



中国科学技术大学
University of Science and Technology of China

Homework 3

Bayesian Network

姓名: 高茂航

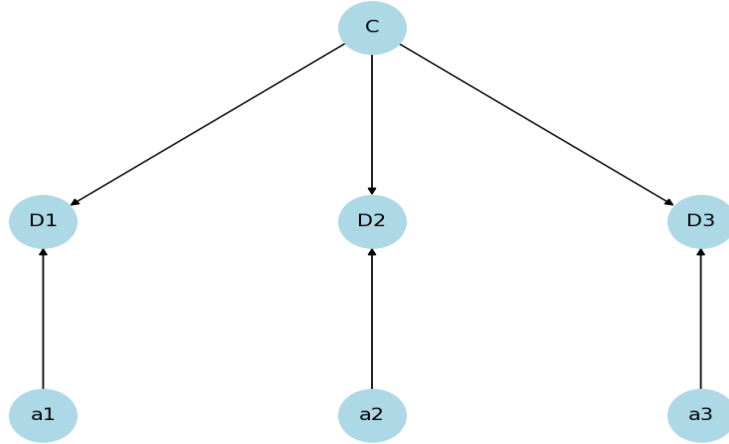
学号: PB22061161

日期: 2024.6.1

Homework 3

1 概率推断 [25%]

1.1



1.2

$\because D_t$ 只依赖于 C 和 a_t ,

$$\therefore P(C = c, D_1 = d_1, D_2 = d_2, D_3 = d_3) = P(C = c)P(D_1 = d_1|C = c, a_1)P(D_2 = d_2|C = c, a_2)P(D_3 = d_3|C = c, a_3)$$

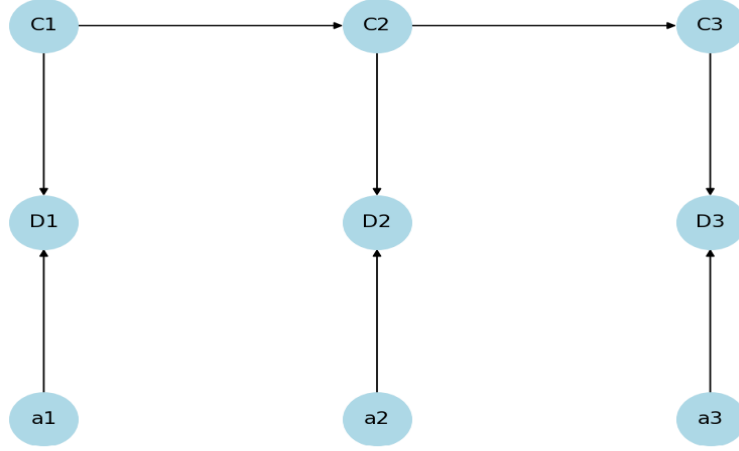
1.3

$$\begin{aligned} P(C = c|D_1 = d_1, \dots, D_t = d_t) &= \frac{P(C = c, D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \frac{P(C = c)P(D_1 = d_1|C = c)P(D_2 = d_2|C = c) \dots P(D_t = d_t|C = c)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \frac{P(C = c, D_1 = d_1, \dots, D_{t-1} = d_{t-1})P(D_t = d_t|C = c)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \frac{P(C = c|D_1 = d_1, \dots, D_{t-1} = d_{t-1})P(D_t = d_t|C = c)}{P(D_t = d_t|D_1 = d_1, \dots, D_{t-1} = d_{t-1})} \\ &\propto P(C = c|D_1 = d_1, \dots, D_{t-1} = d_{t-1})P(D_t = d_t|C = c) \end{aligned}$$

Homework 3

2 转移概率 [25%]

2.1



2.2

$\because D_t$ 依赖于 C_t 和 a_t , 且 C_t 依赖于 C_{t-1} ,

$$\therefore P(C_1 = c_1, C_2 = c_2, C_3 = c_3, D_1 = d_1, D_2 = d_2, D_3 = d_3) = P(C_1 = c_1)P(D_1 = d_1 | C_1 = c_1)P(C_2 = c_2 | C_1 = c_1)P(D_2 = d_2 | C_2 = c_2)P(C_3 = c_3 | C_2 = c_2)P(D_3 = d_3 | C_3 = c_3)$$

2.3

$$\begin{aligned} P(C_{t+1} = c_{t+1} | D_1 = d_1, \dots, D_t = d_t) &= \frac{P(C_{t+1} = c_{t+1}, D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \sum_{c_t} \frac{P(C_{t+1} = c_{t+1}, C_t = c_t, D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \sum_{c_t} \frac{P(C_t = c_t, D_1 = d_1, \dots, D_t = d_t)P(C_{t+1} = c_{t+1} | C_t = c_t, \dots, D_t = d_t)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &= \sum_{c_t} \frac{P(C_t = c_t, D_1 = d_1, \dots, D_t = d_t)P(C_{t+1} = c_{t+1} | C_t = c_t)}{P(D_1 = d_1, \dots, D_{t-1} = d_{t-1}, D_t = d_t)} \\ &\propto \sum_{c_t} P(C_t = c_t | D_1 = d_1, \dots, D_t = d_t)P(C_{t+1} = c_{t+1} | C_t = c_t) \end{aligned}$$

Homework 3

3 是哪辆车?[30%]

3.1

3.2

3.3

3.4

4 模型学习 [10%]

4.1

5 反馈 [10%]