

### 3.5 Functions of random vectors

Sums: Given a joint distribution for  $(X, Y)$   
find the distribution  $Z = X + Y$

Example

Y	2	1	0
X	0	1	0
0	0.2	0.1	0.1
1	0.2	0.1	0.2
2	0	0	0

What are  
possible values  
for  $Z = X + Y$

$$P(Z=0) = \sum_{x,y: x+y=0} P(x,y) = \sum_{x,y=0-x} P(x,y)$$

$$= \sum_x p(x, 0-x)$$

$$P(Z=1) = \sum_x p(x, 1-x)$$

$$P(Z=2) = \sum_x p(x, 2-x)$$

$$P(Z=3) = \dots$$

$$P(Z=4) = \dots$$

Y			
2	0	.2	.2
1	.1	.1	.1
0	.1	.2	0
	0	1	2 X

General formula:

$$\text{of } Z = X + Y$$

Discrete  
case

$$P_Z(z) = \sum_x p(x, z-x)$$

$$\stackrel{\text{or}}{=} \sum_y p(z-y, y)$$

$$\text{Continuous: } f_z(z) = \int_{-\infty}^{\infty} f(x, z-x) dx$$

$$= \int_{-\infty}^{\infty} f(z-y, y) dy$$

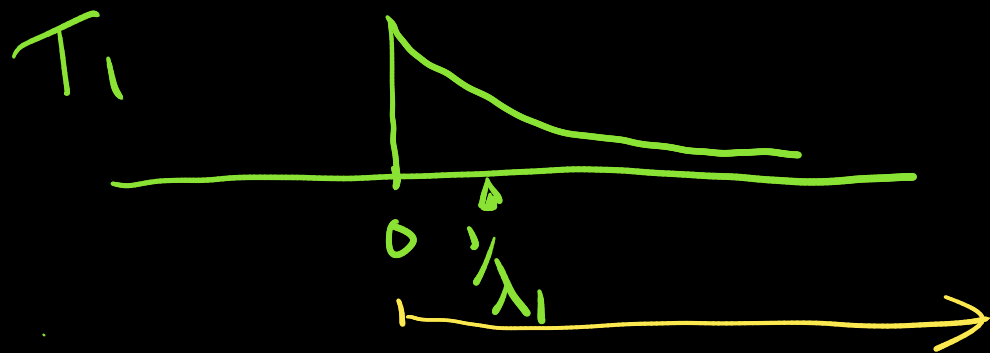
If  $X$  &  $Y$  are independent:  $f(x, y) = f_x(x) f_y(y)$

and  $f_2(z) = \int_{-\infty}^{\infty} f(x, z-x) dx$

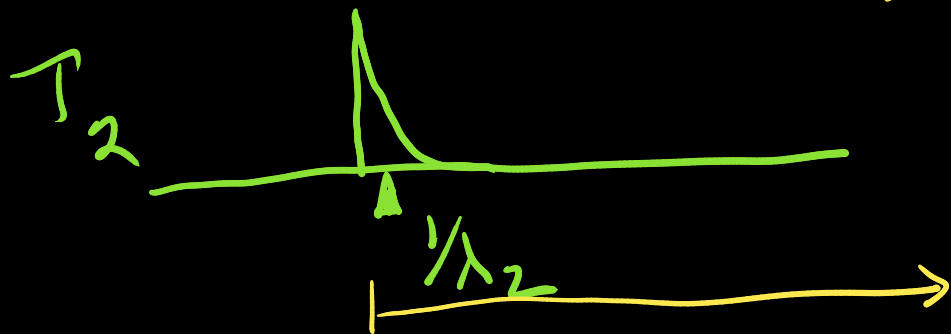
$$= \int_{-\infty}^{\infty} f_x(x) f_y(z-x) dx$$

"convolution of  $f_x$  &  $f_y$ "

