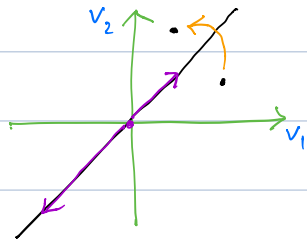


Eigenvalues, Eigenvectors, Row ReductionGeometric Meaning of an Eigenvector

Multiplication by a  $2 \times 2$  matrix  $A$  takes a vector  $\vec{v} \in \mathbb{R}^2$  to another vector  $A\vec{v} \in \mathbb{R}^2$ :

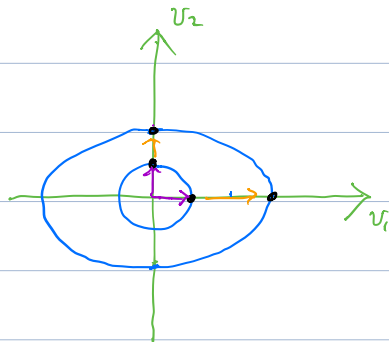
Ex.



$$A \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_2 \\ v_1 \end{bmatrix}$$

is reflection about the diagonal.

Ex.



$$A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$

$$A \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 3v_1 \\ 2v_2 \end{bmatrix}$$

expands by 3 in the  $v_1$ -direction  
and by 2 in the  $v_2$ -direction.

Under such a transformation, sometimes a line is fixed.

An eigenvector is a nonzero vector in a fixed line.

Def. An eigenvector of an  $n \times n$  matrix  $A$  is a nonzero vector  $\vec{v} \in \mathbb{R}^n$  s.t.

$$A\vec{v} = \lambda\vec{v} \quad \text{for some } \lambda \in \mathbb{R} \quad (\lambda \text{ could be } 0.)$$

$\lambda$  is called the eigenvalue corresponding to  $\vec{v}$ .

The eigenvalue  $\lambda$  is the scaling factor for the eigenvector  $\vec{v}$ .

To find an eigenvector, we solve

$$A\vec{v} = \lambda\vec{v} = \lambda I\vec{v}, \quad I = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix} = \text{identity matrix.}$$

$$\Leftrightarrow (A - \lambda I)\vec{v} = \vec{0} \Leftrightarrow -(A - \lambda I)\vec{v} = \vec{0}$$

$$\Leftrightarrow (\lambda I - A)\vec{v} = \vec{0}.$$

By Cramer's rule,  $\exists$  nonzero sol  $\vec{v}$  iff  $\det(\lambda I - A) = 0$ .

Ex.  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$$\begin{aligned} \det(\lambda I - A) &= \det\left(\begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}\right) = \begin{vmatrix} \lambda & -1 \\ -1 & \lambda \end{vmatrix} = \lambda^2 - 1 \\ &= (\lambda+1)(\lambda-1) = 0 \end{aligned}$$

Eigenvalues  $\lambda = -1, 1$

Eigenvectors:

$$\lambda = 1: (I - A)\vec{v} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow v_1 - v_2 = 0 \Rightarrow v_1 = v_2 \Rightarrow \vec{v} = \begin{bmatrix} v_2 \\ v_2 \end{bmatrix} = v_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda = -1: \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow -v_1 - v_2 = 0 \Rightarrow v_1 = -v_2.$$

$$\Rightarrow \vec{v} = \begin{bmatrix} -v_2 \\ v_2 \end{bmatrix} = v_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix}.$$

This calculation shows that  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  has two

fixed lines through  $\vec{0}$ , one going through  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  (the diagonal) and the other going through  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  (the antidiagonal).

### Solutions of $D\vec{x} = A\vec{x}$

If  $A$  has eigenvalue  $\lambda$  with eigenvector  $\vec{v}$ , then  $\vec{x} = e^{\lambda t} \vec{v}$  is a solution of  $D\vec{x} = A\vec{x}$ .

Why? We know  $A\vec{v} = \lambda\vec{v}$ .

$$\begin{aligned} D\vec{x} &= (e^{\lambda t} \vec{v})' = e^{\lambda t} \lambda \vec{v} = e^{\lambda t} A\vec{v} \quad (\text{because } A\vec{v} = \lambda\vec{v}) \\ &= A e^{\lambda t} \vec{v} \quad (\text{linearity}) \\ &= A\vec{x}. \end{aligned}$$

Therefore,  $\vec{x} = e^{\lambda t} \vec{v}$  is a solution of  $D\vec{x} = A\vec{x}$ .

