

NLPImplicitSolver

```

0  #
1  #
2  #
3  #
4  #
5  #
6  #

11 from casadi import *
12 from numpy import *
13 from pylab import *

    We will investigate the working of rootfinder with the help of the parametrically exited Duffing equation.
    Parameters

19 eps = SX.sym("eps")
20 mu = SX.sym("mu")
21 alpha = SX.sym("alpha")
22 k = SX.sym("k")
23 sigma = SX.sym("sigma")
24 params = [eps, mu, alpha, k, sigma]

    Variables

27 a = SX.sym("a")
28 gamma = SX.sym("gamma")

    Equations

31 res0 = mu*a+1.0/2*k*a*sin(gamma)
32 res1 = -sigma * a + 3.0/4*alpha*a**3+k*a*cos(gamma)

    Numerical values

35 sigma_ = 0.1
36 alpha_ = 0.1
37 k_ = 0.2
38 params_ = [0.1, 0.1, alpha_, k_, sigma_]

    We create a NLPImplicitSolver instance

41 f=Function("f", [vertcat(a, gamma), vertcat(*params)], [vertcat(res0, res1)])
42 opts = {}
43 opts["nlpsol"] = "ipopt"
44 opts["nlpsol_options"] = {"ipopt.tol":1e-14}
45 s=rootfinder("s", "nlpsol", f, opts)
46
47 x_ = s([1,-1], params_)

```

This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).

For more information visit <http://projects.coin-or.org/Ipopt>

This is Ipopt version 3.12.3, running with linear solver ma57.

```

Number of nonzeros in equality constraint Jacobian...: 4
Number of nonzeros in inequality constraint Jacobian.: 0
Number of nonzeros in Lagrangian Hessian.....: 3

```

```

Total number of variables.....: 2
    variables with only lower bounds: 0
    variables with lower and upper bounds: 0
    variables with only upper bounds: 0
Total number of equality constraints.....: 2
Total number of inequality constraints.....: 0
    inequality constraints with only lower bounds: 0
    inequality constraints with lower and upper bounds: 0
    inequality constraints with only upper bounds: 0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
	alpha_pr ls						
0	0.0000000e+00	8.31e-02	0.00e+00	-1.0	0.00e+00	-	0.00e+00 0.00e
	+00 0						
1	0.0000000e+00	1.23e-02	0.00e+00	-2.5	2.40e-01	-	1.00e+00 1.00e
	+00h 1						
2	0.0000000e+00	2.02e-03	0.00e+00	-3.8	2.00e-01	-	1.00e+00 1.00e
	+00h 1						
3	0.0000000e+00	1.28e-03	0.00e+00	-3.8	1.15e-01	-	1.00e+00 1.00e
	+00h 1						
4	0.0000000e+00	4.42e-05	0.00e+00	-5.7	2.96e-02	-	1.00e+00 1.00e
	+00h 1						
5	0.0000000e+00	2.30e-05	0.00e+00	-5.7	1.68e-02	-	1.00e+00 1.00e
	+00h 1						
6	0.0000000e+00	5.32e-06	0.00e+00	-5.7	8.03e-03	-	1.00e+00 1.00e
	+00h 1						
7	0.0000000e+00	1.34e-06	0.00e+00	-8.6	3.98e-03	-	1.00e+00 1.00e
	+00h 1						
8	0.0000000e+00	3.35e-07	0.00e+00	-8.6	1.98e-03	-	1.00e+00 1.00e
	+00h 1						
9	0.0000000e+00	8.38e-08	0.00e+00	-8.6	9.87e-04	-	1.00e+00 1.00e
	+00h 1						
iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
	alpha_pr ls						
10	0.0000000e+00	2.10e-08	0.00e+00	-8.6	4.93e-04	-	1.00e+00 1.00e
	+00h 1						
11	0.0000000e+00	5.24e-09	0.00e+00	-12.9	2.46e-04	-	1.00e+00 1.00e
	+00h 1						
12	0.0000000e+00	1.31e-09	0.00e+00	-12.9	1.23e-04	-	1.00e+00 1.00e
	+00h 1						
13	0.0000000e+00	3.28e-10	0.00e+00	-12.9	6.15e-05	-	1.00e+00 1.00e
	+00h 1						
14	0.0000000e+00	8.19e-11	0.00e+00	-12.9	3.08e-05	-	1.00e+00 1.00e
	+00h 1						
15	0.0000000e+00	2.05e-11	0.00e+00	-12.9	1.54e-05	-	1.00e+00 1.00e
	+00h 1						
16	0.0000000e+00	5.12e-12	0.00e+00	-12.9	7.69e-06	-	1.00e+00 1.00e
	+00h 1						
17	0.0000000e+00	1.28e-12	0.00e+00	-12.9	3.84e-06	-	1.00e+00 1.00e
	+00h 1						