Example 1: Computer has lifetime  $T_1 \sim \text{Exponential}(\lambda_1)$   
Automatic backup  $T_2 \sim \text{Exponential}(\lambda_2)$



$$f_1(t_1) = \lambda_1 e^{-\lambda_1 t_1}, t_1 > 0$$

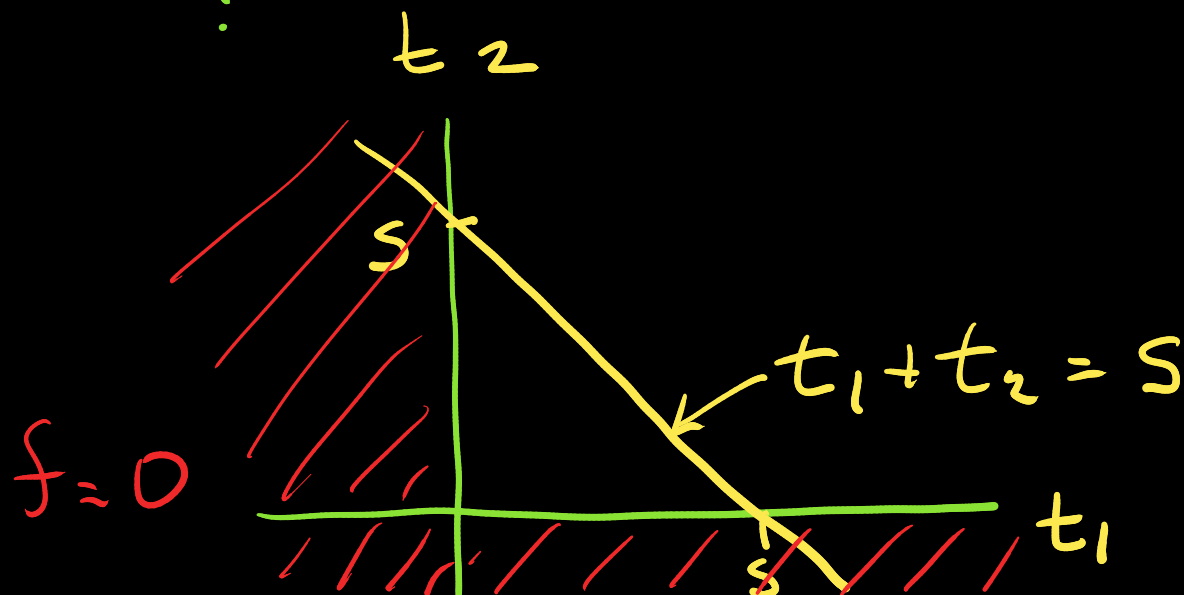


$$f_2(t_2) = \lambda_2 e^{-\lambda_2 t_2}, t_2 > 0$$

$$S = T_1 + T_2 \quad ; \quad T_1, T_2 \text{ independent}$$

$$f_s(s) = \int_{-\infty}^{\infty} f_1(t_1) f_2(s-t_1) dt_1$$

$$= \int_{?}^{?} \lambda_1 e^{-\lambda_1 t_1} \lambda_2 e^{-\lambda_2 (s-t_1)} dt_1$$



$s$   
 $? < t_1 < ?$

$$= \int_{t_1=0}^{t_1=s} \lambda_1 e^{-\lambda_1 t_1} \lambda_2 e^{-\lambda_2 (s-t_1)} dt_1$$

"Simple" if  $\lambda_1 = \lambda_2 = \lambda$  i.e. Same expected lifetime.

$$f_s(s) = \int_0^s \lambda e^{-\lambda t} \lambda e^{-\lambda (s-t)} dt \quad \lambda^2 e^{-\lambda s}$$

$$= \int_0^s \lambda^2 e^{-\lambda s} dt$$

$$= \left[ t \lambda^2 e^{-\lambda s} \right]_0^s$$

$$= s \lambda^2 e^{-\lambda s}, \quad 0 < s$$

$$\sim \text{Gamma}(2, \lambda) \text{ i.e. } \frac{1}{\Gamma(\alpha)} s^{\alpha-1} \lambda^\alpha e^{-\lambda s},$$

$0 < s, \alpha = 2$



## General Case : Using Jacobians

Transformation  $\mathbb{R}^1 \rightarrow \mathbb{R}^d$

of  $y = h(x)$

$h$  is differentiable and monotone

"strictly" increasing on an interval  $I$

or "decreasing" " " " "

