

```
0 #
1 #
2 #
3 #
4 #
5 #
6 #
```

## nlpso

```
11 from casadi import *
12 from numpy import *
```

In this example, we will solve a few optimization problems with increasing complexity

## Scalar unconstrained problem

```
19
20 x= SX.sym('x')
21 nlp = {'x':x, 'f':(x-1)**2}
22
23 solver = nlpso('solver', 'ipopt', nlp)
24 sol = solver(lbx=-10, ubx=10)
```

\*\*\*\*\*

This program contains Ipopt, a library for large-scale nonlinear optimization.  
Ipopt is released as open source code under the Eclipse Public License (EPL).

For more information visit <http://projects.coin-or.org/Ipopt>

\*\*\*\*\*

This is Ipopt version 3.12.3, running with linear solver ma57.

```
Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 0
Number of nonzeros in Lagrangian Hessian.....: 1

Total number of variables.....: 1
   variables with only lower bounds: 0
   variables with lower and upper bounds: 1
   variables with only upper bounds: 0
Total number of equality constraints.....: 0
Total number of inequality constraints.....: 0
   inequality constraints with only lower bounds: 0
   inequality constraints with lower and upper bounds: 0
   inequality constraints with only upper bounds: 0

iter    objective    inf_pr  inf_du lg(mu)  ||d||  lg(rg) alpha_du  alpha_pr  ls
   0:  1.00000000e+00  0.00e+00  2.00e+00 -1.0  0.00e+00 -  0.00e+00  0.00e
```

```
   1:  8.2644627e-03  0.00e+00  1.53e-02 -1.0  9.09e-01 -  9.16e-01  1.00e
   2:  3.3212748e-06  0.00e+00  2.08e-17 -1.0  8.91e-02 -  1.00e+00  1.00e
   3:  9.3171258e-10  0.00e+00  7.11e-17 -2.5  1.79e-03 -  1.00e+00  1.00e
   4:  2.3111166e-12  0.00e+00  2.40e-17 -3.8  2.90e-05 -  1.00e+00  1.00e
   5:  3.4736752e-16  0.00e+00  5.92e-17 -5.7  1.50e-06 -  1.00e+00  1.00e
   6:  6.4072417e-22  0.00e+00  3.96e-17 -8.6  1.86e-08 -  1.00e+00  1.00e
```

Number of Iterations.....: 6

	(scaled)	(unscaled)
Objective.....:	6.4072416740416713e-22	6.4072416740416713e
Dual infeasibility.....:	3.9625445352197450e-17	3.9625445352197450e
Constraint violation.....:	0.0000000000000000e+00	0.0000000000000000e
Complementarity.....:	2.5059073699316697e-09	2.5059073699316697e
Overall NLP error.....:	2.5059073699316697e-09	2.5059073699316697e

Number of objective function evaluations	= 7
Number of objective gradient evaluations	= 7
Number of equality constraint evaluations	= 0
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 0
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 6
Total CPU secs in IPOPT (w/o function evaluations)	= 0.002
Total CPU secs in NLP function evaluations	= 0.000

EXIT: Optimal Solution Found.

	proc	wall mean	num	mean
	time	time	evals	proc time
nlp_f	0.000 [s]	0.000 [s]	7	0.00 [ms]
nlp_grad_f	0.003 [ms]	0.000 [s]	8	0.00 [ms]
nlp_hess_l	0.000 [s]	0.000 [s]	6	0.00 [ms]
all previous	0.000 [s]	0.000 [s]		
callback_prep	0.000 [s]	0.000 [s]	7	0.00 [ms]
solver	0.020 [s]	0.003 [s]		
mainloop	0.020 [s]	0.003 [s]		

The solution is obviously 1:

```
26 print sol['x']
    1
27 assert (abs(sol['x']-1)<1e-9)
```

## Constrained problem

```
32 n = 5
33
34 x=SX.sym('x',n)
35
36 Note how we do not distinguish between equalities and inequalities here
37 nlp = {'x':x, 'f':mtimes((x-1).T,x-1), 'g':vertcat(x[1]+x[2],x[0])}
38 solver = nlpsol('solver', 'ipopt', nlp)
39 sol = solver(lbx=-10, ubx=10, lbg=[0,2], ubg=[1,2])
```

