model must view the anticipated demand (listed in the table) as an upper bound for the amount we can sell. More precisely, we should impose the constraint that the number d_i of kg of apples delivered to customers is \leq the anticipated demand for each month. (Of course, this is what the label on the diagram indicates! Here I'm trying to explain why we have chosen that labeling).

This amount to the condition:

$$\begin{bmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ d_5 \\ d_6 \end{bmatrix} \leq \begin{bmatrix} 10 \\ 15 \\ 15 \\ 15 \\ 13 \\ 10 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} d_7 \\ d_8 \\ d_9 \\ d_{10} \\ d_{11} \\ d_{12} \end{bmatrix} \leq \begin{bmatrix} 10 \\ 10 \\ 9 \\ 7 \\ 5 \\ 5 \end{bmatrix}$$

Conservation:

The internal nodes of our network flow diagram correspond to months. The arrow "going in" to the node amount to available apples, and they correspond to purchases (g_i) and storage (s_{i-1}) unless i=1). The arrows going out correspond to storage (s_i) and to apples delivered to customers (d_i) . Thus, we must have

- $s_1 + d_1 g_1 = 0$
- $s_2 + d_2 g_2 s_1 = 0$. $s_3 + d_3 g_3 s_2 = 0$.

Objective:

The objective function represents profit, and each variable has some contribution to objective/profit function (we call this contribution "cost"). We spend money through apple purchases and through storage costs, and these costs have negative values. We get money through apple sales, and these costs have positive value.

• August contribution to the objective function:

$$-0.80g_1 - 0.025s_1 + 0.9d_1$$

• September contribution to the objective function:

$$-0.55g_1 - 0.025s_1 + 0.65d_1$$

Of course, the objective function is the sum of all 12 of these monthly contributions.

Implementation follows:

```
[]: from scipy.optimize import linprog
     import numpy as np
     float_formatter = "{:.2f}".format
     np.set_printoptions(formatter={'float_kind':float_formatter})
     ## "standard basis vector"
     ##
     def sbv(index,size):
        return np.array([1.0 if i == index-1 else 0.0 for i in range(size)])
     def from_indices(dat,length):
         ## dat is a list [(c,i),,,] of pairs; the pair (c,i) determines
        ## the vector c*e_i where e_i is the ith standard basis vector
        return sum([c*sbv(i,length) for (c,i) in dat],np.zeros(length))
     def row(g=[],
             s=[]
             d=[]):
        gg = from_indices(g,12)
        ss = from indices(s, 12)
        dd = from_indices(d,12)
        return np.block([gg,ss,dd])
     ## for uniformity, we actually consider 12 storage variables event though
     ## we shouldn't really put anything in storage in july (month 12)
     ## let's form the equality constraint matrix from the conservation laws.
     A=np.array([row(s=[(1,1)],d=[(1,1)],g=[(-1,1)])] # first\ row
                [row(s=[(1,i),(-1,i-1)],
                     d=[(1,i)],
                     g=[(-1,i)]) for i in range(2,13)]) # remaining rows
     ## now let's make the inequality constraint matrix
     ## our inequality constraint will have the form Ax <= b,
     ## so any "lower bound" constraints would need to be reversed using a sign_
     ⇔change.
     ## But anyhow we haven't specified any lower bounds...
     Bs = [row(s=[(1,i)]) for i in range(1,13)]
     bs = np.array([50000 for i in range(1,13)])
```

```
## qi bounds
Bg_start = [row(g=[(1,1)]), row(g=[(1,7)])]
Bg_{end} = [row(g=[(1,i)]) \text{ for } i \text{ in } range(8,13)]
Bg = Bg_start + Bg_end
bg = np.array([15000,15000] + 5*[0]) # note that n*[0] is the list [0,0,\ldots,0]_{\sqcup}
 ⇒with n zeros
## di bounds
Bd = [row(d=[(1,i)]) \text{ for } i \text{ in } range(1,13)]
bd = (1000)*np.array([10,15,15,15,13,10,10,10,9,7,5,5])
B = np.array(Bg + Bs + Bd) ## concat the lists of rows; create a matrix from
⇔the resulting list
b = np.block([bg,bs,bd]) ## concat the constraints
## objective function
grower_costs = (-1)*np.array([0.8,0.55,0.55,0.65,0.75,0.85,0.95,0,0,0,0])
storage\_costs = (-1)*np.array(12*[.025])
sale_price = np.array([0.9,0.65,0.65,0.85,1,1,1.2,1.2,1.2,1.2,1,.8,.8])
c = np.block([grower_costs,storage_costs,sale_price])
result = linprog((-1)*c,A_eq=A,b_eq=np.zeros(12),A_ub=B,b_ub=b)
def month(i):
    dict={1:"aug",
          2: "sep",
          3:"oct",
          4: "nov",
          5: "dec",
          6:"jan",
          7:"feb",
          8:"mar".
          9: "apr",
          10: "may",
          11:"jun",
          12:"jul"}
    return dict[i]
def report(res):
    ## the argument ``res`` should be an instance of the class ``scipy.optimize.
 ⇔OptimizeResult`` --
```

```
## i.e. a value of the form returned by ``linprog``
    ##
    x=res.x
    profit = (-1)*result.fun
   return "\n".join([f"linprog succeeded? {result.success}"]
                     [f"Optimal profit ${profit:,.2f}"]
                     ["This is achieved by the following strategy:\n"]
                     [f"purchase in kg for \{month(i+1)\}: \{x[i]:.2f\}" for i in_{\sqcup}
 →range(12)]
                     [""]
                     [f"storage in kg for {month(i+1)}: {x[i+12]:.2f}" for i in__
 →range(12)]
                     [""]
                     [f"sales in kg for {month(i+1)}: {x[i+24]:.2f}" for i in__
 →range(12)])
print(report(result))
```