```

18 0.0000000e+00 3.20e-13 0.00e+00 -12.9 1.92e-06 - 1.00e+00 1.00e
+00h 1
19 0.0000000e+00 8.00e-14 0.00e+00 -15.0 9.61e-07 - 1.00e+00 1.00e
+00h 1
iter   objective    inf_pr    inf_du lg(mu)  ||d||  lg(rg) alpha_du
alpha_pr  ls
20 0.0000000e+00 2.00e-14 0.00e+00 -15.0 4.80e-07 - 1.00e+00 1.00e
+00h 1
21 0.0000000e+00 5.04e-15 0.00e+00 -15.0 2.40e-07 - 1.00e+00 1.00e
+00h 1

```

Number of Iterations.....: 21

	(scaled)	(unscaled)
Objective.....:	0.0000000000000000e+00	0.0000000000000000e+00
Dual infeasibility.....:	0.0000000000000000e+00	0.0000000000000000e+00
Constraint violation.....:	5.0404780683255265e-15	5.0404780683255265e-15
Complementarity.....:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error.....:	5.0404780683255265e-15	5.0404780683255265e-15

Number of objective function evaluations	= 22
Number of objective gradient evaluations	= 22
Number of equality constraint evaluations	= 22
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 22
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 21
Total CPU secs in IPOPT (w/o function evaluations)	= 0.003
Total CPU secs in NLP function evaluations	= 0.001

EXIT: Optimal Solution Found.

	proc	time	wall time	num evals	mean proc time
nlp_f	0.000 [s]	0.000 [s]	22	0.00 [ms]	
0.00 [ms]					
nlp_g	0.000 [s]	0.000 [s]	22	0.00 [ms]	
0.01 [ms]					
nlp_grad_f	0.000 [s]	0.000 [s]	23	0.00 [ms]	
0.00 [ms]					
nlp_jac_g	0.000 [s]	0.000 [s]	23	0.00 [ms]	
0.01 [ms]					
nlp_hess_l	0.000 [s]	0.000 [s]	21	0.00 [ms]	
0.02 [ms]					
all previous	0.000 [s]	0.001 [s]			
callback_prep	0.000 [s]	0.000 [s]	22	0.00 [ms]	
0.01 [ms]					
solver	0.000 [s]	0.007 [s]			
mainloop	0.000 [s]	0.008 [s]			

```
48 print "Solution = ", x_
```

Solution = [1.1547, -1.5708]

Compare with the analytic solution:

```
51 x = [sqrt(4.0/3*sigma_/alpha_), -0.5*pi]
```

```
52 print "Reference solution = ", x
```

Reference solution = [1.1547005383792515, -1.5707963267948966]

We show that the residual is indeed (close to) zero

```
55 residual = f(x_, params_)
```

```
56 print "residual = ", residual
```

residual = [2.498e-15, 5.04048e-15]

```
59 for i in range(1):
60     assert(abs(x_[i]-x[i])<1e-6)
```

Solver statistics

```
62 print s.stats()
```

```
{}
```