

Exact Hessian

```

0 #
1 #
2 #
3 #
4 #
5 #
6 #

11 from casadi import *
12 from numpy import *
13 import casadi as c

    We will investigate the use of an exact Hessian with the help of the Rosenbrock function

16 x= SX.sym('x')
17 y= SX.sym('y')
18 obj = (1-x)**2+100*(y-x**2)**2
19 constr = x**2+y**2
20 nlp={ 'x':vertcat(x,y), 'f':obj, 'g':constr}

    We solve the problem with an exact Hessian (default)

23 solver = nlpsol('solver', 'ipopt', nlp)
24 sol = solver(lbx=-10, ubx=10, lbg=0, ubg=1)

```

This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).

For more information visit <http://projects.coin-or.org/Ipopt>

This is Ipopt version 3.12.3, running with linear solver ma57.

```

Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 2
Number of nonzeros in Lagrangian Hessian.....: 3

Total number of variables.....: 2
    variables with only lower bounds: 0
    variables with lower and upper bounds: 2
    variables with only upper bounds: 0
Total number of equality constraints.....: 0
Total number of inequality constraints.....: 1
    inequality constraints with only lower bounds: 0
    inequality constraints with lower and upper bounds: 1
    inequality constraints with only upper bounds: 0

iter   objective    inf_pr   inf_du lg(mu)  ||d||  lg(rg) alpha_du
alpha_pr ls
  0  1.0000000e+00  0.00e+00  2.00e+00  -1.0  0.00e+00  -  0.00e+00  0.00e
    +00  0

```

```

1  6.8309610e+01  0.00e+00  4.32e+02  -1.0  9.09e-01  -  1.36e-02  1.00e
    +00H  1
2  6.2418830e+00  0.00e+00  7.25e+01  -1.0  3.06e-01  -  6.76e-01  1.00e
    +00F  1
3  6.3023184e-02  0.00e+00  5.46e-01  -1.0  2.58e-01  -  9.97e-01  1.00e
    +00f  1
4  6.5589711e-02  0.00e+00  5.27e-03  -1.7  4.84e-02  -  1.00e+00  1.00e
    +00h  1
5  5.0619847e-02  0.00e+00  3.07e-01  -3.8  9.95e-02  -  9.05e-01  1.00e
    +00f  1
6  4.6180852e-02  0.00e+00  2.45e-02  -3.8  3.71e-02  -  1.00e+00  1.00e
    +00h  1
7  4.5822797e-02  0.00e+00  1.76e-04  -3.8  3.26e-03  -  1.00e+00  1.00e
    +00h  1
8  4.5677137e-02  0.00e+00  3.59e-05  -5.7  1.20e-03  -  1.00e+00  1.00e
    +00h  1
9  4.5676652e-02  0.00e+00  3.22e-10  -5.7  4.39e-06  -  1.00e+00  1.00e
    +00h  1
iter   objective    inf_pr   inf_du lg(mu)  ||d||  lg(rg) alpha_du
alpha_pr ls
10  4.5674810e-02  0.00e+00  5.78e-09  -8.6  1.52e-05  -  1.00e+00  1.00e
    +00h  1

```

Number of Iterations.....: 10

	(scaled)	(unscaled)
Objective.....:	4.5674810088672947e-02	4.5674810088672947e-02
Dual infeasibility.....:	5.7761012971635439e-09	5.7761012971635439e-09
Constraint violation.....:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity.....:	2.5919940506206774e-09	2.5919940506206774e-09
Overall NLP error.....:	5.7761012971635439e-09	5.7761012971635439e-09

```

Number of objective function evaluations = 14
Number of objective gradient evaluations = 11
Number of equality constraint evaluations = 0
Number of inequality constraint evaluations = 14
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 11
Number of Lagrangian Hessian evaluations = 10
Total CPU secs in IPOPT (w/o function evaluations) = 0.003
Total CPU secs in NLP function evaluations = 0.001

```

EXIT: Optimal Solution Found.

	proc	wall mean	num	mean
	time	time	evals	proc time
nlp_f	0.000 [s]	0.000 [s]	14	0.00 [ms]
0.00 [ms]				
nlp_g	0.000 [s]	0.000 [s]	14	0.00 [ms]

```

0.01 [ms]
nlp_grad_f 0.000 [s] 0.000 [s] 12 0.00 [ms]
0.00 [ms]
nlp_jac_g 0.000 [s] 0.000 [s] 12 0.00 [ms]
0.00 [ms]
nlp_hess_l 0.000 [s] 0.000 [s] 10 0.00 [ms]
0.01 [ms]
all previous 0.000 [s] 0.000 [s]
callback_prep 0.000 [s] 0.000 [s] 11 0.00 [ms]
0.00 [ms]
solver 0.010 [s] 0.006 [s]
mainloop 0.010 [s] 0.006 [s]

```

```
25 print 'Optimal solution (exact Hessian): %s' % sol['x']
```

```
Optimal solution (exact Hessian): [0.786415, 0.617698]
```

```
Same problem but with limited memory BFGS
```

```
28 solver = nlpsol('solver', 'ipopt', nlp, {'ipopt.hessian_approximation':
29 limited-memory'})
sol = solver(lbx=-10, ubx=10, lbx=0, ubg=1)
```

```
This is Ipopt version 3.12.3, running with linear solver ma57.
```

```

Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 2
Number of nonzeros in Lagrangian Hessian.....: 0

