## Problem Set 6 Non-homogeneous equations

## Math 51 Fall 2021

due Monday 2022-02-28 at 11:59 PM

1. Find the constant-coefficient linear operator A(D) of smallest order for which

$$A(D)[te^{-t}\cos(2t) + 2e^{3t}] = 0.$$

Solution:

The term  $te^{-t}\cos(2t)$  is made 0 by an operator whose characteristic polynomial has 1+i as a root with multiplicity two. That characteristic polynomial must be  $[(r-(1+2i))(r-(1-2i))]^2=(r^2-2r+5)^2$ ; thus the operator is  $(D^2-2D+5)^2$ .

The term  $2e^{3t}$  is made zero by the operator D-3

Thus 
$$A(D) = (D^2 - 2D + 5)^2 \cdot (D - 3)$$
.

2. Make a simplified guess for a particular solution to the ODE

$$(D-1)^2(D^2+1)x = te^{3t} + e^t - \sin(t).$$

Note: In this problem, you aren't asked to solve for the coefficients.

Solution:

Write 
$$P(D) = (D-1)^2(D^2+1)$$
.

The smallest order operator A(D) which annihilates the right-hand-side of the ODE is

$$A(D) = (D-3)^2(D-1)(D^2+1).$$

To find an the (unsimplified) guess, we must find solutions to the auxiliary equation

$$A(D)P(D)x = 0$$

i.e. to

$$(D-3)^2(D-1)^3(D^2+1)^2x = 0.$$

The solution to this auxiliary equation is generated by

$$e^{3t}$$
,  $te^{3t}$ ,  $e^{t}$ ,  $te^{t}$ ,  $t^{2}e^{t}$ ,  $\sin(t)$ ,  $\cos(t)$ ,  $t\sin(t)$ ,  $t\cos(t)$ 

To simplify this guess, we remove solutions to the homogeneous equation corresponding to the original equation

$$P(D)x = 0$$
 i.e.  $(D-1)^2(D^2+1)x = 0$ .

The solutions to this corresponding homogeneous equation are generated by

$$e^t$$
,  $te^t$ ,  $\sin(t)$ ,  $\cos(t)$ .

Thus a simplified guess for a solution to the give equation is given by

$$p(t) = k_1 e^{3t} + k_2 t e^{3t} + k_3 t^2 e^t + k_4 t \sin(t) + k_5 t \cos(t)$$

3. Find the general solution to the ODE

$$(D^3 - D^2 - 2D)x = 1 + e^{2t}$$
.

Solution:

Observe that

$$(D^3 - D^2 - 2D) = D(D^2 - D - 2) = D(D - 2)(D + 1).$$

Now, a polynomial differential operator A(D) for which  $A(D)[1+e^{2t}]$  is

$$A(D) = D(D-2).$$

Thus, we find a guess for a particular solution q(t) to  $(\clubsuit)$   $(D^3 - D^2 - 2D)x = 1 + e^{2t}$  from among the solutions to the auxiliary homogeneous equation

$$0 = A(D) \cdot (D^3 - D^2 - 2D)x = D(D-2)(D^3 - D^2 - 2D) = D^2(D-2)^2(D+1)$$

The solution to this auxiliary homog equation is generated by

1, 
$$t$$
,  $e^{2t}$ ,  $te^{2t}$ ,  $e^{-t}$ .

Of these functions, 1,  $e^{2t}$  and  $e^{-t}$  are already solutions to the homogeneous equation  $(D^3 - D^2 - 2D)x = 0$  and hence we may and will discard them.

Thus our simplified guess for the particular solution is

$$q(t) = k_1 t + k_2 t e^{2t}$$
.

We must now solve for  $k_1, k_2$ . For this, we must compute

$$(D^3 - D^2 - 2D)[k_1t + k_2te^{2t}].$$

We have  $(D^3 - D^2 - 2D)[t] = -2$  and using the exponential shift formula we find that

$$\begin{split} (D^3-D^2-2D)[te^{2t}] &= e^{2t}((D+2)^3-(D+2)^2-2(D+2))[t] \\ &= e^{2t}(D^3+6D^2+12D+8-D^2-4D-4-2D-4))[t] \\ &= e^{2t}(D^3+5D^2+6D))[t] \\ &= 6e^{2t}. \end{split}$$

This shows that

$$(D^3 - D^2 - 2D)[k_1t + k_2te^{2t}] = -2k_1 + 6k_2e^{2t}.$$

So in order to arrange that  $q(t) = k_1 t + k_2 t e^{2t}$  is a particular solution to  $(\clubsuit)$ , we need that

$$-2k_1 + +6k_2e^{2t} = 1 + e^{2t}.$$

Comparing coefficients, we find that

$$-2k_1 = 1$$
 and  $6k_2 = 1$ .

Thus  $k_1 = -1/2$  and  $k_2 = 1/6$  so the particular solution is

$$q(t) = \frac{te^{2t} - 3t}{6}.$$

Now, the general solution to  $(\clubsuit)$  has the form

$$x(t) = q(t) + H(t)$$

where H(t) is the general solution to the corresponding homogeneous equation. Thus

$$x(t) = \frac{te^{2t} - 3t}{6} + c_1 + c_2e^{2t} + c_3e^{-t}$$

is the general solution to  $(\clubsuit)$ .

## 4. Solve the initial value problem:

$$(D^2-9)x = 9 + 12e^{-3t}; \quad x(0) = x'(0) = 0.$$

Solution:

We first note that the operator

$$A(D) = D(D+3)$$

satisfies

$$A(D)[9 + 12e^{-3t}] = 0.$$

Thus we may look for a particular solution q(t) to

$$(\diamondsuit) \quad (D^2 - 9)x = 9 + 12e^{-3t}$$

among the general solutions to the auxiliary homogeneous equation

$$0 = A(D)(D^2 - 9)x = D \cdot (D+3)^2 \cdot (D-3)x.$$

The general solution to this auxiliary equation is generated by

1, 
$$e^{-3t}$$
,  $te^{-3t}$ ,  $e^{3t}$ .