$$f_y(y) = f_x(g^{-1}(y)) \times \left| \frac{dx}{dy} \right|$$

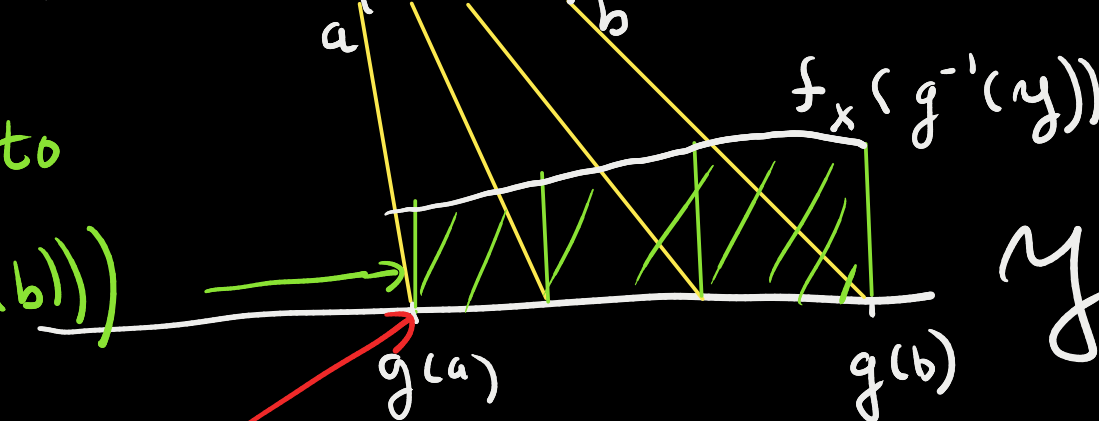
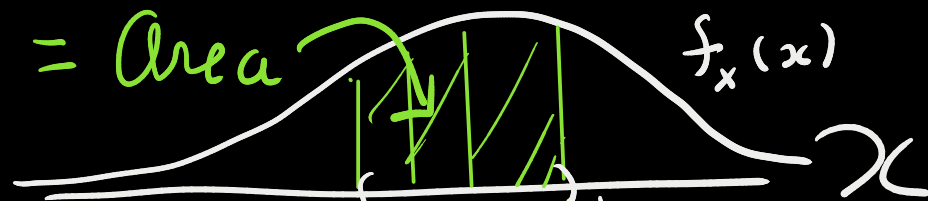
$|\dots|$  so it works  
whether increasing or decreasing

$$P(X \in (a, b)) = \text{Area}$$

||

needs to  
be equal to

$$P(Y \in (g(a), g(b)))$$



$g \downarrow$

But this area is too big because  $g(x)$  stretches the base

What to do?

Undo the effect of stretching  
by dividing by  $\left| \frac{dy}{dx} \right|$   
i.e. the amount of stretching

Now  $\left| \frac{dy}{dx} \right| = \left| \frac{dx}{dy} \right|^{-1}$

So we can multiply by  $\left| \frac{dx}{dy} \right|$

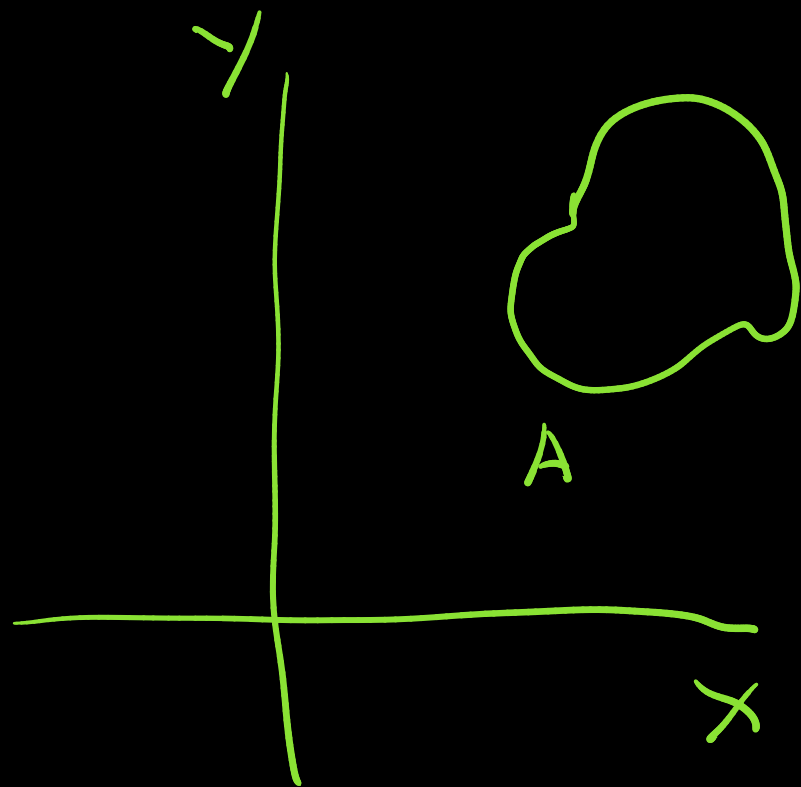
Formula:

$$f_y(y) = f_x(g^{-1}(y)) \times \left| \frac{dx}{dy} \right|$$

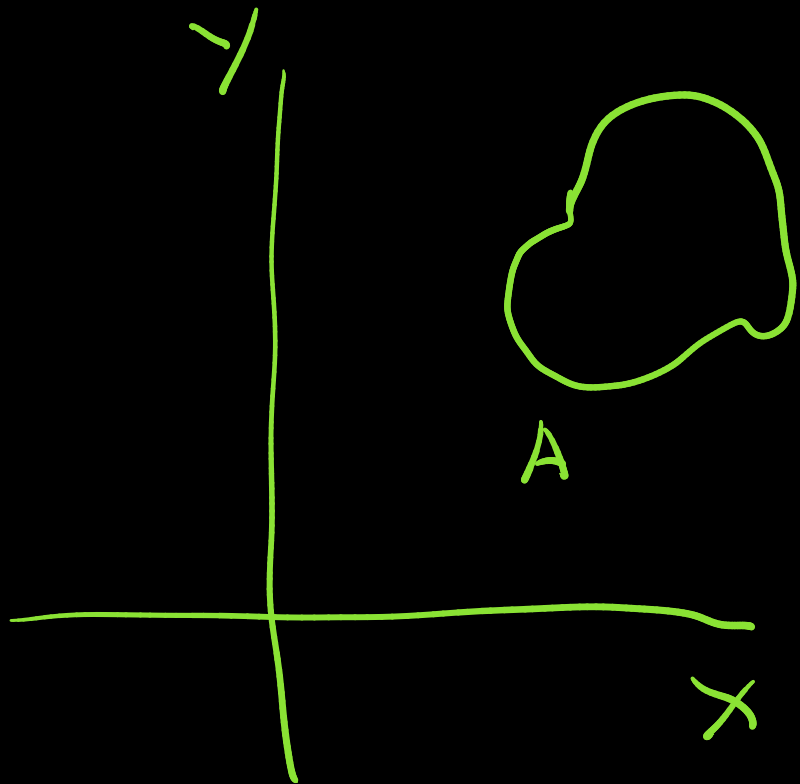
on  $g(I)$

$$= f_x(g^{-1}(y)) \times \left| \frac{d}{dy} g^{-1}(y) \right|$$

How does this work in  $\mathbb{R}^2$ ?



