

## 1.2 Sample Spaces

Probability theory is concerned with situations in which the outcomes occur randomly. Generically, such situations are called *experiments*, and the set of all possible outcomes is the **sample space** corresponding to an experiment. The sample space is denoted by  $\Omega$ , and an element of  $\Omega$  is denoted by  $\omega$ . The following are some examples.

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**EXAMPLE A** Driving to work, a commuter passes through a sequence of three intersections with traffic lights. At each light, she either stops,  $s$ , or continues,  $c$ . The sample space is the set of all possible outcomes:

$$\Omega = \{ccc, ccs, css, csc, sss, ssc, scc, scs\}$$

where  $csc$ , for example, denotes the outcome that the commuter continues through the first light, stops at the second light, and continues through the third light. ■

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**EXAMPLE B** The number of jobs in a print queue of a mainframe computer may be modeled as random. Here the sample space can be taken as

$$\Omega = \{0, 1, 2, 3, \dots\}$$

that is, all the nonnegative integers. In practice, there is probably an upper limit,  $N$ , on how large the print queue can be, so instead the sample space might be defined as

$$\Omega = \{0, 1, 2, \dots, N\}$$
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**EXAMPLE C** Earthquakes exhibit very erratic behavior, which is sometimes modeled as random. For example, the length of time between successive earthquakes in a particular region that are greater in magnitude than a given threshold may be regarded as an experiment. Here  $\Omega$  is the set of all nonnegative real numbers:

$$\Omega = \{t \mid t \geq 0\}$$
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We are often interested in particular subsets of  $\Omega$ , which in probability language are called **events**. In Example A, the event that the commuter stops at the first light is the subset of  $\Omega$  denoted by

$$A = \{sss, ssc, scc, scs\}$$

Events: <sup>↑</sup> measurable Subsets of the sample space

Union (OR):  $A \cup B$  ← Why not "A and B"

Intersection (AND):  $A \cap B$  Because "or" refers to the elements of A and B

Complement (NOT)  $A^c$

" $x \in A \cup B$ " if

$x \in A$  OR  $x \in B$  ... or both.

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Empty set:  $\emptyset$

Disjoint: A & B disjoint if  $A \cap B = \emptyset$

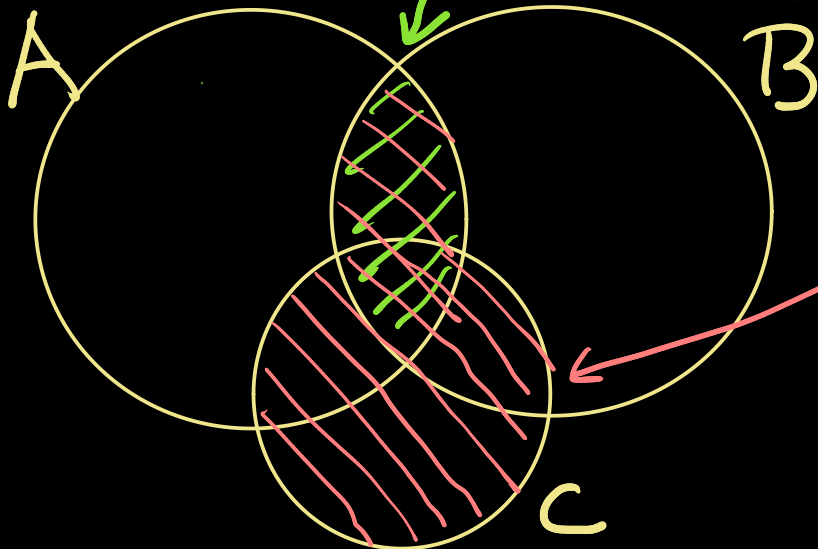
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Commutative Laws:  $A \cup B = B \cup A$   
 $A \cap B = B \cap A$

Associative Laws:  $(A \cup B) \cup C = A \cup (B \cup C)$

Distributive Laws:  $(A \cup B) \cap C = (A \cap C) \cup (B \cap C)$

$$(A \cap B) \cup C = (A \cup C) \cap (B \cup C)$$



## Definition of probability measure:

$P$  is a function:  $\overset{\text{measurable}}{\uparrow}$  Subsets of  $\Omega \rightarrow [0, 1]$

$P$  is a probability measure if

1)  $P(\Omega) = 1$

2)  $A \subset \Omega$  then  $P(A) \geq 0$

3a) If  $A_1 \cap A_2 = \emptyset$  then  $P(A_1 \cup A_2) = P(A_1) + P(A_2)$

3b) If  $A_1, A_2, \dots$  are mutually disjoint then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

# Definition of probability measure:

$P$  is a function:  $\overset{\text{measurable}}{\uparrow}$  Subsets of  $\Omega \rightarrow [0, 1]$

$P$  is a probability measure if

Axioms of  
 $\sigma$ -additive  
probability

"normed"

1)  $P(\Omega) = 1$

"positive"

2)  $A \subset \Omega$  then  $P(A) \geq 0$

"additive"

3a) If  $A_1 \cap A_2 = \emptyset$  then  $P(A_1 \cup A_2) = P(A_1) + P(A_2)$

" $\sigma$ -additive"

3b) If  $A_1, A_2, \dots$  are mutually disjoint then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

Can prove:

$$P(A^c) = 1 - P(A)$$

$$P(\emptyset) = 0$$

$$A \subset B \Rightarrow P(A) \leq P(B)$$

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P(A \cup B \cup C) = P(A) + P(B) + P(C)$$

$$\begin{aligned} & - P(A \cap B) - P(A \cap C) - P(B \cap C) \\ & + P(A \cap B \cap C) \end{aligned}$$

$$P(A \cup B \cup C \cup D) = ?$$



## Counting methods:

When  $\Omega$  is finite and all elements have the same probability, then

$$P(A) = \frac{\#(A)}{\#(\Omega)} = \frac{\# \text{ of ways } A \text{ can occur}}{\#(\Omega)}$$

### EXAMPLE B *Simpson's Paradox*

A black urn contains 5 red and 6 green balls, and a white urn contains 3 red and 4 green balls. You are allowed to choose an urn and then choose a ball at random from the urn. If you choose a red ball, you get a prize. Which urn should you choose to draw from? If you draw from the black urn, the probability of choosing a red ball is  $\frac{5}{11} = .455$  (the number of ways you can draw a red ball divided by the total number of outcomes). If you choose to draw from the white urn, the probability of choosing

... skipping for now — will be back!  
SP has MUCH larger implications in the right context.

# Multiplication Principle

If one experiment has  $m$  outcomes

and

for each outcome a second experiment has  $n$  outcomes,

then there are  $m \times n$  outcomes altogether.

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If experiment 1 has  $n_1$  outcomes, and

for each, experiment 2 has  $n_2$  outcomes, and

for each combination of prior expts,

experiment 3 has  $n_3$  outcomes

...



for each combination of prior expts,  
experiment  $p$  has  $n_p$  outcomes  
Then there are  $n_1 \times n_2 \times n_3 \times \dots \times n_p$  outcomes altogether.

# Permutations and Combinations

$n$  distinct objects :  $n!$  possible orderings.

Choosing  $r$  objects from  $n$ :

# of ways :  $n^r$  with replacement

$n \times (n-1) \times \dots \times (n-(r-1))$  without replacement