```

```

Total number of variables.....: 2
    variables with only lower bounds: 0
    variables with lower and upper bounds: 2
    variables with only upper bounds: 0

```

```

Total number of equality constraints.....: 0
Total number of inequality constraints.....: 1
    inequality constraints with only lower bounds: 0
    inequality constraints with lower and upper bounds: 1
    inequality constraints with only upper bounds: 0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
0	1.0000000e+00	0.00e+00	2.00e+00	0.0	0.00e+00	-	0.00e+00 0.00e
1	8.1099664e-01	0.00e+00	8.51e+00	-5.2	1.67e+00	-	8.49e-01 1.24e
2	7.8913241e-01	0.00e+00	7.56e+00	-0.7	3.79e-01	-	2.45e-01 1.00e
3	5.1038399e-01	0.00e+00	2.00e+00	-1.6	1.47e-01	-	1.00e+00 1.00e
4	9.4636921e-01	0.00e+00	1.66e+01	-1.7	2.10e-01	-	6.36e-01 1.00e
5	4.3659026e-01	0.00e+00	8.99e-01	-2.6	1.70e-01	-	1.00e+00 1.00e
6	3.9428196e-01	0.00e+00	8.08e-01	-3.2	5.30e-02	-	1.00e+00 1.00e
7	1.5277780e+00	0.00e+00	3.32e+01	-4.2	3.31e-01	-	4.87e-01 1.00e
8	3.5006028e-01	0.00e+00	1.56e+00	-3.3	5.71e-01	-	1.00e+00 1.00e

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
9	3.1926755e-01	0.00e+00	1.63e+00	-3.9	1.60e-01	-	1.00e+00 1.00e
10	2.7958742e-01	0.00e+00	4.47e+00	-4.1	8.31e+00	-	1.00e+00 1.15e
11	4.1529404e-01	0.00e+00	1.74e+01	-4.6	3.79e-01	-	7.49e-01 1.00e
12	1.9552435e-01	0.00e+00	7.94e+00	-3.4	1.93e-01	-	1.00e+00 1.00e
13	1.0284176e-01	0.00e+00	1.20e+00	-4.6	5.10e-02	-	1.00e+00 1.00e
14	7.9168874e-02	0.00e+00	1.74e+00	-6.0	1.24e-01	-	1.00e+00 1.00e
15	6.4711554e-02	0.00e+00	3.50e+00	-7.3	1.52e-01	-	1.00e+00 1.00e
16	5.5234143e-02	4.93e-03	3.01e+00	-4.6	1.34e-01	-	1.00e+00 3.44e
17	4.7148548e-02	0.00e+00	9.32e-01	-4.3	7.45e-03	-	1.00e+00 1.00e
18	4.5698648e-02	0.00e+00	1.46e-01	-6.0	6.27e-03	-	1.00e+00 8.55e
19	4.5674859e-02	0.00e+00	1.07e-03	-6.7	1.78e-04	-	1.00e+00 9.95e
20	4.5674809e-02	0.00e+00	1.79e-07	-8.8	1.52e-06	-	1.00e+00 1.00e
21	4.5674808e-02	0.00e+00	2.24e-09	-11.0	1.39e-08	-	1.00e+00 1.00e

```
Number of Iterations....: 21
```

	(scaled)	(unscaled)
Objective.....	4.5674807514535586e-02	4.5674807514535586e
Dual infeasibility.....	2.2446746822391006e-09	2.2446746822391006e
Constraint violation....	0.0000000000000000e+00	0.0000000000000000e
Complementarity.....	1.0000913016783289e-11	1.0000913016783289e
Overall NLP error.....	2.2446746822391006e-09	2.2446746822391006e

```

Number of objective function evaluations = 36
Number of objective gradient evaluations = 22
Number of equality constraint evaluations = 0
Number of inequality constraint evaluations = 36
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 22
Number of Lagrangian Hessian evaluations = 0
Total CPU secs in IPOPT (w/o function evaluations) = 0.007
Total CPU secs in NLP function evaluations = 0.000

```

EXIT: Optimal Solution Found.

	proc	time	wall time	wall mean time	num evals	mean proc time
nlp_f	0.000 [s]	0.000 [s]	0.000 [s]	36	0.00 [ms]	
nlp_g	0.000 [s]	0.000 [s]	0.000 [s]	36	0.00 [ms]	
nlp_grad_f	0.000 [s]	0.000 [s]	0.000 [s]	23	0.00 [ms]	
nlp_jac_g	0.000 [s]	0.000 [s]	0.000 [s]	23	0.00 [ms]	
all previous	0.000 [s]	0.000 [s]	0.000 [s]	22	0.00 [ms]	
callback_prep	0.000 [s]	0.000 [s]	0.000 [s]	22	0.00 [ms]	
solver	0.020 [s]	0.015 [s]	0.015 [s]			
mainloop	0.020 [s]	0.015 [s]	0.015 [s]			

30

```
print 'Optimal solution (BFGS): %s' % sol['x']
```

Optimal solution (BFGS): [0.786415, 0.617698]