ASTR5550 Homework 2

Girish M. Duvvuri

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Problem 1

a) Let $\mu = rAt$:

$$\implies P(k|t) = \frac{\mu^k e^{-\mu}}{k!} = \frac{\mu^3}{6} e^{-\mu} \tag{1}$$

b) Let $\frac{P(t)}{P(k)} = C$:

$$\Longrightarrow P(t|k) = C \times \frac{\mu^3}{6} e^{-mu} \tag{2}$$

$$\implies 1 = C \int_0^\infty \frac{(rAt)^k}{k!} e^{-rAt} dt \tag{3}$$

$$\Longrightarrow 1 = \frac{C}{6} \times \frac{\Gamma(k+1)}{rA} \tag{4}$$

$$\Longrightarrow C = \frac{6rA}{\Gamma(4)} = rA \tag{5}$$

$$\Longrightarrow P(t|k) = \frac{(rA)^4}{6} t^3 e^{-(rAt)} \tag{6}$$

I also verified that the numerical integral of this expression was close to 1. Using a t-array from 0 to 10^{10} years with 10^5 log-spaced points, the trapezoidal-rule integrated probability was $1 + 8.4 \times 10^{-9}$.

- c) 68% of the likelihood P(t|k) is enclosed within the interval 15.59 $< t \le 51.38$ Myr. The maximum likelihood is at t = 30 Myr.
- d) I predict that the range will decrease since we have a greater sample size to work with. This was correct: with the new measurements we get the maximum likelihood t = 37 Myr with a 68% confidence interval: 31.24 < t < 43.43 Myr (See Figure 1).

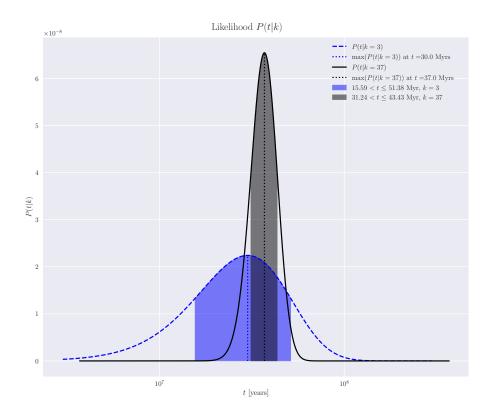


Figure 1: Increasing the measurement area and getting the new count value k=37 narrows the probability distribution to a new value within the 68% confidence interval we had when k=3, but offset from the original peak value of 30 Myr. The newer measurement is 37 Myr with a 68% confidence interval 31.24 < t < 43.43 Myr.

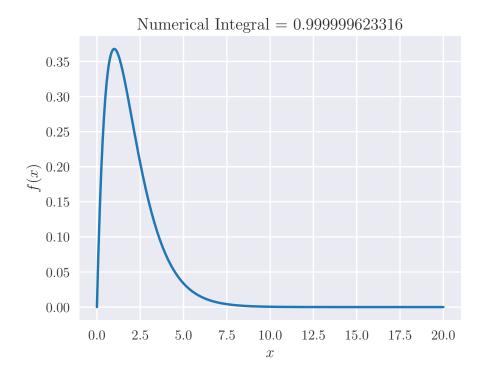


Figure 2: With only a range between 0 and 20 spaced with 10^4 points the numerical integral is nearly 1.

Problem 2

a) See Figure 2 for the plot. The numerical integral is shown in the plot, but analytically:

$$\int_{-\infty}^{\infty} f(x)dx = \int_{-\infty}^{0} 0 \ dx + \int_{0}^{\infty} xe^{-x} dx$$

$$= (-xe^{-x})|_{0}^{\infty} - \int_{0}^{\infty} -e^{-x} dx$$

$$= (0 - 0) - (e^{-x})|_{0}^{\infty}$$

$$= 0 - (0 - 1) = 1$$

$$\implies \int_{-\infty}^{\infty} f(x) dx = 1$$

b)