Among these solutions,  $e^{3t}$  and  $e^{-3t}$  are already solutions to the homogeneous equation  $(D^2 + 9)x = 0$  corresponding to  $(\diamondsuit)$ . Thus we may and will omit them from our simplified guess.

Our guess for q(t) is now:

$$q(t) = k_1 + k_2 t e^{-3t}.$$

We must find  $k_1, k_2$  for which  $(D^2 - 9)[q(t)] = 9 + 12e^{-3t}$ .

We compute, using the exponential shift formula when needed:

$$(D^2 - 9)[1] = -9$$

$$\begin{split} (D^2-9)[te^{-3t}] &= e^{-3t}((D-3)^2-9)[t] \\ &= e^{-3t}(D^2-6D+9-9)[t] \\ &= e^{-3t}(D^2-6D)[t] \\ &= -6e^{-3t} \end{split}$$

We conclude that

$$(D^2-9)[k_1+k_2te^{-3t}]=-9k_1-6k_2e^{-3t}$$

Thus, in order to arrange that q(t) is a particular solution to  $(\diamondsuit)$ , we need

$$-9k_1 - 6k_2e^{-3t} = 9 + 12e^{-3t}$$

Comparing coefficients, we find that

$$k_1 = -1, \quad k_2 = -2.$$

Thus

$$q(t) = -1 - 2te^{-3t}.$$

And we conclude the general solution to  $(\diamondsuit)$  is given by

$$x(t) = q(t) + H(t) = -1 - 2te^{-3t} + c_1e^{3t} + c_2e^{-3t}.$$

Finally, we need

$$0 = x(0) = -1 + c_1 + c_2 = -3 + c_1 + c_2$$

and

$$0 = x'(0) = \left. (-2e^{-3t}(1-3t) + 3c_1e^{3t} - 3c_2e^{-3t}) \right|_{t=0} = -2 + 3c_1 - 3c_2$$

So we must solve the system of equations

$$\begin{cases} 1 &= c_1 + c_2 \\ 2 &= 3c_1 + -3c_2 \end{cases}$$

One finds that  $c_1 = \frac{5}{6}$  and  $c_2 = \frac{1}{6}$ , so the solution to the initial value problem is

$$x(t) = -1 - 2te^{-3t} + \frac{5e^{3t}}{6} + \frac{e^{-3t}}{6}$$
$$= -1 + \frac{5e^{3t}}{6} + \frac{(1 - 12t)e^{-3t}}{6}$$

## 5. Find the general solution to

$$x'' - 2x' + x = e^t \ln(t), \quad t > 0.$$

(You should use variation of parameters)

Solution:

Since the characteristic polyomial is  $r^2 - 2r + 1 = (r - 1)^2$ , the general solution to the corresponding homogeneous equation is generated by

$$h_1(t) = e^t, \quad h_2(t) = te^t.$$

To solve the inhomogeneous equation, it isn't clear how to use the method of undetermined coefficients (what should A(D) be?!?) So we use variation of parameters.

The Wronskian matrix is given by

$$W = W(h_1, h_2)(t) = \det \begin{bmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{bmatrix}.$$

And following the method, we need to solve the matrix equation

$$W \begin{bmatrix} c_1' \\ c_2' \end{bmatrix} = \begin{bmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{bmatrix} \cdot \begin{bmatrix} c_1' \\ c_2' \end{bmatrix} = \begin{bmatrix} 0 \\ e^t \ln(t) \end{bmatrix}.$$

We now use Cramer's Rule to find  $c_i'$ . First note that  $\det W = (t+1)e^{2t} - te^{2t} = e^{2t}$ .

We now have

$$c_1' = \frac{\det \begin{bmatrix} 0 & te^t \\ e^t \ln(t) & (t+1)e^t \end{bmatrix}}{\det W} = \frac{-e^{2t} \ln(t)t}{e^{2t}} = -t \ln(t)$$

and

$$c_2' = \frac{\det \begin{bmatrix} e^t & 0 \\ e^t & e^t \ln(t) \end{bmatrix}}{\det W} - \frac{\ln(t)e^{2t}}{e^{2t}} = \ln(t).$$

We now find the functions  $c_1,c_2$  by anti-differentiation:

$$c_1(t) = \int c_1' dt = -\int t \ln(t) dt = \frac{-t^2 \ln(t)}{2} + \frac{t^2}{4} + C = \frac{t^2 (1 - 2 \ln(t))}{4} + C$$

(integrate by parts with  $u = \ln(t)$  and dv = t).

and

$$c_2(t) = \int c_2' dt = \int \ln(t) dt = t \ln(t) - t + D$$

Now, we only need a particular solution to the ODE, se we take C=D=0, and we find the particular solution

$$\begin{split} p(t) &= c_1(t)h_1(t) + c_2(t)h_2(t) \\ &= \left(\frac{t^2(1-2\ln(t))}{4}\right) \cdot e^t + (t\ln(t)-t) \cdot te^t \\ &= \left(\frac{-2\ln(t)+1}{4}\right) \cdot t^2e^t + \frac{4\ln(t)-4}{4} \cdot t^2e^t \\ &= \frac{2\ln(t)-3}{4}t^2e^t \end{split}$$

Now the general solution is

$$x(t) = p(t) + k_1 e^t + k_2 t e^t = \frac{2\ln(t) - 3}{4} t^2 e^t + k_1 e^t + k_2 t e^t$$

for constants  $k_1, k_2$ .