

Quaternion algebras

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1 Some references

- Some notes of Keith Conrad (UConn)
- first chapter of Gille-Szamuely - “Central Simple Algebras and Galois Cohomology”

2 Quaternion algebras, defined

If k is a field, an *algebra* A over k is a k -vector space A together with operations $+: A \times A \rightarrow A$ and $\cdot: A \times A \rightarrow A$ which satisfy the axioms of a *ring*.

Here, we are going to insist that the algebra A be finite dimensional as a k -vector space, and that there is a multiplicative identity element $1 \in A$.

Given a field ℓ containing k (a “field extension of k ”) we can form an ℓ -algebra A_ℓ by *extension of scalars*. (Really, this is the tensor product: $A_\ell = A \otimes_k \ell$).

The algebra A is said to be *central simple* over k if for some field extension ℓ of k and for some $n \in \mathbb{N}$, the ℓ -algebra A_ℓ is isomorphic as ℓ -algebras to $\text{Mat}_n(\ell)$, the algebra of $n \times n$ matrices over ℓ .

Now, a *quaternion algebra* is a central simple algebra Q over k with $\dim Q = 4$. Thus for some field extension ℓ of k , the ℓ -algebra Q_ℓ is isomorphic to $\text{Mat}_2(k)$

3 A description of quaternion algebras

A quaternion algebra Q over k can be described in an explicit manner. The case where k has characteristic 2 is slightly different and I’ll omit it here, so suppose that k has characteristic $\neq 2$.

Given $a, b \in k$ non-zero elements, we define the k -algebra $(a, b)_k$ to be the k -vector space with basis $1, i, j, ij$ where the multiplication satisfies

$$i^2 = a, j^2 = b, ij = -ji$$

Theorem 3.0.1. *Suppose that k does not have characteristic 2. If Q is a quaternion algebra over k , there are non-zero elements $a, b \in k$ for which $Q \simeq (a, b)_k$.*

If $\alpha = s + ti + uj + vij \in (a, b)_k$ for $s, t, u, v \in k$, the conjugate $\bar{\alpha}$ is defined to be

$$\bar{\alpha} = s - ti - uj - vij$$

Proposition 3.0.2. *The assignment $N : (a, b)_k \rightarrow k$ given by $N(\alpha) = \alpha \cdot \bar{\alpha} = s^2 - at^2 - bu^2 + abv$ defines a non-degenerate quadratic form on the vector space $(a, b)_k$.*

We call this quadratic form N the *norm* – or the *norm form* – of the quaternion algebra $(a, b)_k$.

Theorem 3.0.3. *The quaternion algebra $(a, b)_k$ is a division algebra if and only if the norm N does not vanish at any nonzero element of $(a, b)_k$; i.e. $N(\alpha) = 0 \implies \alpha = 0$.*

4 Associated conics

Associated with the quaternion algebra $(a, b)_k$ is the conic $C = C(a, b)$ which is the set of solutions to the equation $ax^2 + by^2 = z^2$ in the projective plane \mathbb{P}^2 . In turn, we can consider the field of rational functions $k(C)$ on this conic; it is the field of fractions of the algebra $k[x, y]/\langle ax^2 + by^2 - 1 \rangle$. One sometimes calls $k(C)$ the “function field of C ”.

We may now state an important theorem due to Witt:

Theorem 4.0.1. *Let $Q_1 = (a_1, b_1)_k$ and $Q_2 = (a_2, b_2)_k$ be quaternion algebras over k , and let C_1 and C_2 be the associated conics. The algebra Q_1 and Q_2 are isomorphic if and only if the function fields $k(C_1)$ and $k(C_2)$ are isomorphic.*

In particular, Witt’s theorem shows that two quaternion algebras are isomorphic if and only if the associated conics are isomorphic as algebraic curves.