$$F(x) = \int_{-\infty}^{x} f(x')dx'$$

$$= \int_{0}^{x} x'e^{-x'}dx'$$

$$= (-x'e^{-x'})|_{0}^{x} - \int_{0}^{\infty} -e^{-x'}dx'$$

$$= (-xe^{-x} - 0) - (e^{-x'})|_{0}^{x}$$

$$= -xe^{-x} - (e^{-x} - 1) = 1 - e^{-x}(1 + x)$$

$$\Longrightarrow \boxed{F(x) = 1 - e^{-x}(1 + x)}$$

 $\mathbf{c})$

$$E[x] = \int_{-\infty}^{\infty} x f(x) dx$$

$$= \int_{0}^{\infty} x^{2} e^{-x} dx$$

$$= (-x^{2} e^{-x})|_{0}^{\infty} - \int_{0}^{\infty} -2x e^{-x} dx$$

$$= (0 - 0) + 2 \int_{0}^{\infty} x e^{-x} dx$$

$$= 0 + 2(1) \quad \text{From part } \mathbf{a}$$

$$\implies \boxed{E[x] = 2}$$

d)

$$V[x] = E[k^{2}] - (E[k])^{2}$$

$$= \int_{-\infty}^{\infty} x^{2} f(x) dx - 4$$

$$= \int_{0}^{\infty} x^{3} e^{-x} dx - 4$$

$$= (-x^{3} e^{-x})|_{0}^{\infty} - \int_{0}^{\infty} -3x^{2} e^{-x} dx - 4$$

$$= (0 - 0) + 3 \int_{0}^{\infty} x^{2} e^{-x} dx - 4$$

$$= 0 + 3(2) - 4 \quad \text{From part } \mathbf{c}$$

$$\implies V[x] = 2$$

The total probability within the range $E[k] \pm \sqrt{V[x]}$ is:

$$\int_{2-\sqrt{2}}^{2+\sqrt{2}} x e^{-x} dx = (2-\sqrt{2}+1)e^{-(2-\sqrt{2})} - (2+\sqrt{2}+1)e^{-(2+\sqrt{2})}$$

$$\approx 0.73$$

Problem 3

$$f(k) = \frac{\lambda^k e^{-\lambda}}{k!} \tag{7}$$

b)
$$E[k(k-1)] = E[k^2 - k] = E[k^2] - E[k] = V[k] + \lambda^2 - \lambda = V[k]$$

$$\begin{split} E[k(k-1)] &= \sum_{k=0}^{\infty} k(k-1) \frac{\lambda^k e^{-\lambda}}{k!} \\ &= \sum_{k=2}^{\infty} k(k-1) \frac{\lambda^k e^{-\lambda}}{k!} \\ &= \sum_{k=2}^{\infty} \lambda^2 \frac{\lambda^{k-2} e^{-\lambda}}{(k-2)!} \\ &= \lambda^2 \sum_{k=2}^{\infty} \frac{\lambda^{k-2} e^{-\lambda}}{(k-2)!} \end{split}$$

 $=\lambda^2\times 1$ Sum is identical to summing over original Poisson distribution

$$\implies \lambda^2 = V[k] \tag{8}$$

$$\sigma_{\gamma} = \lambda \tag{9}$$

$$\mu_{\gamma} = \lambda = \sigma_{\gamma}$$

$$\mu_{\rm DN} = \sigma_{\rm DN} = \frac{\lambda}{G}$$

 \mathbf{f}) Yes, j also follows a Poisson distribution indicating that the uncertainty of a CCD pixel measurement will follow a Poisson distribution as well.

Poisson Number Generator with $\lambda=10$ and N=1000 samples

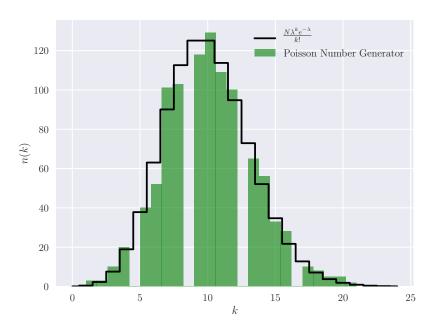


Figure 3: The histogram looks a little weird because of the automatic binsize choice, but it follows the PDF quite well.

