CasADi tutorial

```
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 4
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        This tutorial file explains the use of structures Structures are a python-only feature from the tools library:
15
    from casadi.tools import *
        The struct tools offer a way to structure your symbols and data It allows you to make abstraction of ordering and
     indices.
        Put simply, the goal is to eleminate code with 'magic numbers' numbers such as:
                 f = Function('f', [V], [V[214]]) # time ... x_opt = solver.getOutput()[::5] # Obtain all
                 optimized x's
           and replace it with f = Function('f', [V], [V["T"]]) ... shooting(solver.getOutput())["x",:]
     Introduction
     Create a structured SX.sym
     states = struct_symSX(["x", "y", "z"])
34
35
     print states
        symbolic SX with following structure:
        Structure with total size 3.
        Structure holding 3 entries.
          Order: ['x', 'y', 'z']
          v = 1-bv-1 (dense)
          x = 1-by-1 (dense)
          z = 1-by-1 (dense)
        Superficially, states behaves like a dictionary
    print states["y"]
        To obtain aliases, use the Ellipsis index:
   x, y, z = states[...]
        The cat attribute will return the concatenated version of the struct. This will always be a column vector
     print states.cat
```

[x, y, z]

3 = (3, 1)

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This structure is of size:

print states.size, "=", states.cat.shape

```
f = Function('f', [states.cat], [x*y*z])
       In many cases, states will be auto-cast to SX:
f = Function ('f', [states], [x*y*z])
    Expanded structure syntax and ordering
    The structure definition above can also be written in expanded syntax:
    simplestates = struct_symSX([
64
        entry ("x"),
65
         entry("y"),
66
         entry ("z")
67
      1)
    More information can be attached to the entries shape argument: specify sparsity/shape
    states = struct_symSX([
71
72
        entry ("x", shape=3),
        entry ("y", shape=(2,2)),
73
74
        entry ("z", shape=Sparsity.lower(2))
75
      1)
76
    print states["x"]
      [x_0, x_1, x_2]
   print states["y"]
      [[y_0, y_2],
       [y_1, y_3]
    print states["z"]
      [[z_0, 00],
       [z_1, z_2]]
       Note that the cat version of this structure does only contain the nonzeros
    print states.cat
      [x 0, x 1, x 2, y 0, y 1, y 2, y 3, z 0, z 1, z 2]
       repeat argument: specify nested lists
    states = struct_symSX([
85
        entry ("w", repeat=2),
86
         entry ("v", repeat=[2,3]),
87
      1)
    print states["w"]
      [SX(w_0), SX(w_1)]
   print states["v"]
```

 $[[SX(v_0_0), SX(v_0_1), SX(v_0_2)], [SX(v_1_0), SX(v_1_1), SX(v_1_2)]]$

Notice that all v variables come before the v entries:

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```
for i,s in enumerate(states.labels()):
91
92
       print i, s
       0 [w, 0, 0]
       1 [w,1,0]
       2 [v, 0, 0, 0]
       3 [v, 0, 1, 0]
       4 [v, 0, 2, 0]
       5 [v, 1, 0, 0]
       6 [v,1,1,0]
       7 [v,1,2,0]
        We can influency this order by introducing a grouping bracket:
101
102
     states = struct symSX([
103
         "a",
104
          ( entry ("w", repeat=2),
```

Notice how the w and v variables are now interleaved:

entry ("v", repeat=[2,3])

```
105
    for i,s in enumerate(states.labels()):
      print i, s
106
      0 [a,0]
      1 [w, 0, 0]
      2 [v,0,0,0]
      3 [v, 0, 1, 0]
      4 [v, 0, 2, 0]
      5 [w, 1, 0]
      6 [v,1,0,0]
      7 [v,1,1,0]
      8 [v,1,2,0]
```

Nesting, Values and PowerIndex

Structures can be nested. For example consider a statespace of two cartesian coordinates and a quaternion

```
111
    states = struct symSX(["x", "y", entry("q", shape=4)])
112
113
    shooting = struct symSX([
114
      entry ("X", repeat=[5,3], struct=states),
115
      entry ("U", repeat=4, shape=1),
116
    1)
117
118
    print shooting.size
```

94

105

106

107 108 "b

9 [b, 0]

1)

The canonicalIndex is the combination of strings and numbers that uniquely defines the entries of a structure:

```
121
    print shooting["X", 0, 0, "x"]
       X_0_0_x
```

If we use more exoctic indices, we call this a powerIndex