This is Ipopt version 3.12.3, running with linear solver ma57.

```
Number of nonzeros in equality constraint Jacobian...: 1
Number of nonzeros in inequality constraint Jacobian.: 2
Number of nonzeros in Lagrangian Hessian.....: 5

Total number of variables.....: 5
   variables with only lower bounds: 0
   variables with lower and upper bounds: 5
   variables with only upper bounds: 0
Total number of equality constraints.....: 1
Total number of inequality constraints.....: 1
   inequality constraints with only lower bounds: 0
   inequality constraints with lower and upper bounds: 1
   inequality constraints with only upper bounds: 0

iter   objective    inf_pr  inf_du lg(mu)  ||d|| lg(rg) alpha_du
alpha_pr ls
  0   5.000000e+00  2.00e+00  2.00e+00  -1.0  0.00e+00  -  0.00e+00  0.00e
    +00  0
  1   2.7716739e+00  0.00e+00  1.16e+00  -1.0  2.00e+00  -  3.75e-01  1.00e
    +00f  1
  2   1.5112117e+00  0.00e+00  4.53e-01  -1.0  1.31e+00  -  9.44e-01  6.62e
    -01f  1
  3   1.5183915e+00  0.00e+00  3.20e-16  -1.7  3.46e-02  -  1.00e+00  1.00e
    +00f  1
  4   1.5009100e+00  0.00e+00  2.03e-04  -3.8  1.73e-02  -  9.88e-01  1.00e
    +00f  1
  5   1.5000028e+00  0.00e+00  2.14e-16  -5.7  9.07e-04  -  1.00e+00  1.00e
    +00f  1
  6   1.5000000e+00  0.00e+00  2.04e-16  -8.6  2.85e-06  -  1.00e+00  1.00e
    +00f  1

Number of Iterations.....: 6
```

	(scaled)	(unscaled)
Objective.....:	1.4999999925191814e+00	1.4999999925191814e
+00		
Dual infeasibility.....:	2.0424918385704731e-16	2.0424918385704731e
-16		
Constraint violation....:	0.0000000000000000e+00	0.0000000000000000e
+00		
Complementarity.....:	2.5191812953934411e-09	2.5191812953934411e
-09		
Overall NLP error.....:	2.5191812953934411e-09	2.5191812953934411e
-09		

Number of objective function evaluations	= 7
Number of objective gradient evaluations	= 7
Number of equality constraint evaluations	= 7
Number of inequality constraint evaluations	= 7
Number of equality constraint Jacobian evaluations	= 7
Number of inequality constraint Jacobian evaluations	= 7
Number of Lagrangian Hessian evaluations	= 6
Total CPU secs in IPOPT (w/o function evaluations)	= 0.003
Total CPU secs in NLP function evaluations	= 0.001

EXIT: Optimal Solution Found.

	proc	wall mean time	num evals	mean proc time
nlp_f	0.000 [s]	0.000 [s]	7	0.00 [ms]
0.01 [ms]				
nlp_g	0.010 [s]	0.000 [s]	7	1.43 [ms]
0.01 [ms]				
nlp_grad_f	0.000 [s]	0.000 [s]	8	0.00 [ms]
0.01 [ms]				
nlp_jac_g	0.000 [s]	0.000 [s]	8	0.00 [ms]
0.01 [ms]				
nlp_hess_l	0.000 [s]	0.000 [s]	6	0.00 [ms]
0.01 [ms]				
all previous	0.010 [s]	0.000 [s]		
callback_prep	0.000 [s]	0.000 [s]	7	0.00 [ms]
0.01 [ms]				
solver	0.000 [s]	0.004 [s]		
mainloop	0.010 [s]	0.004 [s]		

The solution is obviously [2,0.5,0.5,1,1]:

```
42 print sol['x']
    [2, 0.5, 0.5, 1, 1]
44
45 for (i,e) in zip(range(n), [2,0.5,0.5,1,1]):
    assert (abs(sol['x'][i]-e)<1e-7)
```

## Problem with parameters

```
50
51 x=SX.sym('x')
```

```

52 a= SX.sym('a')
53 a_ = 2
54 nlp={ 'x':x, 'p':a, 'f':(x-a)**2}
55
56 solver = nlpsol('solver', 'ipopt', nlp)
57 sol = solver(lbx=-10, ubx=10, p=a_)

```

This is Ipopt version 3.12.3, running with linear solver ma57.

```

Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 0
Number of nonzeros in Lagrangian Hessian.....: 1

```

```

Total number of variables.....: 1
    variables with only lower bounds: 0
    variables with lower and upper bounds: 1
    variables with only upper bounds: 0
Total number of equality constraints.....: 0
Total number of inequality constraints.....: 0
    inequality constraints with only lower bounds: 0
    inequality constraints with lower and upper bounds: 0
    inequality constraints with only upper bounds: 0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
0	4.0000000e+00	0.00e+00	4.00e+00	-1.0	0.00e+00	-	0.00e+00 0.00e+00
1	3.3057851e-02	0.00e+00	5.64e-02	-1.0	1.82e+00	-	8.45e-01 1.00e+00
2	2.8894889e-05	0.00e+00	1.53e-16	-1.0	1.76e-01	-	1.00e+00 1.00e+00
3	4.4774726e-09	0.00e+00	1.08e-16	-2.5	5.31e-03	-	1.00e+00 1.00e+00
4	9.8332283e-12	0.00e+00	2.02e-16	-3.8	6.38e-05	-	1.00e+00 1.00e+00
5	1.4777036e-15	0.00e+00	3.79e-18	-5.7	3.10e-06	-	1.00e+00 1.00e+00
6	2.7255842e-21	0.00e+00	1.26e-17	-8.6	3.84e-08	-	1.00e+00 1.00e+00

Number of Iterations.....: 6

	(scaled)	(unscaled)
Objective.....	2.7255841628426173e-21	2.7255841628426173e-21
Dual infeasibility.....	1.2569571890559792e-17	1.2569571890559792e-17
Constraint violation.....	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity.....	2.5059124009153784e-09	2.5059124009153784e-09
Overall NLP error.....	2.5059124009153784e-09	2.5059124009153784e-09

Number of objective function evaluations = 7