$$P((x, y) \in A) = \iint_A f_{xy}(x, y) dx dy$$



$$P\{(x, y) \in A\} = \iint_A f_{xy}(x, y) dx dy$$

too big if  $g$  stretched area

$$P\{(u, v) \in g(A)\} = \iint f_{xy}[x'(u, v), y'(u, v)] du dv$$

need to undo stretching  $g(A)$

stretching by  $g$

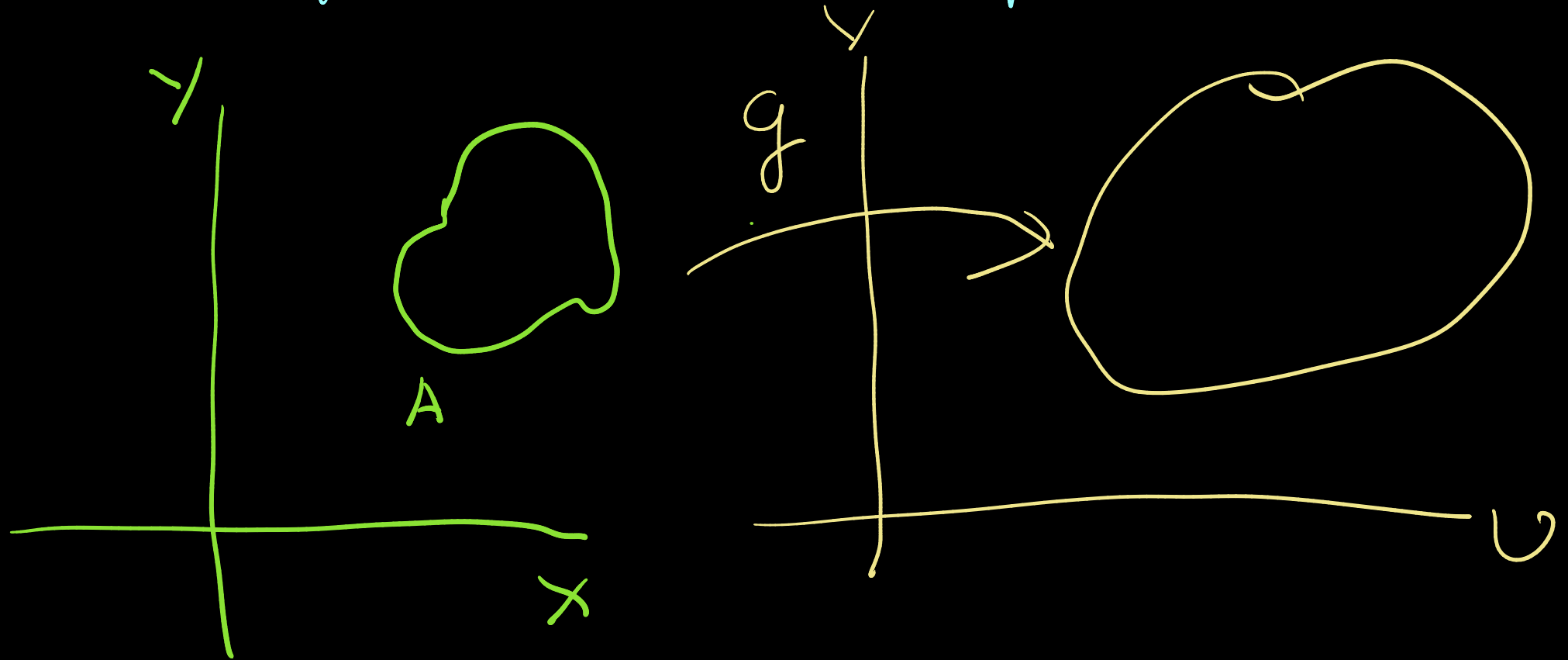
$$= \iint_{g(A)} \frac{f_{xy}(g^{-1}(u, v))}{\left| \frac{d(u, v)}{d(x, y)} \right|} du dv \quad \left. \vphantom{\frac{f_{xy}(g^{-1}(u, v))}{\left| \frac{d(u, v)}{d(x, y)} \right|}} \right\} \begin{array}{l} \text{stretching} \\ \text{by } g \end{array}$$

$$= \iint_{g(A)} f_{xy}(g^{-1}(u, v)) \underbrace{\|J_{g^{-1}}(u, v)\|}_{\text{shrinking by } g^{-1}} du dv$$

So:  $f_{uv}(u, v) = f_{xy}(g^{-1}(u, v)) \underbrace{\|J_{g^{-1}}(u, v)\|}_{\substack{\text{Absolute value of} \\ \text{Jacobian determinant}}}$

$\underbrace{\|J_{g^{-1}}(u, v)\|}_{\substack{\text{Jacobian matrix} \\ \text{Jacobian determinant}}}$

What is  $|J|$ : Determinant of Jacobian Matrix



How much does  $g$  (stretch or shrink) area?



$$J_g(x, y) = \begin{bmatrix} \frac{du}{dx} & \frac{du}{dy} \\ \frac{dv}{dx} & \frac{dv}{dy} \end{bmatrix}$$

$$\underbrace{\left| \overbrace{J_g(x, y)}^{\text{determinant}} \right|}_{\text{absolute value}}$$

$$\underbrace{\left| \overbrace{\frac{du}{dx} \cdot \frac{dv}{dy} - \frac{dv}{dx} \frac{du}{dy}}^{\text{determinant}} \right|}_{\text{absolute value.}}$$

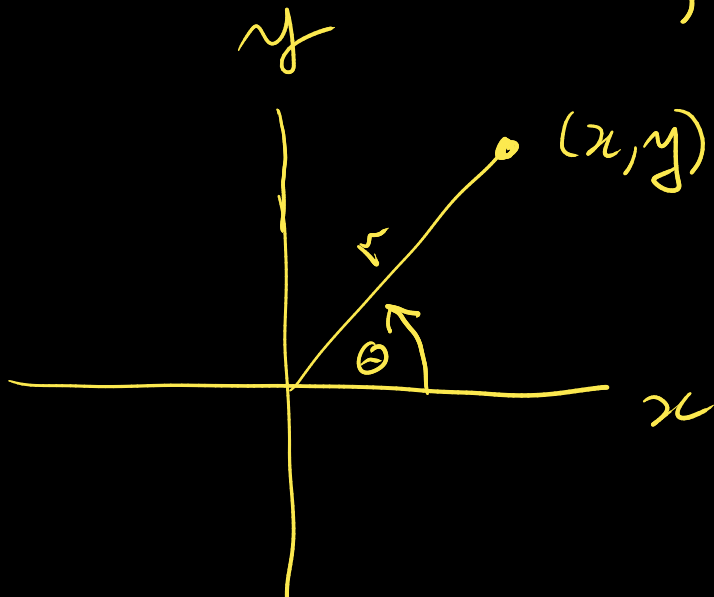
# Example: Polar coordinates

Let  $(X, Y)$  have a bivariate standard normal distribution:

$$f(x, y) = \frac{1}{2\pi} e^{-\frac{1}{2}(x^2 + y^2)}$$

$$-\infty < x < \infty$$

$$-\infty < y < \infty$$



Let  $g$  be transformation to polar co-ordinates.

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}(y/x)$$

Inverse easier

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r \geq 0, \quad 0 \leq \theta < 2\pi$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = g^{-1} \begin{pmatrix} r \\ \theta \end{pmatrix}$$

The arc-tangent of two arguments  $\text{atan2}(y, x)$  returns the angle between the x-axis and the vector from the origin to  $(x, y)$ , i.e., for positive arguments  $\text{atan2}(y, x) == \text{atan}(y/x)$ .

$$\theta = \begin{cases} \tan^{-1}(y/x) & \text{if } x > 0 \\ \tan^{-1}(y/x) + \pi & \text{if } x < 0 \\ \frac{\pi}{2} \text{sgn}(y) & \text{if } x = 0, y \neq 0 \\ 0 & \text{if } x = y = 0 \end{cases}$$

$$J_{g^{-1}}(r, \theta) = \begin{bmatrix} \frac{dx}{dr} & \frac{dx}{d\theta} \\ \frac{dy}{dr} & \frac{dy}{d\theta} \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & r \times (-\sin \theta) \\ \sin \theta & r \cos \theta \end{bmatrix}$$

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

$$|J_{g^{-1}}| = r \cos^2 \theta - r(-\sin^2 \theta) = r(\cos^2 \theta + \sin^2 \theta) = r$$

$\|J_{g^{-1}}\| = |r| = r$  since  $r > 0$  anyways.

$$f_{x,y}(x,y) = \frac{1}{2\pi} e^{-\frac{1}{2}(x^2+y^2)}$$

$$f_{R,\theta}(r,\theta) = \left( \frac{1}{2\pi} e^{-\frac{1}{2}r^2} \right) \times r, \quad \begin{array}{l} r > 0 \\ \underline{0 < \theta < 2\pi} \end{array}$$

See where  $\frac{1}{2\pi}$  came from!

Now let  $Z = R^2$

If one variable stays the same  
you don't need to work out the Jacobian

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$$\begin{pmatrix} z \\ \theta \end{pmatrix} = g \begin{pmatrix} R \\ \theta \end{pmatrix} = \begin{pmatrix} R^2 \\ \theta \end{pmatrix}$$

Note: Even if this is not 0  
we still have  $J_g = \frac{dz}{dr}$

$$J_g = \begin{bmatrix} \frac{dz}{dr} & \frac{dz}{d\theta} \\ \frac{d\theta}{dr} & \frac{d\theta}{d\theta} \end{bmatrix} = \begin{bmatrix} 2R & 0 \\ 0 & 1 \end{bmatrix} = 2R$$

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$$f_{z,\theta}(z,\theta) = \left( \text{Substitute } z,\theta \text{ in } f_{r,\theta} \right) \times \left| \frac{dr}{dz} \right|$$

$$= \frac{1}{2\pi} e^{-\frac{1}{2}r^2} \times r \times \left| \frac{dr}{dz} \right|$$

$$\begin{aligned} z &= r^2 \\ \theta &= \theta \end{aligned}$$

$$= \frac{1}{2\pi} e^{-\frac{1}{2}z} \times \sqrt{z} \times \frac{1}{2} z^{-1/2}$$

$$r = \sqrt{z}$$

$$= \frac{1}{2\pi} \frac{1}{2} e^{-\frac{1}{2}z}, \quad z > 0, \quad 0 < \theta < 2\pi$$

$$\frac{dr}{dz} = \frac{1}{2} z^{-1/2}$$

$$= \underbrace{f_{\theta}(\theta)}_{U(0, 2\pi)} \times \underbrace{f_z(z)}_{\text{Exponential}(1/2)}$$

Independent.

Note: This gives us a way of  
 generating random standard normals  
 in pairs even though it is very difficult  
 to generate them one at a time.

How?