```
124
   print shooting["X",:,0,"x"]
```

```
[SX(X_0_0_x), SX(X_1_0_x), SX(X_2_0_x), SX(X_3_0_x), SX(X_4_0_x)]
```

Having structured symbolics is one thing. The numeric structures can be derived: The following line allocates a DM of correct size, initialised with zeros

```
init = shooting(0)
print init.cat
[init["X", 0, -1, "y"] = 12]
```

The corresponding numerical value has changed now:

```
print init.cat
The entry that changed is in fact this one:
```

print init.f["X", 0, -1, "y"]

[13]

print init.cat[13]

12

145

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One can lookup the meaning of the 13th entry in the cat version as such: Note that the canonicalIndex does not contain negative numbers

```
print shooting.getCanonicalIndex (13)
```

```
print shooting.labels()[13]
```

(X', 0, 2, Y', 0)

```
146
```

[X, 0, 2, y, 0]

Other datatypes

A symbolic structure is immutable

```
156
      states["x"] = states["x"]**2
158
    except Exception as e:
      print "Oops:", e
```

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```
Oops: 'ssymStruct' object does not support item assignment
        If you want to have a mutable variant, for example to contian the right hand side of an ode, use struct_SX:
     rhs = struct SX(states)
159
160
     rhs["x"] = states["x"]**2
161
     rhs["y"] = states["y"]*states["x"]
162
     rhs["q"] = -states["q"]
163
164
     print rhs.cat
       [sq(x), (y*x), (-q_0), (-q_1), (-q_2), (-q_3)]
        Alternatively, you can supply the expressions at defintion time:
    x,y,q = states[...]
167
168
     rhs = struct_SX([
169
         entry (x, expr=x*2),
170
         entry ("y", expr=x*y),
171
         entry ("q", expr=-q)
172
      1)
173
174
     print rhs.cat
       [sq(x), (x*y), (-q_0), (-q_1), (-q_2), (-q_3)]
        One can also construct symbolic MX structures
    V = struct symMX (shooting)
179
    print V
180
       MX.sym with following structure:
       Structure with total size 94.
       Structure holding 2 entries.
         Order: ['X', 'U']
         X = repeated([5, 3]): \{y: 1-by-1 (dense), x: 1-by-1 (dense), q: 4-by-1 (
         U = repeated([4]): 1-by-1 (dense)
        The catted version is one single MX from which all entries are derived:
     print V.cat
       V
     print V.shape
       (94, 1)
     print V["X", 0, -1, "y"]
       vertsplit\;(\,vertsplit\;(V)\;\{2\}\,)\;\{1\}
        Similar to struct_SX, we have struct_MX:
193
    V = struct MX(I
194
195
         entry ("X", expr=[[ MX.sym("x", 6) \star \star 2 for j in range (3)] for i in range (5)])
         entry ("U", expr=[ -MX.sym("u") for i in range (4)])
196
197
198
       ])
```

By default SX.sym structure constructor will create new SX.syms. To recycle one that is already available, use the 'sym' argument:

```
gsym = SX.sym("quaternion", 4)
198
    states = struct_symSX(["x","y",entry("q",sym=qsym)])
199
    print states.cat
```

[x, y, quaternion_0, quaternion_1, quaternion_2, quaternion_3] The 'sym' feature is not available for struct_MX, since it will construct one parent MX.

More powerIndex

As illustrated before, powerIndex allows slicing

```
print init["X",:,:,"x"]
  [[DM(0), DM(0), DM(0)], [DM(0), DM(0), DM(0)], [DM(0), DM(0), DM(0)], [DM(0), DM(0)]
       (0), DM(0), DM(0)], [DM(0), DM(0), DM(0)]
```

The repeated method duplicates its argument a number of times such that it matches the length that is needed at the lhs

```
init["X",:,:,"x"] = repeated(range(3))
210
 212
                                             print init ["X",:,:,"x"]
                                                                             [[DM(0), DM(1), DM(2)], [DM(0), DM(1), DM(1), DM(1), DM(1), DM(1)], [DM(0), DM(1), 
                                                                                                                                  (0), DM(1), DM(2)], [DM(0), DM(1), DM(2)]
```

