KNN (K-Nearest Neighbours)

What is KNN (K- Neavest Neighbour) Algorithm?

The k-Nearest Neighbor (KNN) algorithm is a popular machine learning technique used for classification and regression tasks. It relies on the idea that similar data points tend to have similar labels

During the training phase, the KNN algorithm stone the entire training dataset as a reference when making predictions, it calculates the distance between the infinit data point and all toaining enamples, using a chosen distance metric such as Euclidean

Nent, the algorithm Edentifies the k meareast neighbors

to the input data point based on their distances. In the case of classification, the algorithm

assign the most common class label among the k neighbors as the predicted label as for the Input data point. For regression, it calculates the average or weighted average of the farget value of the kneighbors to predict the value for the

Input datapoint. The KNN algorithm is straightforward and easy to rundustand, making it a popular choice in various domains. However, its performance can be affected by the choice of k and the distance metric, so careful parameter tuning is necessary for Optimal Lesults.

When Do Ne Vse the KNN Algorithm?

KNN can be used for both classification and regression predictive problems. However, it is more widely used in classification problem in the industry. To evaluate any technique, we generally cook at 3 important aspects:

1. Ease of interpreting output the public feeding dates

2. Calculation time

3. Predictive Power

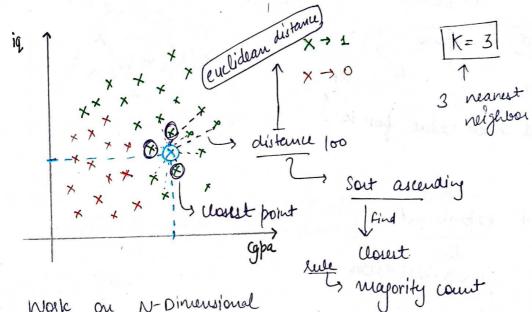
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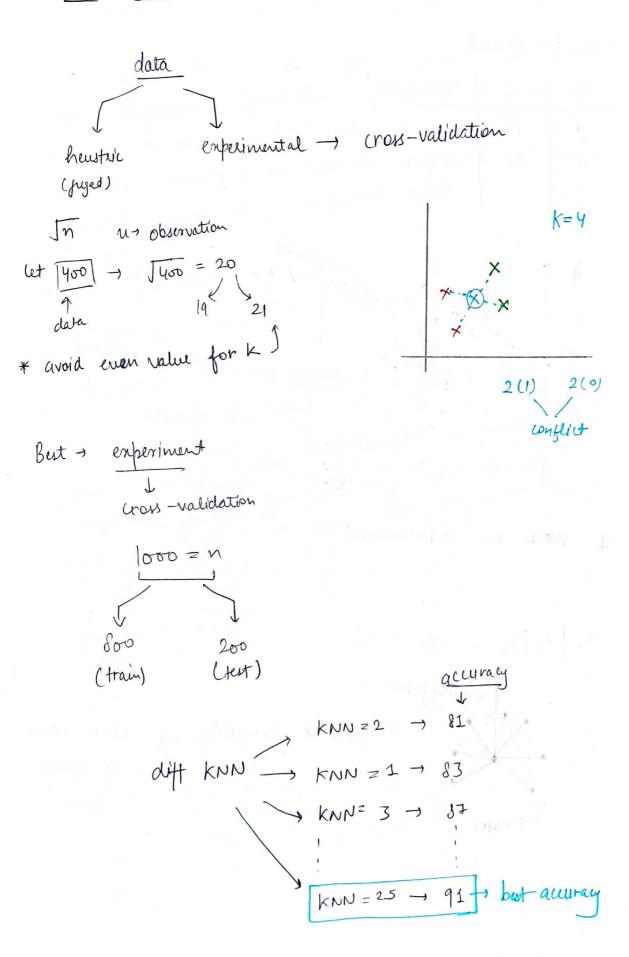