Problem 4

a) The algorithm in [Press et. al (2007)] had sections for the case of small $\lambda < 5$ and large $\lambda > 13.5$ which were not relevant in our case for $\lambda = 10$. Excluding these sections, I adapted the code to Python and ran the sampler for N = 1000 cases. The results are shown in Figure 3.

Code for all Problems:

```
import numpy as np
  import matplotlib.pyplot as plt
  import seaborn as sns
  from astropy import units as u
  sns.set_style('darkgrid')
  sns.set_context('talk')
  plt.rc('text', usetex=True)
  plt.rc('font', family='serif')
 \begin{tabular}{ll} $\tt def & make\_pdf(t\_array=np.logspace(5.0,\ 10.0,\ 10**4)*(u.yr),\ k=3.0, \end{tabular} 
                A=10.0*((u.km)**2.0), r=0.01/((u.km**2)*(10.0**6.0*u.yr))):
      mu = (r*A*t_array).decompose()
      norm\_constant = r*A
      return (r*A)*(mu**k)*np.exp(-mu)/(np.math.factorial(int(k))), t_array
  def calc_p df_t hings(t_array=np.logspace(5.0, 10.0, 10**4)*(u.yr),
                        k = 3.0,
                       A=10.0*((u.km)**2.0),
                        r = 0.01/((u.km**2)*(10.0**6.0*u.yr))):
      pdf, t_array = make_pdf(t_array, k, A, r)
      max_loc = np.argmax(pdf.value)
      t_max = t_array[max_loc]
      pdf_{max\_array} = np.linspace(0.0*pdf[0], pdf[max\_loc], 1000)
      t_max_array = np.ones_like(pdf_max_array)*t_max
      equal_points = np.array([np.where(pdf[max_loc:] \leq pdf[i])[0][0]
                                 for i in range (0, max_loc)])
      integral_value = np.array([np.trapz(pdf[i:max_loc + equal_points[i]],
                                             t_array[i:max_loc + equal_points[i
      ]])
                                   for i in range(0, max_loc)])
      test_integral = np.array([np.abs(integral_value[i] - 0.68)
                                   for i in range(0, max_loc)])
      loc_low = np.argmin(test_integral)
      loc_high = max_loc + equal_points[np.argmin(test_integral)]
      t_{low} = t_{array} [loc_{low}]
      t_high = t_array[loc_high]
      max\_label = r'max\$(P(t \setminus vert k=' + str(int(k)) + r'))\$ at t=\$'
      \max_{label} += "\{:.1f\}".format(t_{\max}.value/(10**6)) + r' Myrs'
```

```
fill_label = "{:.2f}".format(t_low.value/(10**6)) + r'
       fill_label += r' /  < t \leq $\/' + r'',
       fill_label += "{:.2f}".format(t_high.value/(10**6))
      fill_label += r' \text{textrm} \{ Myr \}, \$k=' + str(int(k)) + r' \$'
      return [[pdf, t_array],
               [pdf_max_array, t_max_array],
               [loc_low, loc_high, max_loc, t_low, t_high],
               max_label, fill_label]
{}_{51} \bigg| \, \frac{\text{def plot\_pdf\_things} \, (\, t\_array = np. \, logspace \, (\, 5.0 \, , \, \, \, 10.0 \, , \, \, \, 10**4) \, * (u.\,yr) \, ,}{}
                        k = 3.0,
                        A=10.0*((u.km)**2.0),
                        r = 0.01/((u.km**2)*(10.0**6.0*u.yr)),
                        diff_plot = 2000,
                        save_name='meteor_1.pdf',
                        title_label=r'Likelihood $P(t \vert k)$',
                        figure_size = (12, 10),
                        bbox = (0.98, 1.0),
                        suptitle_y = 0.998):
      [[pdf, t_array], [pdf_max_array, t_max_array],
       [loc-low, loc-high, max-loc, t-low, t-high],
       max\_label, fill\_label] = calc\_pdf\_things()
      mask = np.arange(max_loc - diff_plot, max_loc + diff_plot)
       [[pdf_2, t_array_2], [pdf_max_array_2, t_max_array_2],
       [loc\_low\_2, loc\_high\_2, max\_loc\_2, t\_low\_2, t\_high\_2],
       max_label_2, fill_label_2] = calc_pdf_things(k=37.0, A=100.0*(u.km))
      **2.0))
      mask_2 = np.arange(max_loc_2 - diff_plot, max_loc_2 + diff_plot)