Geometrically a solution of the DE  $D\vec{x} = A\vec{x}$  for a  $2 \times 2$  matrix  $A$  is a curve  $\vec{x}(t)$  in the plane.

The solution  $\vec{x} = e^{\lambda t} \vec{v}$  is the straight line through the eigenvector  $\vec{v}$ .

## Row Reduction

In solving a system of linear algebraic equations  $B\vec{u} = \vec{b}$ ,  
Cramer's rule works 1) only for square systems ( $n \times n$ )  
2) only if  $\det B \neq 0$ .

Thus, we can never use Cramer's rule to find eigenvectors  
since  $\det(\lambda I - A) = 0$ .

Ex. Solve

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 1 & -1 & -3 & 1 \\ 2 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \quad \begin{array}{l} u_1 + 2u_2 + 3u_3 = 1 \\ u_1 - u_2 - 3u_3 + u_4 = 1 \\ \vdots \end{array}$$

Three operations that do not change the solutions:

- 1)  $R_i \rightarrow R_i + cR_j$
- 2)  $R_i \rightarrow cR_i, \quad c \neq 0$
- 3)  $R_i \leftrightarrow R_j$

Use this (pivot) to kill everything else in its column

pivot = first nonzero entry of a nonzero row

$$\begin{bmatrix} \textcircled{1} & 2 & 3 & 0 & | & 1 \\ 1 & -1 & -3 & 1 & | & 1 \\ 2 & 1 & 0 & 1 & | & 2 \end{bmatrix} \xrightarrow[R_3 \rightarrow R_3 - 2R_1]{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 1 & 2 & 3 & 0 & | & 1 \\ 0 & -3 & -6 & 1 & | & 0 \\ 0 & -3 & -6 & 1 & | & 0 \end{bmatrix}$$
$$\xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 2 & 3 & 0 & | & 1 \\ 0 & \textcircled{-3} & -6 & 1 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 \rightarrow -\frac{1}{3}R_2} \begin{bmatrix} 1 & 2 & 3 & 0 & | & 1 \\ 0 & \textcircled{1} & 2 & -\frac{1}{3} & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

make pivot 1

Use this pivot to kill everything else in its column

pivots

$$\xrightarrow{R_1 \rightarrow R_1 - 2R_2} \begin{bmatrix} \textcircled{1} & 0 & -1 & \frac{2}{3} & | & 1 \\ 0 & \textcircled{1} & 2 & -\frac{1}{3} & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

Thus, the solutions are

pivot variables  $\rightarrow$   $u_1$   $-u_3 + \frac{2}{3}u_4 = 1 \Rightarrow u_1 = u_3 + \frac{2}{3}u_4 + 1$   
 $u_2$   $+2u_3 - \frac{1}{3}u_4 = 0 \Rightarrow u_2 = -2u_3 + \frac{1}{3}u_4$

free variables  $\rightarrow$   $u_3 = u_3$   
 $u_4 = u_4$

In matrix notation,

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} = \begin{bmatrix} u_3 + \frac{2}{3}u_4 + 1 \\ -2u_3 + \frac{1}{3}u_4 \\ u_3 \\ u_4 \end{bmatrix} = u_3 \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + u_4 \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

general solution to the related homogeneous system

Reduced matrix:

$u_1$   $u_2$   $u_3$   $u_4$   $u_5$   $u_6$   $u_7$   $u_8$   
 pivot variables  $\rightarrow$   $u_3, u_6, u_8$   
 free variables  $\rightarrow$   $u_4, u_5, u_7$

$$\left[ \begin{array}{cccccccc|c} 0 & 0 & 1 & * & * & 0 & * & 0 & * \\ & & 0 & & 1 & * & 0 & & * \\ & & 0 & & 0 & & 1 & & * \\ & & 0 & & 0 & 0 & 0 & & 0 \end{array} \right]$$

staircase pattern

Pivot variables  $\leftrightarrow$  pivot columns

free variables  $\leftrightarrow$  nonpivot columns