Callables/functions can be thrown in in the powerIndex at any location. They operate on subresults obtain from resolving the remainder of the powerIndex

```
217
     print init["X",:,lambda v: horzcat(*v),:,"x"]
       [DM([[0, 1, 2]]), DM([[0, 1, 2]]))
            0, 1, 2]])]
     print init["X",lambda v: vertcat(*v),:,lambda v: horzcat(*v),:,"x"]
```

```
[[0, 1, 2],
[0, 1, 2],
 [0, 1, 2],
 [0, 1, 2],
 [0, 1, 2]]
```

print init["X", blockcat,:,:,"x"]

```
[[0, 1, 2],
 [0, 1, 2],
 [0, 1, 2],
 [0, 1, 2],
 [0, 1, 2]]
```

Set all quaternions to 1,0,0,0

```
222 | init["X",:,:,"q"] = repeated (repeated (DM([1,0,0,0])))
```

{} can be used in the powerIndex to expand into a dictionary once

```
225 [init["X",:,0,{}] = repeated({"y": 9})
```

```
226
227
    print init["X",:,0,{}]
       [{'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0])}, {'y': DM(9), 'x': DM(0),
             'q': DM([1, 0, 0, 0])}, {'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0]
           )}, {'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0])}, {'y': DM(9), 'x':
            DM(0), 'q': DM([1, 0, 0, 0])}
        lists can be used in powerIndex in both list context or dict context:
    print shooting["X",[0,1],[0,1],"x"]
230
       [[SX(X_0_0_x), SX(X_0_1_x)], [SX(X_1_0_x), SX(X_1_1_x)]]
    print shooting["X",[0,1],0,["x","y"]]
       [[SX(X_0_0_x), SX(X_0_0_y)], [SX(X_1_0_x), SX(X_1_0_y)]]
        nesteddict can be used to expand into a dictionary recursively
    print init[nesteddict]
       {'X': [[{'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0])}, {'y': DM(0), 'x':
            DM(1), 'q': DM([1, 0, 0, 0])}, {'y': DM(12), 'x': DM(2), 'q': DM([1, 0, 0])
           0, 0, 0])}], [{'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0])}, {'y':
           DM(0), 'x': DM(1), 'q': DM([1, 0, 0, 0])}, {'y': DM(0), 'x': DM(2), 'q
            ': DM([1, 0, 0, 0])}], [{'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0, 0])
            }, {'y': DM(0), 'x': DM(1), 'q': DM([1, 0, 0, 0])}, {'y': DM(0), 'x':
           DM(2), 'q': DM([1, 0, 0, 0])], [{'y': DM(9), 'x': DM(0), 'q': DM([1, 0, 0])]
           0, 0, 0])}, {'y': DM(0), 'x': DM(1), 'q': DM([1, 0, 0, 0])}, {'y': DM
            (0), 'x': DM(2), 'q': DM([1, 0, 0, 0])}], [{'y': DM(9), 'x': DM(0), 'q
            ': DM([1, 0, 0, 0])}, {'y': DM(0), 'x': DM(1), 'q': DM([1, 0, 0, 0])},
            { (y': DM(0), 'x': DM(2), 'q': DM([1, 0, 0, 0]) }], 'U': [DM(0), DM(0)] }
            , DM(0), DM(0)]}
        ... will expand entries as an ordered list
    print init["X",:,0,...]
       [[DM(0), DM(9), DM([1, 0, 0, 0])], [DM(0), DM(9), DM([1, 0, 0, 0])], [DM(0), DM(9), DM(1, 0, 0, 0])]
            (0), DM(9), DM([1, 0, 0, 0])], [DM(0), DM(9), DM([1, 0, 0, 0])], [DM
            (0), DM(9), DM([1, 0, 0, 0])]]
        If the powerIndex ends at the boundary of a structure, it's catted version is returned:
    print init["X",0,0]
       [0, 9, 1, 0, 0, 0]
       If the powerIndex is longer than what could be resolved as structure, the remainder, extraIndex, is passed onto
    the resulting Casadi-matrix-type
    print init["X", blockcat,:,:,"q",0]
       [[1, 1, 1],
        [1, 1, 1],
        [1, 1, 1],
        [1, 1, 1],
        [1, 1, 1]]
245
    print init["X", blockcat,:,:,"q",0,0]
```

```
[[1, 1, 1],
[1, 1, 1],
[1, 1, 1],
[1, 1, 1],
[1, 1, 1]]
```

shapeStruct and delegated indexing

When working with covariance matrices, both the rows and columns relate to states

P has a 4x4 shape

```
print V["P", 0]
```

```
[[P_0_0, P_0_4, P_0_8, P_0_12], [P_0_1, P_0_5, P_0_9, P_0_13], [P_0_2, P_0_6, P_0_10, P_0_14], [P_0_3, P_0_7, P_0_11, P_0_15]]
```