```

Number of objective gradient evaluations      = 7
Number of equality constraint evaluations      = 0
Number of inequality constraint evaluations    = 0
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 0
Number of Lagrangian Hessian evaluations      = 6
Total CPU secs in IPOPT (w/o function evaluations) = 0.003
Total CPU secs in NLP function evaluations    = 0.000

```

EXIT: Optimal Solution Found.

	proc	wall time	num evals	mean
nlp_f	0.000 [s]	0.000 [s]	7	0.00 [ms]
nlp_grad_f	0.000 [s]	0.000 [s]	8	0.00 [ms]
nlp_hess_l	0.000 [s]	0.000 [s]	6	0.00 [ms]
all previous	0.000 [s]	0.000 [s]		
callback_prep	0.000 [s]	0.000 [s]	7	0.00 [ms]
solver	0.010 [s]	0.003 [s]		
mainloop	0.010 [s]	0.003 [s]		

The solution is obviously a:

```
59 print sol['x']
```

2

```
60 assert(abs(sol['x']-a_)<1e-9)
```

The parameter can change inbetween two solve calls:

```
63 sol = solver(lbx=-10, ubx=10, p=2*a_)
```

This is Ipopt version 3.12.3, running with linear solver ma57.

```

Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 0
Number of nonzeros in Lagrangian Hessian.....: 1

```

```

Total number of variables.....: 1
    variables with only lower bounds: 0
    variables with lower and upper bounds: 1
    variables with only upper bounds: 0
Total number of equality constraints.....: 0
Total number of inequality constraints.....: 0
    inequality constraints with only lower bounds: 0
    inequality constraints with lower and upper bounds: 0
    inequality constraints with only upper bounds: 0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du
0	1.6000000e+01	0.00e+00	8.00e+00	-1.0	0.00e+00	-	0.00e+00 0.00e+00
1	1.3223140e-01	0.00e+00	1.95e-01	-1.0	3.64e+00	-	7.31e-01 1.00e+00

```

+00f 1
2 3.6066256e-04 0.00e+00 1.04e-16 -1.0 3.45e-01 - 1.00e+00 1.00e
+00f 1
3 1.0362906e-06 0.00e+00 3.71e-16 -1.7 1.80e-02 - 1.00e+00 1.00e
+00f 1
4 5.6293833e-11 0.00e+00 8.15e-17 -3.8 1.01e-03 - 1.00e+00 1.00e
+00f 1
5 7.7214018e-15 0.00e+00 3.56e-16 -5.7 7.42e-06 - 1.00e+00 1.00e
+00f 1
6 1.4239938e-20 0.00e+00 3.69e-16 -8.6 8.78e-08 - 1.00e+00 1.00e
+00f 1

```

Number of iterations.....: 6

	(scaled)	(unscaled)
Objective.....:	1.4239938056866796e-20	1.4239938056866796e
-20		
Dual infeasibility.....:	3.6930385037381279e-16	3.6930385037381279e
-16		
Constraint violation.....:	0.0000000000000000e+00	0.0000000000000000e
+00		
Complementarity.....:	2.5059305083202185e-09	2.5059305083202185e
-09		
Overall NLP error.....:	2.5059305083202185e-09	2.5059305083202185e
-09		

Number of objective function evaluations	= 7
Number of objective gradient evaluations	= 7
Number of equality constraint evaluations	= 0
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 0
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 6
Total CPU secs in IPOPT (w/o function evaluations)	= 0.002
Total CPU secs in NLP function evaluations	= 0.000

EXIT: Optimal Solution Found.

	proc	time	wall time	mean time	num evals	mean proc time
nlp_f	0.000 [s]	0.000 [s]	0.000 [s]	7	0.00 [ms]	
0.01 [ms]						
nlp_grad_f	0.000 [s]	0.000 [s]	0.000 [s]	8	0.00 [ms]	
0.00 [ms]						
nlp_hess_l	0.000 [s]	0.000 [s]	0.000 [s]	6	0.00 [ms]	
0.00 [ms]						
all previous	0.000 [s]	0.000 [s]	0.000 [s]			
callback_prep	0.000 [s]	0.000 [s]	0.000 [s]	7	0.00 [ms]	
0.01 [ms]						
solver	0.000 [s]	0.003 [s]	0.003 [s]			
mainloop	0.000 [s]	0.003 [s]	0.003 [s]			

The solution is obviously 2\*a:

```
print sol['x']
```

4

```
assert (abs(sol['x']-2*a_)<1e-9)
```