      plt.figure(figsize=figure_size)
      plt.semilogx(t_array[mask], pdf[mask], '--b', label=r'$P(t\vert k=3)$')
      plt.plot(t_max_array, pdf_max_array, ':b', label=max_label)
      plt.fill_between(t_array[loc_low:loc_high],
                         pdf[loc_low:loc_high], 0.0,
                         color='b', alpha=0.5,
                         label=fill_label)
      plt.semilogx(t_array_2[mask_2],
                     pdf_2[mask_2], '-k', label=r'P(t \vee t k=37)')
      plt.plot(t_max_array_2, pdf_max_array_2, ':k', label=max_label_2)
      t_fill_array = np.array(t_array_2[loc_low_2:loc_high_2], dtype=float)
       pdf_fill_array = np.array(pdf_2[loc_low_2:loc_high_2], dtype=float)
      plt.fill_between(t_fill_array,
                         pdf_fill_array, 0.0,
```

```
color='k', alpha=0.5,
                        label=fill_label_2)
       plt.ylabel(r'$P(t\vert k)$')
       plt.xlabel(r'$t$ [years]')
       plt.legend(bbox_to_anchor=bbox)
       plt.suptitle(title_label,
                    y=suptitle_y)
       plt.tight_layout()
       plt.savefig(save_name)
       plt.show()
  def do_single_press_Poisson(mean_rate=10):
       old_mean = -1.0
       mean\_now = mean\_rate
       logfact = np.ones((1024), dtype=np.longdouble)*(-1.0)
       if mean_now != old_mean:
           sqlam = np.sqrt(mean_now)
           loglam = np.math.log(mean_now)
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       blah = True
       while blah:
           u = 0.64*np.random.uniform()
           v = -0.68 + 1.28*np.random.uniform()
           k = int(np.floor(sqlam*(v/u)+mean_now+0.5))
           if k < 0:
               continue
           u2 = u*u
           if k < 1024:
               if logfact[k] < 0:
                   logfact[k] = np.math.log(np.math.factorial(k))
               lfac = logfact[k]
           else:
               lfac = np.math.log(np.math.factorial(k))
           p = sqlam*np.exp(-mean\_now + k*loglam - lfac)
           if u2 < p:
               break
       mean\_old = mean\_now
       return k
  def do_N_Poisson_samples(mean_rate, N):
       return np.array([do_single_press_Poisson(mean_rate)
                        for i in range (0, N)
```

```
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   def problem_4 (mean_rate=10, N=1000):
       sample_results = do_N_Poisson_samples(mean_rate, N)
       plt.figure(figsize = (8, 6))
       plt.hist(sample_results,
                 label='Poisson Number Generator', alpha=0.6, bins='auto',
                 color='green')
       k_{array} = np.arange(0, 25)
       factorial\_array = np.array([np.math.factorial(k) for k in k\_array],
                                     dtype=float)
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       pdf\_array \, = \, np.\,array \, (\, [\, (\, 1.0 \, / \, np.\, math.\, factorial \, (\, k\, )\, ) * (\,
            mean_rate**k)*np.exp(-mean_rate)
                                for k in range (0, 25)
       plt.plot(k_array, N*pdf_array,
                 label=r'$\frac{N \lambda^k e^{-\lambda}}{k!}$', color='k',
       drawstyle='steps-mid')
       plt.xlabel(r'$k$')
       plt.ylabel(r'$n(k)$')
       title_label = r'Poisson Number Generator with $\lambda=\$' + str(
       mean_rate)
       title_label += r' and N='' + str(N) + r' samples'
       plt.suptitle(title_label)
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       plt.legend()
       plt.savefig('poisson.pdf')
       plt.show()
   if __name__ == '__main__':
       plot_pdf_things()
       problem_2()
       problem_4()
```

 $hw_2.py$

References

[Press et. al (2007)] W. H. Press, S. A. Teukolsky, W. T. Vetterling, B. P. Flannery. *Numerical Recipes*, Cambridge University Press, Third edition, 2007.