Now we can use powerIndex-style in the extraIndex:

```
print V["P",0,["x","y"],["x","y"]]
```

```
[[P_0_0, P_0_4],
[P_0_1, P_0_5]]
```

There is a problem when we wich to use the full potential of powerIndex in these extraIndices: The following is in fact invalid python syntax:

We resolve this by using delegater objects index/indexf:

```
269
270 print V["P",0,indexf["q",:],indexf["q",:]]
```

```
[[P_0_10, P_0_14], [P_0_11, P_0_15]]
```

Of course, in this basic example, also the following would be allowed

```
print V["P",0,"q","q"]
```

```
[[P_0_10, P_0_14], [P_0_11, P_0_15]]
```

Prefixing

The prefix attribute allows you to create shorthands for long powerIndices

```
279

280  states = struct(["x","y","z"])

V = struct_symSX([
```

337

```
entry ("X", repeat=[4,5], struct=states)
283
     1)
284
285
    num = V()
        Consider the following statements:
288
289
     num["X", 0, 0, "x"] = 1
290
     num["X", 0, 0, "y"] = 2
291
    num["X", 0, 0, "z"] = 3
        Note the common part ["X",0,0]. We can pull this apart with prefix:
295
296
     initial = num.prefix["X",0,0]
297
```

This is equivalent to the longer statements above

Helper constructors

initial["x"] = 1

initial["v"] = 2initial["z"] = 3

298

299

300

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print output

If you work with Simulator, ControlSimulator, you typically end up with wanting to index a DM that is n x N with n the size of a statespace and N an arbitrary integer

```
310
     states = struct(["x", "y", "z"])
311
         We artificially construct here a DM that could be a Simulator output.
     output = DM.zeros(states.size,8)
         The helper construct is 'repeated' here. Instead of "states(output)", we have
     outputs = states.repeated(output)
                                                                                                          354
         Now we have an object that supports powerIndexing:
     outputs [-1] = DM([1,2,3])
320
     outputs [:, "x"] = range(8)
321
```

```
[[0, 1, 2, 3, 4, 5, 6, 7],
  [0, 0, 0, 0, 0, 0, 0, 2],
   [0, 0, 0, 0, 0, 0, 0, 3]]
print outputs[5,{}]
  \{ y': DM(0), x': DM(5), z': DM(0) \}
```

Next we represent the 'squared' helper construct Imagine we somehow obtain a matrix that represents covariance

```
P0 = DM.zeros(states.size, states.size)
```

We can conveniently access it as follows:

```
P = states.squared(P0)
   P["x", "y"] = 2
331
332
   P["y", "x"] = 3
333
```

```
print P0
```

```
[[0, 2, 0],
 [3, 0, 0],
[0, 0, 0]]
```

P itself is a rather queer object

```
print P
```

```
prefix ( ('t',), Mutable DM (\{t: 3-by-3 (dense)\}))
```

You can access its concents with a call:

```
340
    print P()
```

```
[[0, 2, 0],
[3, 0, 0],
[0, 0, 0]]
```

But often, it will behave like a DM transparantly:

```
343 P0 + P
```

353

Next we represent the 'squared' repeated' helper construct Imagine we somehow obtain a matrix that represents a horizontal concatenation of covariance

```
347
    PO = horzcat (DM.zeros (states.size, states.size), DM.ones (states.size, states.
```

We can conveniently access it as follows:

```
P = states.squared repeated (P0)
   P[0, "x", "y"] = 2
352 P[:, "y", "x"] = 3
    print P0
```

```
[[0, 2, 0, 1, 1, 1],
[3, 0, 0, 3, 1, 1],
[0, 0, 0, 1, 1, 1]]
```

Finally, we present the 'product' helper construct

```
controls = struct(["u","v"])
357
358
359
    J0 = DM.zeros(states.size, controls.size)
360
361
    J = states.product(controls, J0)
362
363
    J[:,"u"] = 3
    J[["x", "z"], :] = 2
    print J()
```

```
[[2, 2],
 [3, 0],
 [2, 2]]
```

Saving and loading

It is possible to save and load some types of structures. Supported types are pure structures (the ones created with 'struct') and numeric structures.

Saving: mystructure.save("myfilename")

Loading:

struct_load("myfilename")

or pickle.load(file('myfilename','r'))