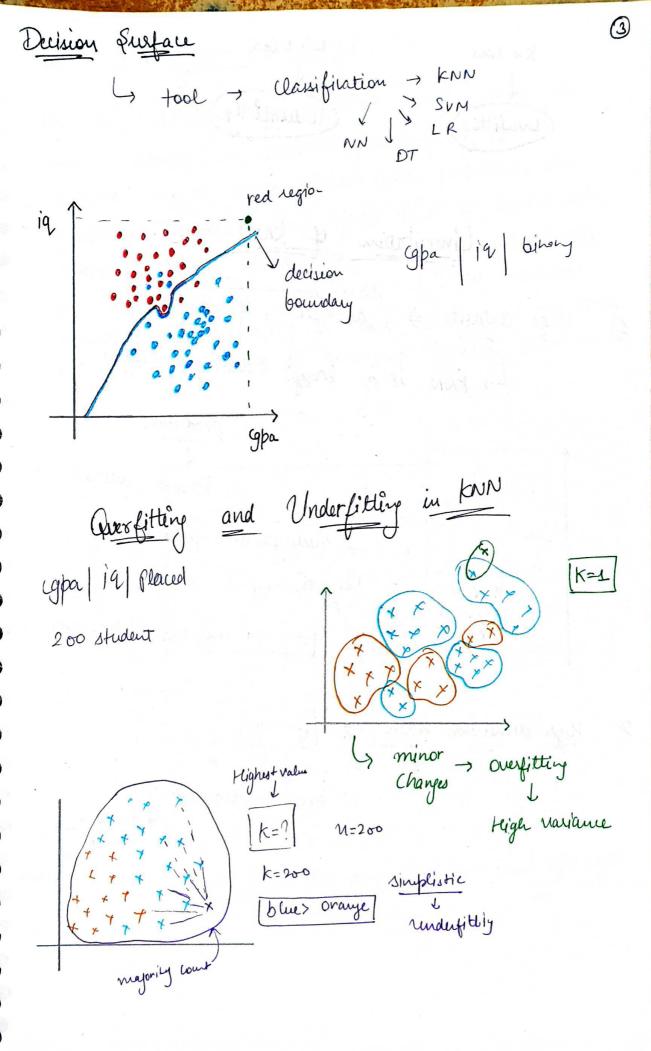
N-Dimensional ou

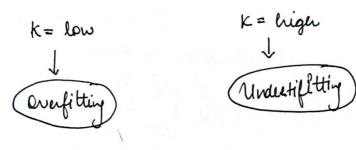
majority class X1 | X2 | X3 --- Xn

-> query point majority 3 vectors -> -> class label Count

How to Select K?







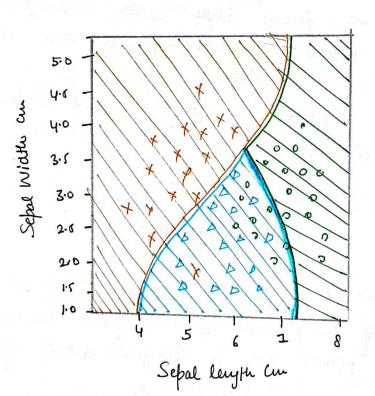
Limnitation of KNN (500000, 100) large datasets > n = 5L, f=100 Ly knn is a large learning technique query point -> prediction * 4 training 51 distance > Sort = negarity Kigh dimension data > [f=500] Cursi of dimension & distan

reliable

3

In a classification problem with two or more classes, a decision boundary of decision buylare is a hypersurface that partitions the surface is a hypersurface that partitions the moderlying vector space into two or more sets, one for each class The classifier will classify one for each class The classifier will classify all the points on one side of the decision and the points on one side of the decision boundary as belonging to one class and all those on the other side as belonging to the other class.

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Decision Region boundary: Schol leight and Schol wiah

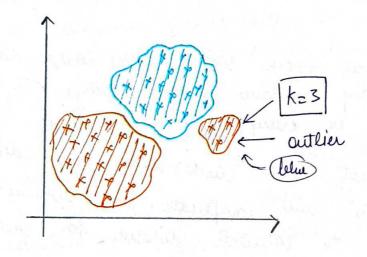
Emportant Points

1. We can draw decision boundary for all the Classification algorithms including Newal Networks 0

- 2. Decision boundary can be both linear (as in the case of SUM) or mon-linear (as in the case of Decision tree classifier or knn)
- 3. Decision boundaries are not always clear cut.
 That is, the teausition from one class in the fearsture spacer to another is not discortinous, but gradul. This effect is common in fuzzy logic based classification algorithms, where membership in one class of another is ambigous.
- 4. for higher dimension problems the deckeon boundary acts as a hyperplane (for linear ones)

Vornoi Diagram

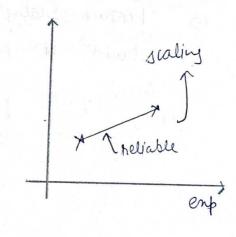
In mathematics, a Voronoi diagram is a partitioning of a plane into regions based on distance to points in a specific subset of the plane.



4) Non-homogeneous scales

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> doninant because of scale

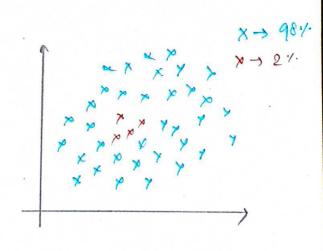


5) ambalance dataset

Sys → 984.

No → 24.

Sbiased



- 6) Inference (fail KNN or not good KNN pr Inference)

 L3 black box model
- Does not work well with large dataset as calculating distance between each data instance would be every costly.
- 8) Does not nook well with high dimensionality as this will complicate the distance calculated process to calculate distance for each dimension.
- 9) Sensitive to moisy and missing data
- 19) Feature Scaling Data in all the dimension should be scaled peopledy.

- 1. Train the classifier on the baining set.
- 2. Create a ruiform grid (ruith the help of Numby Meshgrid) of points that densely cover the region of input space containing the training set.
- 3. Classify each point on the glid. Store the lesset in an areay A, where Aij contains the predicted class for the point at lowi, column j on the grid.
- 4' Plot the array of an image, where each pinel corresponds to a grid point and its color represents the predicted class, The decision boundary can be seen as constours where the image
- changes color.

 Their respective color on the same contour.

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