

Lab: 03

Group No-10

Controlling the LEDs of MDA-8086 Kit

Objectives:

To interface LEDs with 8086 microprocessors by 8255 PPI

Basic Theory:

♦ **Controlling LEDs in MDA 8086 Kit:**

There are 4 LEDs namely RED (L1), GREEN (L2), Yellow(L3) and RED (L4) inside the MDA-8086 Trainer kit and can be modeled to design a simpler application. This requires 8255 PPI ports which are already connected to the 4 LEDs internally. Through a code we can access these ports and provide binary or hex values to switch on the required LED (on or OFF). In order to turn a particular LED ON, a logical '1' should be provided to a particular port. Note that only Port B of 8255A PPI is used in the following code to control the LEDs.

RED(L1)	GREEN(L2)
YELLOW(L3)	RED(L4)

Different ports of programmable peripherals interface (PPI) 8255 is used for switching on LEDs, the addresses of the ports are:

Port A: 19h

✓ Port B: 1Bh

Port C: 1Dh

✓ Control register: 1Fh



To control the LEDs, port B will be used for the value to select the LEDs and Port A and C will be set with constant values. In-case of Port B, pass a value of '11110001' to select the L1 LED and pass a value of '11110010' to select the L2 LED and so on.

Example Example code to illuminate LEDs with a sequence of L1, L2, L3 and L4.

CODE SEGMENT

ASSUME CS: CODE, DS: CODE

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PPIC_C EQU 1FH ✓ ; Control register address
PPIC EQU 1DH ✓ ; Port C address
PPIB EQU 1BH ✓ ; Port B address
PPIA EQU 19H ✓ ; Port A address

ORG 1000H ;The code is placed at offset 1000h
MOV AL, 10000000B ;Mode set for Control Word to control 8255 PPI
OUT PPIC_C, AL ; Control register
MOV AL, 11111111B ; 7 segment Display
OUT PPIA, AL
MOV AL, 00000000B ; ADC Controller connected to
OUT PPIC, AL

L1: MOV AL, 11110001B ; I/O Related for LED
L2: OUT PPIB, AL ; Select a L1 LED with AL value and make it ON
CALL TIMER
SHL AL, 1
TEST AL, 00010000B ; Perform Logical AND and set Zero Flag (ZF), SF, PF
JNZ L1
OR AL, 11110000B ; Perform Logical OR and store the result in AL
JMP L2
INT 3 ; Single-step interrupt

TIMER: MOV CX, 1
TIMER2: PUSH CX
MOV CX, 0
TIMER1: NOP
NOP
NOP
NOP
LOOP TIMER1
    
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POP CX
LOOP TIMER2
RET

```

CODE ENDS
END

Experiment Procedure:

1. Write the above program in notepad and save the file as "filename.asm". Place this file in the folder where "masm.exe" exists.
2. Go to the command prompt and execute "masm.exe". You will see the following message:
Microsoft (R) Macro Assembler Version 5.10
Copyright (C) Microsoft Corp 1981, 1988. All right reserved
Source filename [ASM]
3. Follow the procedure given below to prepare machine code for your program.
Source filename [ASM]: filename Press ENTER
Object filename [C:\file name.OBJ]: Press ENTER
Source listing [NUL.LST]: filename Press ENTER
Cross reference [NUL.CRF]: Press ENTER
4. Execute "LOD186.exe". You will see the following message: Paragon LOD186 Loader-Version 4.0h
Copyright (C) 1983 - 1986 Microtec Research Inc.
ALL RIGHT RESERVED
Object/Command File [OBJ].
5. Follow the procedure given below to prepare HEX (ABS) file for your program:

Object/Command File	[OBJ]:	
	filename	Press ENTER
Output Object File	[C:\filename.ABS]:	Press ENTER
Map Filename	[C:\NUL.MAP]	Press ENTER

****LOAD COMPLETE**

6. Turn on the 8086 microprocessor kit.
7. Open the "Wincomm" window. Press "L" then "Enter". You will see the following message:

** Serial Monitor 1.0 **
** Midas 335-0964/5 **
8086 >L. Press ENTER
Down load start!!
8. Strike PgUp or F3 key of your keyboard. A new window will appear. Locate the "filename.ABS" file and open it.
9. You will observe that file download has started. A message like the following one will be shown:
:14100000B800008ED88EC0BB00208B078A6F028A4F038BB6
:101014003E8B5604268B76068B7E088B1E0A20CCCC
0E20000012345678ABCD0146853B1C41020E2
:00000001FF
OK completed!!
10. After loading the program, run the program in (press G from the keyboard, then press enter) in MDA-8086 kit and ensure the display output.

Task to do:

Write a program to illuminate LEDs for implementation of Simple Traffic Control Light Signaling model. Vehicles will be STOP (with red color), WAIT (with yellow color) & GO (i.e., with green color) states for a moderately long time and vice-versa.

